

# CS2040S

## Data Structures and Algorithms

### Augmented Trees!

#### Puzzle of the Week: Prime Cubes

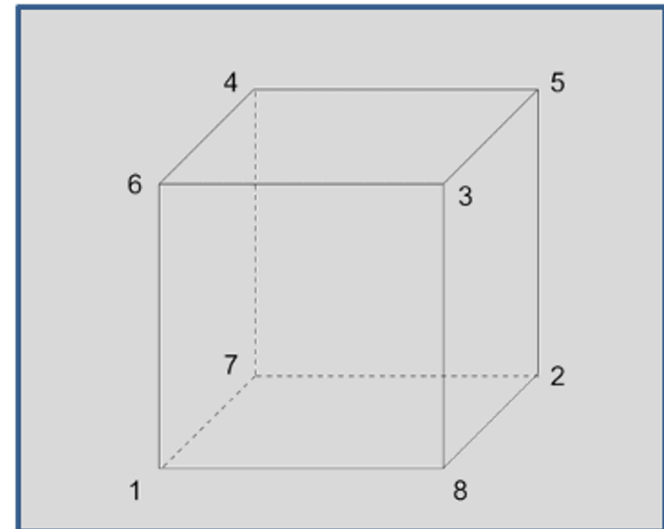
A cube has eight vertices.

Assign a prime number to each vertex.

A FaceSum is the sum of the four vertices on a face.

Can you find an assignment of prime numbers so that all six FaceSums are equal?

Example: all FaceSums = 18



# Where we are...

---

Dictionaries

Binary search trees

Tries

Balanced search trees

- AVL trees
- Scapegoat Trees
- B-trees

# Admin

---

## Coursemology Survey

- Anonymous
- Goal: to understand how things are going
- Goal: calibration
- Goal: feedback to TAs and tutors.
- Goal: feedback to me!

Appreciate constructive feedback!

Also appreciate some understanding when things haven't gone perfectly.  
Remember, the tutors are *also* students with problem sets, midterms, etc.

# Midterm

---

Thurs. March 10 6:30pm

- Location: MPSH
- < 50 students / rooms TBA
- 13+ rooms

Bring to quiz:

- One double-sided sheet of paper with any notes you like.
- Pens/pencils.
- You may not use anything else. (No calculators, no phones, etc.)



# Midterm

---

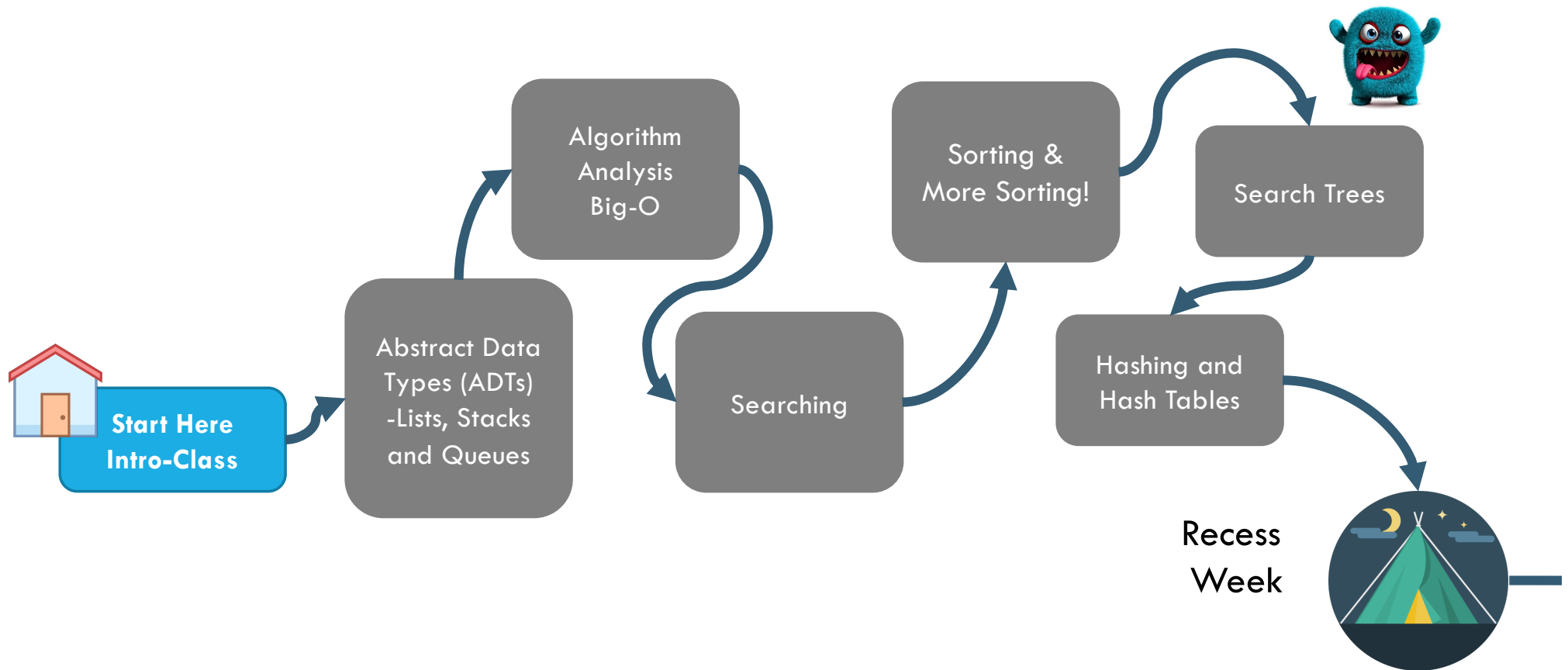
Midterm covers everything through the end of this week.

## Practice Material:

- Posted on Coursemology
- Beware previous years were not necessarily the same as this year.



# What have we done so far?



## Part I: Organizing your Data

Range trees

Interval trees

Order statistics

AVL

B-trees

Binary Search

SelectionSort

So much material?

BubbleSort

InsertionSort

PancakeSort

QuickSelect

ReversalSort

MergeSort

QuickSort

BogoSort

Binary tree

CardFlipTrees

Tries

Hash table

Random Permutations

Range trees

Interval trees

Order statistics

AVL

B-trees

Binary Search

SelectionSort

Three Parts

BubbleSort

InsertionSort

QuickSelect

1) Basic Theory / Algorithm Analysis

2) Major Algorithms

3) Overarching Principles

Steepest descent

Random Permutations



# Basic Theory: Key Topics



- Asymptotic notation (big-O, etc.)
- Simple recurrences
- Asymptotic analysis
- Basic probability (e.g., CS1231 review)

# Key Algorithms

- Binary Search
- Sorting
- Balanced binary trees
- Augmented trees
- Hash table (introduction, Wednesday)



# Key Ideas



- Basic strategies for solving problems
- Invariants
- Trade-offs: how to choose which data structure
- Augmenting data structures

# Basic strategies for solving problems

---

Try something simple

E.g., naïve search

Reduce-and-conquer

E.g., binary search

Divide-and-conquer

E.g., MergeSort

Maintaining an invariant

E.g., AVL trees

E.g., keep your data sorted

Augment an existing data structure

E.g., AVL trees

## Two important questions:

How do you understand what an algorithm is doing?

How do you show that an algorithm is correct?

## To understand algorithms:

For every algorithm in the class, identify all of its important invariants.

Range trees

Interval trees

Order statistics

AVL

B-trees

Binary Search

SelectionSort

BubbleSort

InsertionSort

Three Parts

1) Basic Theory / Algorithm Analysis

2) Major Algorithms

3) Overarching Principles

Permutations

# Midterm

---

Thurs. March 10 6:30pm

- Location TBA (MPSH)
- < 50 students / room
- 13+ rooms

Bring to quiz:

- One double-sided sheet of paper with any notes you like.
- Pens/pencils.
- You may not use anything else. (No calculators, no phones, etc.)



# Dynamic Data Structures

---

1. Maintain a set of items
2. Modify the set of items
3. Answer queries.

Big picture idea:

Trees are a good way to store, summarize, and search dynamic data.



# Dynamic Data Structures

---

- Operations that create a data structure
  - build (preprocess)
- Operations that modify the structure
  - insert
  - delete
- Query operations
  - search, select, etc.

# Augmented Data Structures

---

Many problems require storing additional data in a standard data structure.

Augment more frequently than invent...

# Plan

---

Three examples of augmenting balanced BSTs

1. Order Statistics
2. Interval Queries
3. Orthogonal Range Searching

# Augmenting data structures

---

## Basic methodology:

1. Choose underlying data structure  
(tree, hash table, linked list, stack, etc.)

# Augmenting data structures

---

## Basic methodology:

1. Choose underlying data structure  
(tree, hash table, linked list, stack, etc.)
2. Determine additional info needed.

# Augmenting data structures

---

## Basic methodology:

1. Choose underlying data structure  
(tree, hash table, linked list, stack, etc.)
2. Determine additional info needed.
3. Modify data structure to *maintain* additional info when the structure changes.  
(subject to insert/delete/etc.)

# Augmenting data structures

---

## Basic methodology:

1. Choose underlying data structure  
(tree, hash table, linked list, stack, etc.)
2. Determine additional info needed.
3. Modify data structure to *maintain* additional info when the structure changes.  
(subject to insert/delete/etc.)
4. Develop new operations.

