# Package 'RGPR'

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```
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Description S4 classes and R functions to read, write, analyse and visualise
     ground-penetrating radar (GPR) data.
Depends base
License GPL (>= 2)
{\bf URL} \ {\tt https://github.com/emanuelhuber/RGPR}
BugReports https://github.com/emanuelhuber/RGPR/issues
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Collate 'RGPR.R'
     'global.R'
     'ClassGPR.R'
     'ClassGPR survey.R'
     'ClassMisc.R'
     'data.R'
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```

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# **R** topics documented:

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Description

The RGPR package provides two classes GPR and GPRsurvey

## Reading/writing/export functions

• readGPR(): format DT1 (Sensors&Software), rds (R-format)

• writeGPR(): format DT1 (Sensors&Software), rds (R-format)

data radar (GPR) data.

• exportPDF()

• exportDelineations()

• exportFid(): ASCII-file

• exportCoord(): ASCII, SpatialLines or SpatialPoints

• exportProc(): ASCII-file

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## **Plot functions**

- plot(): raster or wiggles.
- plot3D():
- plotAmpl()
- plotDelineations()

#### Coercion

- as.matrix():
- as.numeric():
- as.list():
- as.SpatialPoints():
- as.SpatialLines():

#### **Delineation**

- delineate():
- plotDelineations():
- delineations(): list of the delineations
- addDelineation:
- rmDelineations:
- exportDelineations:
- plotDelineations3D:
- identifyDelineation:

## Author(s)

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Authors:

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## References

Several books!

#### See Also

Useful links:

- https://github.com/emanuelhuber/RGPR
- Report bugs at https://github.com/emanuelhuber/RGPR/issues

ampl

Amplitude of the GPR data

## Description

Amplitude of the GPR data

## Usage

```
## S4 method for signature 'GPR'
ampl(x, FUN = mean, ...)
```

ann

Annotations of the GPR data

# Description

Annotations of the GPR data

## Usage

```
## S4 method for signature 'GPR'
ann(x)
## S4 replacement method for signature 'GPR'
ann(x) <- value</pre>
```

Arith, GPR, ANY-method Basic arithmetical functions

## Description

Basic arithmetical functions

```
## S4 method for signature 'GPR,ANY'
Arith(e1, e2)

## S4 method for signature 'GPR,GPR'
Arith(e1, e2)

## S4 method for signature 'ANY,GPR'
Arith(e1, e2)
```

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## **Arguments**

e1 An object of the class RGPR.

e2 An object of the class RGPR.

## **Examples**

```
data(frenkeLine00)
A <- exp(frenkeLine00)
B <- A + frenkeLine00</pre>
```

as.matrix

Coercion to matrix

## **Description**

Coercion to matrix

Coercion to vector

Coercion to SpatialLines

Coercion to SpatialPoints

Coercion to numeric

Coercion from matrix to GPR

Coercion from list to GPR

```
## S4 method for signature 'GPR'
as.matrix(x)

## S4 method for signature 'GPR'
as.vector(x, mode = "any")

## S4 method for signature 'GPR'
as.SpatialLines(x)

## S4 method for signature 'GPR'
as.SpatialPoints(x)

## S4 method for signature 'GPR'
as.numeric(x, ...)

as.GPR.matrix(x, ...)

as.GPR.list(x, ...)
```

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clip

Clip the amplitude

## **Description**

Clip the amplitude

## Usage

```
## S4 method for signature 'GPR'
clip(x, Amax = NULL, Amin = NULL)
```

CMPAnalysis

Common mid-point (CMP) analysis

## Description

either use 'rec' and 'trans' to compute the distance between the antennas or give the distance between the antennas (asep) or seq(x@antsep, by = x@dx, length.out = length(x))

#### Usage

```
## S4 method for signature 'GPR'
CMPAnalysis(x, method = c("semblance", "winsemblance",
   "wincoherence", "wincoherence2"), v = NULL, asep = NULL, w = NULL)
```

## **Arguments**

X	An object of the class GPR
method	A length-one character vector
V	A numeric vector defining at which velocities the analysis is performed
asep	A length-n numeric vector defining the antenna separation for each trace $(n = number\ of\ traces)$
W	A length-one numeric vector defining the window length for the methods 'wincoherence' and 'wincoherence2'.

#### **Details**

**semblance** also described as the ratio of input to output energy (Niedell and Taner, 1971) **semblance2** windowed semblance

wincoherence Windowed coherence measure based on eigen-decomposition that estimates the signal-to-noise ratio for high resolution velocity analysis (Sacchi, 2002)

wincoherence 2 Windowed coherence measure based on a log-generalized likelihood ratio which tests the hypothesis of equality of eigenvalues (Key and Smithson, 1990)

colFromPal 9

## References

• Neidell and Taner (1971) Semblance and other coherency measures for multichannel data. Geophysics, 36(3):482-497.

- Key and Smithson (1990) New approach to seismic-reflection event detection and velocity determination. Geophysics, 55(8):1057-1069.
- Textbook: Sacchi (2002) Statistical and Transform Methods in Geophysical Signal Processing

colFromPal

Return color from palette

## **Description**

Return color from palette

#### Usage

```
colFromPal(A, col = palGPR(n = 101))
```

conv1D

Trace convolution (1D)

## Description

Convolution of the GPR traces with a wavelet

#### Usage

```
## S4 method for signature 'GPR'
conv1D(x, w)
```

#### **Arguments**

x A GPR data

A numeric vector defining a wavelet or a matrix with number of columns equal to the number of traces.

#### Value

The convolved GPR data.

10 convolution

conv2D

2D onvolution

## **Description**

Convolution of the GPR data with a kernel

## Usage

```
## S4 method for signature 'GPR'
conv2D(x, w)
```

#### **Arguments**

x A GPR data

w A numeric matrix with smaller dimension than the GPR data.

