

Deep Learning for Natural Language Processing



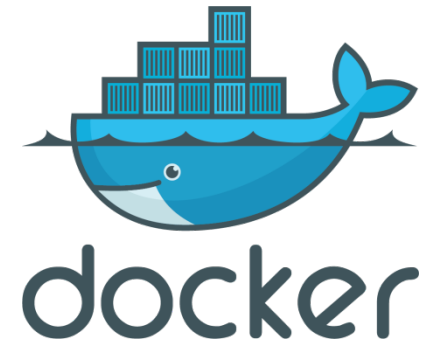
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Exercise 1 – Tool Kick-off

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- „Containerization“ tool which can provide the same execution environment on different operating systems
- Idea:
 1. We provide you with a Docker container on [Moodle](#).
 2. You will write code runnable in that container and submit your python scripts
 3. The tutor, can execute your code without worrying about virtualenvironments, conflicting Keras versions, etc.
- Careful warning: This is our first year of using Docker for DL4NLP.



Docker (cont.)

- Installation: see readme.md in the ZIP archive from moodle
- A hint from 2019 to Windows users:
 - Use Linux in a VM or use docker-toolbox

- Home exercises have to be implemented in Python 3
- Example: read numbers from a file and compute the median value

```
1  def median(num):      # function definition
2      num.sort()
3      length = len(num)
4      if length % 2 == 1:
5          return num[(length) // 2]
6      return 0.5 * (num[length // 2 - 1] + num[(length // 2)])
7
8  filename = "num.txt"
9  numbers = list()
10 with open(filename) as f:    # open file and close it later on (even after an exception)
11     for line in f:
12         numbers += [int(x) for x in line.split()]
13
14
15 med = median(numbers)      # call custom function
16 print(med)                 # and print result
```

Python – Programming Language (cont.)

- Good quick reference for newcomers to Python: <https://learnxinyminutes.com/docs/python3/>

NumPy – Python Library

- Powerful library for scientific computing in Python
 - ndarray: special n-dimensional data type optimized for vector computations
 - **significant performance speedup** possible compared to native Python
 - linear algebra methods
 - **broadcasting** functions
- Installation (if numpy isn't already packaged with your Python distribution)
 - Refer to the installation guide at <https://scipy.org/install.html> (SciPy contains NumPy)
 - Mind your PATH variables when using different Python installations!

NumPy by Example



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- element-wise computations are the default case

```
1  input_list_a = [ [2,-4,2], [1, 5, 0], [-2,6,8] ]
2  a_m = np.matrix(input_list_a)                # numpy matrix
3  a_arr = np.array([e for lst in input_list_a for e in lst]) # ndarray
4
5  input_list_b = [ [1,2,3], [6,2,1], [2,0,1] ]
6  b_m = np.matrix(input_list_b)                # numpy matrix
7  b_arr = np.array([e for lst in input_list_b for e in lst]) # ndarray
8
9  c_m = a_m * b_m                             # matrix multiplication
10 c_arr = a_arr * b_arr                       # element-wise multiplication
11
12 print(c_m)
13 # [[-18  -4   4]
14 #  [ 31  12   8]
15 #  [ 50   8   8]]
16
17
18 print(c_arr)
19 # [ 2 -8  6  6 10  0 -4  0  8] # 1D list
```

$$\begin{pmatrix} 2 & -4 & 2 \\ 1 & 5 & 0 \\ -2 & 6 & 8 \end{pmatrix} \cdot \begin{pmatrix} 1 & 2 & 3 \\ 6 & 2 & 1 \\ 2 & 0 & 1 \end{pmatrix} = ?$$

NumPy: Easy mathematical computations (1)

- Perform mathematical operations easily using NumPy
- *ndarray* != list

```
1  m1 = np.matrix([ [2,-4,2], [1, 5, 0], [-2,6,8] ])
2  m2 = np.matrix([ [2,2,3], [6,6,9], [1,4,8] ])
3
4  matrices = [m1, m2]
5  invertible = list()
6
7  # compute inverse matrix if possible
8  for m in matrices:
9      print("Current matrix: ", m)
10     print("Shape of current matrix: ", m.shape)
11
12     det = np.linalg.det(m)
13     print("Determinant of current matrix: ", det)
14
15     if det != 0:
16         inv = np.linalg.inv(m)
17         invertible.append(inv)
18         print("Inverse of current matrix: ", inv)
19     else:
20         print("Current matrix is not invertible.")
```

*use Python lists to define
matrices in NumPy*

*compute determinante to
check if matrix is invertible*

invert matrix

NumPy: Easy mathematical computations (2)



- Efficient implementations of reoccurring mathematical tasks
- Check documentation to understand behavior

```
1  import numpy as np
2
3  input_1 = [[1,2], [3,4]]
4  input_2 = [[2,3], [4,5]]
5
6  v1 = np.array(input_1).flat[:]
7  v2 = np.array(input_2).flat[:]
8  d = np.dot(v1, v2)                # dot product
9  print(d)
10 # 40
11
12 v1 = np.matrix(input_1)
13 v2 = np.matrix(input_2)
14 d = np.dot(v1, v2)                # dot product
15
16 print("dot product = ", d)
17 # [[10, 13]
18 #   [22, 29]]
```