# Plan

---

Three examples of augmenting balanced BSTs

1. ~~Order Statistics~~

2. Interval Queries

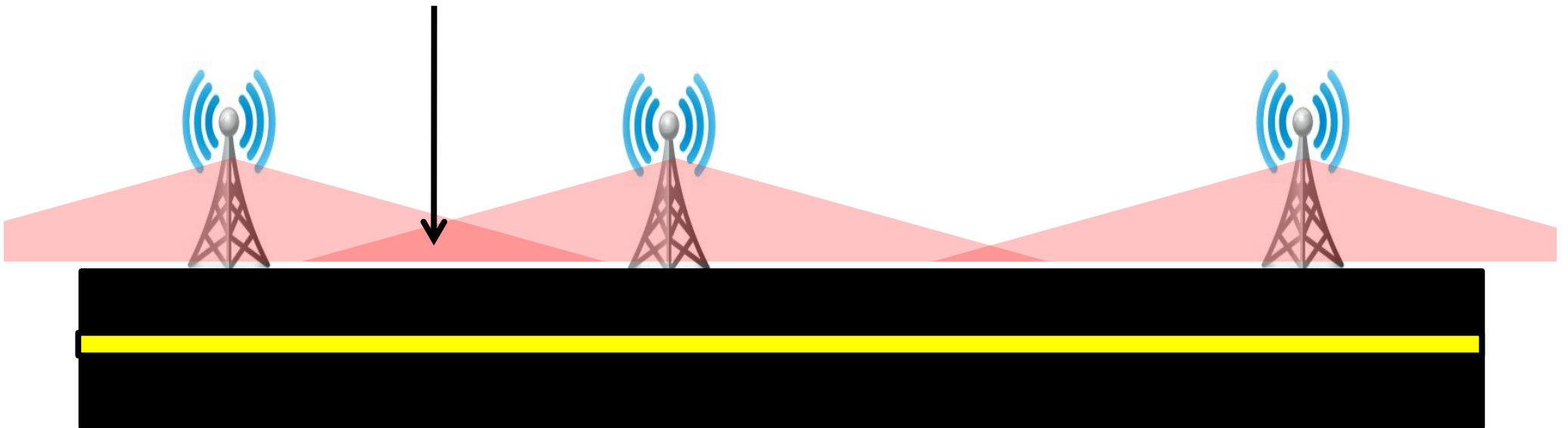
3. Orthogonal Range Searching



# Cell Tower Coverage

---

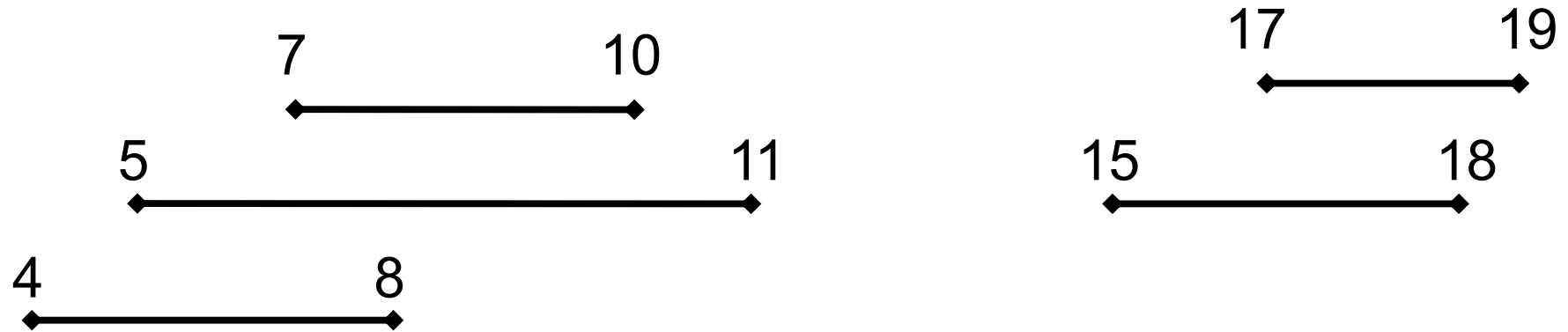
Find a tower that covers my location.



# Cell Tower Coverage

---

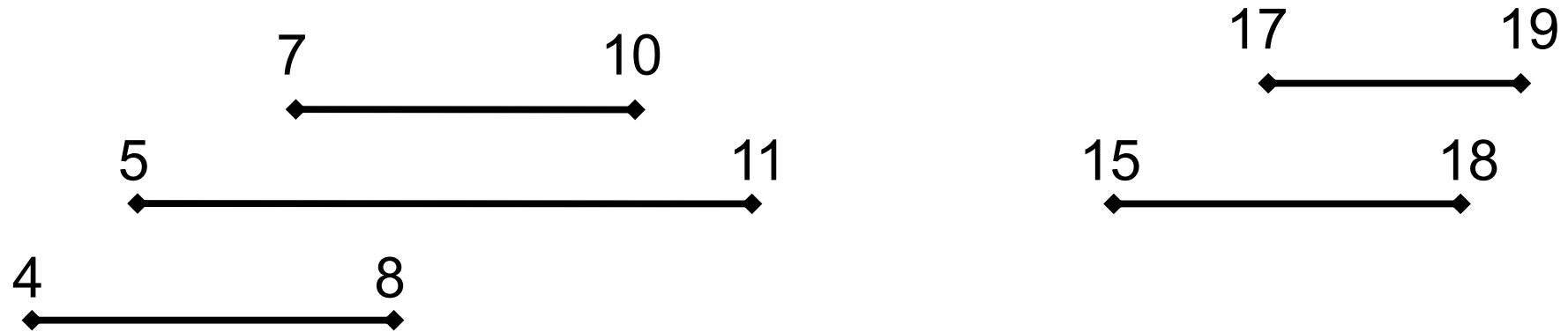
Find a tower that covers my location.



# Cell Tower Coverage

---

Dynamic data structure: supports new towers.

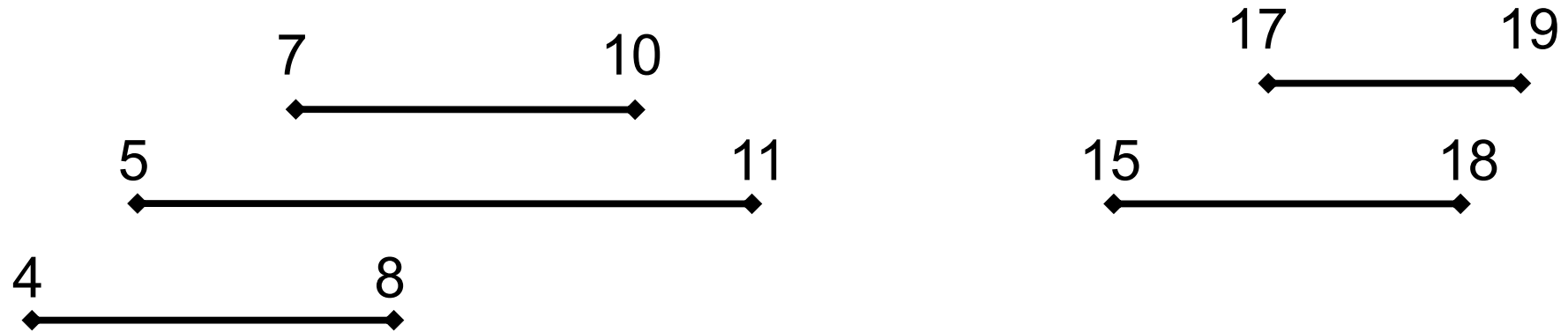


**insert(begin, end)**  
**delete(begin, end)**

# Cell Tower Coverage

---

Find a tower that covers my location.



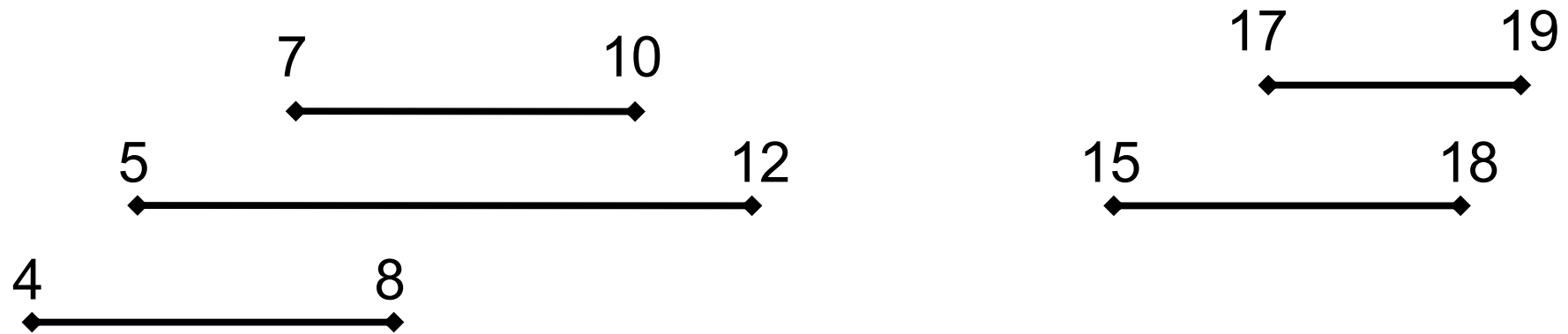
**insert(begin, end)**  
**delete(begin, end)**

**query(x): find an interval that overlaps x.**

# Cell Tower Coverage

---

Find a tower that covers my location.



