

ä½ äŸ!÷!¼(Ææˆæ±ç)ˆâˆšâ€œ,æ¬çè;Žă½ ç)§ç»è·Ÿæˆˆă! ç°;æ€§ă)ƒæ•°ă€,

ă»Šă□©è;™ă,€èŠ,è³⁄₄çš,ă†...ă®¹æ¬ăŸ°ç;€€šă...³ă€,è;™é‡(Ĉă¼šç”5é“ă...
,ăžă¼<éçˆ!¼(Ĉè®Ĉă½ă·Ĉă°ă,ăă,<ç°;æ€§ă)ƒæ•°çš,ăŸ°ç;€çŸŸè¬†!¼(Ĉè;™ă¹Ÿæ¬è;ă...Ÿă”ç”ç¬‡ă-
|ă¹ă¹!ă°%çš,ă,ăæ¬ĵăšˆæ°%«æœ°ă¼šă€„ă»Žè³⁄₄çˆă,Šç°;ă°çŽ°ăœˆă;«æœ%ăă,ăă,ªæœă°††¼(Ĉè;™æœŸé—ˆæˆˆæˆŸă°ă†ă,ă°ăăăă|çš,æé—
®ă¹(Ĉă°è®®†¼(Ææœ%ăœ)é—®éçˆă¹Ÿæ¬æˆˆæ²;æœ%œæf³ă°çš,†¼(Ĉéžă,æœ%œ±ă°†¼(Ĉèˆă®žèè;™è®Ĉæˆˆæ,,Ÿèš%œ(Ĉ°æ,ă□—
çš,†¼(Ĉă,(Ææœă½ăă†æŽŸă†ăŽ%ă€,

çŽ°ăœˆ!¼(Ĉă½ăă¬)Ÿœăă,ăă,ăŸ°ç;€€šă...³çš,5é“ă³⁄₄<éçˆă°††¼(Ĉéçˆç>®ă¹(Ĉèšƒæžéƒ¹⁄₂æ³⁄₄ăœˆă°†æƒæ¬‡ă,-
†¼(Ĉă½ăăăŸè‡ă±è•çăšăă,ăă,ăŸ°ç;€€šă...³ăŽ†¼(Ææˆă)¬ă”ç”ç¬‡ă†èšă€,

ă³⁄₄<éçˆă,ă

æ°%³ăˆç°;æ€§šæ¬¹çˆ<ç>,,\$Ax=b\$çš,æ°%œæœ%œèšƒ†¼(Ĉă...¶ă,†¼š

\$\$
A=\left[\begin{array}{cc}
1 & 2 \\\\
3 & 0 \\\\
-1 & 2
\end{array}\right], b=\left[\begin{array}{c}
1 \\\\
0 \\\\
1
\end{array}\right]
\$\$

èšƒæž†¼š

è;™é‡(ĈèçƒăŸă°†èššƒç°;æ€§šæ¬¹çˆ<ç>,,çš,æ¬¹æ³•†¼(Ĉç°ăăˆ<æ¬é<æ¬æ¶ă...ƒæ³•†¼(Ĉă½ăă¬)Ÿăă,èçƒç¬4èš,çš,ă†...ă®¹ă€,

é|¬ă...ˆ†¼(Ĉă½çæˆăçžă¹;çŸ°œˆµ†¼š

\$\$
\left[\begin{array}{cccc}
1 & 2 & & 1 \\\\
3 & 0 & 0 & 0 \\\\
-1 & 2 & & 1
\end{array}\right]
\$\$

æŽŸç†¼(Ĉăˆ†æŸè;ç®—ăçžă¹;çŸ°œˆµçš,è;Ĉé¶æç¬ă¼ççŸ°œˆµ†¼š

- 1. ç¬ă,€è;Ĉăˆ-3ă¹Ĉç¬ă°Ĉè;Ĉç>,ăšă€,
- 2. ç¬ă,€è;Ĉă¹Ĉç¬ă,°œè;Ĉç>,ăšă€,

\$\$
\left[\begin{array}{cccc}
1 & 2 & & 1 \\\\
0 & -6 & & -3 \\\\
0 & 4 & & 2
\end{array}\right]
\$\$

