

THE UNIVERSITY OF BRITISH COLUMBIA  
MECH 479/587

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## Module 2 Example Problems

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September 21, 2022

## Review

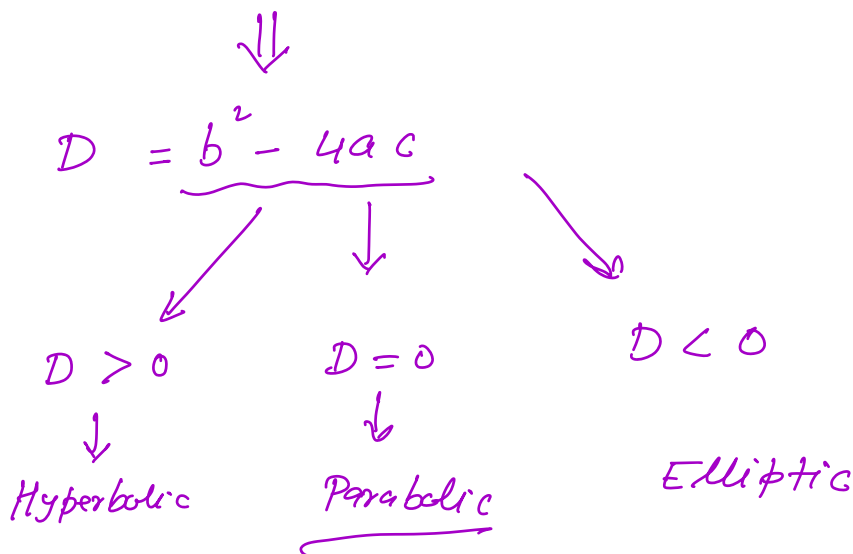
1. First-order PDE system

$$\underline{W} = \begin{pmatrix} u \\ v \end{pmatrix} \quad \frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial v}{\partial x}, \frac{\partial v}{\partial y} \dots$$
$$\frac{\partial \underline{W}}{\partial x} + \underline{[A]} \frac{\partial \underline{W}}{\partial y} = 0$$

2. Second-order PDE:  $u$

$$\frac{\partial^2 u}{\partial x^2}, \frac{\partial^2 u}{\partial y^2}, \frac{\partial^2 u}{\partial x \partial y} \dots$$

$$\Rightarrow a \frac{\partial^2 u}{\partial x^2} + b \frac{\partial^2 u}{\partial x \partial y} + c \frac{\partial^2 u}{\partial y^2} = \underline{d(x, y, \dots)}$$



### Example 1

Consider the following PDE describing the advection behavior (first-order wave equation):

$$\frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} = 0.$$

with the wave speed  $c = 1$ . The initial condition is  $u = u_0(x)$  on  $t = 0$

Solution: Loosely speaking, a characteristic is a curve or line along which a PDE reduces to an ODE. Suppose that one follows some particular path  $x(t)$ . Then, along that line,  $u = u(x(t), t)$  is a function of  $t$  only and its total derivative with respect to  $t$  is (using chain-rule)

$$\frac{du}{dt} = \frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} \frac{dx}{dt}$$

Compare this with the original differential equation. It is exactly the same as the LHS of that equation provided that the chosen path satisfies

$$\frac{dx}{dt} = 1$$

or

$$x = t + \text{const}$$

Along these lines,  $\frac{du}{dt} = 0$  (an ordinary differential equation). Hence,  $u$  propagates unchanged along the lines.