## Value

The convolved GPR data.

convolution

Linear convolution based on FFT

## Description

If A (or B) is a numeric vector, it is converted into a one-column matrix. Then if A and B do not have the same number of column, then the first column of the matrix with the smallest number of column is repeated to match the dimension of the other matrix. match the dimension of the other matrix.

## Usage

```
convolution(A, k)
```

## **Arguments**

A A numeric vector or matrix.

A B numeric vector or matrix.

convolution2D 11

convolution2D

Two-dimensional convolution

## **Description**

The convolution is performed with 2D FFT

# Usage

```
convolution2D(A, k)
```

coord

Coordinates of the GPR data

# Description

Coordinates of the GPR data

## Usage

```
## S4 method for signature 'GPR'
coord(x, i, ...)
## S4 replacement method for signature 'GPR'
coord(x) <- value</pre>
```

coordref

Define a local reference coordinate

# Description

Define a local reference coordinate

```
## S4 method for signature 'GPRsurvey'
coordref(x)
```

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coords

Return coordinates

## Description

Return coordinates

Set coordinates

## Usage

```
## S4 method for signature 'GPRsurvey'
coords(x, i)
## S4 replacement method for signature 'GPRsurvey'
coords(x) <- value</pre>
```

crs

Coordinate reference system (CRS) of the GPR data

## Description

Coordinate reference system (CRS) of the GPR data

```
## S4 method for signature 'GPR'
crs(x)

## S4 replacement method for signature 'GPR'
crs(x) <- value

## S4 method for signature 'GPRsurvey'
crs(x)

## S4 replacement method for signature 'GPRsurvey'
crs(x) <- value</pre>
```

deshift 13

dcshift	Direct-Current shift removal	

## Description

The direct-current shift is estimated for each traces based on a specified number of time samples (normally the samples before time-zero). Then, the direct-current shift of every trace is substracted from every trace.

## Usage

```
## S4 method for signature 'GPR'
dcshift(x, u = 1:10, FUN = mean)
```

#### **Arguments**

X	An object of the class 'GPR'.
u	Number of time samples used to evaluate the DC-shift.
FUN	A function to apply on the first 'u' time samples (default is 'mean'; alternatively 'median' could be used or any user defined function).
n	<pre>[integer(1)] My argument. Default is 1.</pre>

deconv Deconvolution

## **Description**

A generic function to perform different types of convolution

## Usage

```
## S4 method for signature 'GPR'
deconv(x, method = c("spiking", "wavelet", "min-phase",
    "mixed-phase"), ...)
```

## **Arguments**

```
method Type of deconvolution method.
... additional arguments, see details.
```

## Value

A list containing the deconvolued GPR data (and possibly other variables.

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#### Spiking and mixed-phase deconvolution

The required arguments for method = "spiking" and method = "mixed-phase" are:

 W: A length-two numeric vector defining the time/depth window for which the wavelet is estimated

- wtr: A length-one numeric vector defining the number of neighbrough traces to be combine into a "super trace" (the total number of traces is 2\*wtr + 1).
- nf: A length-one numeric vector defining the filter length.
- mu: A length-one numeric vector defining the amount of noise.

#### Wavelet deconvolution

The required arguments for method = "wavelet" are:

- h: A numeric vector corresponding to the wavelet used to deconvolve the GPR data.
- mu: A length-one numeric vector defining the amount of noise.

delineate

Delineate structure on GPR data

#### **Description**

Delineate structure on GPR data

```
## S4 method for signature 'GPR'
delineate(x, name = NULL, type = c("raster", "wiggles"),
    addTopo = FALSE, nupspl = NULL, n = 10000, ...)

## S4 method for signature 'GPR'
addDelineation(x, itp, name = NULL, type = c("raster",
    "wiggles"), addTopo = FALSE, ...)

## S4 replacement method for signature 'GPR'
rmDelineations(x) <- value

## S4 method for signature 'GPR'
delineations(x, sel = NULL, ...)

## S4 method for signature 'GPR'
exportDelineations(x, dirpath = "")

## S4 method for signature 'GPR'
plotDelineations3D(x, sel = NULL, col = NULL, add = TRUE,
    ...)</pre>
```

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```
## S4 method for signature 'GPR'
plotDelineations(x, sel = NULL, col = NULL, ...)
## S4 method for signature 'GPR'
identifyDelineation(x, sel = NULL, ...)
```

depth

Depth/time of the GPR data

## Description

Depth/time of the GPR data

## Usage

```
## S4 method for signature 'GPR'
depth(x)
## S4 replacement method for signature 'GPR'
depth(x) <- value</pre>
```

depth0

Depth zero

## Description

Depth zero

## Usage

```
depth0(time_0, v = 0.1, antsep = 1, c0 = 0.299)
```

depthToTime

Depth to time conversion

## Description

Depth to time conversion

```
depthToTime(z, time_0, v = 0.1, antsep = 1, c0 = 0.299)
```

16 dewow

depthunit

Depth unit of the GPR data

## Description

Depth unit of the GPR data

## Usage

```
## S4 method for signature 'GPR'
depthunit(x)
## S4 replacement method for signature 'GPR'
depthunit(x) <- value</pre>
```

description

Description of the GPR data

## **Description**

Description of the GPR data

## Usage

```
## S4 method for signature 'GPR'
description(x)
## S4 replacement method for signature 'GPR'
description(x) <- value</pre>
```

dewow

Trace dewowing

## Description

dewow remove the low-frequency component (the so-called 'wow') of every trace..