**Idea 1:** Keep intervals in a list.  
Sort by minimum value in interval.  
Query: scan entire list.

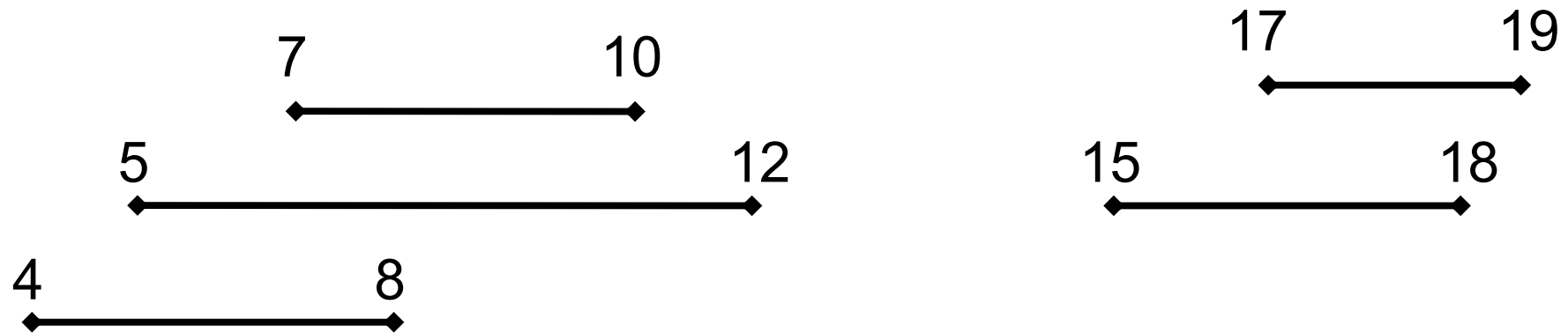
Does sorting help? Can we binary search?

# Cell Tower Coverage

---

Find a tower that covers my location.

example: query(11)



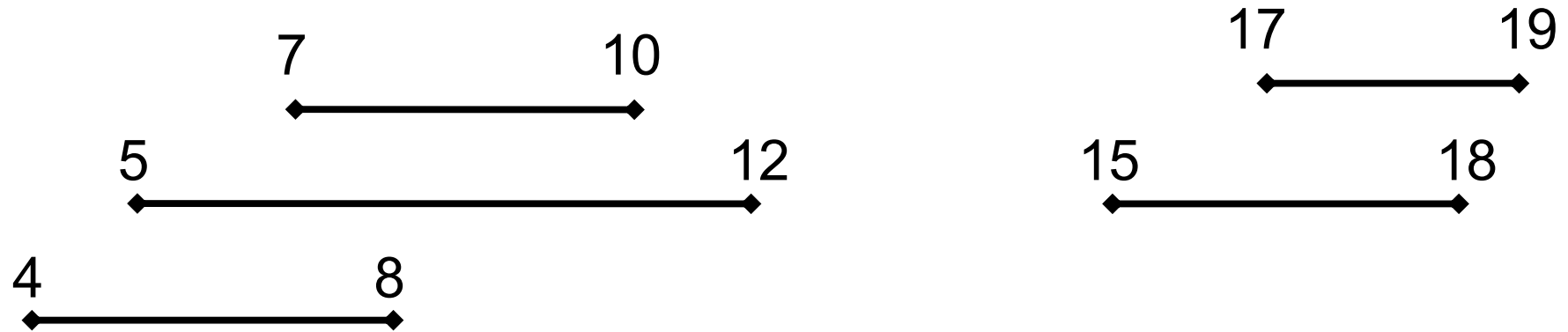
**Idea 1:** Keep intervals in a list.  
Sort by minimum value in interval.  
Query: scan entire list.

Does sorting help? Can we binary search?

# Cell Tower Coverage

---

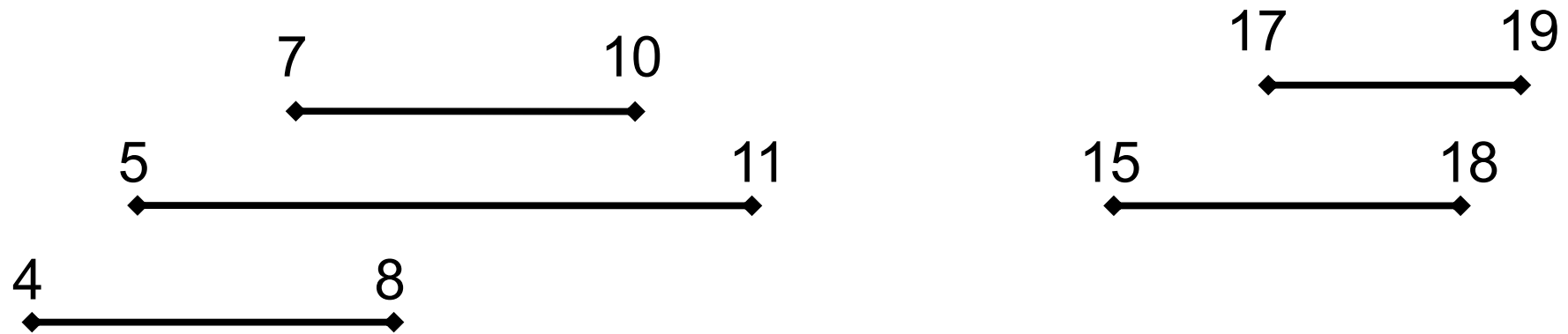
Find a tower that covers my location.



Idea 2:  $O(1)$  queries??

# Cell Tower Coverage

Find a tower that covers my location.



Idea 2:  $O(1)$  queries



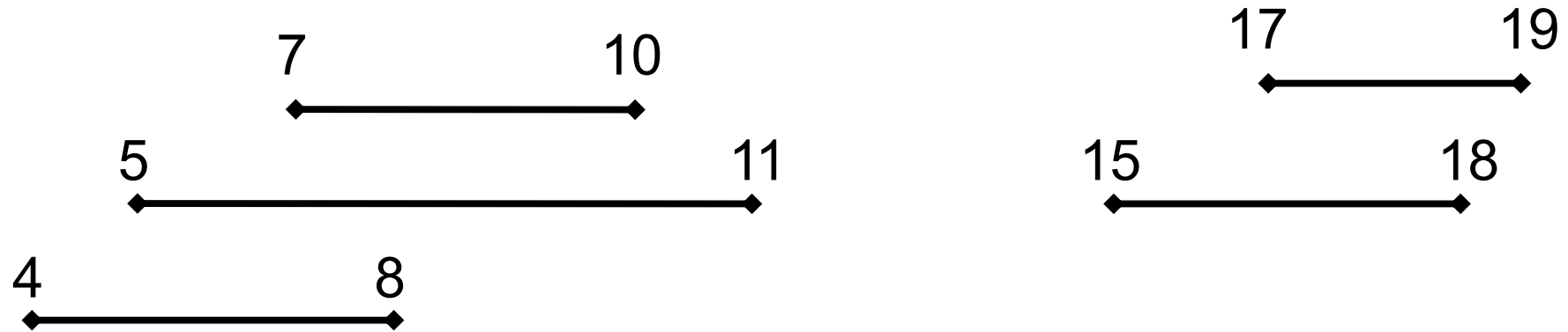
			A	A	A	A	A	B	B	C				D	D	D	D	E	
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20

Problems??



# Cell Tower Coverage

Find a tower that covers my location.



Idea 2:  $O(1)$  queries

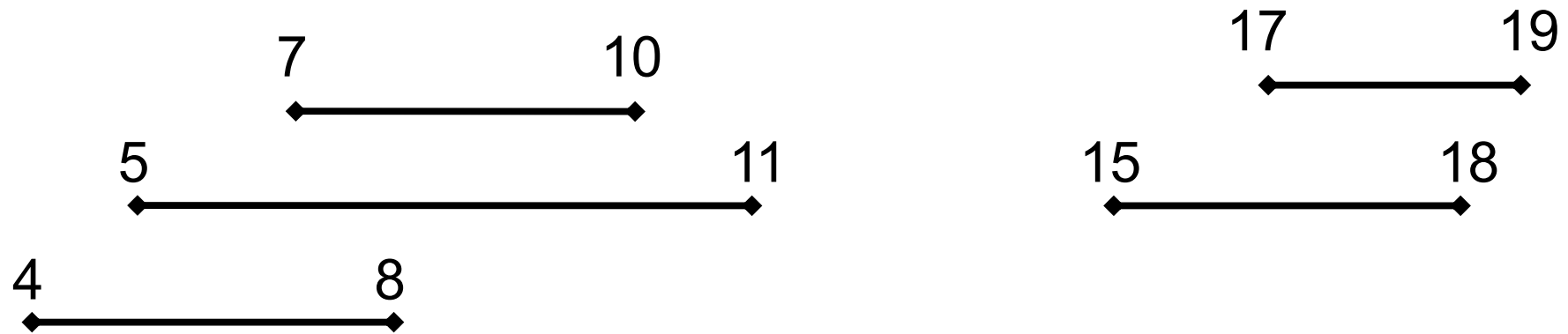
			<b>A</b>	<b>A</b>	<b>A</b>	<b>A</b>	<b>A</b>	<b>B</b>	<b>B</b>	<b>C</b>				<b>D</b>	<b>D</b>	<b>D</b>	<b>D</b>	<b>E</b>	
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20

Space usage, requires discrete integers, potentially expensive to update.

# Cell Tower Coverage

---

Find a tower that covers my location.



