

## Process Principles

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Abstract

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9       *Keywords:* ....

10       Word count: 95

## Process Principles

We – organizational psychologists – are increasingly interested in process and dynamic phenomena. Longitudinal studies are becoming more prevalent in our literature and the number of time points they employ appears to be growing (???). The empirical literature uses the term “dynamics” at exponentially larger rates in recent years (???). A majority of published methods literature now focuses on longitudinal data analysis (???), and there are now many great reviews on the conceptual and methodological issues related to process and dynamics (???; ???; ???; ???). Moreover, this interest covers many content areas, including emotional labor (???; ???; ???), workplace stress and well-being (???; ???), organizational performance (???), self-regulation (???), newcomer adjustment (???), justice and trust (???), leadership (???; ???; ???), decision-making (???), team performance (???), counterproductive work behaviors (???), work-family conflict (???), job satisfaction (???), and team emergent states (???). In summary, explaining how a process functions appears to be of great interest to current organizational science.

There are many ways to do so – alternative representations that we might use when we want to describe sequences of events and their relationships. Just as different statistical models can be used to draw the same inference given the appropriate assumptions about the data generating process, we can use different forms of explanation to describe process. For example, Bandura (???) and Kuwabara et al. (???), respectively, explain self regulation and lay beliefs about networking with verbal theories, (???) presents a mathematical explanation of social impressions, and (???) employ both mathematical and computational approaches to explain self-regulation. All of these authors use different techniques and forms of representation, but they are all trying to convey how the processes they study behave.

In this paper, we present some of the fundamental principles researchers use to convey process. The principles come from a number of areas, including mathematics,

systems theory, dynamics, and computational modeling, and they are all ways to represent and describe relationships over time at different levels of abstraction. For example, we could use a difference equation to explain the trajectory of one variable, or we could use terms like trend or cycles that describe the emergent behavior of the variable but through a different lens. What is important is that there are fundamental principles/concepts that go into to describing a process over time. Don't necessarily need to be causal; we can explain something and it can be causal or non causal.

We provide several contributions in doing so. First, we believe our discussion will help researchers augment their current approach to explaining process. It can be helpful to be exposed to different approaches, provide ideas etc., and we hope our paper provides new ideas to seasoned researchers in this area. Second, although there is a substantial amount of literature on mathematical process principles and dynamics, it is sophisticated and technical. Much of this work is not easily accessible to researchers with the usual methodological and statistical background obtained from doctoral level training in OP/OB; we want to help distill it. Finally, we discuss ways to study process for researchers who may not want to want to develop sophisticated math or computational models. Some people claim that math is the only option. For example, Pearl (2009) states that any explanation "worthy of the title theory must be able to represent causal questions in some mathematical language" (p. 102). There is also some pressure to produce computational theories. For example, VANCOUVER COMP MODELS ARE BETTER; AND KOZLOWSKI COMP FRAMEWORKS ARE BETTER. But there are not many comp modelers in organizational psychology (vancouver orm); and the social sciences do not emphasize mathematics as much as some of the more physical sciences (vancouver orm). Moreover, Renee Thom points out that sometimes qualitative representations produce more error than their quantitative counterparts but nonetheless are better clues to the underlying process. We do not claim that one approach is better or worse than another; we simply want to describe process principles from different domains to give researchers

alternative ways of talking about, specifying, and representing process behavior.

Below, we do these things. There are other excellent papers on aspects that we will not cover. Ployhart and Vandenberg discuss how to design and analyze a longitudinal study, Pitariu and Ployhart how to propose dynamic hypotheses, and Wang provides an overview of dynamic statistical models. In this paper, conversely, we focus solely on principles researchers use when they explain process.