### Example 2

The Laplace equation can be written as first-order Cauchy-Riemann equations

$$\begin{aligned}\frac{\partial u}{\partial x} &= +\frac{\partial v}{\partial y} \\ \frac{\partial u}{\partial y} &= -\frac{\partial v}{\partial x}\end{aligned}$$

and

$$\frac{\partial \mathbf{w}}{\partial x} + [A] \frac{\partial \mathbf{w}}{\partial y} = 0$$

where

$$\mathbf{w} = \begin{bmatrix} u \\ v \end{bmatrix}$$

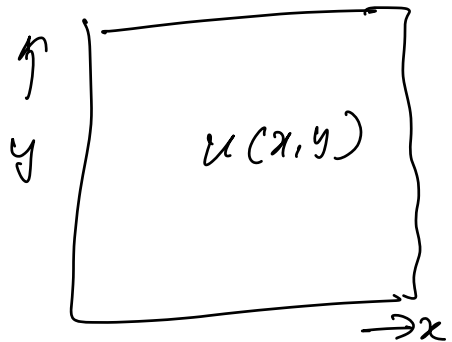
and

$$[A] = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} = 0$$

$\xrightarrow{\text{Laplace}}$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} = 0$$



$$\begin{aligned}\rightarrow \frac{\partial u}{\partial x} &= +\frac{\partial v}{\partial y} \rightarrow \left. \begin{aligned} &\text{Diff. w.r.t. } x \\ &\text{Diff. w.r.t. } y \end{aligned} \right\} \\ \frac{\partial u}{\partial y} &= -\frac{\partial v}{\partial x}\end{aligned}$$

Write in vector-matrix form:

$$\underline{\mathbf{w}} = \begin{pmatrix} u \\ v \end{pmatrix}$$

$$\frac{\partial \underline{\mathbf{w}}}{\partial x} + [A] \frac{\partial \underline{\mathbf{w}}}{\partial y} = 0$$

$$[A] = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$\underline{\det(A - \lambda I)} \Rightarrow +\lambda^2 - 1 = 0 \\ = \pm i$$

### Example 3

Show that the one-dimensional Navier-Stokes equation without pressure gradient (known as the 'viscous' Burger's equation)  $\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = \alpha \frac{\partial^2 u}{\partial x^2}$  is parabolic in  $x, t$ .

Compare with the form  $a \frac{\partial^2 u}{\partial x^2} + b \frac{\partial^2 u}{\partial x \partial y} + c \frac{\partial^2 u}{\partial y^2} = d$ , we have  $a = -\alpha, b = 0, c = 0$ . Because  $b^2 - 4ac = 0$ , the given PDE is parabolic in  $x, t$ .

$$\text{Compare } \begin{cases} \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = \alpha \frac{\partial^2 u}{\partial x^2} \\ a \frac{\partial^2 u}{\partial x^2} + b \frac{\partial^2 u}{\partial x \partial y} + c \frac{\partial^2 u}{\partial y^2} = d \end{cases}$$

$$a = -\alpha, \quad b = 0, \quad c = 0$$

Discriminant :  $b^2 - 4ac$

$$0 - 4(-\alpha)0 = 0$$

$$\boxed{b^2 - 4ac = 0} \Rightarrow \underline{\text{Parabolic}}$$

$$\begin{cases} -\frac{\partial \underline{u}}{\partial t} + \frac{1}{2} \frac{\partial u}{\partial x} + \frac{\partial v}{\partial x} = 0 & \text{--- ①} \\ -\frac{\partial \underline{v}}{\partial t} + \frac{\partial u}{\partial x} + \frac{1}{2} \frac{\partial v}{\partial x} = 0 & \text{--- ②} \end{cases}$$

$$\underline{w} = \begin{pmatrix} u \\ v \end{pmatrix}, \quad (t, x)$$

$$\frac{\partial}{\partial t} \begin{bmatrix} u \\ v \end{bmatrix} + \underbrace{\begin{bmatrix} \frac{1}{2} & 1 \\ 1 & \frac{1}{2} \end{bmatrix}}_{[A]} \frac{\partial}{\partial x} \begin{bmatrix} u \\ v \end{bmatrix} = 0$$

$$\frac{\partial \underline{w}}{\partial t} + [A] \frac{\partial \underline{w}}{\partial x} = 0 \quad [A]$$

(a) Find eigenvalues:

$$\det(A - \lambda I) = 0$$

$$\Rightarrow \left| \begin{bmatrix} \frac{1}{2} & 1 \\ 1 & \frac{1}{2} \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} \right| = 0$$

$$\Rightarrow \begin{vmatrix} \frac{1}{2} - \lambda & 1 \\ 1 & \frac{1}{2} - \lambda \end{vmatrix} = 0$$

$$\Rightarrow \left( \frac{1}{2} - \lambda \right)^2 - 1 = 0$$

$$\lambda_1 = \frac{3}{2}, \quad \lambda_2 = -\frac{1}{2}$$

Hyperbolic !