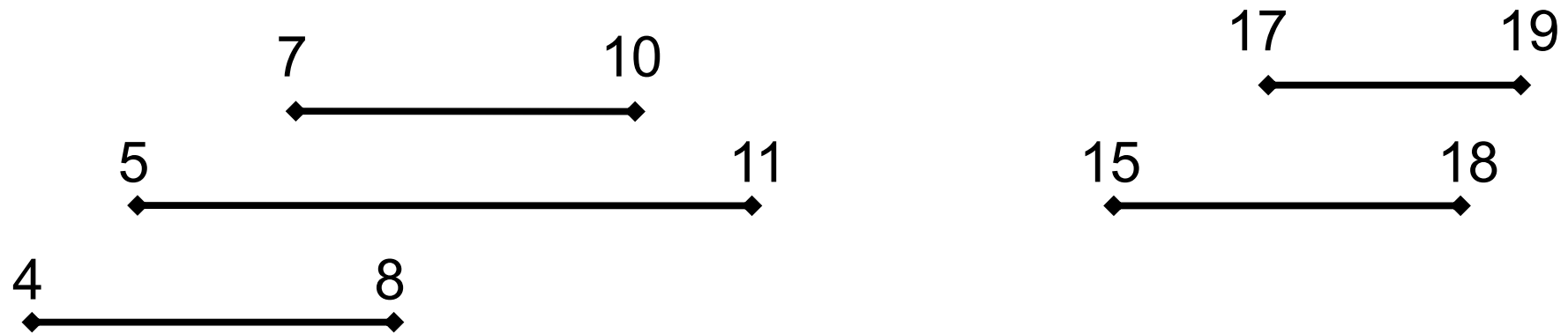
Not ideal solution:

- Space depends on the values stored.
- Time depends on the values stored.

# Cell Tower Coverage

---

Find a tower that covers my location.



Goal:

- Solutions where space is linear (or near linear) in the number of things stored (i.e., intervals).
- Operations are logarithmic in # of things stored.

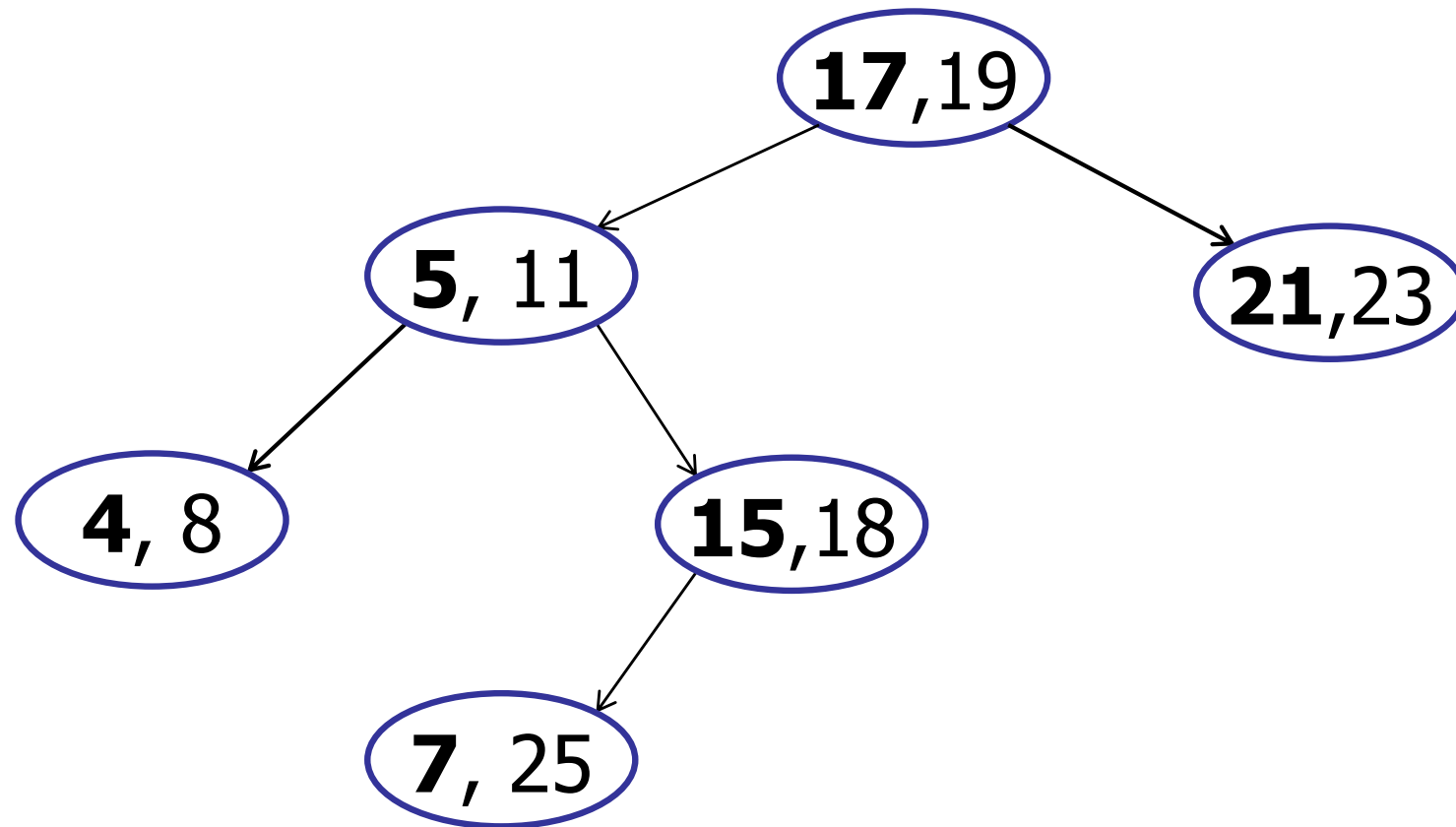
# Idea 3: Interval Trees

---

# Interval Trees

---

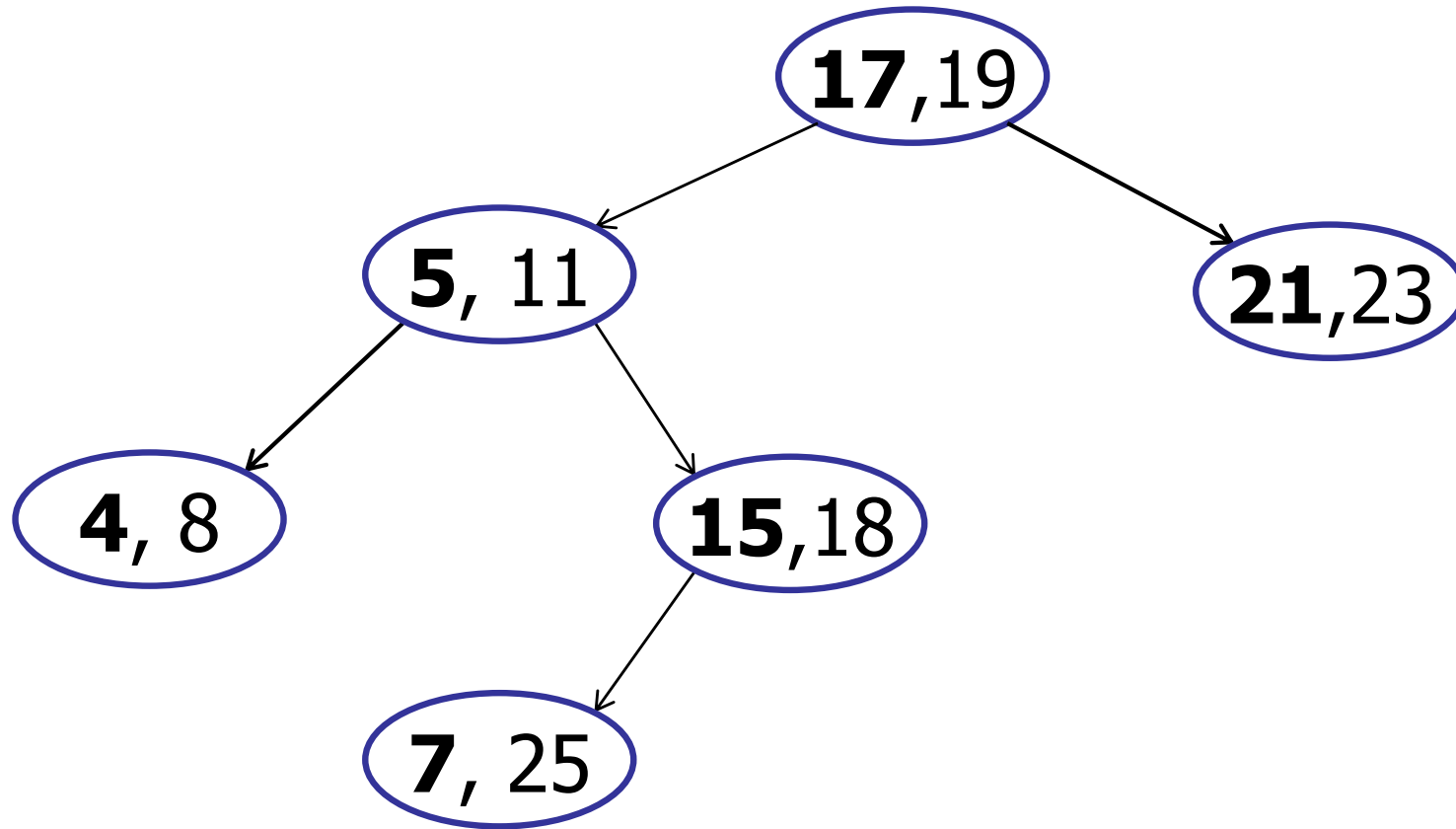
Each node is an interval



# Interval Trees

---

Sorted by left endpoint

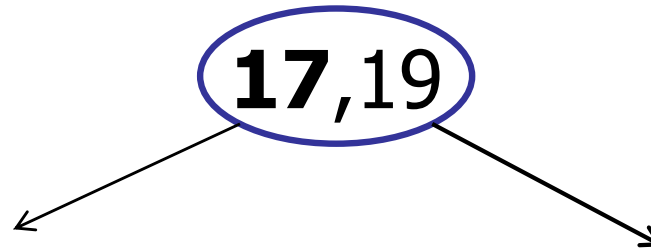


Important: always specify what your tree is sorted by!

