The University of British Columbia MECH 479

# Module 3 Example Problems

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### Example 1

Consider the below discretization

$$\left(\frac{\partial T}{\partial y}\right)_{i,j} = \frac{1}{6h} \left(-11T_{i,j} + 18T_{i,j+1} - 9T_{i,j+2} + 2T_{i,j+3}\right) + O\left(h^3\right)$$

Find the truncation error for the above approximation.

Hint: Express the variables on the RHS by Taylor series expansions about the point (i, j):

$$T_{i,j+1} = T_{i,j} + \left(\frac{\partial T}{\partial y}\right)_{i,j} \Delta y + \left(\frac{\partial^2 T}{\partial y^2}\right)_{i,j} \frac{(\Delta y)^2}{2!} + \left(\frac{\partial^3 T}{\partial y^3}\right)_{i,j} \frac{(\Delta y)^3}{3!} + \left(\frac{\partial^4 T}{\partial y^4}\right)_{i,j} \frac{(\Delta y)^4}{4!} + \cdots$$

$$T_{i,j+2} = T_{i,j} + \left(\frac{\partial T}{\partial y}\right)_{i,j} (2\Delta y) + \left(\frac{\partial^2 T}{\partial y^2}\right)_{i,j} \frac{(2\Delta y)^2}{2!} + \left(\frac{\partial^3 T}{\partial y^3}\right)_{i,j} \frac{(2\Delta y)^3}{3!} + \left(\frac{\partial^4 T}{\partial y^4}\right)_{i,j} \frac{(2\Delta y)^4}{4!} + \cdots$$

$$T_{i,j+3} = T_{i,j} + \left(\frac{\partial T}{\partial y}\right)_{i,j} (3\Delta y) + \left(\frac{\partial^2 T}{\partial y^2}\right)_{i,j} \frac{(3\Delta y)^2}{2!} + \left(\frac{\partial^3 T}{\partial y^3}\right)_{i,j} \frac{(3\Delta y)^3}{3!} + \left(\frac{\partial^4 T}{\partial y^4}\right)_{i,j} \frac{(3\Delta y)^4}{4!} + \cdots$$

Now substitute the RHS expressions above for the terms that appear in the RHS and simplify. We find that

$$\frac{1}{6h}\left(-11T_{i,j}+18T_{i,j+1}-9T_{i,j+2}+2T_{i,j+3}\right)=\left(\frac{\partial T}{\partial y}\right)_{i,j}+\frac{1}{4}\left(\frac{\partial^4 T}{\partial y^4}\right)_{i,j}(\Delta y)^3+\cdots$$

so, the truncation error has been identified and is

$$\frac{1}{4} \left( \frac{\partial^4 T}{\partial y^4} \right)_{i,j} (\Delta y)^3 + \dots = O(\Delta y)^3$$

#### Example 2

Develop a finite difference approximation with truncation error of  $O(\Delta y)^2$  for  $\partial T/\partial y$  at point (i,j) using  $T_{i,j}$ ,  $T_{i,j+1}$ , and  $T_{i,j+2}$ , when the grid spacing is not uniform.

Hint: To find a second-order approximation for  $\frac{\partial T}{\partial y}$ , let

$$\frac{\partial T}{\partial y} = \frac{cT_{i,j} + aT_{i,j+1} + bT_{i,j+2}}{\Delta y_1} + O\left(\Delta y_1^2\right)$$

Substituting the following Taylor series expansions

$$T_{i,j} = T(x_0, y_0)$$

$$T_{i,j+1} = T(x_0, y_0 + \Delta y_1) = T(x_0, y_0) + \frac{\partial T}{\partial y} \Delta y_1 + \frac{1}{2} \frac{\partial^2 T}{\partial y^2} \Delta y_1^2 + \cdots$$

$$T_{i,j+2} = T(x_0, y_0 + \Delta y_1 + \Delta y_2) = T(x_0, y_0)$$

$$+ \frac{\partial T}{\partial y} (\Delta y_1 + \Delta y_2) + \frac{1}{2} \frac{\partial^2 T}{\partial y^2} (\Delta y_1 + \Delta y_2)^2 + \cdots$$

