

# Implicit/Explicit scheme for 2D advection diffusion problem

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## Mech587 Project #2

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# 2D advection-diffusion: Definition

## ➤ Problem description:

- The current value of the function is known.
- The function follows certain condition on the boundary.
- The evolution of the function is governed by the governing equation.
- We want to predict the solution in the future

## ➤ Governing equation

$$\underbrace{\frac{\partial \phi}{\partial t}}_{\text{Evolution}} + \underbrace{u \frac{\partial \phi}{\partial x} + v \frac{\partial \phi}{\partial y}}_{\text{advection Wave-like solution}} = \alpha \underbrace{\left( \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} \right)}_{\text{Diffusion Damping/smear}} \text{ in } (0, T) \times \Omega$$

## ➤ Initial condition (IC)

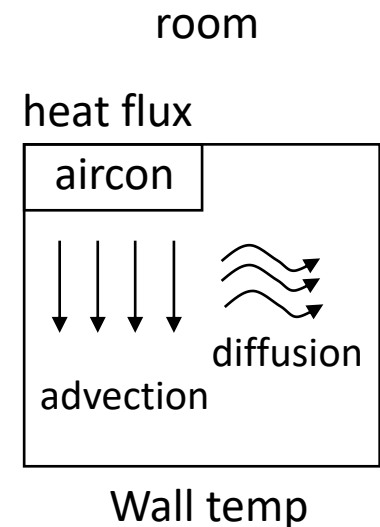
$$\phi(x, y, 0) = f(x, y)$$

## ➤ Boundary condition (BC)

- Dirichlet (function value is given):  $\phi = \phi_0$

- Neumann (flux is given, e.g., heat flux):  $\frac{\partial \phi}{\partial n} = g$

( $n$  denote the normal direction to the boundary)



# Discretization

- Governing equation is satisfied at every point  $(i, j)$
- Discretization of the governing equation at each point gives us an algebra equation. Putting all of them together, we have a linear system.

$N_{0,Ny-1}$	$N_{i,Ny-1}$	$N_{Nx-1,Ny-1}$
$N_{0,j}$	$N_{i,j}$	$N_{Nx-1,j}$
$N_{0,0}$	$N_{i,0}$	$N_{Nx-1,0}$

$$\left( \frac{\partial \phi}{\partial t} + u \frac{\partial \phi}{\partial x} + v \frac{\partial \phi}{\partial y} = \alpha \left( \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} \right) \right)_{i,j} \Rightarrow a\phi_{i,j} + b\phi_{i,j-1} + \dots = 0$$

⇓ All together

$$a\phi_{1,1} + b\phi_{1,0} + \dots = 0$$

$$a\phi_{1,2} + b\phi_{1,1} + \dots = 0$$

⋮

$$a\phi_{Nx-2,Ny-2} + b\phi_{Nx-2,Ny-3} + \dots = 0$$

$(Nx - 2 \times Ny - 2)$  interior points

$(Nx - 2 \times Ny - 2)$  algebra equations

$(Nx - 2 \times Ny - 2)$  unknowns

Can be solved!

$$\Rightarrow \mathbf{A}\boldsymbol{\phi} = \mathbf{b}$$

$\mathbf{b}$  come from BC  
or source term

- We can treat the terms **one by one**
- Spatial discretization

- How the spatial derivatives are evaluated with given mesh?

Diffusion:  $\left( \alpha \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \phi \right)_{i,j}$

Advection:  $\left( \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} \right) \phi \right)_{i,j}$

- Temporal discretization

- At which moment am I approximating the evolution?

Explicit Euler:  $\frac{\partial \phi}{\partial t} = f(\phi^n)$

Implicit Euler:  $\frac{\partial \phi}{\partial t} = f(\phi^{n+1})$

# Spatial discretization

## ➤ Example: diffusion with central difference

$$\left( \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \phi \right)_{i,j} = \frac{1}{\Delta x^2} \phi_{i-1,j} + \frac{1}{\Delta y^2} \phi_{i,j-1} + \left( -\frac{2}{\Delta x^2} - \frac{2}{\Delta y^2} \right) \phi_{i,j} + \frac{1}{\Delta y^2} \phi_{i,j+1} + \frac{1}{\Delta x^2} \phi_{i+1,j}$$

⇓ All together

- $\phi$  is the vector of unknown  $D\phi$
- $D$  is a matrix decided by:
  - PDE operator: diffusion operator  $\left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right)$
  - Discretization scheme: central difference
- $D$  has nothing to do with which variable you are discretizing
- $D\phi$  is a vector which gives the approximated  $\left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \phi$  value on each grid point.
  - If  $\phi$  is known, you can directly calculate the value. Formation of the matrix is not needed (Similar to calculate the residual in Project 1)
- Boundary value needs to be considered separately because governing equation don't apply to the boundary nodes

$$\text{PDE:} \quad \frac{\partial \phi}{\partial t} = -u \frac{\partial \phi}{\partial x} - v \frac{\partial \phi}{\partial y} + \alpha \left( \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} \right)$$

Spatial discretization: ⇓

$$\text{Semi discrete form:} \quad \frac{\partial \phi}{\partial t} = -A\phi + D\phi$$

# Upwind discretization for advection term

- Advection term:

$$\left(u \frac{\partial}{\partial x} \phi\right)_i$$

- First order upwind

- When  $u > 0$ , information propagates from left to right
- We use  $\phi_{i-1}$  and  $\phi_i$  to approximate the derivative (backward)

$$\left(\frac{\partial}{\partial x} \phi\right)_i = \frac{\phi_i - \phi_{i-1}}{\Delta x}$$