(ii) Eigenvectors

$$A X_1 = \lambda_1 X_1$$

$$\Rightarrow X_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$A X_2 = \lambda_2 X_2$$

$$\Rightarrow X_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\underline{\tilde{Q}}, \quad \underline{\tilde{S}}, \quad \underline{\tilde{L}}$$

$$\underline{\tilde{L}} = \begin{bmatrix} \vdots & \vdots \\ \dot{x}_1 & \dot{x}_2 \\ \vdots & \vdots \end{bmatrix}$$

$$= \begin{bmatrix} \frac{x_1}{\|x_1\|} & \frac{x_2}{\|x_2\|} \end{bmatrix}$$

$$\underline{\tilde{L}} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

This is eigenvector matrix!

$$\underline{\tilde{L}}^{-1} \left( \frac{\partial \underline{\tilde{W}}}{\partial t} + \underline{\tilde{A}} \frac{\partial \underline{\tilde{W}}}{\partial x} \right) = 0$$

$$\frac{\partial}{\partial t} (\underline{\tilde{L}}^{-1} \underline{\tilde{W}}) + \underline{\tilde{L}}^{-1} \underline{\tilde{A}} \frac{\partial \underline{\tilde{W}}}{\partial x} = 0$$

$$\Rightarrow \frac{\partial}{\partial t} (\underline{\tilde{L}}^{-1} \underline{\tilde{W}}) + \underline{\tilde{L}}^{-1} \underline{\tilde{A}} \underline{\tilde{L}} \underline{\tilde{L}}^{-1} \frac{\partial \underline{\tilde{W}}}{\partial x} = 0$$

$$I = \underline{\tilde{L}} \underline{\tilde{L}}^{-1}$$



$$\frac{\partial}{\partial t} (\underline{\underline{L}}^{-1} \underline{w}) + \underline{\underline{L}}^{-1} \underline{A} \underline{L} \frac{\partial}{\partial x} (\underline{\underline{L}}^{-1} \underline{w}) = 0$$

$\Downarrow$

$$\underline{\underline{L}}^{-1} \underline{A} \underline{L} = \underline{\underline{\Lambda}}$$

$$\underline{w} = \begin{pmatrix} u \\ v \end{pmatrix}$$

$$= \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$$

$$\boxed{\underline{\underline{L}}^{-1} \underline{w}} \Rightarrow \text{characteristic variables}$$

$$\underline{\underline{\phi}}_1$$

$$\underline{\underline{\phi}}_2$$

$$\rightarrow \left. \begin{aligned} \frac{\partial \phi_1}{\partial t} + \lambda_1 \frac{\partial \phi_1}{\partial x} &= 0 \\ \frac{\partial \phi_2}{\partial t} + \lambda_2 \frac{\partial \phi_2}{\partial x} &= 0 \end{aligned} \right\} \begin{aligned} &\rightarrow \phi_1 \\ &\rightarrow \phi_2 \end{aligned}$$

$$\left. \begin{aligned} \phi_1 &= \frac{1}{\sqrt{2}} (u-v) \\ \phi_2 &= \frac{1}{\sqrt{2}} (u+v) \end{aligned} \right\}$$

These are two characteristic variables !

