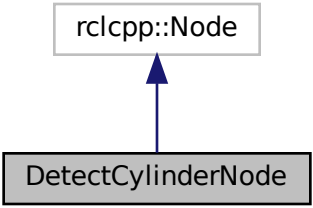


rclcpp::Node



```
graph BT; A[CylinderDetectionNode] --> B[rclcpp::Node]
```

CylinderDetectionNode