

Heapsort

Data Structures and Algorithms
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Heap Property

A heap is a nearly complete binary tree, satisfying an extra condition

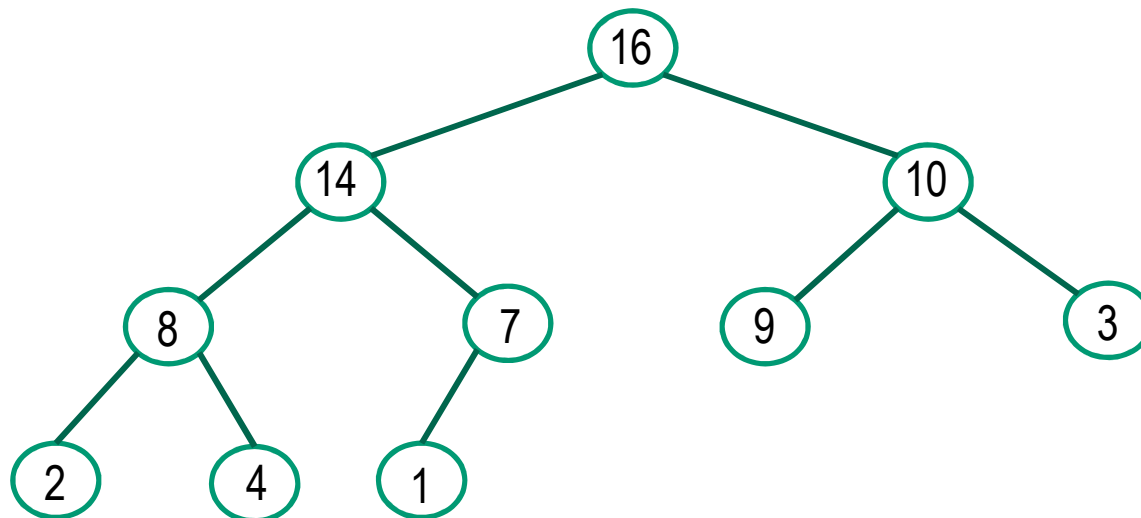
Let $\text{Parent}(i)$ denote the parent of the vertex i

Max-Heap Property:

$\text{Key}(\text{Parent}(i)) \geq \text{Key}(i)$ for all i

Min-Heap Property:

$\text{Key}(\text{Parent}(i)) \leq \text{Key}(i)$ for all i



Heaps

Nearly complete binary tree means that the length of any path from the root to a leaf can vary by at most one

The **height** of a vertex i is the length of the longest simple downward path from i

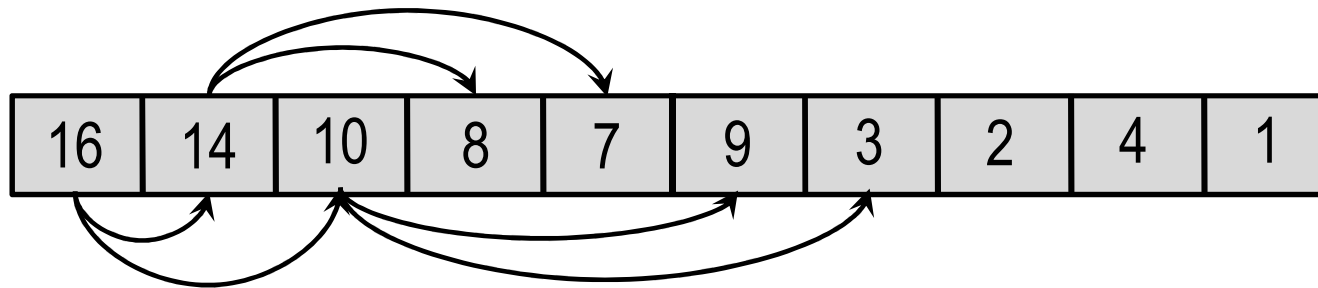
Therefore the height of the root is around $\log n$

