## Applications of Taylor Polynominals

1. **Quote.** "I have been impressed with the urgency of doing. Knowing is not enough; we must apply."

(Leonardo da Vinci, Italian polymath, 1452-1519)

## 2. Reminder 1.

If f has a power series representation at a then

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x - a)^n$$

and this representation is called the Taylor series of the function f at a.

3. Reminder 2 - Taylor's Inequality.

If

$$\left| f^{(n+1)}(x) \right| \le M \text{ for } |x-a| \le d$$

then the remainder of the Taylor series satisfies the inequality

$$|R_n(x)| \le \frac{M}{(n+1)!} |x-a|^{n+1}$$
 for  $|x-a| \le d$ .

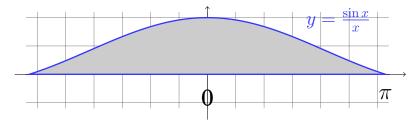
## 4. Example.

- (a) Approximate  $f(x) = x^{2/3}$  by a Taylor polynomial centred at a=1 with degree 3.
- (b) Use Taylor's Inequality to estimate the accuracy of the approximation  $f(x) \approx T_3(x)$  when  $0.8 \le x \le 1.2$ .



5. **Example.** Approximate the area between the curve  $y = \frac{\sin x}{x}$  and the x-axis for

$$-\pi \leq x \leq \pi$$
.

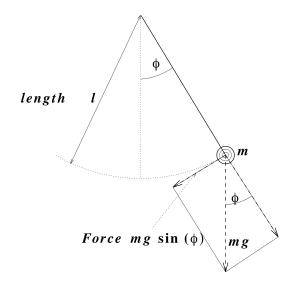


6. **Example.** A classic example from Physics – the frictionless pendulum.

We consider a pendulum of mass m and length  $\ell$ , and ignore friction. Denote by  $\phi(t)$  the angle of displacement at time t, and let  $g\approx 9.81ms^{-2}$ , the gravitational constant. Newton's law of motion states  $\vec{F}=m\vec{a}$ , where  $\vec{a}$  denotes acceleration. In our case this leads to  $m\ell\phi''(t)=-mg\sin{(\phi(t))}$ . Setting  $\omega^2=\frac{g}{l}$  this becomes a differential equation for the function  $\phi(t)$ ,

$$\phi''(t) + \omega^2 \sin(\phi(t)) = 0$$

**Taylor approximation:**  $\sin \phi =$ 



Let's try to solve this new differential equation via power series.



## Notes.