# Interval Trees

---

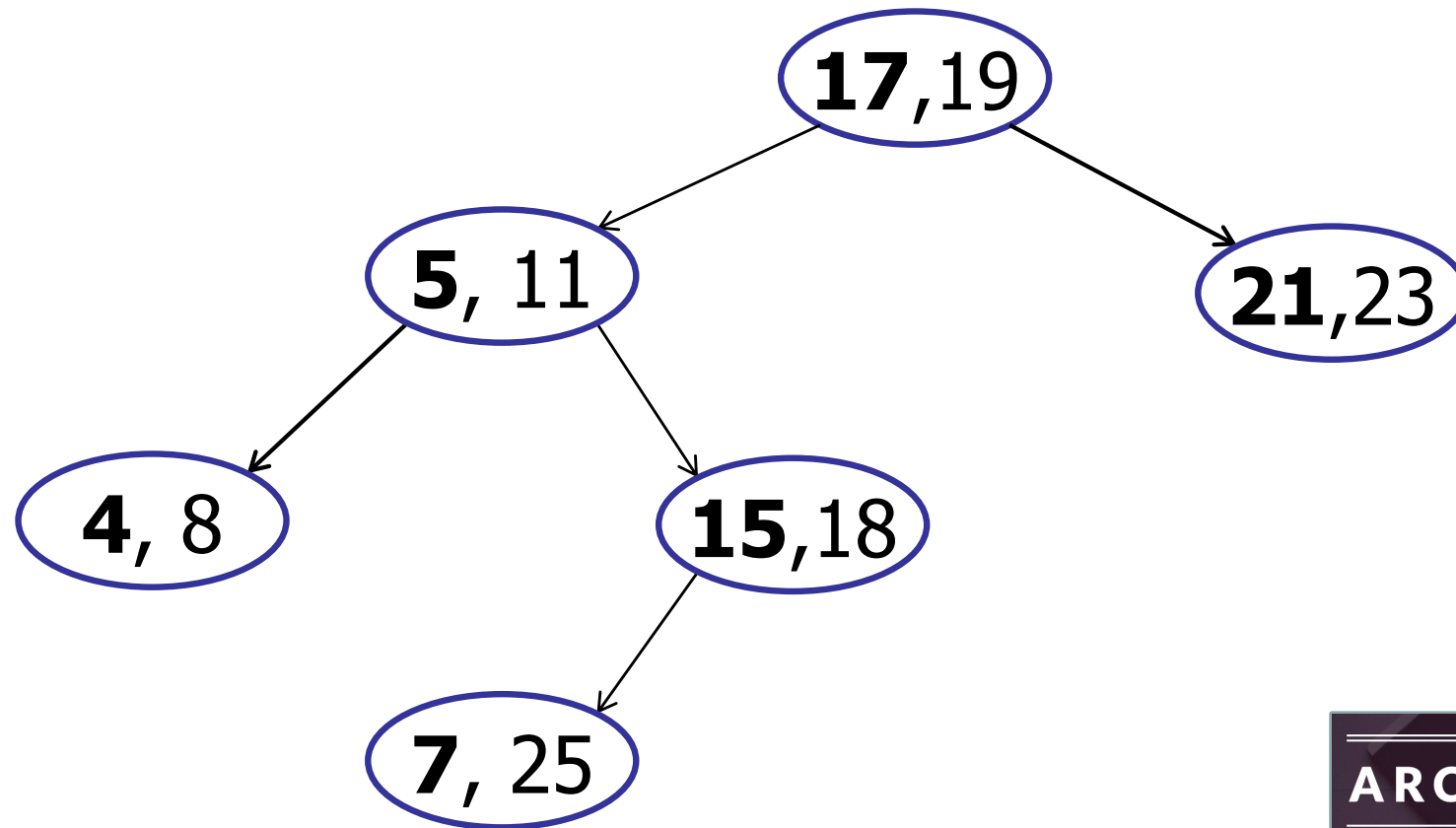
search-interval(25) = ?



# Interval Trees

---

Augment: ??