- 2. ç¬ă°Ĉè;Ĉă¹~\$\\frac{1}{3}\$ă¹Ĉç¬ăă,€è;Ĉç>,ăšă€,
- 3. ç¬ă°Ĉè;Ĉă¹~\$\\frac{2}{3}\$ă¹Ĉç¬ăă,°œè;Ĉç>,ăšă€,
- 4. ç¬ă,°œè;Ĉă¹~\$-\\frac{1}{6}\$ă€,

\$\$
\left[\begin{array}{cccc}
1 & 0 & & 0 \\\\
0 & 1 & & \\frac{1}{2} \\\\
0 & 0 & & 0
\end{array}\right]
\$\$

æœăăžă¼—ă†°èŸç°;æ€§šæ¬¹çˆ<ç>,,çš,ăˆˆă,€èšƒ†¼š

ä¾<éç~ä°œ

$$x^{\frac{3}{4}} \cdot x^0 = x^{-1} \cdot x^{\frac{7}{4}}$$
$$\mathfrak{e}\mathfrak{s}\mathfrak{x}\mathfrak{a}\mathfrak{z}\mathfrak{i}^{1/4}\mathfrak{s}$$
[illegible]
$$e_1 - a \dots i^{1/4} C e^{1/2} c a^{\hat{a}} c z^{\hat{a}} ; c \ddot{Y} \odot e \sim \mu i^{1/4} s$$
[illegible]

1. $\zeta \rightarrow \bar{a}, \epsilon \in \langle \mathbb{E} \bar{a}^{1 \sim 1} a' \mathbb{E} \zeta \rightarrow \bar{a}^0 \mathbb{E} \epsilon \rangle, \check{a} \check{S} \text{ i/4} \rangle$
2. $\zeta \rightarrow \bar{a}^0 \mathbb{E} \epsilon \in \langle \mathbb{E} \bar{a}^{1 \sim 1/2} \check{a} \epsilon,$

$$\ddot{a}^{1/2}_i \zeta'' \ddot{a}_j \rangle \ddot{a} \dots f \hat{a} - i^{1/4} \mathbb{E} \hat{a}^{3/4} - \hat{a}^\circ \zeta^{001} \mathfrak{x} \textcircled{\mathbb{S}} \mathfrak{S} \mathfrak{e} \S \mathfrak{f} i^{1/4} \mathfrak{S}$$

ä,ä,æ,æ,ÿ,ÿ,4,4,Ê,Ê,Ž,Ž,â,â,ç,ç,;æ,æ,§,§,æ,æ,¹,¹,ç,ç,«»,«»,\$A,x=0\$,ç,ç,é,é,ç,ç,»è,è,§,§,fi,fi,4,4,Ê,Ê,ä,ä,ç,ç,ž,ž,ä,ä,¹,¹,ç,ç,ÿ,ÿ,©,©,é,é,µ,µ,š,š,â,â,è,è,³,³,¹,¹,4,4,Ê,Ê,f,f,½,½,â,â,ÿ,ÿ,ç,ç,««â,â,³,³,â,â,¼,¼—â,â,†,†,¹,¹,4,4,š,š

$$\lambda \begin{bmatrix} c \\ 1 \\ 1 \\ -1 \end{bmatrix}$$

æœĤăŽĩ¼ĈæŠšç%¹æ®ŠèšŁă’ĈéĈšç”’èšŁç»„ă^èµ:æŸă°±æ~ĩ¼š

\$\$
x=\left[\begin{array}{l}\end{array}\right]
0 \\\frac{1}{2} \\\0
\end{array}\right]+\lambda\left[\begin{array}{c}\end{array}\right]
1 \\\1 \\\-1
\end{array}\right]
\$\$

ă³¼<éç~ă,%

è®¡ç®—çŸŸ©é~µăĩ~\$AB\$ăĤ,

\$\$
A=\left[\begin{array}{ccc}\end{array}\right]
1 \& 2 \& 3 \\\0 \& -1 \& 2
\end{array}\right], B=\left[\begin{array}{ccc}\end{array}\right]
4 \& -1 \& 2 \\\0 \& 2 \& 1
\end{array}\right]
\$\$

