

# Deterministic Fifth-Force Falsification for a Higgs-Mixed Scalar Portal

## Using Eöt–Wash Yukawa Limits

Author Name(s)  
Affiliation(s)  
`email@domain`

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### Abstract

This note transcribes a lab-mode analysis into a reviewer-proof, publication-style form. We treat the torsion-balance Yukawa constraint as an *exact falsification check* for a specific portal mapping rather than a generic parameter scan. The key observable is the ratio  $r(\lambda) = \alpha_{\text{pred}}/\alpha_{\text{max}}(\lambda)$ . In the real-only window considered here, the closest-approach result  $r_{\text{max}} \simeq 2.4 \times 10^{-9}$  implies the mapping would need to be wrong by  $\mathcal{O}(10^8)$  (multiplicatively) for this channel to become near-detectable or excluding. We also summarize a robust workflow: fixed-point mapping sweeps, real-domain envelope construction, targeted mixture sampling, and audit-ready outputs.

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## 1 Context and the core observable

Temporary URLs and link rot are a practical reproducibility hazard, so the pipeline should be built around versioned, permanent artifacts (see Sec. 8). Science-wise, the real-only result  $r_{\max} \approx 2.4 \times 10^{-9}$  is an unusually clean outcome: it is dimensionless, operationally meaningful, and difficult to critique as a presentation artifact.

Define

$$r(\lambda) = \frac{\alpha_{\text{pred}}(\lambda)}{\alpha_{\max}(\lambda)}, \quad (1)$$

where  $\alpha_{\max}(\lambda)$  is the experimental upper bound on Yukawa strength at range  $\lambda$ , and  $\alpha_{\text{pred}}(\lambda)$  is the model prediction under a specified mapping.

## 2 Crisp scaling numbers from the real-only maximum

Let  $r_{\max} = 2.4 \times 10^{-9}$ . The multiplicative scale factors required on  $\alpha_{\text{pred}}$  to reach:

- near-detectable-ish  $r = 0.1$ :

$$s_{0.1} = \frac{0.1}{2.4 \times 10^{-9}} = \frac{1}{2.4} \times 10^8 \approx 4.1667 \times 10^7, \quad (2)$$

- the exclusion boundary  $r = 1$ :

$$s_1 = \frac{1}{2.4 \times 10^{-9}} = \frac{1}{2.4} \times 10^9 \approx 4.1667 \times 10^8. \quad (3)$$

The corresponding “orders of magnitude below” statement is

$$\log_{10}\left(\frac{1}{2.4 \times 10^{-9}}\right) = \log_{10}(4.1667 \times 10^8) \approx 8.62. \quad (4)$$

This single scaling sentence is useful because it converts a null result into:

*“The model-to-observable mapping would need to change by  $\sim 10^8$  to matter in this experimental window.”*

## 3 Exact falsification check for a Higgs-mixed scalar portal

### 3.1 Experimental template

Eöt-Wash constraints are commonly presented as an upper bound on Yukawa deviations of the form

$$V(r) = -\frac{Gm_1m_2}{r} \left(1 + \alpha e^{-r/\lambda}\right). \quad (5)$$

To test a scalar mediator, the mapping needs:

- mass → range:  $\lambda = \hbar/(m_\phi c)$ ,
- coupling → Yukawa strength:  $\alpha = \alpha(m_\phi; \text{model parameters})$ .

If the pipeline uses a placeholder such as  $\alpha_{\text{pred}} = \alpha_{\text{eff}}^2$  without physical normalization, then  $r \ll 1$  can mean only “the placeholder is tiny,” not “the scalar is safe.”

### 3.2 Higgs mixing bridge and the $K \sin^2 \theta$ normalization

For an unscreened scalar coupling through Higgs mixing, the macroscopic Yukawa strength can be written

$$\alpha \approx K \sin^2 \theta, \quad K = \frac{f_N^2}{4\pi} \left( \frac{\bar{M}_{\text{Pl}}}{v} \right)^2, \quad (6)$$

where  $f_N$  is the effective nucleon scalar form factor,  $\bar{M}_{\text{Pl}}$  is the reduced Planck mass, and  $v \simeq 246 \text{ GeV}$  is the Higgs vacuum expectation value.