### Example 3

Consider the system

$$\begin{aligned} \frac{\partial u}{\partial t} + \frac{1}{2} \frac{\partial u}{\partial x} + \frac{\partial v}{\partial x} &= 0 & \text{--- (1)} \\ \frac{\partial v}{\partial t} + \frac{\partial u}{\partial x} + \frac{1}{2} \frac{\partial v}{\partial x} &= 0 & \text{--- (2)} \end{aligned}$$

(a) Write the system in matrix form and obtain the matrix  $A$ :

$$\underline{v} = \begin{bmatrix} u \\ v \end{bmatrix}$$

$$\frac{\partial \underline{v}}{\partial t} + A \frac{\partial \underline{v}}{\partial x} = 0$$

$$\frac{\partial \underline{v}}{\partial t} + \begin{bmatrix} \frac{1}{2} & 1 \\ 1 & \frac{1}{2} \end{bmatrix} \frac{\partial}{\partial x} \begin{bmatrix} u \\ v \end{bmatrix} = 0$$

$A$

(b) Find the eigenvalues of  $A$  and show that the system is hyperbolic.

$$\det(A - \lambda I) = 0$$

$$\lambda_1 = \frac{3}{2}, \quad \lambda_2 = -\frac{1}{2}$$

Real Eigenvalues

Hyperbolic: Directions / characteristic can be found!

(c) Derive the left and right eigenvectors and obtain the matrix  $L$  which diagonalizes  $A$ . Let's obtain the characteristic variables as follows:

$$\begin{cases} A \underline{x}_1 = \lambda_1 \underline{x}_1 \Rightarrow \underline{x}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \\ A \underline{x}_2 = \lambda_2 \underline{x}_2 \Rightarrow \underline{x}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \end{cases}$$

$$L = \begin{bmatrix} \frac{\underline{x}_1}{\|\underline{x}_1\|} & \frac{\underline{x}_2}{\|\underline{x}_2\|} \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$\rightarrow \frac{\partial (\bar{L}^{-1} U)}{\partial t} + \bar{L}^{-1} A L \frac{\partial (\bar{L}^{-1} U)}{\partial x} = 0$$

Characteristic variables are:

$\boxed{\bar{L}^{-1} U}$  will give two sets of

characteristic variables

$$\phi_1 \rightarrow \frac{1}{\sqrt{2}} (u - v)$$

$$\phi_2 \rightarrow \frac{1}{\sqrt{2}} (u + v)$$

characteristic  
eqns

$$\left\{ \begin{array}{l} \frac{\partial \phi_1}{\partial t} + \lambda_1 \frac{\partial \phi_1}{\partial x} = 0 \\ \frac{\partial \phi_2}{\partial t} + \lambda_2 \frac{\partial \phi_2}{\partial x} = 0 \end{array} \right. \quad \underline{AX = \lambda X}$$

$$A \Rightarrow \underline{\bar{L}^{-1} A L} = \Lambda$$

# Eigenvalue Decomposition (Review)

$$\underline{A} \underline{x} = \underline{\lambda} \underline{x}$$

Consider square matrix

&

positive definite

Eigenvector matrix:  $\underline{Q}$

$$\begin{bmatrix} \underline{A} \end{bmatrix}_{m \times m} \underline{x} = \underline{\lambda} \underline{x} \quad \underline{x} = \text{eigenvector}$$

$$= \begin{bmatrix} \vdots & \vdots & \vdots \\ \underline{x}_1 & \underline{x}_2 & \underline{x}_3 \\ \vdots & \vdots & \vdots \end{bmatrix}$$

Multiply with  $\underline{Q}^{-1}$ :

$$\underline{Q}^{-1} (\underline{A} \underline{Q}) = \underline{\lambda} \underline{Q}$$

$$\underline{A} = \underline{Q}^{-1} \underline{\lambda} \underline{Q}$$

$$\underline{\lambda} = \begin{bmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots \end{bmatrix}$$

Spectral Theorem

(Eigenvalue Decomposition)