## What is process

### Dynamics

The system has memory. The past has memory. Monge: “In most forms of dynamic analysis it is essential to know how variables depend upon their own past history” p. 409 Wang: “A dynamic model can be defined as a representation of a system that evolves over time. In particular it describes how the system evolves from a given state at time  $t$  to another state at time  $t + 1$  as governed by the transition rules and potential external inputs.” p. 242 Vancouver 2012 orm. “Dynamic variables behave as if they have memory; that is, their value at any one time depends somewhat on their previous value.” p. 604 pitariu and ployhart. “A dynamic relationship is defined as a longitudinal relationship between two variables” p. 406 – but this doesn’t say anything about memory

### Longitudinal and Change

Ployhart and Vandenberg. “Longitudinal research emphasizes the study of change and contains at minimum three repeated observations on at least one of the substantive constructs of interest” p. 97. Notice that they emphasize change. “an emphasis on change permits researchers to capture two important characteristics of change: a) within-unit change across time, or growth trajectories, and b) interunit differences in change that can be either predicted or used for prediction” p. 97

Notice that ployhart tends to align with the growth modeling literature, where the modes of exploration are:

- intra-individual change
- interindividual differences in intra-individual change
- interrelationships of change
- determinants of intra-individual change
- determinants of inter-individual differences in intra-individual change

“The study of phenomena in their time-related constancy and change is the aim of longitudinal methodology” baltes and nesselroade 1979.

## Process

Things that happen over time. Mememory may or may not matter...but it usually does. Change – and by change I mean non-stationary – may or may not happen. Process is about sequences of events and trajectories. What is the behavior of the variables and the system over time? What happens? Explain how things happen over time. Causal or non causal.

## Systems Theory Principles

We start with some principles from systems theory – they have some overlapping terms with the growth modeling literature and should be somewhat familiar to most in our field.

## Stocks and Flows

One common approach to explaining how things happen over time is to identify stocks and flows. Meadows (???) defines both with the following:

A stock is a store, a quantity, an accumulation of material or information that has built up over time. It may be the water in a bathtub, a population, the books in a bookstore, the wood in a tree, the money in a bank, your own self confidence. A stock does not have to be physical. Your reserve of good will toward others or your supply of hope that the world can be better are both stocks.

Stocks change over time through the actions of flows. Flows are filling and draining, births and deaths, purchases and sales, growth and decay, deposits and withdrawals, successes and failures. A stock, then, is the present memory of the history of changing flows within the system (18).

That last sentence is what makes a stock imply behavior over time. We speak about stocks by both referring to what they contain right now but also how they have developed and where they are likely to go. Also note that stocks do not have to change.

The behavior of a stock – whether it rises, falls, or remains the same – depends on the nature of flows. We can learn about stock behavior by subtracting outflows from inflows. Doing so leads to three general principles about stocks. They will (???):

1. rise when inflows exceed outflows
2. fall when outflows exceed inflows
3. remain the same when inflows equal outflows.

In other words, stocks change with respect to the summative properties of their flows. Stocks also set the pace for the cumulative rhythm of the system. Even when flows are changing rapidly, the stock may change slowly because accumulation occurred over a long period of time.

Figure 1 plots a simple stock and flow system over 20 time periods.

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Insert Figure 1 Here

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Beginning at the first time point, inflows are equal to outflows and the stock therefore sits at zero. Over the first ten time points, however, outflows remain the same whereas inflows increase. With inflows exceeding outflows the stock also increases up until time point ten. At this time, inflows drop back down to five whereas outflows increase – leading to a large reduction in the stock. As outflows continue to rise over time – with no counterbalancing movement from the inflow – the stock ultimately decreases.

Systems theory uses stocks and flows as general labels for each of the things in the system. Above, we described the behavior of the stocks and flows with simple terms – increasing, decreasing, or constant. Systems theory also provides a more systematic way of describing trajectories and explaining behavior over time. These are unpacked in an excellent paper by Monge (1990), and the framework includes trend, magnitude, rate of change, and periodicity. These are shown respectively in figure 2.

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Insert Figure 2 Here

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## Trend

Dividing figure 2 into two portions – the top and bottom – reveals differences in trend. All of the panels on the top of the figure have trend, whereas those on the bottom do not. Trend is the systematic increase or decrease of a variable over time.



## Magnitude

Magnitude is the level, value, or amount of the variable at each time point – the number on the  $y$  axis at each respective point in time. For example, in panel  $C$  of figure two the magnitude is low at times 1, 2, and 3, but is high at later points in time. Additionally, panel  $E$  and  $F$  have the same magnitude if we average their values over time, but panel  $E$  contains both high and low magnitude, whereas the magnitude for the trajectory in panel  $F$  remains relatively constant.