- When  $u < 0$ , information propagates from right to left
- We use  $\phi_{i+1}$  and  $\phi_i$  to approximate the derivative (forward)

$$\left(\frac{\partial}{\partial x} \phi\right)_i = \frac{\phi_{i+1} - \phi_i}{\Delta x}$$

- Define  $u^+ = 0.5(u + |u|)$ , we have  $u^+ = u$  for  $u > 0$  and  $u^+ = 0$  for  $u \leq 0$
- Define  $u^- = 0.5(u - |u|)$ , we have  $u^- = u$  for  $u < 0$  and  $u^- = 0$  for  $u \geq 0$

$$\left(u \frac{\partial}{\partial x} \phi\right)_i = u^+ \left(\frac{\phi_i - \phi_{i-1}}{\Delta x}\right) + u^- \left(\frac{\phi_{i+1} - \phi_i}{\Delta x}\right)$$

- Second order upwind

$$\left(u \frac{\partial}{\partial x} \phi\right)_i = u^+ \left(\frac{3\phi_i - 4\phi_{i-1} + \phi_{i-2}}{2\Delta x}\right) + u^- \left(\frac{-3\phi_i + 4\phi_{i+1} - \phi_{i+2}}{2\Delta x}\right)$$

- $\left(u \frac{\partial}{\partial x} \phi\right)_i = \mathbf{A} \phi$ . Upwind is not symmetry.  $\mathbf{A}^{-1}$  may be hard to calculate

# Temporal discretization

- Consider problem 
$$\frac{\partial \phi}{\partial t} = f(\phi)$$
- Explicit schemes evaluated the derivative at previous time steps:
  - Forward Euler: 
$$\frac{\partial \phi}{\partial t} = f(\phi^n) \Rightarrow \frac{I}{\Delta t} (\phi^{n+1} - \phi^n) = M\phi^n$$
$$\phi^{n+1} = (I + M\Delta t)\phi^n$$
  - Adams-Bashforth:  
Two-step method  
You can start with FE 
$$\frac{\partial \phi}{\partial t} = 1.5f(\phi^n) - 0.5f(\phi^{n-1})$$
$$\frac{I}{\Delta t} (\phi^{n+1} - \phi^n) = 1.5M\phi^n - 0.5M\phi^{n-1}$$
$$\phi^{n+1} = \phi^n + 1.5M\Delta t\phi^n - 0.5M\Delta t\phi^{n-1}$$
  - No inverse of matrix
- Implicit schemes evaluated the derivative at previous time steps:
  - Backward Euler: 
$$\frac{\partial \phi}{\partial t} = f(\phi^{n+1}) \Rightarrow \frac{I}{\Delta t} (\phi^{n+1} - \phi^n) = M\phi^{n+1}$$
$$\phi^{n+1} = (I - M\Delta t)^{-1}\phi^n$$
  - Need to calculate inverse of matrix
- For  $M$  which is easy to be inversed, we want to used implicit scheme.
- For  $M$  which is hard to be inversed, we want to used explicit scheme.

# Implicit/Explicit scheme

- Consider the problem:

$$\frac{\partial \phi}{\partial t} = - \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} \right) \phi + \alpha \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \phi$$

- The semi-discrete form:

$$\frac{\partial \boldsymbol{\phi}}{\partial t} = -\mathbf{A}\boldsymbol{\phi} + \mathbf{D}\boldsymbol{\phi}$$

- With central difference,  $\mathbf{D}$  is easy to be inverted
  - With upwind,  $\mathbf{A}$  is hard to be inverted
- Explicit for  $\mathbf{A}\boldsymbol{\phi}$  (AB2), Implicit for  $\mathbf{D}\boldsymbol{\phi}$  (Trapezoidal)

$$\frac{I}{\Delta t} (\boldsymbol{\phi}^{n+1} - \boldsymbol{\phi}^n) = -(1.5\mathbf{A}\boldsymbol{\phi}^n - 0.5\mathbf{A}\boldsymbol{\phi}^{n-1}) + \mathbf{D}(0.5\boldsymbol{\phi}^n + 0.5\boldsymbol{\phi}^{n+1})$$

Explicit scheme, forward calculation. Don't need to form matrix

- You need to use Newton-Raphson method to calculate  $\delta\boldsymbol{\phi}$

➤ Use as much existing code as you can!

# Neumann boundary condition

- Suppose we have Neumann boundary condition on the bottom boundary:

$$\frac{\partial \phi}{\partial n} = \frac{\partial \phi}{\partial y}(y = 0) = h$$

- With first order one-side difference at  $N_{i,0}$

$$\frac{\phi_{i,1} - \phi_{i,0}}{\Delta y} = h$$

$N_{0,Ny-1}$	$N_{i,Ny-1}$	$N_{Nx-1,Ny-1}$
$N_{0,j}$	$N_{i,j}$	$N_{Nx-1,j}$
$N_{0,0}$	$N_{i,0}$	$N_{Nx-1,0}$

- The boundary condition needs to be satisfied after updating:

$$\frac{\phi_{i,1}^{k+1} - \phi_{i,0}^{k+1}}{\Delta y} = h \quad \frac{(\phi_{i,1}^k + \delta\phi_{i,1}^k) - (\phi_{i,0}^k + \delta\phi_{i,0}^k)}{\Delta y} = h$$

- Finally we have the discrete form of the Neumann boundary condition:

$$\frac{1}{\Delta y} \delta\phi_{i,1}^k - \frac{1}{\Delta y} \delta\phi_{i,0}^k = h - \frac{\phi_{i,1}^k - \phi_{i,0}^k}{\Delta y}$$