NumPy – Broadcasting (1)

- allows computations on arrays with different but compatible shapes
- can result in a significant performance speedup
- improves code readability and reduces code length

```
1  import numpy as np
2
3  input = [ [2,-4,2], [1, 5, 0], [-2,6,8] ]
4  a_m = np.matrix(input)
5
6  scalar = 3
7  res = scalar * a_m  # scalar is "broadcast" across the larger
8                      # array so that they have compatible shapes
9
10 print(res)
11 # [[ 6 -12  6]
12 #  [ 3  15  0]
13 #  [-6  18 24]]
```

Multiply a matrix by a scalar

NumPy – Broadcasting (2)

- Broadcasting is not always possible
- *numpy.reshape* allows to change explicitly the dimension

1	<code>x = np.arange(4)</code>	array containing the integer values 0,1,2,3
2	<code>y = x.reshape(1,4)</code>	first argument: #rows second argument: #columns
3	<code># error = x.reshape(4,2)</code>	Impossible to fill a 4x2 matrix with four numbers
4	<code>yy = x.reshape(1,4)</code>	
5	<code>yyy = x.reshape(2,2)</code>	2x2 matrix
6	<code>z = np.ones(5)</code>	get list with 5 ones
7	<code>w = np.ones((3,4))</code>	get 3x4 matrix initialized with ones

-
- ValueError: operands could not be broadcast together with shapes (1,4) (5,)

NumPy – Broadcasting (3)

- Possible use case:
 - 256x256x3 array of RGB values
 - Scale each color in the image by a different value
- Use broadcasting mechanism to solve trivial problems

„Find the nearest value to x in the list l“

```
1  x = 3.14159265359
2  l = np.random.uniform(3,4,1000000)
3  pi = l.flat[np.abs(l - x).argmin()]
4  print(pi)
```

returns a ndarray

Do you see the
broadcasting operation?

NumPy – Performance Tips (1)

- It is possible to write highly optimized code with NumPy.
- It is possible to write non-optimized and even slow code with NumPy.

Is data copied or not? Memory alignment
Efficient data access Broadcasting rules
Fancy indexing

- Copy: Original data is copied to a newly allocated memory
- View: Modifications affect the original data
 - Compare with pointers in C

NumPy – Performance Tips (2)

Copy vs. View:

```
1  x = np.arange(100)
2  y = x.view()           # equivalent to y = x[:]
3  z = x.copy()
4
5  print(x)
6  y[0] = 99
7  print(x)
8  print(z)
```

- It is not always obvious if you work on a copy or on a view

```
1  x = 5
2  x += 5           # inplace
3
4  # vs.
5
6  x = 5
7  x = x + 5       # data copy is made
```

*Imagine you work on an array
containing some billion values...*

NumPy – Performance Tips (3)

- Think about indexing!

```
1  x = np.array([[1,2,3,4],[5,6,7,8]])
2  y = x[[0], :]    # copy
3  print(y)
4  y = x[:1, :]
5  print(y)         # view
```

- Many NumPy functions have an additional 'out' parameter.

- avoid allocating new memory data, but reuse memory

```
1  arr = np.arange(-5,5)
2  arr_copy = np.abs(arr)
3  print(arr)                # [-5 -4 -3 -2 -1  0  1  2  3  4]
4
5  print(arr_copy)           # [5 4 3 2 1 0 1 2 3 4]
6
7  np.abs(arr, out=arr)
8  print(arr)                # [5 4 3 2 1 0 1 2 3 4]
```

NumPy – Performance Tips (4)



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Trigonometric functions

<code>sin(x[, out])</code>	Trigonometric sine, element-wise.
<code>cos(x[, out])</code>	Cosine element-wise.
<code>tan(x[, out])</code>	Compute tangent element-wise.
<code>arcsin(x[, out])</code>	Inverse sine, element-wise.
<code>arccos(x[, out])</code>	Trigonometric inverse cosine, element-wise.
<code>arctan(x[, out])</code>	Trigonometric inverse tangent, element-wise.
<code>hypot(x1, x2[, out])</code>	Given the “legs” of a right triangle, return its hypotenuse.
<code>arctan2(x1, x2[, out])</code>	Element-wise arc tangent of <code>x1/x2</code> choosing the quadrant correctly.
<code>degrees(x[, out])</code>	Convert angles from radians to degrees.
<code>radians(x[, out])</code>	Convert angles from degrees to radians.
<code>unwrap(p[, discout, axis])</code>	Unwrap by changing deltas between values to 2π complement.
<code>deg2rad(x[, out])</code>	Convert angles from degrees to radians.
<code>rad2deg(x[, out])</code>	Convert angles from radians to degrees.

Hyperbolic functions

<code>sinh(x[, out])</code>	Hyperbolic sine, element-wise.
<code>cosh(x[, out])</code>	Hyperbolic cosine, element-wise.

...

