# **Caveatron Hardware Version Code Description**

2023-12-31

Software Versions: 3.10 - Current

This is an 11-digit alphanumeric code that defines the specific hardware components inside the Caveatron allowing for different hardware modules to be used with the same software. The table and list below describe what each digit of the code means and provides valid values for each parameter. Note that this list is only valid with the software versions listed above.

Character #	Value Range	Description
0	A-Z	Hardware Revision
1	0-9	Display
2	0-9	Font/Graphics Storage
3	0-9	Laser Rangefinder
4	0-9	Compass
5	0-9	IMU/Gyro
6	0-9	Battery
7	0-9	Battery Gauge
8	0-9	Piezo Buzzer
9	0-9	Bluetooth/GPS (Caveatron SV)
10	-	
11	0-9	LIDAR Module

Example: C434232310-3

### **Hardware Revision**

A = Arduino Due Processor Board (not supported starting with version 2.0)

B = Standard Caveatron (LIDAR) with Teensy 3.6 processor board

C = Standard Caveatron (LIDAR) with Teensy 4.1 processor board

S = Survey Caveatron (non-LIDAR) with Teensy 3.6 processor board

### Display

1 = Coldtears 3.5" 480x320 LCD — Normal (For use with displays with non-inverted colors. This includes both some newer models that use the UTFT\_GHL library and older models with the CTE library)

2 =Updated Coldtears 3.5'' 480x320 LCD - Inverted (For use with some displays that have inverted colors in the default state that use the UTFT\_GHL library. This setting corrects the colors.)

3 = Coldtears 4.0" 480x320 LCD (Uses UTFT\_CTE library)

4 = BuyDisplay 3.5" 480x320 LCD module, 16-bit, capacitive touchscreen

#### **Font/Graphic Storage**

1 = UTFT\_CTE font library

2 = UTFT\_GHL font library (not supported starting with version 2.0)

3 = CVFONT graphic library for use with Teensy 4.1

## **Laser Rangefinder**

- 1 = Uni-T UT390B early version with verbose output
- 2 = Uni-T UT390B normal version
- 3 = JRT Laser distance module with ASCII communications protocol (large or small modules)

4 = JRT Laser distance module with HEX communications protocol (may only be in the smaller sized JRT modules)

# Compass

- 1 = Pololu LSM303DLM, LSM303DLHC, LSM303D, AltIMU-10 v3, AltIMU-10 v4, or MinIMU-9 v3
- 2 = Pololu MinIMU-9 v5 or AltIMU-10 v5

# Gyro/IMU

- 0 = None
- 1 = Pololu L3GD20, L3GD20H, AltIMU-10 v3, AltIMU-10 v4, or MinIMU-9 v3
- 2 = Pololu MinIMU-9 v5 or AltIMU-10 v5
- 3 = Witmotion RM3100 Magnetometer

### **Battery**

- 1 = 4400 mAh 3.7V Li-Ion
- 2 = 5200 mAh 3.7V Li-Ion

## **Battery Gauge**

- 0 = None
- 1 = MAX17043 LiPo Fuel Gauge
- 2 = Sparkfun LiPo Battery Manager (not supported starting with version 2.0)
- 3 = Resistor Voltage Divider

#### Piezo Buzzer

- 0 = None
- 1 = 1-3V directly driven Piezo Buzzer

# Bluetooth/GPS (only applies to Caveatron SV)

- 0 = None
- 1 = HC-05 Bluetooth 2
- 2 = HM-10 Bluetooth 4 BLE
- 6 = Adafruit Ultimate GPS Rev 3

#### **LIDAR**

- 1 = XV LIDAR (4m) (not supported starting with version 2.0)
- 2 = SWEEP LIDAR (25m)
- 3 = RPLIDAR A1M8 (12m) and A2M6 (18m)