Phil 320

Chapter 5, §5.3: The scope of abacus computability

Assume that in computing $f(x_1,...,x_r)$, some stipulations are followed:

- (a) The arguments $x_1, ..., x_r$ are stored in registers 1 to r.
- (b) The output register must be r+1.
- (c) If the computation halts, the original arguments are still in registers 1 to r.

We show that a broad class of functions (the recursive functions) are all abacus-computable.

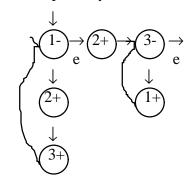
A. Initial or basic functions.

- a) The zero function. z(x) = 0 for all $x \in N$.
- b) The successor function. s(x) = x + 1
- c) The *identity* or *projection functions*. $id_i^n(x_1,...,x_n) = x_i$. The ith element of an n-tuple.

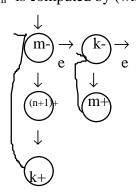
Examples:
$$id_1^{\ 1}(x_1) = x_1.$$

 $id_3^{\ 5}(x_1, x_2, ..., x_5) = x_3$
 $id_3^{\ 3}(4, 2, 25) = 25$

- z is computed by an empty abacus. For the abacus halts with 0 in R_2 .
- s is computed by the abacus



• id_m^n is computed by (where $k \ge n+1$ is the index of an auxiliary register)



Next, we show that three important operations applied to functions already known to be abacus-computable will give us new functions that are still abacus-computable.

B. Composition

Example 1: f(x) = x+2. Write as f(x) = s(s(x)).

Example 2: f(x) = 12. Write as f(x) = s(s(...s(z(x))...)).

Example 3: $f(x_1, x_2, x_3) = x_2 + 1$. Write as $f(x_1, x_2, x_3) = s(id_2^3(x_1, x_2, x_3))$.

In general: suppose f is a function of m arguments and each of $g_1,...,g_m$ is a function of n arguments. Then

$$h(x_1,...,x_n) = f(g_1(x_1,...,x_n),...,g_m(x_1,...,x_n))$$

is defined by composition from f and $g_1, ..., g_m$.

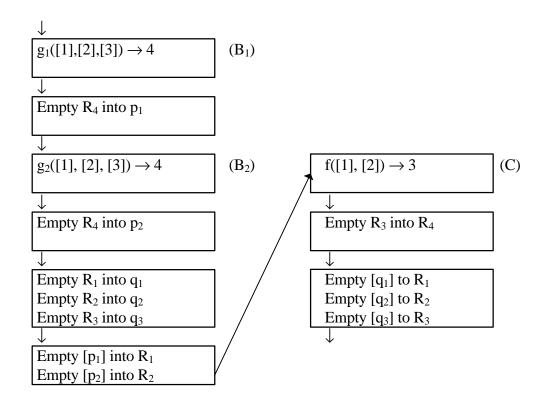
If all the g_i 's and f are abacus-computable, so is h.

Here is an outline of the proof. Given arguments $x_1, ..., x_n$ in registers R_1 through R_n , apply each of $g_1, ..., g_m$ in turn and store the results in auxiliary registers. Clear everything and put these m numbers in R_1 through R_m . Now apply f, and finish up by putting the result in R_{n+1} . In effect, we just glue the different abacus machines together.

The method is illustrated by taking r = 3 (3 arguments for each g) and m = 2 (2 arguments for f). So

$$h(x_1,...,x_3) = f(g_1(x_1,...,x_3), g_2(x_1,...,x_3)).$$

Here is the picture of the abacus that computes h, where B_1 , B_2 are the abaci that compute g_1 , g_2 and C is the abacus that computes f. (The description follows.)



Start with $x_1,..., x_3$ in R_1, R_2, R_3 . Select registers p_1, p_2 which are well beyond any registers used in any of the existing abacus machines. Select registers $q_1, ..., q_3$ which are also well beyond any registers used in the programs and beyond p_1, p_2 .

<u>Step 1</u>: Compute and store the result of $g_1(x_1,...,x_3)$ in p_1 and $g_2(x_1,...,x_3)$ in p_2 , in turn, and erase R_4 after each calculation. Temporarily store the arguments x_1, x_2, x_3 in the three q registers.

<u>Step 2</u>: Move the contents $[p_1]$ and $[p_2]$ into the first two registers and erase R_3 . Compute f, put the result into R_4 , and restore the arguments from $q_1, ..., q_3$ into $R_1, ..., R_3$.

C. Primitive recursion

We will have much more to say about this operation in chapter 6.