we find that

$$a+b+c = 0$$
  

$$a + (1+\alpha)b = 1$$
  

$$a + (1+\alpha)^2b = 0$$

where  $\alpha = \frac{\Delta y_2}{\Delta y_1}$ . Solving these equations for a, b, c gives

$$a = \frac{1+\alpha}{\alpha}$$

$$b = -\frac{1}{\alpha(1+\alpha)}$$

$$c = -\frac{2+\alpha}{1+\alpha}$$

The T.E. is  $(1+\alpha)\frac{\left(\Delta y_1\right)^2}{6}\frac{\partial^3 T}{\partial y^3}$ 

# Example 3

Consider the following FDE:

$$(u_x)_{i+1} + 4(u_x)_i + (u_x)_{i-1} = \frac{3}{h}(u_{i+1} - u_{i-1})$$

Find the truncation error. Hint: Using the following Taylor series expresssions:

$$(u_x)_{i+1} = (u_x)_i + (u_{xx})_i \frac{h^2}{2} + (u_{xxxx})_i \frac{h^3}{6} + (u_{xxxx})_i \frac{h^4}{24} + \cdots$$

$$(u_x)_{i-1} = (u_x)_i - (u_{xx})_i h + (u_{xxx})_i \frac{h^2}{2} - (u_{xxxx})_i \frac{h^3}{6} + (u_{xxxxx})_i \frac{h^4}{24} - \cdots$$

$$u_{i+1} = u_i + (u_x)_i h + (u_{xx})_i \frac{h^2}{2} + (u_{xxx})_i \frac{h^3}{6} + (u_{xxxx})_i \frac{h^4}{24} + (u_{xxxxx})_i \frac{h^5}{120} + \cdots$$

$$u_{i-1} = u_i - (u_x)_i h + (u_{xx})_i \frac{h^2}{2} - (u_{xxx})_i \frac{h^3}{6} + (u_{xxxx})_i \frac{h^4}{24} - (u_{xxxxx})_i \frac{h^5}{120} + \cdots$$

we find

$$(u_x)_{i+1} + 4 (u_x)_i + (u_x)_{i-1} = 6 (u_x)_i + (u_{xxx})_i h^2 + (u_{xxxxx}) \frac{h^4}{12} + \cdots$$

$$\frac{3}{h} (u_{i+1} - u_{i-1}) = \frac{3}{h} \left[ 2 (u_x)_i h + (u_{xxx})_i \frac{h^3}{3} + (u_{xxxxx})_i \frac{h^5}{60} \right] + \cdots$$

which simplifies to

$$(u_x)_{i+1} + 4(u_x)_i + (u_x)_{i-1} = \frac{3}{h}(u_{i+1} - u_{i-1}) + \frac{1}{30}(u_{xxxx})_i h^4$$

Hence the truncation error is  $O(h^4)$ 

### Example 4

Application of Taylor Table: Consider 3-point backward difference operator for  $\frac{\partial u}{\partial x}$  up to order  $O(\Delta x)^p$ . The idea is to determine values of  $\alpha_{-2}, \alpha_0, \alpha_{-1}, \cdots$  such that

$$U'_{j} + \alpha_{-2}U_{j-2} + \alpha_{-1}U_{j-1} + \alpha_{0}U_{j} + \dots = O(\Delta x^{p})$$

 $U'_j$  — Differential operator of interest to have minimum truncation error  $O(\Delta x^p)^*$  Similar to the example in the handout, let's say that we have 3 unknowns  $\alpha_{-2}, \alpha_{-1}, \alpha_0$ 

	$U_j$	$U_j'$	$U_j^{(2)}$	$U_j^{(3)}$
$U_i'$	0	1	0	0
$\alpha_0 U_j$	$\alpha_0$	0	0	0
$\alpha_{j-1}U_{j-1}$	$\alpha_{j-1}$	$-\alpha_{j-1}\Delta x$	$\frac{1}{2}\alpha_{j-1}\Delta x^2$	$-\frac{1}{6}\alpha_{j-1}\Delta x^3$ $-\frac{1}{6}\alpha_{j-2}(2\Delta x)^3$
$\alpha_{j-2}U_{j-2}$	$\alpha_{j-2}$	$-\alpha_{j-2}2\Delta x$	$\frac{1}{2}\alpha_{j-2}(2\Delta x)^2$	$-\frac{1}{6}\alpha_{j-2}(2\Delta x)^{\circ}$
LHS	RHS1	RHS2	RHS3	RHS4

hence we can set three equations of RHS equal to zero (starting from  $1^{\rm st}$  column ), i.e.