Given a digitized  $\alpha_{\text{max}}(\lambda)$  curve, this implies the bound

$$\theta_{\text{max}}(\lambda) \approx \sqrt{\frac{\alpha_{\text{max}}(\lambda)}{K}} \quad (\text{small-angle regime}). \quad (7)$$

In the window reported in the lab notes, the inferred bounds were:

- $\theta_{\text{max}}$  ranging from  $\sim 7.9 \times 10^{-13}$  down to  $\sim 6.7 \times 10^{-17}$  across  $\lambda \approx 3.0 \times 10^{-5} \text{ m}$  to  $9.3 \times 10^{-4} \text{ m}$ ,
- corresponding mediator masses  $m_\phi \approx 2.1 \times 10^{-4} \text{ eV}$  to  $6.6 \times 10^{-3} \text{ eV}$  (via  $\lambda = \hbar/(m_\phi c)$ ).

This yields a clean falsifier sentence:

*If the model predicts  $\theta(\lambda) > \theta_{\text{max}}(\lambda)$  anywhere in the real-covered window, it is excluded by Eöt-Wash; if  $\theta(\lambda) < \theta_{\text{max}}(\lambda)$  everywhere, it is allowed (and likely undetectable in that window).*

### 3.3 Portal coefficient bound

For a typical Higgs-portal term

$$\mathcal{L} \supset \mu S |H|^2, \quad (8)$$

the small-mixing limit gives

$$\theta \approx \frac{\mu v}{m_h^2 - m_\phi^2} \approx \frac{\mu v}{m_h^2} \quad (m_\phi \ll m_h). \quad (9)$$

Therefore,

$$\mu_{\text{max}}(\lambda) \approx \theta_{\text{max}}(\lambda) \frac{m_h^2}{v}. \quad (10)$$

Using  $m_h \simeq 125 \text{ GeV}$  and  $v \simeq 246 \text{ GeV}$ ,

$$\frac{m_h^2}{v} \approx \frac{125^2}{246} \text{ GeV} \approx 63.5 \text{ GeV}. \quad (11)$$

With the  $\theta_{\text{max}}$  range above, this corresponds to approximately

$$\mu \lesssim 4 \times 10^{-6} \text{ to } 5 \times 10^{-2} \text{ eV} \quad (\text{depending on } \lambda \text{ within the window}). \quad (12)$$

## 4 Mapping sensitivity sweep: make mapping the only dial that moves

The reviewer-proof trick is to freeze the sampled hypothesis ensemble so every mapping mode is evaluated on the same point cloud.

## 4.1 Deterministic point cloud

Step A: generate and save a deterministic point cloud once (store whatever the mapping needs, e.g.,  $\lambda$ ,  $\alpha_{\text{eff}}$ , and any underlying parameters that feed  $\alpha_{\text{pred}}$ ).

## 4.2 Evaluation-only passes

Step B: run evaluation-only passes:

- Mode A: current placeholder mapping,
- Mode B: alternate functional dependence (not just a scale),
- Mode C: explicit scale knob  $s_{\text{ff}}$  multiplying a baseline mapping.

For a methods section, define mapping modes explicitly:

$$\text{A: } \alpha_{\text{pred}} = f_A(\theta), \quad (13)$$

$$\text{B: } \alpha_{\text{pred}} = f_B(\theta), \quad (14)$$

$$\text{C: } \alpha_{\text{pred}} = s_{\text{ff}} f_A(\theta). \quad (15)$$

Only the mapping changes; sampled points remain identical.

## 4.3 Reported metrics

Step C: report per mode:

- coverage fraction (should be 1.000 in real-only mode),
- $r_{\text{max}}$ , median  $r$ , and a tail metric such as  $r_{95}$  or  $r_{99}$ ,
- required scale  $s$  to reach  $r = 0.1$  and  $r = 1$  computed from  $r_{\text{max}}$ .