```
## S4 method for signature 'GPR'
dewow(x, type = c("MAD", "Gaussian"), w)
```

displacement 17

## **Arguments**

X	An object of the class GPR.
type	A length-one character vector, either MAD (Median Absolute Deviation filter) (Gaussian (Gaussian filter)

A length-one numeric vector equal to the window length of the filter. Per default,

or

the filter length is five times the GPR pulse width.

#### Value

An object of the class GPR whose traces are dewowed.

## **Examples**

```
data(frenkeLine00)
A <- dewow(frenkeLine00, type = "Gaussian")
A</pre>
```

displacement

Displacement to align two matrix

## Description

Displacement to align two matrix

## Usage

```
displacement(x, y, method = c("phase", "WSSD"), dxy = NULL)
```

distTensors

Distance between structure tensors

## **Description**

Distance between structure tensors

```
distTensors(J1, J2, method = c("geodesic", "log-Euclidean", "angular", "L2"),
    normalise = FALSE)
```

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exportCoord

Export the trace coordinates.

## **Description**

Export the trace coordinates.

## Usage

```
## S4 method for signature 'GPR'
exportCoord(x, type = c("SpatialPoints", "SpatialLines",
   "ASCII"), fPath = NULL, driver = "ESRI Shapefile", ...)
```

exportFid

Export fiducial markers

## **Description**

Export fiducial markers

## Usage

```
## S4 method for signature 'GPR'
exportFid(x, fPath = NULL)
```

exportPDF

Export a PDF showing the GPR profile.

## Description

Export a PDF showing the GPR profile.

```
## S4 method for signature 'GPR'
exportPDF(x, fPath = NULL, addTopo = FALSE, clip = NULL,
    normalize = NULL, nupspl = NULL, type = "wiggles", ...)
```

exportProc 19

exportProc

Export the process steps.

## Description

Export the process steps.

## Usage

```
## S4 method for signature 'GPR'
exportProc(x, fPath = NULL, sep = "\t",
  row.names = FALSE, col.names = FALSE, ...)
```

fFilter

Frequency filter

## Description

Frequency filter

## Usage

```
## S4 method for signature 'GPR'
fFilter(x, f = 100, type = c("low", "high", "bandpass"),
  L = 257, plotSpec = FALSE)
```

fid

Fiducial markers of the GPR data

## Description

Fiducial markers of the GPR data

```
## S4 replacement method for signature 'GPR'
fid(x) <- value
## S4 method for signature 'GPR'
fid(x)</pre>
```

20 filter2D

filepath

Filepath of the GPR data

## Description

Filepath of the GPR data

## Usage

```
## S4 method for signature 'GPR'
filepath(x)

## S4 replacement method for signature 'GPR'
filepath(x) <- value</pre>
```

filter1D

One dimensional filters

## **Description**

One dimensional filters

## Usage

```
## S4 method for signature 'GPR'
filter1D(x, type = c("median", "hampel", "Gaussian"), ...)
```

filter2D

Two-dimensional filters

## Description

Two-dimensional filters

```
## S4 method for signature 'GPR'
filter2D(x, type = c("median3x3", "adimpro"), ...)
```

firstBreak 21

firstBreak First wave break
-----------------------------

## Description

Compute the first wave break.

## Usage

```
## S4 method for signature 'GPR'
firstBreak(x, method = c("coppens", "coppens2", "threshold",
   "MER"), thr = 0.12, w = 11, ns = NULL, bet = NULL)
```

## **Arguments**

X	An object of the class GPR
method	A length-one character vector. "coppens" corresponds to the modified Coppens method, "threshold" to the threshold method, and "MER" to the modified energy ratio method.
thr	A length-one numeric vector defining the threshold signal amplitude (in %) at which time zero is picked (only for the threshold method).
W	A length-one numeric vector defining the length of leading window (only for the modified Coppens and modified energy ratio methods). Recommended value: about one period of the first-arrival waveform.
ns	A length-one numeric vector defining the length of the edge preserving smoothing window (only for the modified Coppens method). Recommended value: between one and two signal periods. When $ns = NULL$ the value of $ns$ is set to $1.5 * w$ .
bet	A length-one numeric vector defining the stabilisation constant (only for the modified Coppens method). Not critical. When bet = NULL the value of bet is set to 20% of the maximal signal amplitude.

#### References

**Modified Coppens method** Sabbione J.I. and Velis D. (2010) Automatic first-breaks picking: New strategies and algorithms. Geophysics, 75(4): 67-76.

**Modified Energy Ratio (MER) method** Han L., Wong J., and John C. (2010) Time picking on noisy microseismograms. In: Proceedings of the GeoCanada 2010 Convention - Working with the Earth, Calgary, AB, Canada, p. 4

## See Also

time0 to set time zero and time0Cor to shift the traces such that they start at time zero.

22 fkFilter

firstBreakToTime0

Convert first wave break to time-zero

## **Description**

Account for the delay time between time of wave emission and time of first wave break recording due to the antenna separation (offset).

Time correction for each trace to compensate the offset between transmitter and receiver antennae (it converts the trace time of the data acquired with a bistatic antenna system into trace time data virtually acquiered with a monostatic system under the assumption of horizontally layered structure). If all the traces have the same time-zero, this function does not change the trace but only the time (time scale). If the traces have different time-zero, the traces are first aligned to have the same time-zero (spline interpolation)

## Usage

```
firstBreakToTime0(fb, x, c0 = 0.299)
## S4 method for signature 'GPR'
timeCorOffset(x, t0 = NULL)
```

#### **Arguments**

X	A object of the class GPR
с0	Propagation speed of the GPR wave through air (used only when keep = $NULL$ ).
t0	A numeric vector with length equal either to NULL, or one or to the number
	traces. If $t0 = NULL$ 'time $O(x)$ ' will be used.

#### See Also

time0 to set time zero and firstBreakToTime0 to convert the first wave break into time zero.

fkFilter

Frequency-wavenumber filter

#### **Description**

Frequency-wavenumber filter

```
## S4 method for signature 'GPR'
fkFilter(x, fk = NULL, L = c(5, 5), npad = 1)
```

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frenkeLine00

Ground-penetrating radar data.

## **Description**

Surface ground-penetrating radar data recorded the 25 April 2014 in Frenkental (Swizerland). Coordinates: CH1903+/LV95:2'622'209.66, 1'256'907.54 Elevation: 345.8 m

## Usage

frenkeLine00

#### **Format**

An object of the class RGPR

## Source

University of Basel (Switzerland)

gain

Gain compensation

## Description

Gain compensation

## Usage