### Example 6

Classify the system of equations:

$$\frac{\partial}{\partial t} \begin{bmatrix} u \\ v \end{bmatrix} + \underbrace{\left( \frac{\partial}{\partial x} \right) \begin{bmatrix} 0 & 8 \\ 2 & 0 \end{bmatrix}}_A \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} \frac{\partial u}{\partial t} + 8 \frac{\partial v}{\partial x} = 0 \\ \frac{\partial v}{\partial t} + 2 \frac{\partial u}{\partial x} = 0 \end{bmatrix}$$

$$\det(A - \lambda I) = 0$$
$$\Rightarrow \begin{bmatrix} 0 & 8 \\ 2 & 0 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} = 0$$

$$\rightarrow \det(A - \lambda I) = 0$$

$$\lambda_1 = 4, \quad \lambda_2 = -4$$

Two real eigenvalues

$\Rightarrow$  Hyperbolic

$$\left\{ \begin{array}{l} \frac{\partial \phi_1}{\partial t} + \lambda_1 \frac{\partial \phi_1}{\partial x} = 0 \\ \frac{\partial \phi_2}{\partial t} + \lambda_2 \frac{\partial \phi_2}{\partial x} = 0 \end{array} \right\} \begin{array}{l} \phi_1 \\ \phi_2 \end{array}$$

$$\begin{aligned} a_1 &= 1, & b_1 &= 0, & c_1 &= 0, & d_1 &= 8 \\ a_2 &= 0, & b_2 &= 2, & c_2 &= 1, & d_2 &= 0 \end{aligned}$$

$$N = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 0 & 8 \\ 2 & 0 \end{bmatrix} \quad (1)$$

Solve  $\det(N - \lambda I) = 0$ , we have  $\lambda_1 = 4$ ,  $\lambda_2 = -4$ . Two real eigenvalues, the system of equations is hyperbolic.

### Example 7

Determine the mathematical character of the equations given by below:

$$\begin{aligned} \beta^2 \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} &= 0 \\ \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} &= 0 \end{aligned}$$

$$A = \begin{bmatrix} 0 & -\frac{1}{\beta^2} \\ -1 & 0 \end{bmatrix}$$

$$\det(A - \lambda I) = 0$$

if  $\beta = 0$ ,  $v = v(x)$ . Along the characteristics  $x = \text{const}$  the value of  $v$  keeps the same.  $-\frac{\partial u}{\partial y} = \frac{\partial v(x)}{\partial x}$  becomes an ODE along characteristics  $y = \text{const}$ . So the system is hyperbolic if  $\beta \neq 0$ , we have

$$A = \begin{bmatrix} 0 & -\frac{1}{\beta^2} \\ -1 & 0 \end{bmatrix} \quad (2)$$

$\det(A - \lambda I) = \lambda^2 - \frac{1}{\beta^2} = 0$ . Because  $\frac{1}{\beta^2} > 0$ , we have two real eigenvalues. So the system is hyperbolic.

### Example 8

Given the following second order partial differential equation

$$\frac{\partial^2 u}{\partial x^2} + 3 \frac{\partial^2 u}{\partial x \partial y} - \frac{1}{2} \frac{\partial^2 u}{\partial y^2} + \left( \left( \frac{\partial u}{\partial y} \right)^2 - 2 \frac{\partial u}{\partial x} + 7 \right) = 0$$

(a) Classify the equation (hyperbolic, parabolic, or elliptic).

Compare with the form  $a \frac{\partial^2 u}{\partial x^2} + b \frac{\partial^2 u}{\partial x \partial y} + c \frac{\partial^2 u}{\partial y^2} = d$ ,  $a = 1, b = 3, c = -\frac{1}{2}$   
 $b^2 - 4ac > 0$ . The equation is hyperbolic.

$$b^2 - 4ac > 0$$

(b) Write it as a system of first order equations

Define  $\phi = \frac{\partial u}{\partial x}$  and  $\psi = \frac{\partial u}{\partial y}$ :

$$\frac{\partial \phi}{\partial x} + 3 \frac{\partial \phi}{\partial y} - \frac{1}{2} \frac{\partial \psi}{\partial y} + \psi^2 - 2\phi + 7 = 0$$

$$\frac{\partial \psi}{\partial x} - \frac{\partial \phi}{\partial y} = 0$$



### Example 9

Consider the following quasi-linear partial differential equation:

$$x \frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} = 0$$

Suppose the domain is  $x \geq 0, t \geq 0$ . Write down the characteristic equation.