ARCHIPELAGO

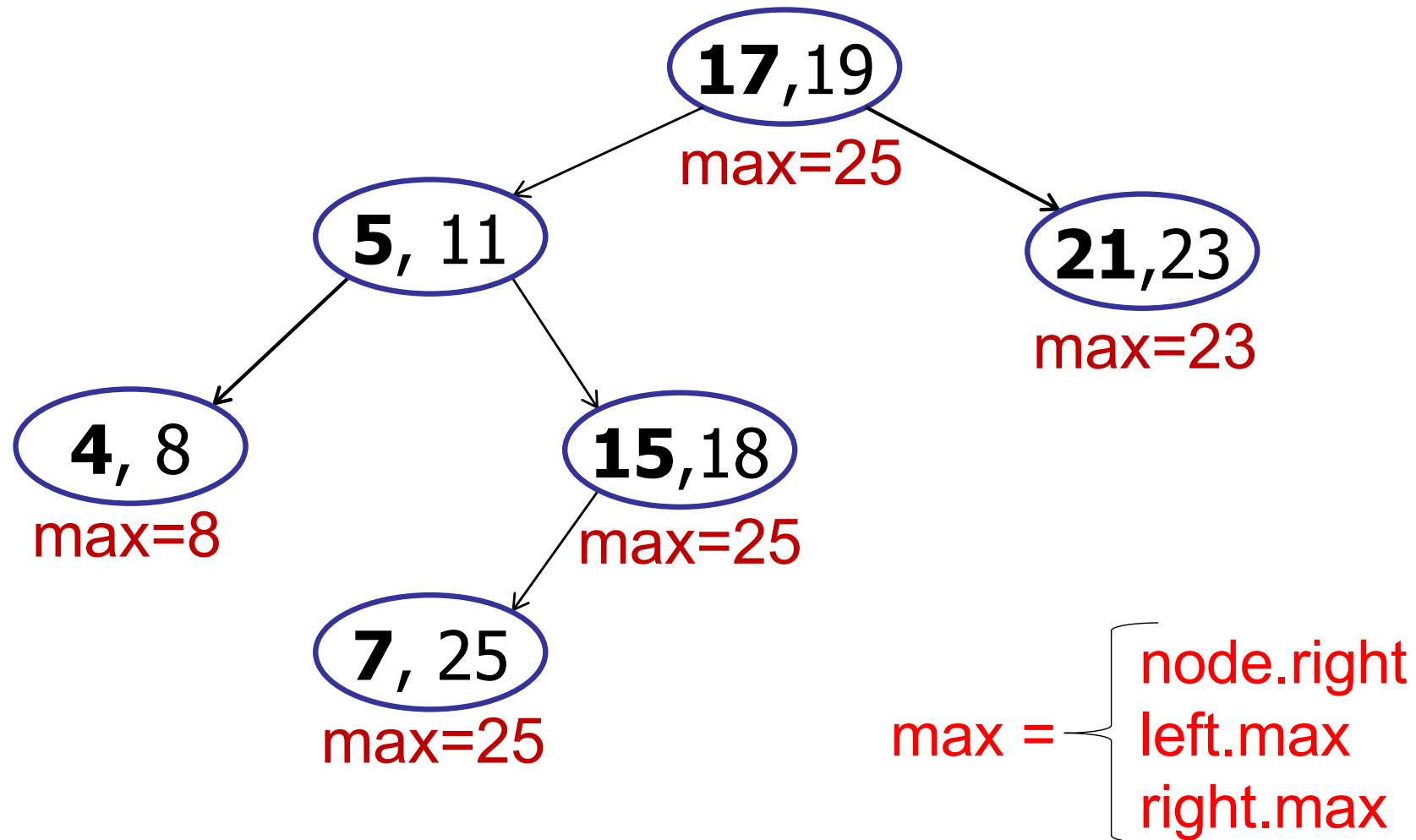
is open



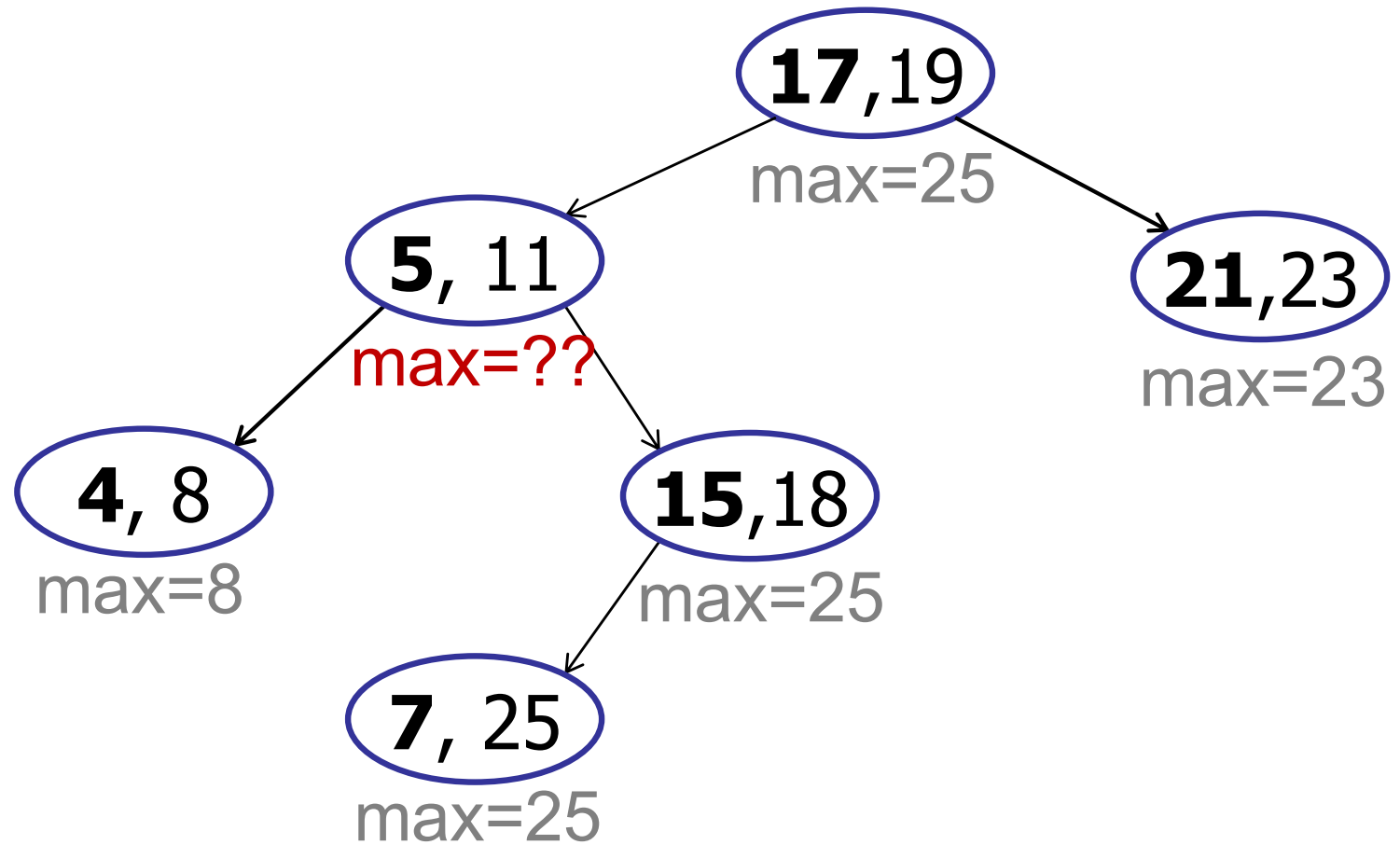
# Interval Trees

---

**Augment:** maximum endpoint in subtree



max=??



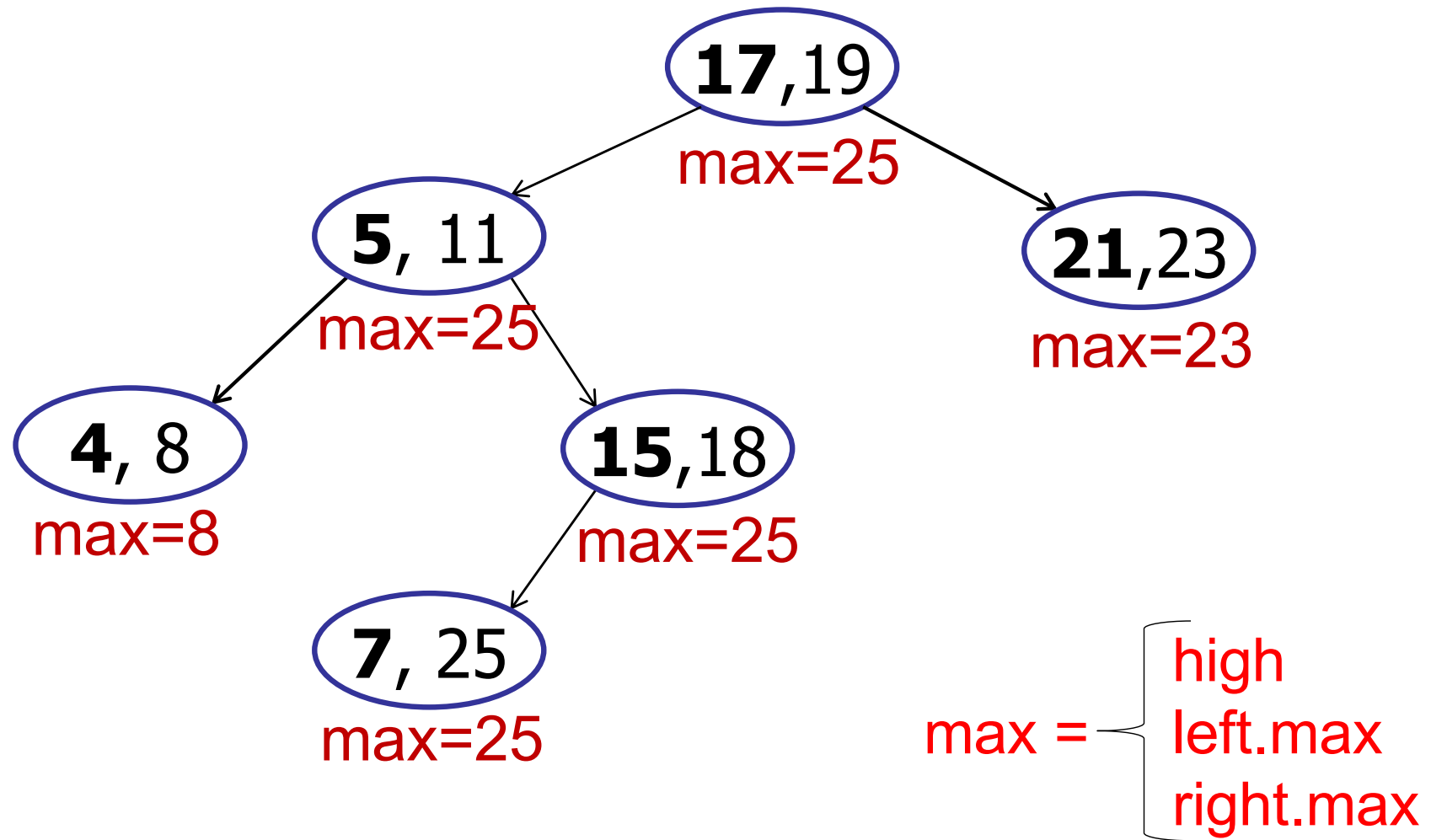
1. 5
2. 8
3. 11
4. 18
- ✓ 5. 25
6. 19



# Interval Trees

---

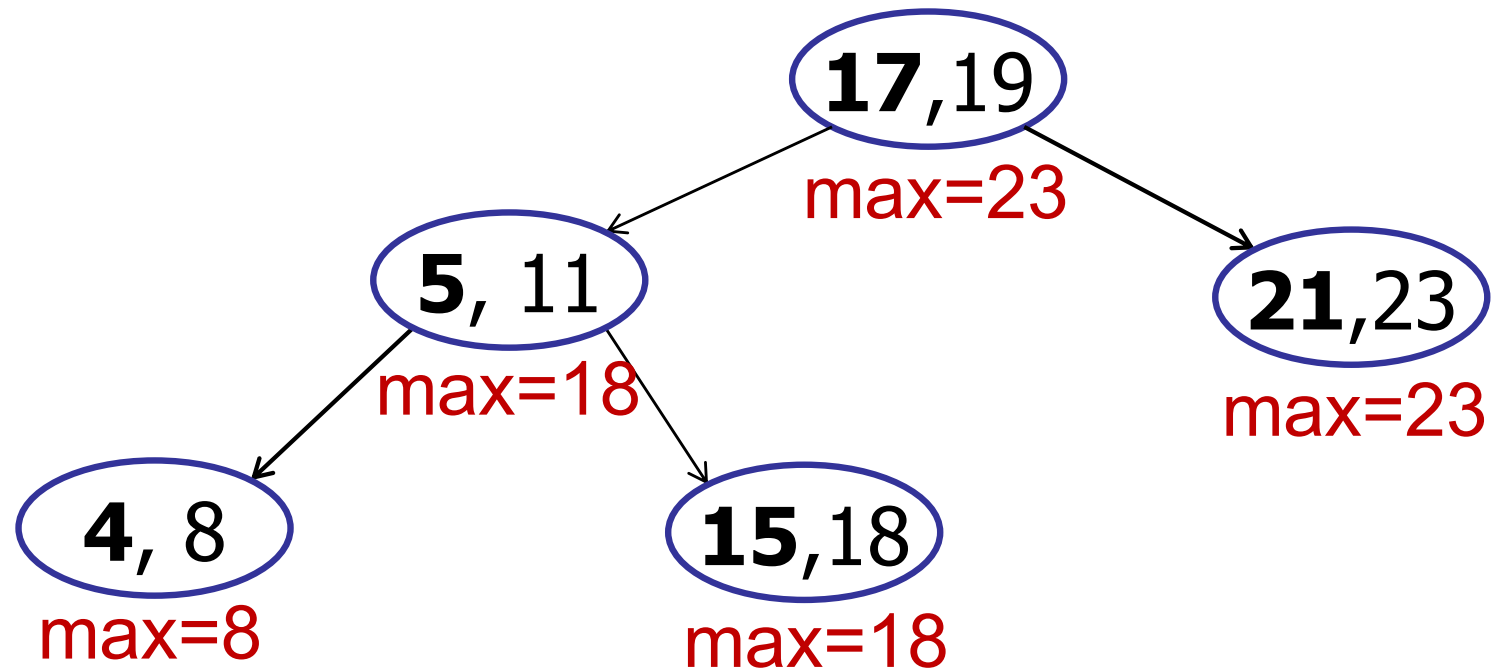
**Augment:** maximum endpoint in subtree