Heap Operations

	Goal running time
● Creating a max-heap	$O(n)$
● Accessing the maximal element (root)	$O(1)$
● Inserting an element	$O(\log n)$
● Deleting an element	$O(\log n)$

Implementing Heaps and Operations

Heap can be implemented by an array



Children:

$$\text{leftChild}(i) = 2i$$

$$\text{rightChild}(i) = 2i + 1$$

Parent: $\text{parent}(i) = \lfloor i / 2 \rfloor$

Length: $\text{length}(H) = \text{the number of elements in } H$

Insertion

```
Insert(H, key)
  set  $n := \text{length}(n)$ ,
  set  $H[n+1] := \text{key}$ 
  HeapifyUp(H, n+1)
```

H is **almost heap with** $H[i]$ **too big** if
decreasing $H[i]$ by a certain amount
turns H into a heap

```
HeapifyUp(H, i)
  if  $i > 1$  then
    set  $j := \text{parent}(i) = \lfloor i/2 \rfloor$ 
    if  $\text{Key}[H[i]] > \text{Key}[H[j]]$  then
      swap array entries  $H[i]$  and  $H[j]$ 
      HeapifyUp(H, j)
    endif
  endif
```

HeapifyUp: Soundness

Theorem

The procedure $\text{HeapifyUp}(H,i)$ fixes the heap property in $O(\log i)$ time, assuming that the array H is almost a heap with the key of $H[i]$ too large.

The running time of Insertion is $O(\log n)$

Proof

Induction on i .

Base Case $i = 1$ is obvious

Induction Case: Swapping elements takes $O(1)$ time

It remains to observe that after swapping H remains a heap or almost heap

Deletion

```
Delete(H,i)
  set n:=length(n),
  set H[i]:=H[n]
  if Key[H[i]]>Key[H[parent(i)]] then
    HeapifyUp(H,i)
  endif
  if Key[H[i]]<Key[H[leftChild(i)]] or
     Key[H[i]]<Key[H[rightChild(i)]] then
    HeapifyDown(H,i)
  endif
```

H is **almost heap with** H[i] **too small** if increasing H[i] by a certain amount turns H into a heap

Deletion (cntd)

```
HeapifyDown(H,i)
set n:=length(H)
if 2i>n then Terminate with H unchanged
else if 2i<n then do
    set left:=2i, right:=2i+1
    let j be the index that minimizes Key[H[left]]
    and Key[H[right]]
else if 2i=n then    set j:=2i
endif
if Key[H[j]]>Key[H[i]] then
    swap array entries H[i] and H[j]
    HeapifyDown(H,j)
endif
```

HeapifyDown: Soundness

Theorem

The procedure $\text{HeapifyDown}(H,i)$ fixes the heap property in $O(\log i)$ time, assuming that the array H is almost a heap with the key of $H[i]$ too small.

The running time of Deletion is $O(\log n)$

Proof DIY

Building a Heap

```
Build-a-Heap(A)
set n:=length(A)
for i=1 to n do
    set H[i]:=A[i]
    HeapifyUp(H,i)
endfor
```

HeapSort

HeapSort(A)

Input: array A

Output: sorted array A

Method:

set $H := \text{Build-a-Heap}(A)$

set $n := \text{length}(H)$

for $i = n$ downto 1 do

 set $A[i] := H[1]$

 set $\text{length}(H) := \text{length}(H) - 1$

 Delete($H, 1$)

endfor

Priority Queues

A priority queue is a data structure for maintaining a set S of elements, each with associated value called a key.

Priority Queue operations

Insert(S, x) Insert element x into the set S

Maximum(S) Returns the element of S with the largest key

Extract-Max(S) Removes and returns the element of S with the largest key

Increase-Key(S, x, k) Increases the value of element x 's key to the new value k , which is at least as large as x 's current key value

Homework

Write pseudocode for procedure

Decrease-Key

that works in the same way as Increase-Key, except that it replaces the key with a smaller value.