

# “cycle” == “processing cycle”

```
def cycles(d, g, h, m):  
    # -->SENSORY INPUTS --> CCA3 --> MOTOR  
    for d.evaluation_cycles in range(sys.  
        autonomic_check(g)  
        next_scene_from_envrt = (h.envrt_  
        h.input_sensory_vectors_associati  
        h.sequential_error_correcting_mod  
        h.object_segmentation_module(g)  
        h.navigation_module(d, g)  
        h.output_vector_association_module  
        if (next_scene_from_envrt < 0 or  
            d, g, h = update_expected_val  
        return d, g, h, m
```