## 4.4 Conservative monotone filtering: a reviewer trap to avoid

If you apply a monotone filter to a digitized  $\alpha_{\text{max}}(\lambda)$  curve, document precisely what “conservative” means:

- If conservative means *avoid false exclusion / avoid overstating detectability*, then bias  $\alpha_{\text{max}}$  upward (since larger  $\alpha_{\text{max}}$  makes  $r$  smaller).
- A running-min on  $\alpha_{\text{max}}$  makes constraints more stringent (smaller  $\alpha_{\text{max}}$ ), increases  $r$ , and can create a false “closer to detectable” impression.

## 5 Expand real constraints into the mm–cm regime: delete the mirage properly

If the “hunt band” lived outside real  $\lambda$  coverage, it was not an empirical statement. The clean extension is to ingest additional *real* curves.

## 5.1 Curve objects and domain handling

Treat each experiment curve as an object with:

- a domain  $[\lambda_{\min}, \lambda_{\max}]$ ,
- a defined interpolation method (log–log interpolation is typical for these plots).

## 5.2 Real envelope construction

Build the combined real envelope as

$$\alpha_{\max}^{\text{env}}(\lambda) = \min_i \alpha_{\max}^{(i)}(\lambda), \quad (16)$$

only where at least one curve is defined.

The coverage rule becomes:

A real-only point is valid iff  $\lambda$  lies in the union of all real domains.

Include a coverage-map plot (even a shaded interval bar) so readers can see at a glance which ranges are real-supported.

## 6 Increase NPTS and targeted sampling: make the statistics boring

The goal is to stop fractions from wobbling and to make  $r$ -distribution summaries stable. The key is targeted sampling matched to real-only support.

Sample  $\log \lambda$  from a mixture of log-uniform windows, one per real interval, optionally with a smaller broad component to capture transitions at window boundaries:

- choose a window index  $k$  according to weights (equal, or proportional to window log-width),
- sample  $\log \lambda \sim \text{Uniform}(\log a_k, \log b_k)$ .

Keep seeds fixed and record them (plus git commit hash) into every artifact.

## 7 Audit bundle: minimal “boring science UI” fields

A reviewer-proof summary output should include:

- Run metadata: date, seed, git hash, NPTS, mapping mode, real-only flag.
- Coverage: real-only coverage fraction + list of real windows used.
- Results: excluded fraction ( $r > 1$ ), near-detectable fraction ( $r > 0.1$ ),  $r_{\max}$ ,  $r_{50}$ ,  $r_{95}$  (or  $r_{99}$ ).
- Sensitivity:  $s_{0.1}$  and  $s_1$  computed from  $r_{\max}$ .
- Location of max:  $\lambda(r_{\max})$ .

## 8 Licensing and permanence hygiene

Even if reviewers should not care, humans do. A mismatched LICENSE vs CITATION vs README is a low-effort doubt generator.

Clean options:

- One-license everywhere (CC0 everywhere, or CC-BY everywhere), or
- Standard research stack: code MIT/Apache-2.0; paper/docs CC-BY-4.0; data CC0 (optional).

Then ensure README + LICENSE + CITATION.cff agree.

For link permanence: GitHub Release (tagged) + attach zips as assets, then Zenodo GitHub integration to mint a DOI per release, and point CITATION.cff to the DOI.

## 9 Conclusion

The real-only result is a strong null outcome: under current mapping assumptions and real-only constraints, this channel does not test the model in the examined window. The next step is not to “find a signal” but to make the mapping and coverage so deterministic and honest that the conclusion becomes unavoidable: to matter here, the model-to-observable mapping must change by  $\sim 10^8$ .

## A Optional: minimal pseudocode for a mapping sweep

Listing 1: Shape of a fixed-point mapping sweep (pseudocode).

```
# 1) Sample model points ONCE (deterministic seed)
points = sample_point_cloud(seed=SEED, npts=NPTS, real_only=True)

# 2) Evaluate-only passes: mapping modes
for mode in ["A", "B", "C"]:
    s_list = SFF_VALUES if mode == "C" else [1.0]
    for s_ff in s_list:
        r = compute_r(points, mode=mode, s_ff=s_ff)
        summarize(r) # max, tail quantiles, fractions, scaling factors
```