## Rate of Change

Monge refers to rate of change as “How fast the magnitude increases or decreases per one unit of time.” Panels  $G$  and  $H$  reveal differences in rates of change.

## Periodicity

Periodicity is the amount of time before a pattern repeats itself, and it is equivalent to the term cycle. The most important piece about periodicity is that it must be couched with “controlling for trend.” Notice that panel  $A$  is periodic because, after controlling for trend, there are repeated patterns over time.

## Now two variables

It is of course possible to combine these notions when researchers are studying processes with more than one variable. For example, a researcher might describe the magnitude in their presumed dependent variable with respect to the magnitude of their independent variable, or the rates of change across the system of variables. When we turn to the behavior and relationships among a system of variables a few additional principles are available.

## Lags

How long does it take for the presumed independent variable to produce an effect on the outcome? This is the notion of lag.

## Permanence

Once the effect happens, how long does it last?

## Feedback Loops

Systems theory researchers often convey process by using feedback loops. Feedback loops describe processes where a variable eventually relates back to itself.

There are two common ways to describe the behavior of a focal variable within a feedback loop. When feedback causes the variable to move in the opposite direction than it initially moved, this is known as negative feedback, deviation counteraction, or a balancing feedback loop (???; ???). Here, an initial increase in  $x$  leads to subsequent changes in the system that, through time, eventually cause  $x$  to decrease. Now that  $x$  has gone down, more changes happen in the system that, through time, eventually cause  $x$  to increase.

When feedback, instead, causes the variable to move in the same direction that it initially moved, this is known as positive feedback, deviation amplification, or a reinforcing feedback loop (???; ???). Here, changes in  $x$  in one direction lead to eventual changes in  $x$  in the same direction and thus produce exponential, explosive, or amplifying behavior. Of course, we can also identify whether there is positive or negative feedback for every variable in the system.

## Example

People from our literature using these terms and principles to explain something.

## Summary

These systems theory notions are valuable tools to explain and describe process. Note that we did not cover everything to keep the reading concise and consistent. For example, (???) also covers discontinuous systems, so please refer to his excellent paper for an even deeper discussion. Now we turn to mathematics and statistics and describe principles from these domains that are used to explain process.

## Mathematical, Statistical and Dynamics Principles

### Difference Equations

In mathematics, a basic representation of a process over time is a difference equation:

$$y_t = y_{t-1} \tag{1}$$

where  $y_t$  represents  $y$  now and  $y_{t-1}$  is the variable at the prior time point. Here, the value of  $y$  is the same at each  $t$ , and the emergent behavior would be a flat line across time. In systems theory terms, there would be no trend.

Although equation 1 seems simple, it introduces a fundamental concept in dynamics: memory. The variable now depends on where it was in the past. It is constrained, there are boundaries on where it can go.

As we add terms to this basic difference equation the behavior of the variable becomes more complex. Adding a forcing constant,  $c$  in equation 1 produces positive or negative trend depending on whether  $c$  is, respectively, positive or negative. For example, the following equation:

$$\begin{aligned} y_t &= y_{t-1} + c \\ c &= -4 \end{aligned} \tag{2}$$

produces a line that decreases by four units at each time point.

The next level of complexity comes from autoregressive terms, which represent the extent to which the variable relates to itself over time. Here:

$$\begin{aligned} y_t &= ay_{t-1} \\ a &= 0.5 \end{aligned} \tag{3}$$

the variable is described over time but it does not retain the same value at each  $t$ . Instead, the variable is *similar* over time and the autoregressive term,  $a$ , describes the extent of that similarity. In equation 3,  $a$  is 0.5, meaning that the relationship between the variable now and itself at the next time point will be 0.5.

There are fundamental behaviors of dynamic variables based on their autoregressive terms, and these are shown in figure 3. The top row of figure 3 shows the trajectory of variables with autoregressive terms that are greater than one in absolute value. These large terms produce explosive behavior – exponential growth when  $a$  is positive and oscillating chaos when  $a$  is negative. When the autoregressive term falls between zero and one in absolute value, conversely, the variable converges to equilibrium – shown in the bottom two panels. Either the variable oscillates at a decreasing rate until it reaches equilibrium (when  $a$  is negative) or it converges there smoothly (when  $a$  is positive).