```
## S4 method for signature 'GPR'
gain(x, type = c("power", "exp", "agc"), ...)
```

gammaCorrection

Gamma correction of the amplitude

# Description

Gamma correction of the amplitude

```
## S4 method for signature 'GPR'
gammaCorrection(x, a = 1, b = 1)
```

24 getGPR

|--|

# Description

Perform on a set of x,y coordinates (1) a translation by  $\neg cloc$ , then (2) a rotation by alpha (radian), and (3) a translation by creg. If creg is NULL, then creg is set equal to cloc.

# Arguments

getGPR	Extract GPR object from GPRsurvey object
FUN	If alpha = NULL, a function to estimate the rotation angle from the angles computed for each pairs of coordinates of ploc-preg.
preg	A matrix with the first two columns corresponding to coordinates in the regional reference system.
ploc	A matrix with the first two columns corresponding to coordinates in the local reference system.
creg	A length-two numeric vector corresponding to the coordinate center of the regional reference system. Setting creg = NULL (default) is equivalent to apply a rotation of angle alpha and center cloc.
cloc	A length-two numeric vector corresponding to the coordinate center of the local reference system
alpha	A length-one numeric vector corresponding to the rotation angle in radians. If alpha = NULL, alpha is estimated from the pairs of points in the local reference system (ploc) and in the regional reference system (preg).
Х	A matrix with the first two columns corresponding to coordinates.

# Description

Extract GPR object from GPR survey object

```
## S4 method for signature 'GPRsurvey'
getGPR(x, id)
```

gethd 25

gethd

Return data header

# Description

Return data header

## Usage

```
## S4 method for signature 'GPR'
gethd(x, hd = NULL)
```

gkernel

Gaussian 2d-kernel

## Description

Gaussian 2d-kernel

Gaussian x-derivative kernel (edge detector)

Gaussian y-derivative kernel (edge detector)

# Usage

```
gkernel(n, m, sd = 1)

dx_gkernel(n, m, sd = 1)

dy_gkernel(n, m, sd = 1)
```

GPR-class

Class GPR

# Description

An S4 class to represent a ground-penetrating radar (GPR) data.

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#### **Slots**

version A length-one character vector indicating the version of RGPR

data A  $m \times n$  numeric matrix consiting of a cross-section of signal amplitudes as a function of the GPR position. The columns of data correspond to the GPR traces and the row of data to the time/depth samples.

traces A length-m numeric vector corresponding to the trace number.

depth A length-n numeric vector indicating the sampling time or the vertical position of the trace samples.

pos A length-m numeric vector indicating the relative position of the trace along the survey profile.

time0 A length-m numeric vector containing the 'time-zero' of every trace.

time A length-m numeric vector containing the recording time of every trace.

fid A length-m character vector containing fiducial markers associated with the traces.

ann A length-m character vector containing annotations associated with the traces.

coord A  $m \times 3$  matrix containing the (x, y, z) positions of every trace.

rec A  $m \times 3$  matrix containing the (x, y, z) positions of the receiver for every trace.

trans A  $m \times 3$  matrix containing the (x, y, z) positions of the transmitter for every trace.

coordref A length-3 numeric vector containing the coordinates of a local reference.

freq A length-one numeric vector corresponding to the GPR antennae frequency (in MHz).

dz A length-one numeric vector corresponding to the time or depth sampling step.

dx A length-one numeric vector corresponding to the trace step.

antsep A length-one numeric vector corresponding to the antenna separation.

name A length-one character vector containing the name of the GPR data.

description A length-one character vector containing the description of the GPR data.

filepath A length-one character vector containing the file path of the original GPR data.

depthunit A length-one character vector corresponding to the time/depth unit (e.g., "ns", "m").

posunit A length-one character vector corresponding to the (x, y)-unit (e.g., "m").

surveymode A length-one character vector containing the survey mode (e.g., "Reflection", "CMP")

date A length-one character vector containing the date of the survey in the format "yyyy-mm-dd".

crs A length-one character vector containing the coordinate reference system following the R notation of proj4string from the PROJ.4 library.

proc A length-varying character vector whose each element correspond to a processing step applied to the data.

vel A list containing the velocity model.

delineations A list containing delineated structures.

hd A list containing less relevant additional informations.

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GPR-subset

extract parts of GPR

## Description

Object of the class GPR can be manipulated as matrix

## Usage

```
## S4 method for signature 'GPR,ANY,ANY,ANY'
x[i, j, drop]
## S4 replacement method for signature 'GPR,ANY,ANY,ANY'
x[i, j] <- value</pre>
```

# Arguments

i integer j integer

GPRsurvey

Create an object of the class GPRsurvey

## **Description**

Create an object of the class GPR survey using a vector of GPR data filepath

# Usage

```
GPRsurvey(LINES)
```

GPRsurvey-subset

extract parts of GPRsurvey

## **Description**

Return an object of class GPR survey

```
## S4 method for signature 'GPRsurvey, ANY, ANY, ANY' x[i, j, drop]
```

28 interpPos

```
GPRsurvey.as.SpatialLines

Coerce to SpatialLines
```

## **Description**

Coerce to SpatialLines
Coerce to SpatialPoints

## Usage

```
## S4 method for signature 'GPRsurvey'
as.SpatialLines(x)
## S4 method for signature 'GPRsurvey'
as.SpatialPoints(x)
```

inPoly

Return points that are within a polygon

## **Description**

Return points that are within a polygon

## Usage

```
inPoly(x, y, vertx, verty)
```

interpPos

Interpolate trace positions from measurement (e.g., GPS).

## **Description**

Interpolate trace positions from measurement (e.g., GPS).

