Supplementary Material 2. Matrix Algebra

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Differentiation 1

1. $\mathbf{a} = (a_1, \dots, a_n)'$ and $\mathbf{x} = (x_1, \dots, x_n)'$, let $y = \mathbf{a}'\mathbf{x} = \sum_{i=1}^n a_i x_i$. Then

$$rac{\partial \left(\mathbf{a}^{\prime}\mathbf{x}
ight) }{\mathbf{x}}=\mathbf{a}.$$

2. $A = \begin{vmatrix} \mathbf{a}_1' \\ \vdots \\ \mathbf{a}' \end{vmatrix}$, and $\mathbf{x} = (x_1, \dots, x_n)'$, let $\mathbf{y} = \mathbf{A}\mathbf{x}$, then

$$\mathbf{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_k \end{bmatrix} = \begin{bmatrix} \mathbf{a}_1' \mathbf{x} \\ \vdots \\ \mathbf{a}_k' \mathbf{x} \end{bmatrix}$$

and

$$\frac{\partial \mathbf{A}\mathbf{x}}{\partial \mathbf{x}'} = \begin{bmatrix} \partial y_1 / \partial \mathbf{x}' \\ \vdots \\ \partial y_k / \partial \mathbf{x}' \end{bmatrix} = \begin{bmatrix} \mathbf{a}_1' \\ \vdots \\ \mathbf{a}_k' \end{bmatrix} = A.$$

Also,

$$\frac{\partial \mathbf{A}\mathbf{x}}{\partial \mathbf{x}} = A'$$

3.
$$\frac{\partial f(\mathbf{x})}{\partial \mathbf{x}'} = \left(\frac{\partial f(\mathbf{x})}{\partial \mathbf{x}}\right)'$$

4. $\mathbf{x}'A\mathbf{x} = \sum_{i=1}^{n} \sum_{j=1}^{n} a_{ij}x_{i}x_{j}$, then

(1) $\frac{\partial(\mathbf{x}'A\mathbf{x})}{\partial\mathbf{x}} = (A+A')\mathbf{x}$. And when A is symmetric, $\frac{\partial(\mathbf{x}'A\mathbf{x})}{\partial\mathbf{x}} = 2A\mathbf{x}$;

(2) $\frac{\partial(\mathbf{x}'A\mathbf{x})}{\partial A} = \mathbf{x}\mathbf{x}'$, especially, $\frac{\partial(\mathbf{x}'A\mathbf{x})}{\partial a_{ij}} = x_{i}x_{j}$.

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2 Kronecker Product

1.
$$A \otimes B = \begin{bmatrix} a_{11}B & a_{12}B & \cdots & a_{1K}B \\ a_{21}B & a_{22}B & \cdots & a_{2K}B \\ a_{n1}B & a_{n2}B & \cdots & a_{nK}B \end{bmatrix}$$

$$2. (A \otimes B)' = A' \otimes B'$$

3.
$$(A \otimes B)^{-1} = A^{-1} \otimes B^{-1}$$

4.
$$(A \otimes B) (C \otimes D) = AC \otimes BD$$

3 Eigenvalues and Matrix Decomposition

1. Definition: we say λ is the *eigenvalue* (or characteristic root) of A and \mathbf{x} is the *eigenvector* (or characteristic vector) of A if

$$A\mathbf{c} = \lambda \mathbf{c}$$

And **x** is often normalized such that c'c = 1.

- 2. Suppose that A has k non-zero eigenvalues, then rank(A) = k, $tr(A) = \sum_{i=1}^{k} \lambda_i$ and $det(A) = \prod_{i=1}^{k} \lambda_i$.
- 3. Suppose A is a $k \times k$ real symmetric matrix, it has k distinct eigenvalues, $\lambda_1, \dots, \lambda_k, c_1, \dots, c_k$ are the corresponding eigenvectors, and they are **orthonormal**. Let $C = [c_1 \dots, c]$ and $\Lambda = diag(\lambda_1, \dots, \lambda_k)$. Then $AC = C\Lambda$.
 - (a) The *diagonalization* of A is $C'AC = C'C\Lambda = \Lambda$.
 - (b) The **spectral decomposition** of A is $A = CAC' = \sum_{i=1}^{k} \lambda_k c_k c_k'$.
- 4. Let A be an $m \times n$ matrix of rank r > 1. Then there exists orthogonal matrices $U \in \mathbb{R}^{m \times m}$ and $V \in \mathbb{R}^{n \times n}$. The **singular value decomposition (SVD)** of A is

$$A = U\Lambda V',$$

where $\Lambda \in \mathbb{R}^{m \times n}$ has $\Lambda_{ij} = 0$ for $i \neq j$ and $\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_r > \lambda_{r+1} = \cdots = \lambda_{\min\{m,n\}} = 0$, where $\lambda_i := \Lambda_{ii}$ is the i - th singular value of A. And

$$A = \sum_{i=1}^{r} \lambda_i u_i v_i',$$

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where u_i is the i-th column of U and v_i is the i-th column of V.