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Insert Figure 3 Here

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## Equilibrium

Equilibrium, then, describes the state of a variable that no longer changes unless disturbed by an outside force. It can also be used to describe multiple variable systems. In

these contexts, equilibrium again means that the state remains constant unless disturbed by an outside force, but here state refers to the the entire system (i.e., all of the variables). In *static* equilibriums, the system has reached a point of stability with no change, whereas *dynamic* equilibrium refers to systems with changes and fluctuations but no net change. That is, the variables fluctuate across time in periodic ways but the general state of the system does not diverge so as to change the behavior of the entire system.

Predator-prey relationships are a typical example of a system in dynamic equilibrium. For example, consider a predator-prey relationship between bobcats and rabbits. As the rabbit population increases, the amount of available food for the bobcats goes up. Over time, this raises the population of the bobcats as well. Now with a greater bobcat population, the rabbit population decreases because more are being killed. Over time, this reduction in food opportunity decreases the bobcat population. This back and forth oscillating pattern between variables describes a dynamic equilibrium. The variables change and there may be random disturbances to the system across time, but the net dynamics of the system remain stable.

## System of Equations

A difference equation with X influencing Y – now I have lags represented in math. A difference equation with X influencing Y and Y influencing X – now I have a feedback loop represented in a difference equation. I may also get priodicity, trend, and equilibrium – we could work that out analytically but it is easier just to graph it.

Our route so far has been deterministic – the mathematical representations do not contain error. When we want to convey that the underlying process – the data generating mechanism – contains error we can consider a host of additional principles.

## Stochastics

Stochastics, stated simply, refers to processes with error. Consider our simple difference equation from above, adding an error component produces:

$$y_t = ay_{t-1} + c + e_t \quad (4)$$

where all terms are defined above but  $e_t$  represents an error term that is incorporated into  $y$  at each time point. Errors cause  $y$  to be higher or lower at specific points in time than we would have expected given a deterministic process. For example, at time  $t$  the error might push  $y$  to a higher value, and at  $t + 1$  to a lower value. Errors are therefore said to be random because we cannot predict their value at any specific  $t$ . In aggregation (i.e., averaged across time), however, positive errors cancel negative errors, and large errors are less likely than small errors. Any time we have an accumulation of random error we get a normal distribution (???). In stochastic systems, therefore, the errors are said to be distributed  $N(0, 1)$  – that is, random and unpredictable at any specific  $t$  but distributed with certain constraints across time.

It can also be helpful to think about what error is not. Anything that is systematic, predictable, or common (using those in layman’s terms) cannot be error – leaving error to be the random “left overs.” An aggregation of randomness is a normal distribution.

## White Noise and Random Walks

There are two fundamental stochastic processes: white noise and random walks. White noise is a process that only has error. Setting  $c$  and  $a$  to zero in equation 4 produces a white noise process.

$$\begin{aligned}
y_t &= ay_{t-1} + c + e_t \\
a &= 0 \\
c &= 0
\end{aligned}
\tag{5}$$

Here, all we have is error over time. Panel “A” of figure 4 shows the behavior of a white noise process over time. Random walks are similar, but  $a$  is now equal to one.

$$\begin{aligned}
y_t &= ay_{t-1} + c + e_t \\
a &= 1 \\
c &= 0
\end{aligned}
\tag{6}$$

This representation is also an error process, but there is self-similarity across time. Panel “B” of figure 4 presents a random walk. Although random walks can sometimes appear to be moving in a systematic direction, ultimately their behavior is unpredictable: they could go up or down at any moment.

Random walks and white noise are error processes over time. White noise processes fluctuate randomly, whereas random walks fluctuate randomly while retaining some self-similarity through time. These two principles are the null hypotheses of time-series analysis in econometrics – where the first task in a longitudinal study is to demonstrate that you are investigating something that is not a random walk or white noise.

Now that we have added the concept of error our focus changes from the exact values of variables over time to their distributions.