```
## S4 method for signature 'GPR'
interpPos(x, topo, plot = FALSE, r = NULL, tol = NULL,
  method = c("linear", "spline", "pchip"), ...)
```

intersections 29

#### **Arguments**

x	An object of the class GPR.
topo	A $m \times 4$ numeric matrix, with m the number of traces in 'x'. The columns names of topo must be "E", "N", "Z" and "TRACE".
plot	A length-one boolean vector. If TRUE some control plots are displayed.
r	A 'RasterLayer' object from the package 'raster' from which trace elevation z will be extracted based on the trace position (x, y) on the raster.
tol	Length-one numeric vector: if the horizontal distance between two consecutive trace positions is smaller than tol, then the traces in between as well as the second trace position are removed. If tol = NULL, tol is set equal to sqrt(.Machine\$double.eps).
method	A length-three character vector defining the interpolation methods (same methods as in signal::interp1: "linear", "nearest", "pchip", "cubic", and "spline"). First element for the interpolation of the inter-trace distances, second element for the interpolation of the horizontal trace positions, and third element for the interpolation of the vertical trace positions.

intersections

Return intersection from GPRsurvey

# Description

Return intersection from GPRsurvey

## Usage

```
## S4 method for signature 'GPRsurvey'
intersections(x)
```

latlongToUTM

latitude-longitude to UTM

# Description

see https://stackoverflow.com/a/30225804

```
latlongToUTM(lat, long, zone = NULL, south = FALSE)
```

30 linkCoordFid

lines

Add a GPR trace on a plot

## Description

```
Add a GPR trace on a plot
Plot the GPR survey as lines
```

# Usage

```
## S3 method for class 'GPR'
lines(x, ...)
## S3 method for class 'GPRsurvey'
lines(x, ...)
```

linkCoordFid

Link coordinates to fiducial marker

## Description

To interpolate topo

## Usage

```
linkCoordFid(y, xyz, pcode, tol = 0.1)
```

## **Arguments**

У	object of class GPSsurvey	

xyz matrix of coordinates

pcode character vector (length(pcode) = nrow(xyz)) indicating which coordinates to

which GPR data belongs

tol Tolerance to detect duplicates from topo data

Math,GPR-method 31

Math, GPR-method

Basic mathematical functions

## Description

Methods for the base Math methods S4groupGeneric

## Usage

```
## S4 method for signature 'GPR'
Math(x)
```

## **Arguments**

Χ

An object of the class RGPR.

#### **Details**

Currently implemented methods include:

```
• "abs", "sign", "sqrt", "ceiling", "floor", "trunc", "exp", "expm1", "log", "log10", "log2", "log1p", "cos", "cosh", "sin", "sinh", "tanh"
```

## **Examples**

```
data(frenkeLine00)
A <- exp(frenkeLine00)</pre>
```

 ${\tt migration}$ 

Migration of the GPR data

## **Description**

Migration of the GPR data

```
## S4 method for signature 'GPR'
migration(x, type = c("static", "kirchhoff"), ...)
```

NMOCor

name

Name of the GPR data

## Description

Name of the GPR data

## Usage

```
## S4 method for signature 'GPR'
name(x)
## S4 replacement method for signature 'GPR'
name(x) <- value</pre>
```

NM0Cor

Normal Move-Out correction

## **Description**

Remove the Normal Move-Out (NMO) from the trace given a constant velocity: this is a non-linear correction of the time axis that require interpolation. Note that only the conventional NMO correction is currently implemented. The conventional NMO introduces a streching effect. A nonstretch NMO will be implemented in a near future.

## Usage

```
## S4 method for signature 'GPR'
NMOCor(x, v = NULL, asep = NULL)
```

# **Arguments**

<b>v</b>	An object	of the c	lace CPR
X	All object	or the c	1ass GFR

v A length-one numeric vector defining the radar wave velocity in the ground

asep A length-n numeric vector defining the antenna separation for each trace (n =

number of traces; for example: seq(x@antsep, by = x@dx, length.out = length(x))).

If NULL, the slots rec and trans of x are used to compute the distance between

the antennas

optPhaseRotation 33

#### **Details**

Assuming a horizontal reflecting plane and homogeneous medium, the two-way bistatic travel time of the reflected wave for an antenna separation x follows directly from the Pythagorean theorem:

$$t_{TWT}(x,z) = \sqrt{\frac{x^2}{v^2} + \frac{4z^2}{v^2}}$$

where  $t_{TWT}(x)$  is the two-way travel time at antenna separation x of the wave reflected at depth z with propagation velocity v. This equation defines an hyperbola (keep z constant, increase the antenna separation x and you obtain a hyperbola similar to the reflection signals you obtain with common-mid point survey). The idea behind NMO-correction is to correct the signal for the antenna separation (offset) and therefore to transform the signal to the signal we would have recorded with zero offset (x=0). We write the vertical two-way traveltime at zero offset

$$t_0 = t_{TWT}(x=0) = \frac{2z}{v}$$

Therefore, the NMO-correction  $\Delta_{NMO}$  is

$$\Delta_{NMO} = t_{TWT}(x) - t_0$$

$$\Delta_{NMO} = t_0(\sqrt{1 + \frac{x^2}{v^2 t_0^2}} - 1)$$

#### References

- Tillard and Dubois (1995) Analysis of GPR data: wave propagation velocity determination. Journal of Applied Geophysics, 33:77-91
- Shatilo and Aminzadeh (2000) Constant normal-moveout (CNMO) correction: a technique and test results. Geophysical Prospecting, 473-488

optPhaseRotation

Optimum Phase Rotation

#### **Description**

**Optimum Phase Rotation** 

## Usage

optPhaseRotation(x, rot = 0.01, plot = TRUE)

#### **Arguments**

x any data that can be converted into a numeric vector with as vector.

rot The phase rotation increment.

plot A lenth-one boolean vector. If TRUE, the kurtosis as a function of phase angle

is plotet.

34 papply

padmat

pad a matrix

## Description