èšŁæžĩ¼š

èĭ™é†ĈèĈfă~Ÿă°†ăŸ°æœ~çš„çŸŸ©é~µăĩ~èĭç®—ĩ¼Ĉç%¹ă^«æ~æ™®éĈšçŸŸ©é~µăĩ~ĩ¼Ĉăªæœ%œç>‚é„»éŸªæ•°ăĈĤ'é...
çš„çŸŸ©é~µæ%œf½ç>‚ăĩ~ĩ¼Ĉăĩ½ă~ă»Ÿă„èĈfç—3èš„çš„ă†...ă®¹ăĤ,
çŸŸ©é~µăĩ~æ—æ³•ă®Ĉæ~ĩ¼Ĉăª>ă„°\$A\$æ~2èĭĈ3ă^—çŸŸ©é~µĩ¼Ĉ\$B\$ă¹Ÿæ~2èĭĈ3ă^—çŸŸ©é~µĩ¼Ĉ\$A\$ă'Ĉé„»ă±...ç»'ă°ă„ăĈăĤ,

ă³¼<éç~ă»

è®¡ç®—çŸŸ©é~µăĩ~\$AB\$ăĤ,

\$\$
A=\left[\begin{array}{ccc}\end{array}\right]
1 \& 2 \& 3 \\\0 \& -1 \& 2
\end{array}\right], B=\left[\begin{array}{cc}\end{array}\right]
4 \& -1 \\\2 \& 0 \\\2 \& 1
\end{array}\right]
\$\$

èšŁæžĩ¼š

èĭ™é†ĈèĈfă~Ÿă°†ăŸ°æœ~çš„çŸŸ©é~µăĩ~èĭç®—ĩ¼Ĉç%¹ă^«æ~æ™®éĈšçŸŸ©é~µăĩ~ĩ¼Ĉăª½ă~ă»Ÿă„èĈfç—3èš„çš„ă†...ă®¹ăĤ,
çŸŸ©é~µăĩ~ă~ă»Ÿă®Ĉæ~ĩ¼Ĉăª>ă„°ă„ă„çŸŸ©é~µçš„é„»ă±...ç»'ă°ĭç>‚ăĈĩ¼Ĉæ<Ł\$a_{11}\$ă„¾ă¾¼ĩ¼š\$a_{11}=1\times 4+2\times 2+3\times 2=14\$ĩ¼Ĉç>“æžœĩ¼š

\$\$
A B=\left[\begin{array}{cc}\end{array}\right]
14 \& 2 \\\2 \& 2
\end{array}\right]
\$\$

ă³¼<éç~ă°”

â†€®¼\$R^{3}\$â'Œâ®fçš,è¿ç®—\$\\angle\hat{A},\hat{A}\cdot\angle\$î¼Œ\$ x,y\in R^{3}\$î¼Œæ^“ä»¬æœ%oi¼š

\$\$
\\angle x,y\\angle =x^{T}\\ A\\ y,\\ A=\\left[\\begin{array}{ccc}
4\\&2\\&1\\|\\|\\|
0\\&4\\&-1\\|\\|\\|
1\\&-1\\&5\\
\\end{array}\\right]
\$\$

é,£ä¹¼Œ\$\\angle\hat{A},\hat{A}\cdot\angle\$æ~â†…ç§~â—î¼Ÿ

è\$£æž¹¼š

è¿™é†Œèƒä¬Ÿä°†â†…ç§¬¼Œä»Ÿäšâ†…ç§¬çš,æŒ§è¬¬ä¹¼,Œî¼šâ¬¼ç§°æŒ§î¼Œä½ä¬ä»Ÿä,èƒƒç¬10èš,çš,â†…â®'äŒ,

é%œœ©\$x=\\left[\\begin{array}{lll}1\\&1\\&0\\end{array}\\right]^{T}\$î¼Œ\$y=\\left[\\begin{array}{lll}1\\&2\\&0\\end{array}\\right]^{T}\$î¼ŒŒŒšè¿®¿ç®—î¼ŒŒèƒ¹½âŒŸâ¼—â^oî¼š

\$\$
\\begin{array}{l}
\\angle x,y\\angle =16\\|\\|\\|
\\angle y,x\\angle =14\\|\\|\\|
\\angle x,y\\angle \\neq\\angle y,x\\angle
\\end{array}
\$\$

ä°žæ~î¼Œ\$\\angle\hat{A},\hat{A}\cdot\angle\$æ~ä,â¬¼ç§°çš,äŒ,