## Stationary

Stationary is a term that describes the properties of a process. If a process is stationary, its mean and variance are stable – they are similar across all  $t$ . In simple terms,

this means that we expect the properties (mean and variance) of a time series at time  $t$  to be the same at time  $t + 1$ .

## Cointegration and Granger Causality

### Example: Dishop (maybe); Denrell

People from our literature using these principles to explain something.

## Summary

## Computational Principles

Above, we described and explained behavior over time by using representations most people are familiar with: verbal descriptions, plots, and math. There has recently been a push to comp model. These people are trying to do the same thing, but represent their process in a computer.

Think of it this way. Above, we represented process with graphs, equations, and terms. To do so required certain principles. When we want to describe something in a computer language we also need certain principles: certain requirements or fundamentals about how we explain the process.

Vancouver has pointed out some of these. He framed them as difficult pieces to putting stuff into code.

## Key States

What are the important states? A variable is an entity that can take different values at one point in time. A state is a variable that fluctuates over time. In information technology and computer science, a program is described as stateful if it is designed to



remember preceding events or user interactions; the remembered information is called the state of the system.

We can also talk about the global state of the system as a whole – its cumulative form. The state of the *system* describes enough about the system to determine its future behavior in the absence of any external forces affecting the system. The set of possible combinations of state variables is called the state space of a system.

## State Dynamics

### Constants

Values that do not change over time. Usually constants occur in the coefficients, or the weights. Vancouver's comp model 2018 included a weight relating assigned goal difficulty and goal specificity to self-efficacy that did not change over time.

### Actions

### Action selection

### Context/Environment

How is the process situated? Simon's mouse behavior environment. He defines the context in which it can move around. Things happen with respect to the environment.

### Noise

Is there error in the system, if so, where?

### Time Scale

How long does the process operate for? How many iterations does my for loop go for?

**Example: Simon 1956****key states:**

- hunger and thirst
- It is easier to think of these as stocks: food and water.

**State dynamics:**

- The body requires energy, so the food and water stocks decrease over time (i.e., hunger and thirst increase)

**Actions.**

- these actions satisfy the state dynamics
  - resting, exploration, goal striving

**Action selection.**

- If the food and water stocks are above threshold, the agent rests
- When the stock of any need dips below threshold, the agent explores
- During exploration
  - agent randomly runs into objects. If they encounter a single object relevant to one of the needs, the agent acquires it
  - If the agent encounters two or more need-relevant objects, they evoke a simple ratio to make a decision
    - \* compare energy required to meet the need (M) to the storage capacity with respect to the need (S)
    - \* or the effort required to get the object to how large the stock for this need is. Super large stocks take precedence

**Environment.**

- a space with goals within which the entity moves
- the individual is located in an environment that contains spatially distributed goal-relevant objects such as sources of food and water (239).
- the size of the food and water stocks are determined by the availability of the resources in the environment. Water is easier to come by than food and so food storage requirements are greater. Similarly, breathable air is easier to obtain than water and so its storage requirements are less than both food and water (239).