<http://docs.scipy.org/doc/numpy-1.10.0/reference/routines.math.html>

NumPy – Performance Tips (5)

Data Alignment

- contiguous array: array is stored in an unbroken block of memory
- rows are stored next to each other \Rightarrow C contiguous (NumPy)
- columns are stored next to each other \Rightarrow Fortran contiguous

NumPy – Performance Tips (7)

Data Alignment

- Broadcasting not possible if data is not contiguously stored in memory

```
1  a = np.array([[1,2,4,4], [3,9,8,1], [1,1,7,5]])
2  b = a.copy()
3  print(a)
4  # [[1 2 4 4]
5  #   [3 9 8 1]
6  #   [1 1 7 5]]
7
8  a.shape = (12)
9  print(a)
10 # [1 2 4 4 3 9 8 1 1 1 7 5]
11
12 b = b.T                # transpose matrix
13 print(b)
14 # [[1 3 1]
15 #   [2 9 1]
16 #   [4 8 7]
17 #   [4 1 5]]
18
19 c = b.copy()
20 b.shape = (12)         # AttributeError: incompatible shape for a non-contiguous array
21 c = c.reshape(12)      # new memory allocated
22 print(c)
23 # [1 3 1 2 9 1 4 8 7 4 1 5]
```

Operation would require jumping forwards and backwards in memory ⇨ A transposed 2D matrix cannot be flattened without a copy.

NumPy – Compute the outer product (1)

- short reminder: special case of the *Kronecker product* of matrices
 - operation on two matrices of arbitrary size
- Example:

NumPy – Compute the outer product (2)



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Traditional approach

```
1  x = np.array([1,3,2])
2  y = np.array([2,1,0,3])
3
4  x=x[:, np.newaxis]
5  x = np.tile(x, (1,4))
6  y=y[np.newaxis, :]
7  y=np.tile(y, (3,1))
8
9  print(x)
10 # [[1 1 1 1]
11 #   [3 3 3 3]
12 #   [2 2 2 2]]
13
14 print(y)
15 # [[2 1 0 3]
16 #   [2 1 0 3]
17 #   [2 1 0 3]]
18
19 print(x*y)
20 # [[2 1 0 3]
21 #   [6 3 0 9]
22 #   [4 2 0 6]]
23
24 ..
```

Broadcasting approach

```
1  x = np.array([1,3,2])
2  x = x.reshape(3,1)
3  y = np.array([2,1,0,3])
4
5  print(x.shape)
6  # (3,1)
7
8  print(y.shape)
9  # (4,)
10
11 print(x*y)
12 # [[2 1 0 3]
13 #   [6 3 0 9]
14 #   [4 2 0 6]]
```

□ shorter and *faster*

NumPy – Implementation of evaluation system

- Evaluation of classification problems:
 - **Accuracy**: fraction of correct classifications
 - **Recall**: the fraction of relevant instances that are retrieved
 - **Precision**: fraction of retrieved instances that are relevant
 - **F1**: harmonic mean of precision and recall

- **Contingency matrix:**

		gold				
predicted		Label 1	Label 2	Label 3	Label 4	Label 5
	Label 1	3	6	1	3	7
	Label 2	5	6	7	4	5
	Label 3	5	3	4	2	9
	Label 4	3	1	0	8	1
	Label 5	13	2	1	4	7

Computation of Accuracy

- Accuracy: fraction of correct classifications
 - (sum of diagonal) / (sum of all cells)

gold

	Label 1	Label 2	Label 3	Label 4	Label 5
Label 1	3	6	1	3	7
Label 2	5	6	7	4	5
Label 3	5	3	4	2	9
Label 4	3	1	0	8	1
Label 5	1	2	1	4	7

predicted

- **cm**: contingency matrix
 - Quadratische Matrix

```
denominator = np.sum(cm)
if denominator != 0:
    accuracy = sum(np.diagonal(cm)) / denominator
```

Computation of Precision

- Precision: fraction of retrieved instances that are relevant
 - respectively a specific label \times computation of a confusion matrix for label
 - Precision = $12/(12+14)$

		gold	
predicted			
		12	14
		14	16

fixed row,
all columns except current one

```
denominator = cm[label_id, label_id] + sum(cm[label_id, :][i] for i in range(len(cm[label_id, :]))) if i != label_id
if denominator != 0:
    precision = cm[label_id, label_id] / denominator
```

Final Result



```
def aprf(self, cm, label_id):  
  
    accuracy = 0  
    precision = 0  
    recall = 0  
    f1 = 0  
  
    denominator = np.sum(cm)  
    if denominator != 0:  
        accuracy = sum(np.diagonal(cm)) / denominator  
  
    denominator = cm[label_id, label_id] + sum(cm[label_id,:][i] for i in range(len(cm[label_id,:]))) if i != label_id  
    if denominator != 0:  
        precision = cm[label_id, label_id] / denominator  
  
    denominator = cm[label_id, label_id] + sum(cm[:,label_id][i] for i in range(len(cm[:,label_id]))) if i != label_id  
    if denominator != 0:  
        recall = cm[label_id, label_id] / denominator  
  
    denominator = precision + recall  
    if denominator != 0:  
        f1 = 2 * precision * recall / denominator  
  
    return (accuracy, precision, recall, f1)
```