```
pad a matrix
```

## Usage

```
padmat(x, n, m, what = 0)
```

palGPR

Plot single colour palette

# Description

```
source: vignette of the R-package "colorspace" (Color Space Manipulation) Colour palette
```

#### Usage

```
palGPR(colPal = "default", n = 101, power = 1, returnNames = FALSE)
plotPal(col, border = NA)
displayPalGPR()
```

# **Examples**

```
plotPal(palGPR("hcl_5"))
displayPalGPR()
```

papply

Apply processing to GPRsurvey object

## Description

Apply processing to GPRsurvey object

```
## S4 method for signature 'GPRsurvey'
papply(x, prc = NULL)
```

phaseRotation 35

phaseRotation

Phase rotation shift the phase of signal by phi (in radian)

## Description

Phase rotation shift the phase of signal by phi (in radian)

## Usage

```
phaseRotation(x, phi)
```

plot

Plot the GPR object.

## **Description**

If the GPR object consists of a single trace, wiggle plot is shown. Plot GPR suvey lines

## Usage

```
## S3 method for class 'GPR'
plot(x, y, ...)
## S3 method for class 'GPRsurvey'
plot(x, y, ...)
```

plot3DRGL

Three-dimensional plot of the GPR data with Open-GL

## Description

Three-dimensional plot of the GPR data with Open-GL

```
## S4 method for signature 'GPR'
plot3DRGL(x, addTopo = FALSE, clip = NULL,
    normalize = NULL, nupspl = NULL, add = TRUE, xlim = NULL,
    ylim = NULL, zlim = NULL, ...)
```

36 plotRaster

p]	0	+ 4	١m	n	1
P	LU	L,	7111	ν	_

Plot the trace amplitude

#### Description

Plot the amplitude estimated over the whole GPR data as a function of time/depth.

## Usage

```
## S4 method for signature 'GPR'
plotAmpl(x, FUN = mean, add = FALSE, all = FALSE,
    plotLog = TRUE, ...)
```

## **Arguments**

х	An object of the class GPR.
FUN	A function to be applied on each row of the GPR data to estimate the wave amplitude as a function of time/depth.
add	A length-one boolean vector. If TRUE the amplitude is plotted on the previous plot. If FALSE (default) a new plot is created.
all	A length-one boolean vector. If TRUE the logarithm of the amplitude of every trace is ploted on the estimate amplitude. Default is FALSE. processing functions with their arguments applied previously on the GPR data.

## **Examples**

```
data(frenkeLine00)
plotAmpl(frenkeLine00, FUN = median)
```

plotRaster

Plot GPR as image (raster)

## **Description**

```
Plot GPR as image (raster)
```

```
plotRaster(z, x = NULL, y = NULL, main = "", xlim = NULL, note = NULL,
  ratio = 1, time_0 = 0, antsep = 1, v = 0.1, surveymode = NULL,
  addFid = TRUE, fid = NULL, ylim = NULL, addAnn = TRUE,
  annotations = NULL, depthunit = "ns", posunit = "m",
  rasterImage = TRUE, resfac = 1, clab = "mV", add = FALSE,
  barscale = TRUE, addGrid = FALSE, col = palGPR(n = 101), yaxt = "s",
  bty = "o", relTime0 = TRUE, clim = NULL, pdfName = NULL, ...)
```

plotTensor 37

plotTensor

Plot structure tensor on GPR data

## Description

Plot structure tensor on GPR data

#### Usage

```
plotTensor(x, 0, type = c("vectors", "ellipses"), normalise = FALSE,
   spacing = c(6, 4), len = 1.9, n = 10, ratio = 1, ...)
```

plotTensor0

Plot structure tensor on GPR data

## Description

Plot structure tensor on GPR data

#### Usage

```
plotTensor0(alpha, 11, 12, x, y, col = NULL, type = c("vectors",
  "ellipses"), normalise = FALSE, spacing = c(6, 4), len = 1.9, n = 10,
  ratio = 1, ...)
```

points

Add a GPR trace points on a plot

# Description

Add a GPR trace points on a plot

```
## S3 method for class 'GPR'
points(x, ...)
```

38 posunit

pos

Position of the GPR traces

## Description

Position of the GPR traces

## Usage

```
## S4 method for signature 'GPR'
pos(x)
## S4 replacement method for signature 'GPR'
pos(x) <- value</pre>
```

posLine

Position on a multiline

# Description

Position on a multiline

#### Usage

```
posLine(loc, last = FALSE)
```

posunit

Position unit of the GPR data

# Description

Position unit of the GPR data

```
## S4 method for signature 'GPR'
posunit(x)
## S4 replacement method for signature 'GPR'
posunit(x) <- value</pre>
```

print 39

print

Print GPR

## Description

```
Print GPR
Identical to print().
Print GPR survey
Identical to print().
```

#### Usage

```
## S3 method for class 'GPR'
print(x, ...)

## S4 method for signature 'GPR'
show(object)

## S3 method for class 'GPRsurvey'
print(x, ...)

## S4 method for signature 'GPRsurvey'
show(object)
```

proc

Processing steps applied to the data

#### Description

```
processing returns all the processing steps applied to the data.
Add a processing step
```

## Usage

```
## S4 method for signature 'GPR'
proc(x)
## S4 replacement method for signature 'GPR'
proc(x) <- value</pre>
```

#### **Arguments**

(

An object of the class GPR.

40 readFID

#### Value

A character vector whose elements contain the name of the processing functions with their arguments applied previously on the GPR data.

#### **Examples**

```
data(frenkeLine00)
A <- dewow(frenkeLine00, type = "Gaussian")
proc(A)</pre>
```

processing

DEPRECATED - Processing steps applied to the data

#### **Description**

DEPRECATED - use proc instead! processing returns all the processing steps applied to the data.

#### Usage