**Summary**

## References

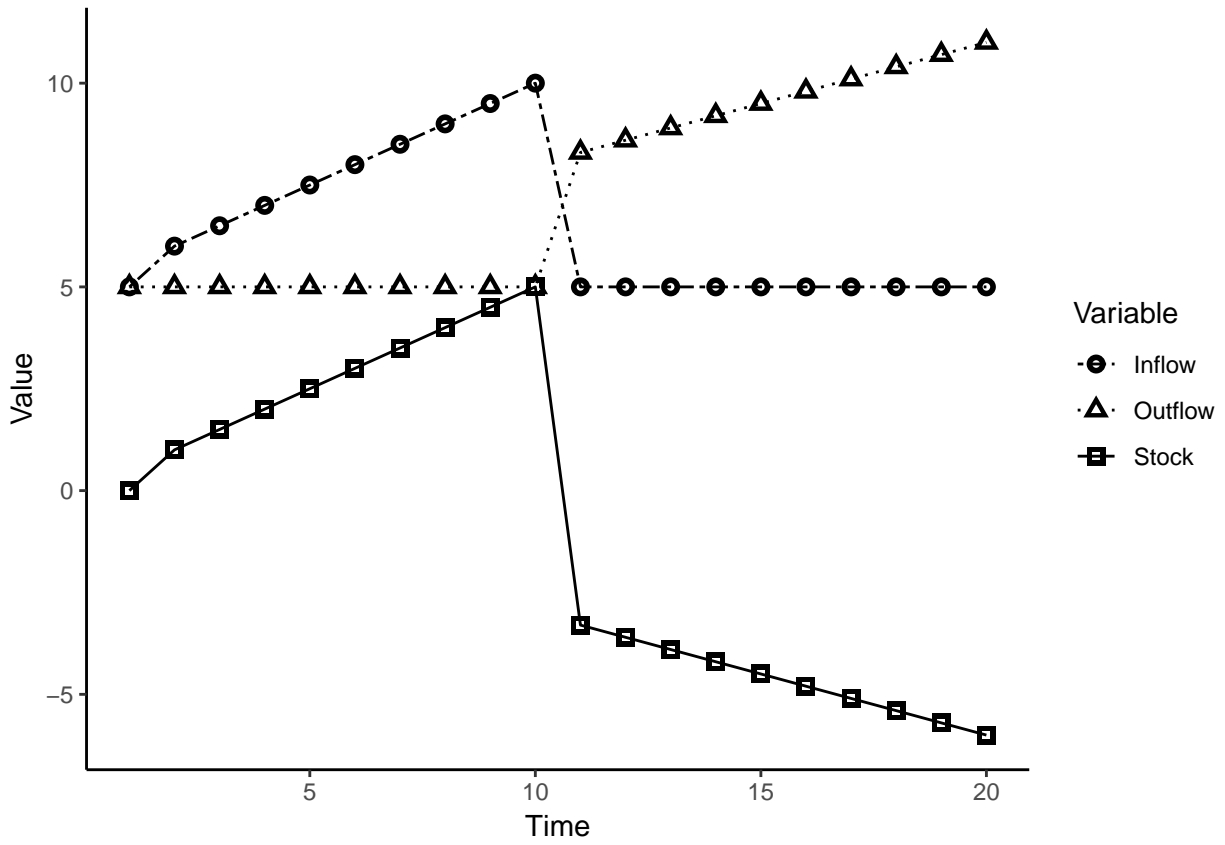