# Interval Trees

---

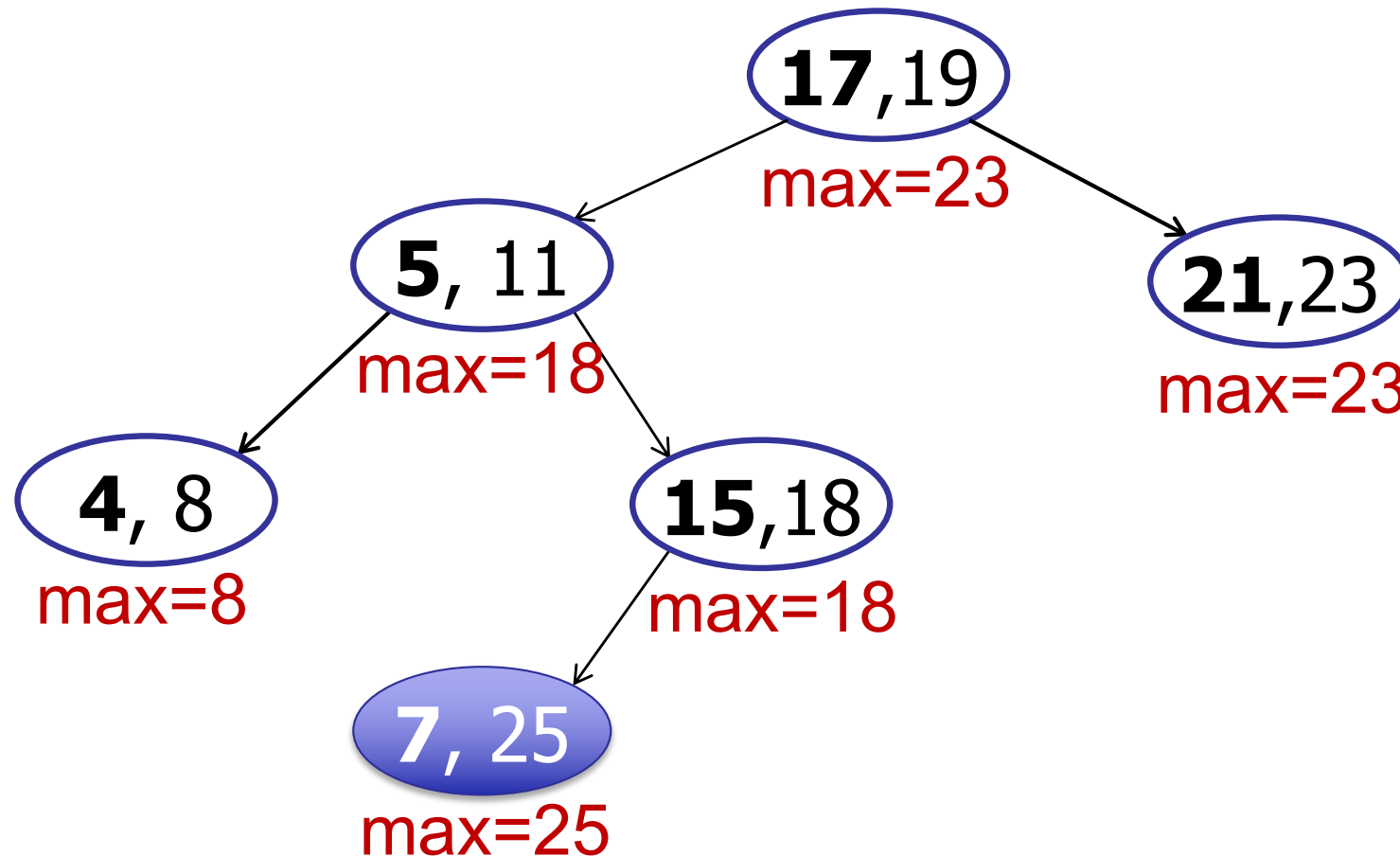
Insertion: *example* – **insert(7, 25)**



# Interval Trees

---

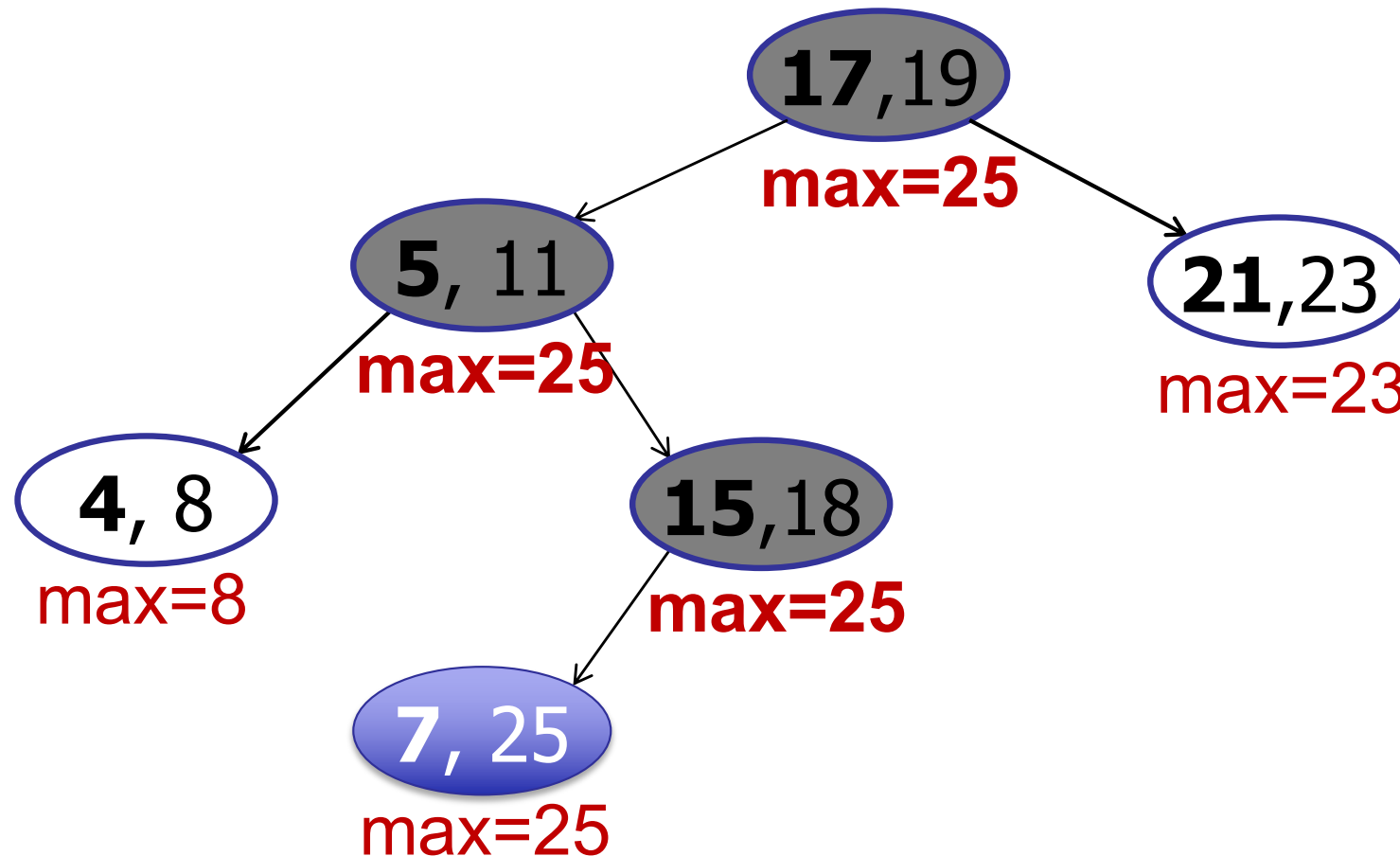
Insertion: *example* – **insert(7, 25)**



# Interval Trees

---

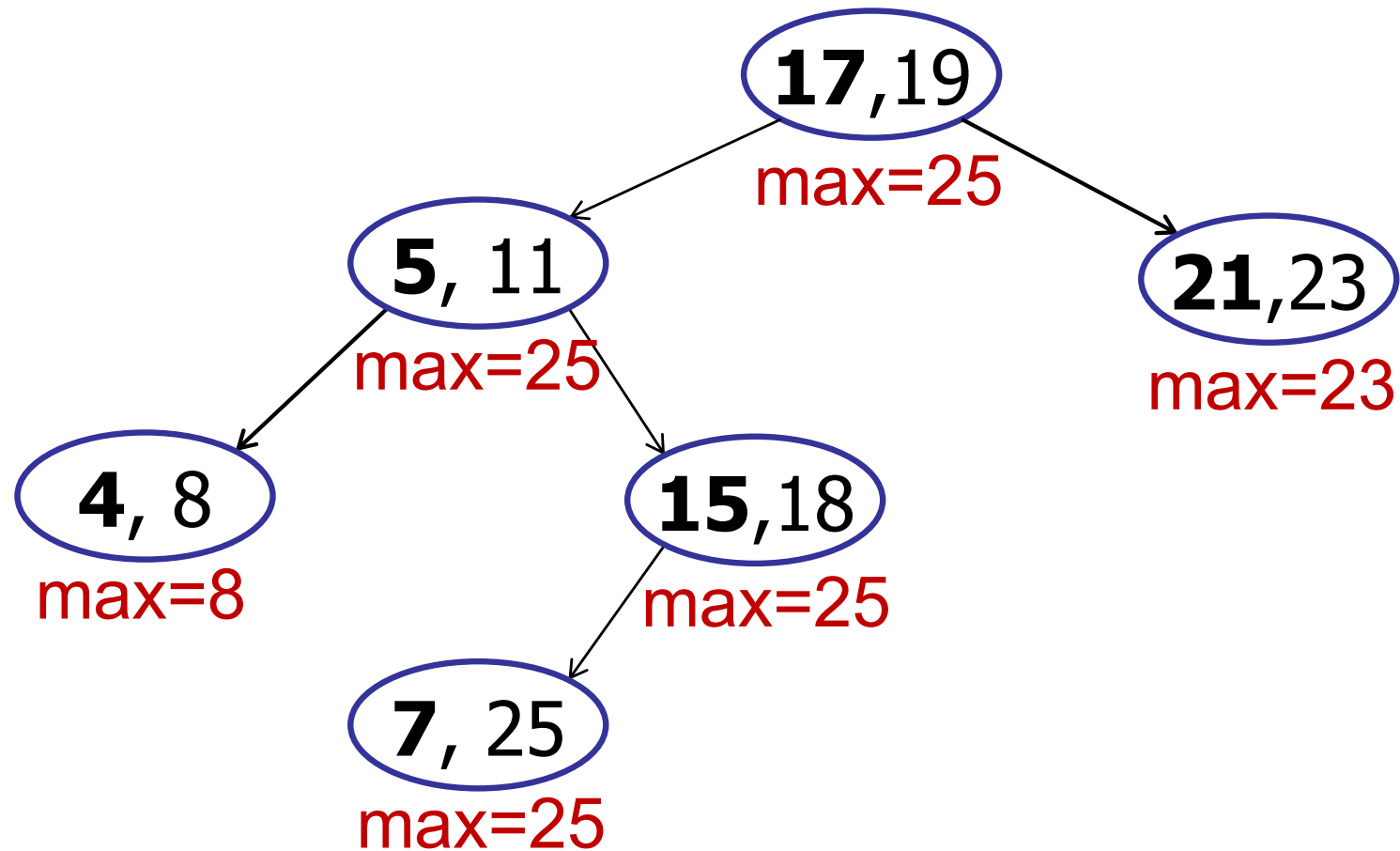
Insertion: *example* – **insert(7, 25)**