```
## S4 method for signature 'GPR'
processing(x)
```

#### **Arguments**

Χ

An object of the class GPR.

#### Value

A character vector whose elements contain the name of the processing functions with their arguments applied previously on the GPR data.

# **Examples**

```
data(frenkeLine00)
A <- dewow(frenkeLine00, type = "Gaussian")
processing(A)</pre>
```

readFID

read fiducial marker files

#### **Description**

read fiducial marker files

```
readFID(FID, sep = ",")
```

readGPR 41

readGPR

Read a GPR data file

#### **Description**

Read a GPR data file

#### Usage

```
## S4 method for signature 'character'
readGPR(fPath, desc = "")
```

## Arguments

fPath Filepath (character).

desc Short description of the file (character).

coordfile Filepath of a text file containing the coordinates (x,y,z) of each traces.

crs Coordinate reference system (character)

intfile Filepath of a text file containing the intersection.

#### Value

The GPR data as object of the class RGPR.

# **Examples**

NULL

readTopo	read topo file
readiobo	reaa topo jite

## Description

read topo file

```
readTopo(TOPO, sep = ",")
```

42 repmat

regInterpPos

Trace interpolation at regularly spaced positions

# Description

Trace interpolation at regularly spaced positions

#### Usage

```
## S4 method for signature 'GPR'
regInterpPos(x, type = c("linear", "cosine"), dx = NULL)
```

relPos

Relative trace position on the GPR profile.

#### **Description**

Relative trace position on the GPR profile.

#### Usage

```
## S4 method for signature 'GPR'
relPos(x)
```

repmat

Repeat matrix

#### **Description**

Repeat a matrix row-wise n times and column-wise m times.

# Usage

```
repmat(A, n, m)
```

#### **Details**

Source A replication of MatLab repmat function! R FOR OCTAVE USERS version 0.4, Copyright (C) 2001 Robin Hankin http://cran.r-project.org/doc/contrib/R-and-octave.txt

reverse 43

reverse

Reverse the trace position.

## Description

Reverse the trace position.

Reverse the trace position.

## Usage

```
## S4 method for signature 'GPR'
reverse(x, id = NULL, tol = 0.3)
## S4 method for signature 'GPRsurvey'
reverse(x, id = NULL, tol = 0.3)
```

rotatePhase

Phase rotation

## Description

Rotate the phase of the GPR data by a given angle phi.

# Usage

```
## S4 method for signature 'GPR'
rotatePhase(x, phi)
```

# Arguments

x A GPR data

phi A length-one numeric vector defining the phase rotation in radian.

#### Value

The GPR data with rotated phase.

spec spec

shiftEst

Shift estimation between two GPR profiles.

#### **Description**

Shift estimation between two GPR profiles.

#### Usage

```
## S4 method for signature 'GPR'
shiftEst(x, y = NULL, method = c("phase", "WSSD"),
    dxy = NULL, ...)
```

shiftmat

shift a matrix by n and m shift a matrix by n and m

## Description

```
shift a matrix by n and m shift a matrix by n and m
```

## Usage

```
shiftmat(x, n, m)
```

spec

Return the amplitude spectrum of the GPR object.

# Description

Return the amplitude spectrum of the GPR object.

```
## S4 method for signature 'GPR'
spec(x, type = c("f-x", "f-k"), plotSpec = TRUE,
   unwrapPhase = TRUE, ...)
```

strTensor 45

strTensor

Structure tensor field of GPR data

#### **Description**

Structure tensor field of GPR data

surveyIntersect

Compute the survey intersections

#### **Description**

Compute the survey intersections

#### Usage

```
## S4 method for signature 'GPRsurvey'
surveyIntersect(x)
```

svDate

Survey date

#### **Description**

Return NULL if no date exists, else an object of the class 'Date'

# Usage

```
## S4 method for signature 'GPR'
svDate(x)
## S4 replacement method for signature 'GPR'
svDate(x) <- value</pre>
```

#### **Arguments**

x An object of the class 'GPR'value An object of the class 'Date'

46 time0Cor

time0

'time-zero' of every traces

#### **Description**

time0 returns the 'time-zero' of every traces. Generally, 'time-zero' corresponds to the first wave arrival (also called first wave break).

#### Usage

```
## S4 method for signature 'GPR'
time0(x)
## S4 replacement method for signature 'GPR'
time0(x) <- value</pre>
```

#### **Arguments**

Χ

An object of the class GPR.

#### Value

A vector containing the time-zero values of each traces.

#### See Also

firstBreak to estimate the first wave break.

#### **Examples**

```
data(frenkeLine00)
time0(frenkeLine00)
```

time0Cor

Time zero correction

#### **Description**

time@Cor shift the traces vertically such that they start at time zero (time zero of the data can be modified with the function)

```
## S4 method for signature 'GPR'
time0Cor(x, t0 = NULL, method = c("spline", "linear",
   "nearest", "pchip", "cubic", "none"), crop = TRUE, keep = 0)
```

timeToDepth 47

#### **Arguments**

X	A object of the class GPR
t0	A numeric vector with length equal either to NULL, or one or to the number traces. The traces will be shifted to $t0$ . If $t0 = NULL$ 'time $O(x)$ ' will be used instead. If $t0$ is the time-zero, set keep = $0$ .
method	A length-one character vector defining the interpolation method that are from the function 'interp1' from the 'signal' package.
crop	If TRUE (defaults), remove the rows containing only zero's (no data).
keep	A length-one numeric vector indicating in time units how much of the trace has to be kept before time zero.
с0	Propagation speed of the GPR wave through air (used only when keep = NULL).

#### **Details**

When keep = NULL the amount of time kept is equal to time taken by the air wave to travel from the transmitter to the receiver.

#### Value

An object of the class GPR.

#### See Also

time0 to set time zero and firstBreak to estimate the first wave break. firstBreakToTime0 to convert the first wave break into time zero.

#### **Examples**