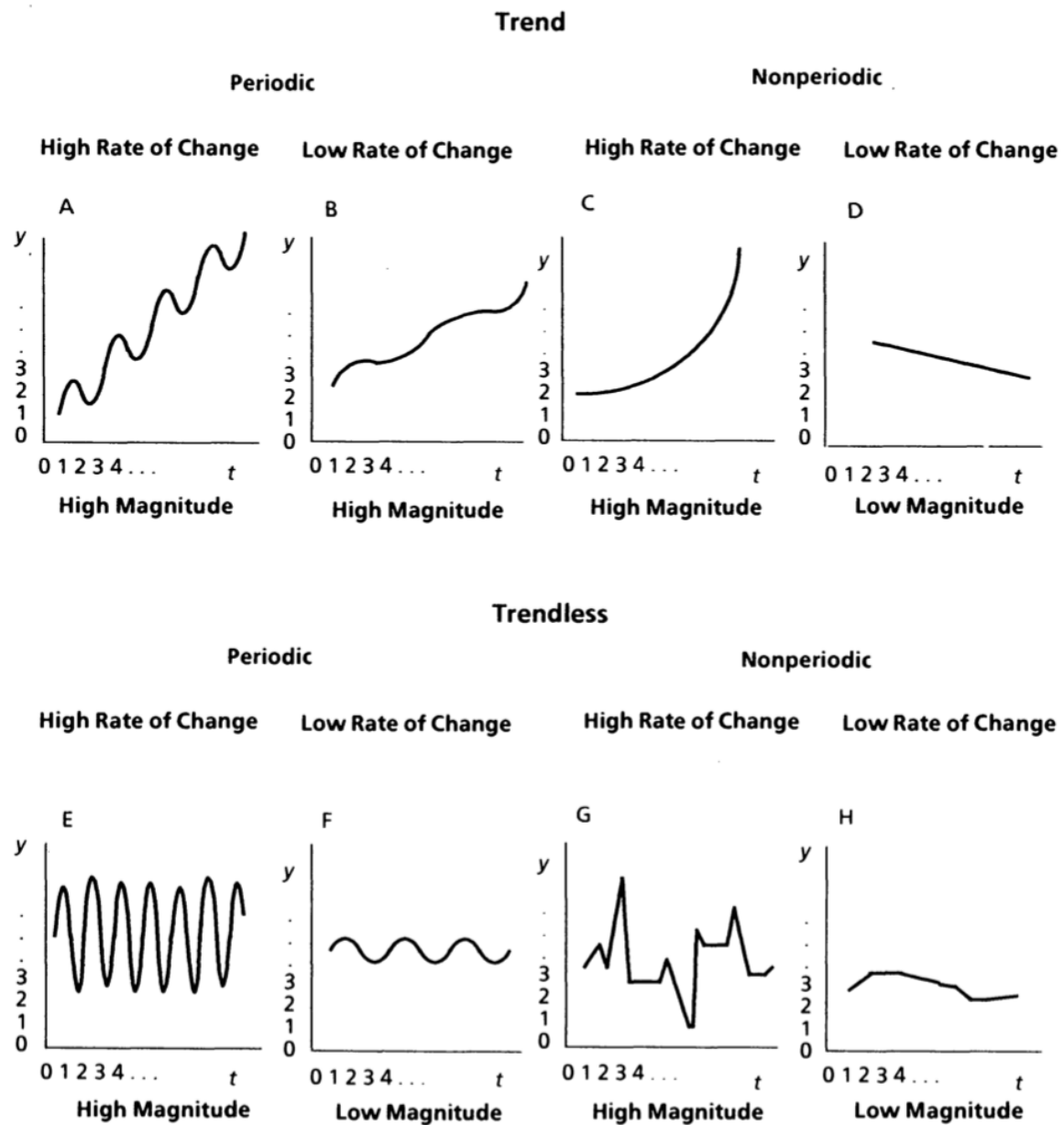