Example 1: Addition (sum). Compute sum(x, y) = x + y in the following way:

```
sum(x, 0) = x

sum(x, y+1) = sum(x, y)+1
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To compute sum(x, y), we now just have to work our way through sum(x, 0), sum(x, 1), ..., sum(x, y-1) and sum(x, y). For instance:

```
sum(3, 2) = sum(3, 1) + 1

sum(3, 1) = sum(3, 0) + 1

sum(3, 0) = 3

\Rightarrow so sum(3, 2) = 5
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Idea: There is a recipe that lets you compute the value when the second argument is y+1 if you know the value when the second argument is y. And there is a recipe for what to do if the second argument is y. So we can work our way up to any second argument, one step at a time.

Example 2: Multiplication (prod)

```
Prod(x, 0) = 0

Prod(x, y+1) = sum(x, prod(x, y))

prod(3, 2) = sum(3, prod(3, 1))

prod(3, 1) = sum(3, prod(3, 0)) = sum(3, 0) = 3 \Rightarrow prod(3, 2) = 6
```

Precise definition (for 2-place function):

h is defined by primitive recursion from 1-place f and 3-place g if:

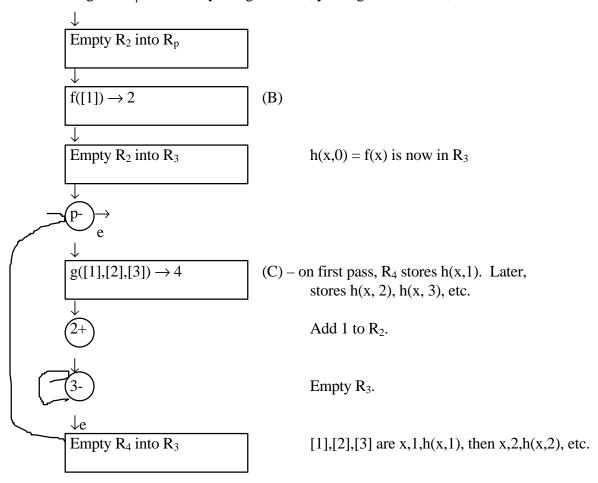
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h(x, 0) = f(x) and

h(x, y+1) = g(x, y, h(x, y)).
```

If f and g are abacus-computable, so is h.

Proof: Suppose abacus B computes f (with result in register 2) and C computes g (with result in register 4). Show that there is an abacus A that computes h (with result in register 3).

Select a register R_p not used by f or g. Store x, y in registers 1 and 2, with 0 elsewhere.



The calculation starts by putting f(x) in R_3 and increases R_2 from 0 up to y.

D. Minimization

Here, we will only define this operation for a 2-place function f(x, y), but it can be defined more generally, and the proof below can also be made more general.

Example: Let
$$f(x, y) = \{x^2 - y^2, \text{ if this is positive } \{0, \text{ if negative } \}$$

Define

 $h(x) = \{ \text{smallest y such that } f(x, y) = 0 \text{ IF there is such a y and } f(x, 0), f(x, 1), ..., f(x, y-1) \text{ are all defined} \}$ {undefined, otherwise

Then h(x) = x.

Example: Let $f(x, y) = \{x - y^2, \text{ if positive } \{0, \text{ if negative } \}$

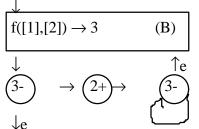
Define h as before. Then

 $h(x) = \sqrt{x}$, rounded up to nearest integer.

In general, h(x) is defined as above. Note that h(x) is undefined if either f(x, y) is never 0 or f(x, i) is undefined for some i < y. h is said to be obtained from f by *minimization*.

To show computability:

Suppose abacus B computes f(x, y) and consider 1-place h obtained by minimization. Initially all registers but R_1 are empty; the solution h(x) will go in R_2 (if defined).



Start with 0 for y in [2]; compute f. If val is 0, stops. Else, add 1 to y, compute f again, etc.

Empty out 3; add 1 to y and repeat the computation.

If the program stops, it can only be at the least y such that f(x, y) = 0 and f(x, t) is defined and positive for t < y; for if f is undefined somewhere along the way to y, then by definition the abacus B will not halt in computing f, so that the function defined by the above abacus will be undefined at (x,y).

RESULT:

The class of functions defined from the initial functions using composition, primitive recursion and minimization is called the *recursive functions* R. We have proved:

Theorem 5.8: All recursive functions are abacus computable.