```
data(frenkeLine00)
tfb <- firstBreak(frenkeLine00)
t0 <- firstBreakToTime0(tfb, frenkeLine00, c0 = 0.299)
time0(frenkeLine00) <- t0
frenkeLine00_2 <- time0Cor(frenkeLine00, method = "pchip")</pre>
```

 ${\tt timeToDepth}$ 

time to depth conversion

#### **Description**

time to depth conversion

```
timeToDepth(tt, time_0, v = 0.1, antsep = 1, c0 = 0.299)
```

48 traceAverage

traceAverage

Trace average

#### **Description**

Compute the average trace of a radargram (resulting in a single trace) or a moving average of the traces.

#### Usage

```
## S4 method for signature 'GPR'
traceAverage(x, w = NULL, FUN = mean, ...)
```

## Arguments

X	An object of the class GPR
W	A length-one integer vector equal to the window length of the average window. If $w = NULL$ a single trace corresponding to the average trace of the whole profile is returned.
FUN	A function to compute the average (default is mean)
	Additional parameters for the FUN functions

#### Value

An object of the class GPR. When w = NULL, this function returns a GPR object with a single trace corresponding to the average trace of the whole radargram. When w is equal to a strictly positive interger this function returns a GPR object with a size identical to x where each trace corresponds to the average of the w neighbouring traces centered on the considered trace.

## **Examples**

```
data("frenkeLine00")

f0 <- frenkeLine00

f1 <- traceAverage(f0)
plot(f1)
# substract the average trace
plot(f0 - f1)

f2 <- traceAverage(f0, w = 20)
plot(f2)
plot(f0 - f2)

f3 <- traceAverage(f0, w = 20, FUN = median)
plot(f3)
plot(f0 - f3)</pre>
```

traceScaling 49

traceScaling	Trace scaling

#### Description

Trace scaling

#### Usage

```
## S4 method for signature 'GPR'
traceScaling(x, type = c("stat", "min-max", "95", "eq", "sum",
    "rms", "mad", "invNormal"))
```

traceShift

Shift vertically the traces by an amount of depth units.

#### **Description**

Shift vertically the traces by an amount of depth units.

#### Usage

```
## S4 method for signature 'GPR'
traceShift(x, ts, method = c("spline", "linear", "nearest",
    "pchip", "cubic", "none"), crop = TRUE)
```

## Arguments

x A object of the class GPR

ts A numeric vector defining the amount of depth the traces have to shifted

method A length-one character vector indicating the interpolation method. "none" means that the trace is shifted by the amount of points that is the closest to amount of depth ts.

crop If TRUE (defaults), remove the rows containing only zero's (no data).,

#### Value

An object of the class GPR.

#### See Also

time@Cor to shift the traces such that they start at time zero.

50 trRmDuplicates

trAmplCor

Gain compensation

#### **Description**

Gain compensation

#### Usage

```
## S4 method for signature 'GPRsurvey'
trAmplCor(x, type = c("power", "exp", "agc"), ...)
```

trimStr

Trim string

#### Description

returns string w/o leading or trailing whitespace

#### Usage

```
trimStr(x)
```

trRmDuplicates

Remove traces with duplicated trace positions

#### **Description**

checks for duplicates trace positions (up to precision defined by 'tol') and remove them from 'x' (object of the class GPR or GPRsurvey). If there is a series of consecutive traces with an interdistance smaller than the tolerance threshold defined by the computer precision, the function starts by removing traces every two traces and repeat the procedure until the trace inter-distances are larger that the threshold. Example with 5 traces:

- distance between trace 1 and 2 < tol
- distance between trace 2 and 3 < tol
- distance between trace 3 and 4 < tol
- distance between trace 4 and 5 < tol

The algorithm first remove trace 2 and 4 and recompute the inter-trace distances:

- distance between trace 1 and 3 < tol
- distance between trace 3 and 5 > tol

The algorithm remove trace 3. END!

trTime 51

#### Usage

```
## S4 method for signature 'GPR'
trRmDuplicates(x, tol = NULL)
```

#### **Arguments**

x An object of the class GPR

tol Length-one numeric vector: if the horizontal distance between two consecutive

traces is smaller than tol, then the second trace is removed. If tol  $\,=\,$  NULL, tol

is set equal to sqrt(.Machine\$double.eps).

trTime

Time of data collection for each trace

# Description

Time of data collection for each trace

upsample

*Up-sample the GPR data (1D and 2D sinc-interpolation)* 

#### **Description**

Up-sample the GPR data (1D and 2D sinc-interpolation)

## Usage

```
## S4 method for signature 'GPR'
upsample(x, n)
```

values

Values of the GPR data

# Description

Values of the GPR data

```
## S4 method for signature 'GPR'
values(x)

## S4 replacement method for signature 'GPR'
values(x) <- value</pre>
```

52 writeGPR

vel

Velocity model of the GPR data

## Description

Velocity model of the GPR data

## Usage

```
## S4 method for signature 'GPR'
vel(x)
## S4 replacement method for signature 'GPR'
vel(x) <- value</pre>
```

wapplyRow

Wapply on the row of a matrix (windowed)

#### Description

NOT CURRENTLY USED mod by MANU

#### Usage

```
wapplyRow(x = NULL, width = NULL, by = NULL, FUN = NULL, ...)
```

writeGPR

Write the GPR object in a file.

# Description

Write the GPR object in a file.

writeSurvey 53

writeSurvey

Write GPRsurvey object

## Description

Write GPRsurvey object

# Usage

```
## S4 method for signature 'GPRsurvey'
writeSurvey(x, fPath, overwrite = FALSE)
```

extract a GPR object from a GPR survey object

# Description

Return an object of class GPR

```
## S4 method for signature 'GPRsurvey, ANY, ANY'
x[[i, j, ...]]
## S4 replacement method for signature 'GPRsurvey, ANY, ANY'
x[[i]] <- value</pre>
```

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