Figure 1. the ol stock system

*Figure 2.* monge image

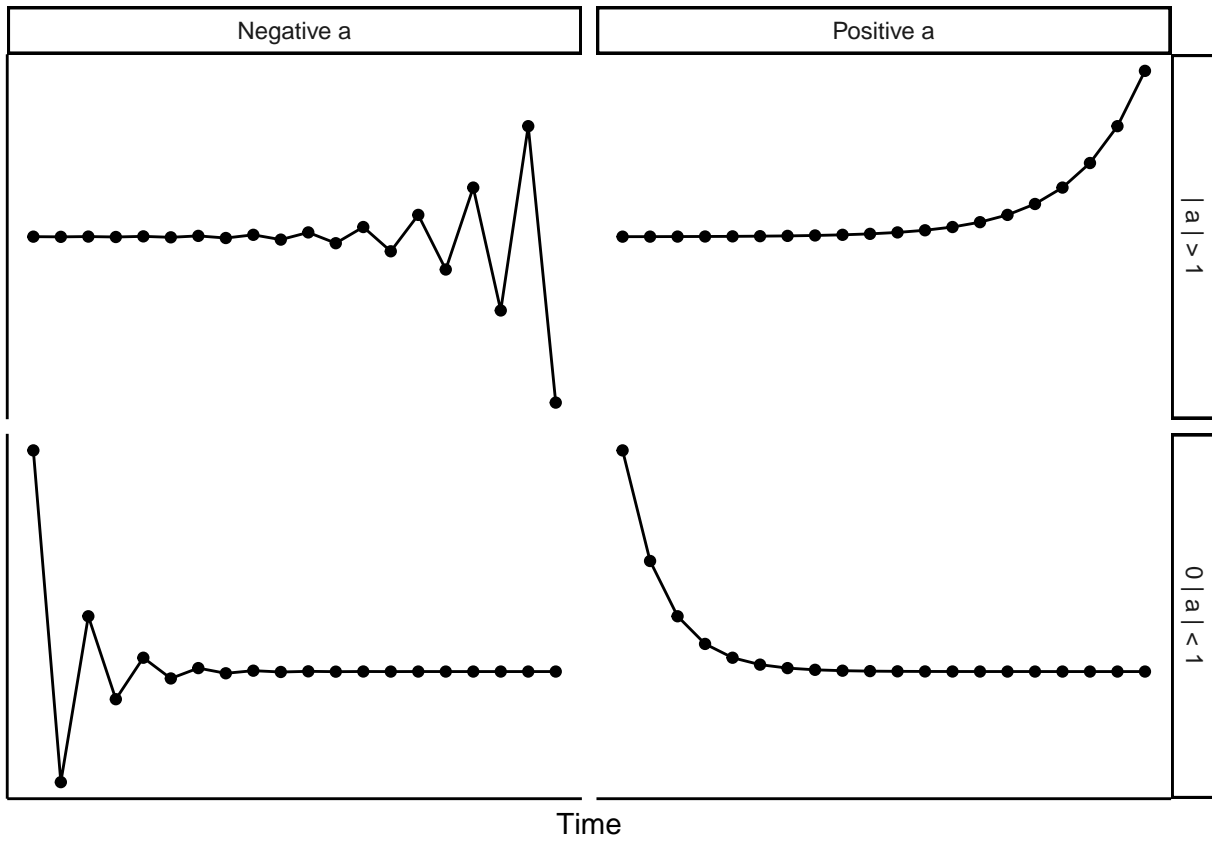


Figure 3. dynamic equilibrium fig

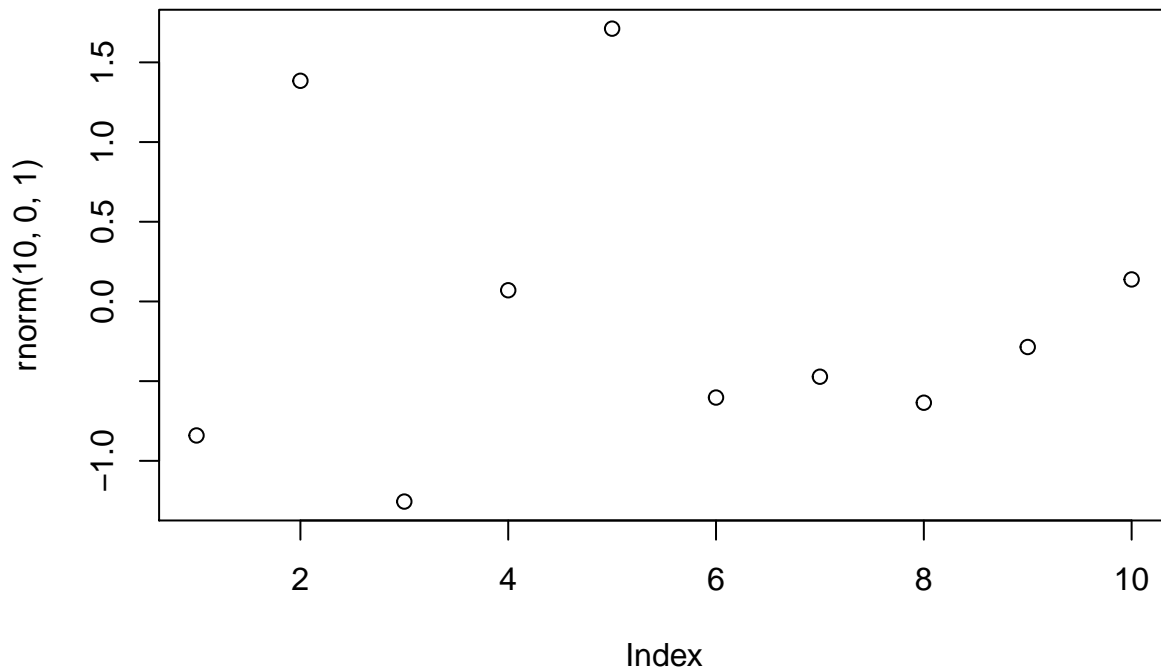


Figure 4. this one will be a white noise process and a random walk