Solution:

$$\begin{aligned} \frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} &= 0 & \frac{\partial u}{\partial t} + \frac{1}{x} \frac{\partial u}{\partial x} &= 0 \\ \frac{dx}{dt} = c & \rightarrow \frac{\partial u}{\partial t} + \frac{dx}{dt} \frac{\partial u}{\partial x} &= 0 \end{aligned}$$

Characteristic eq<sup>n</sup>:

$$\frac{dx}{dt} = \frac{1}{x}$$

$$\Rightarrow \int x \, dx = \int dt$$

$$\boxed{\frac{x^2}{2} = t + C}$$

$u = \text{const}$

Consider:

$$e^x \frac{\partial u}{\partial t} + t \frac{\partial u}{\partial x} = 0$$

Write down characteristic eq<sup>n</sup>:

$$\frac{dx}{dt} = \frac{t}{e^x}$$

$$\rightarrow \boxed{\frac{t^2}{2} = e^x + c}$$

### Example 10

Consider the ODE:  $\frac{du}{dt} = -u$  with initial condition  $u(0) = 1$ . The exact solution is

$$u(t) = e^{-t}$$

Forward Euler:

$$u^{n+1} = u^n - u^n \Delta t \rightarrow u^{n+1} = (1 - \Delta t)u^n$$
$$\left| \frac{u^{n+1}}{u^n} \right| \leq 1 \quad \text{only if} \quad \Delta t \leq 2.$$

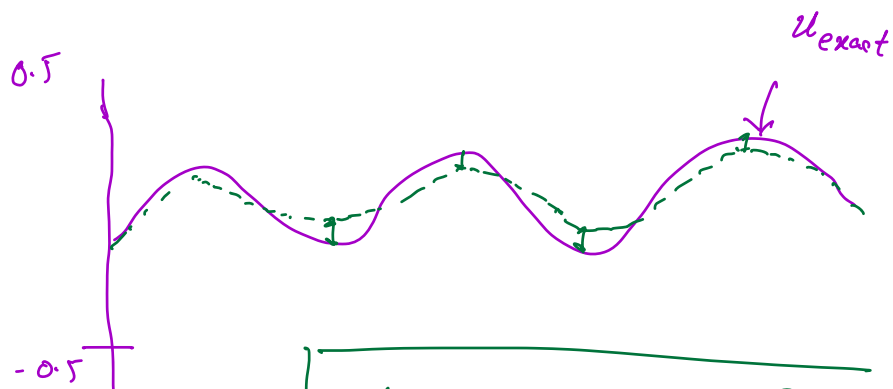
We can write a numerical sequence for the Forward Euler method:

$$u^{n+1} = (1 - \Delta t)u^n = (1 - \Delta t)^2 u^{n-1}$$
$$= \dots = (1 - \Delta t)^n u^1$$

Obviously,  $u$  oscillates unless  $\Delta t \leq 1$

Now let's use Backward Euler:

$$u^{n+1} = u^n - u^{n+1} \Delta t \rightarrow \frac{u^{n+1}}{u^n} = \frac{1}{(1 + \Delta t)}$$
$$\left| \frac{u^{n+1}}{u^n} \right| \leq 1 \quad \text{for all } \Delta t$$



$$\text{Error} = \frac{\sum_{j=1}^N (u_j - u_{\text{exact}})^2}{N}$$

$$N = \frac{T}{\Delta t}$$

$$p=2$$

$$E = C(\Delta t)^p = C\left(\frac{1}{\Delta t}\right)^{-p}$$

✓  
Taking the log:

$$\ln E = \ln \left( C \left( \frac{1}{\Delta t} \right)^{-p} \right)$$

$$= \ln C - p \ln \left( \frac{1}{\Delta t} \right)$$