$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 0 \\ 4 & 1 & 0 \end{bmatrix} \begin{bmatrix} \alpha_{-2} \\ \alpha_{-1} \\ \alpha_{0} \end{bmatrix} = \begin{bmatrix} 0 \\ 1/\Delta x \\ 0 \end{bmatrix}$$

which gives  $[\alpha_{-2}, \alpha_{-1}, \alpha_0] = -\frac{1}{2\Lambda x}[1, -4, 3].$ 

$$\left(\frac{\partial u}{\partial x}\right)_{j} \equiv U'_{j} = \frac{1}{2\Delta x} \left(u_{j-2} - 4u_{j-1} + 3u_{j}\right) + O\left(\Delta x^{2}\right)$$

# Example 5

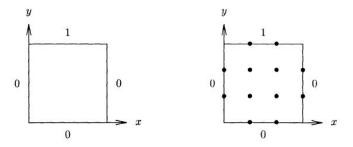


Figure 1: Laplace example (from Heath book)

Consider the Laplace equation on the unit square

$$u_{xx} + u_{yy} = 0$$
,  $0 \le x \le 1$ ,  $0 \le y \le 1$ 

with boundary conditions as shown on the left in Fig. 2. Including boundaries, we define a uniform mesh in the domain, as shown on the right in Fig. 2. We wish compute the approximate solution at the interior points

$$(x_i, y_j) = (ih, jh), \quad i, j = 1, \dots, n$$

where in our example n = 2 and h = 1/(n+1) = 1/3. We replace the second derivatives in the equation with the second-order centered difference approx-

imation at each interior mesh point to obtain the finite difference equations

$$\frac{u_{i+1,j}-2u_{i,j}+u_{i-1,j}}{h^2}+\frac{u_{i,j+1}-2u_{i,j}+u_{i,j-1}}{h^2}=0, \quad i,j=1,\ldots,n$$

where  $u_{i,j}$  is an approximation to the true solution  $u\left(x_i,y_j\right)$  and represents one of the given boundary values if i or j is 0 or n+1. Simplifying and writing out the resulting four equations explicitly, we obtain

$$4u_{1,1} - u_{0,1} - u_{2,1} - u_{1,0} - u_{1,2} = 0$$

$$4u_{2,1} - u_{1,1} - u_{3,1} - u_{2,0} - u_{2,2} = 0$$

$$4u_{1,2} - u_{0,2} - u_{2,2} - u_{1,1} - u_{1,3} = 0$$

$$4u_{2,2} - u_{1,2} - u_{3,2} - u_{2,1} - u_{2,3} = 0$$

Writing these four equations in matrix form, we obtain

$$Ax = \begin{bmatrix} 4 & -1 & -1 & 0 \\ -1 & 4 & 0 & -1 \\ -1 & 0 & 4 & -1 \\ 0 & -1 & -1 & 4 \end{bmatrix} \begin{bmatrix} u_{1,1} \\ u_{2,1} \\ u_{1,2} \\ u_{2,2} \end{bmatrix} = \begin{bmatrix} u_{0,1} + u_{1,0} \\ u_{3,1} + u_{2,0} \\ u_{0,2} + u_{1,3} \\ u_{3,2} + u_{2,3} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} = b$$

The above system can be solved via Matlab yielding:

$$x = \begin{bmatrix} u_{1,1} \\ u_{2,1} \\ u_{1,2} \\ u_{2,2} \end{bmatrix} = \begin{bmatrix} 0.125 \\ 0.125 \\ 0.375 \\ 0.375 \end{bmatrix}$$