# Interval Trees

---

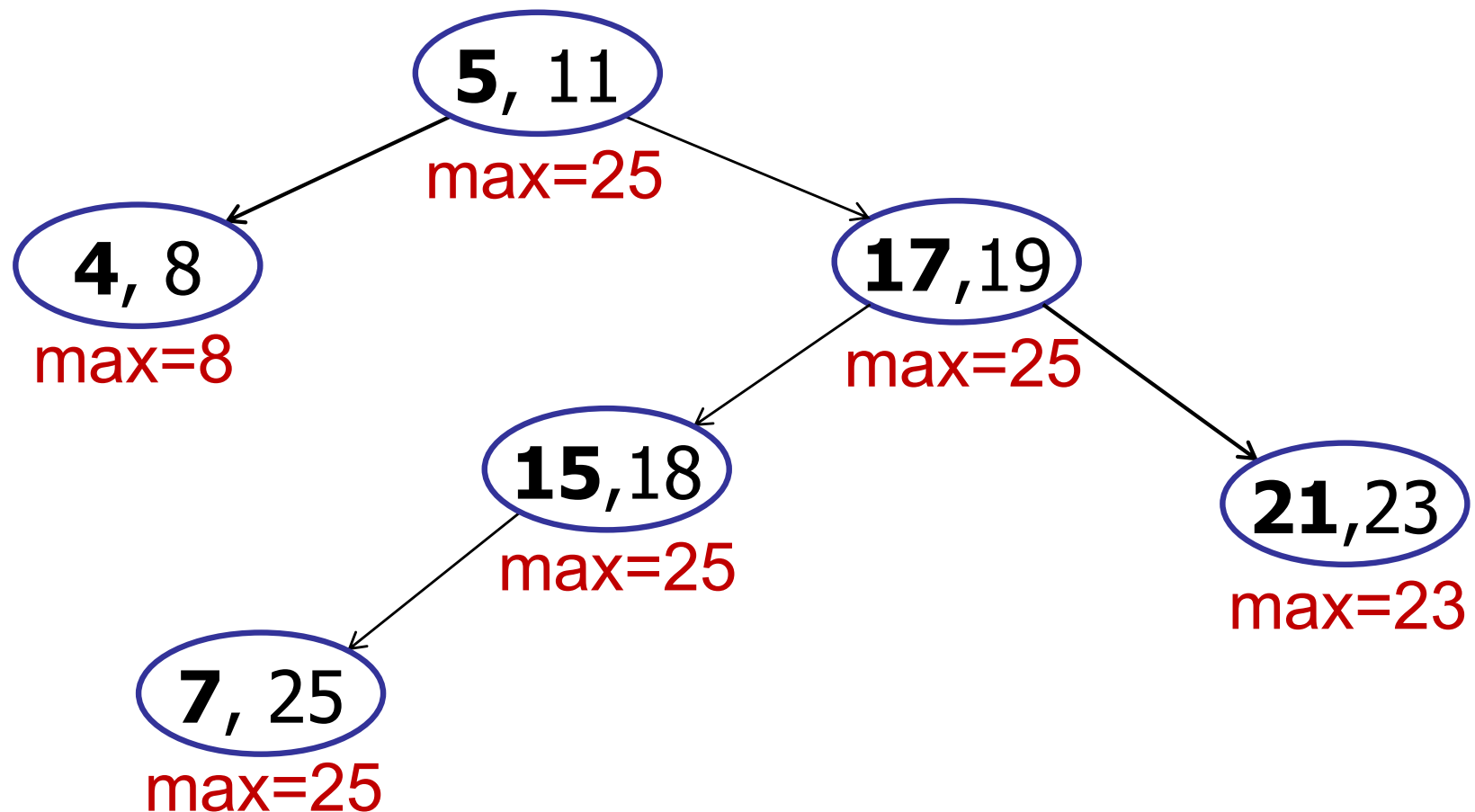
Insertion: *out-of-balance*



# Interval Trees

---

Insertion: **right-rotate** (17, 19)



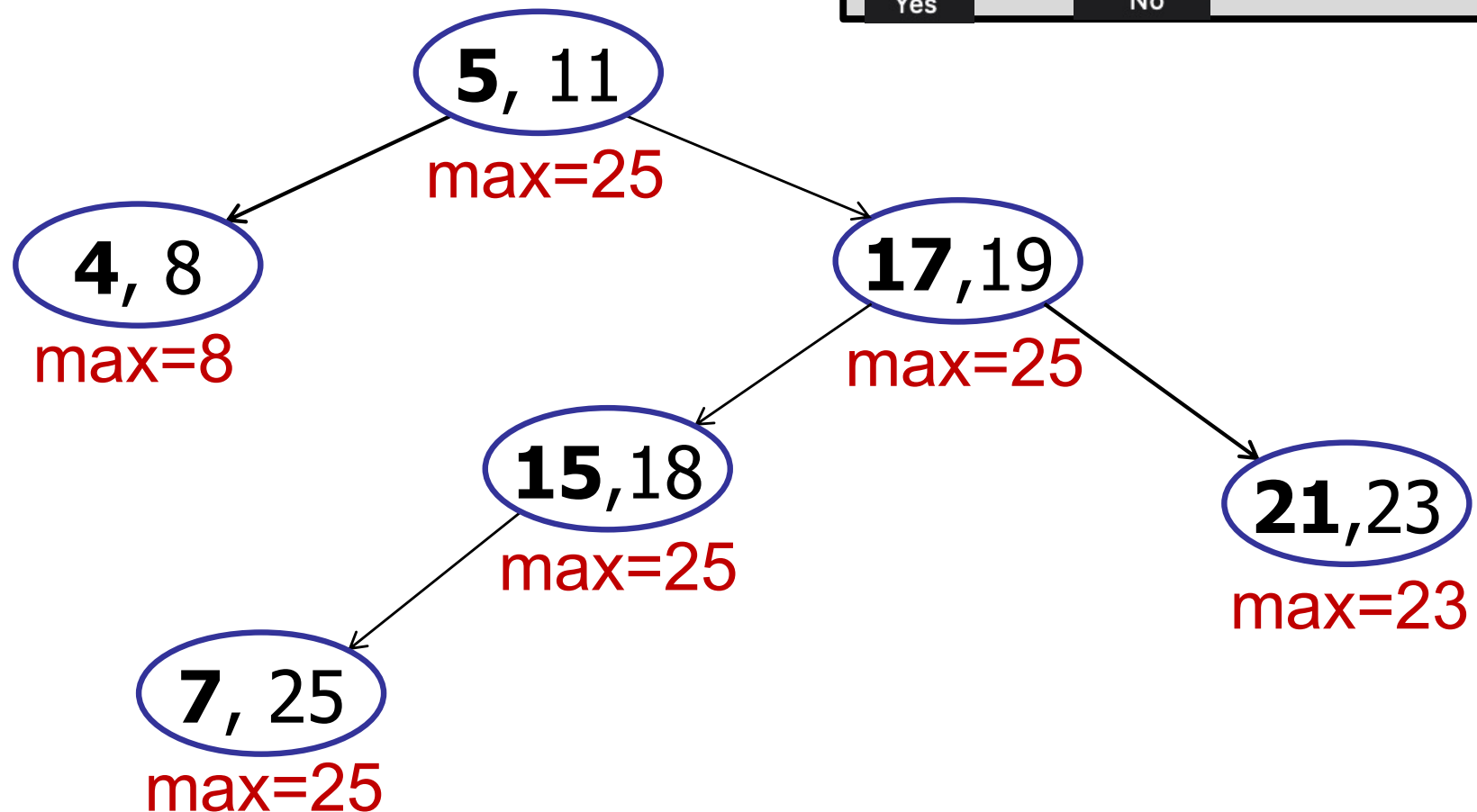


# Interval Trees

Insertion: **right-rotate (17, 19)**

Is the tree now balanced?

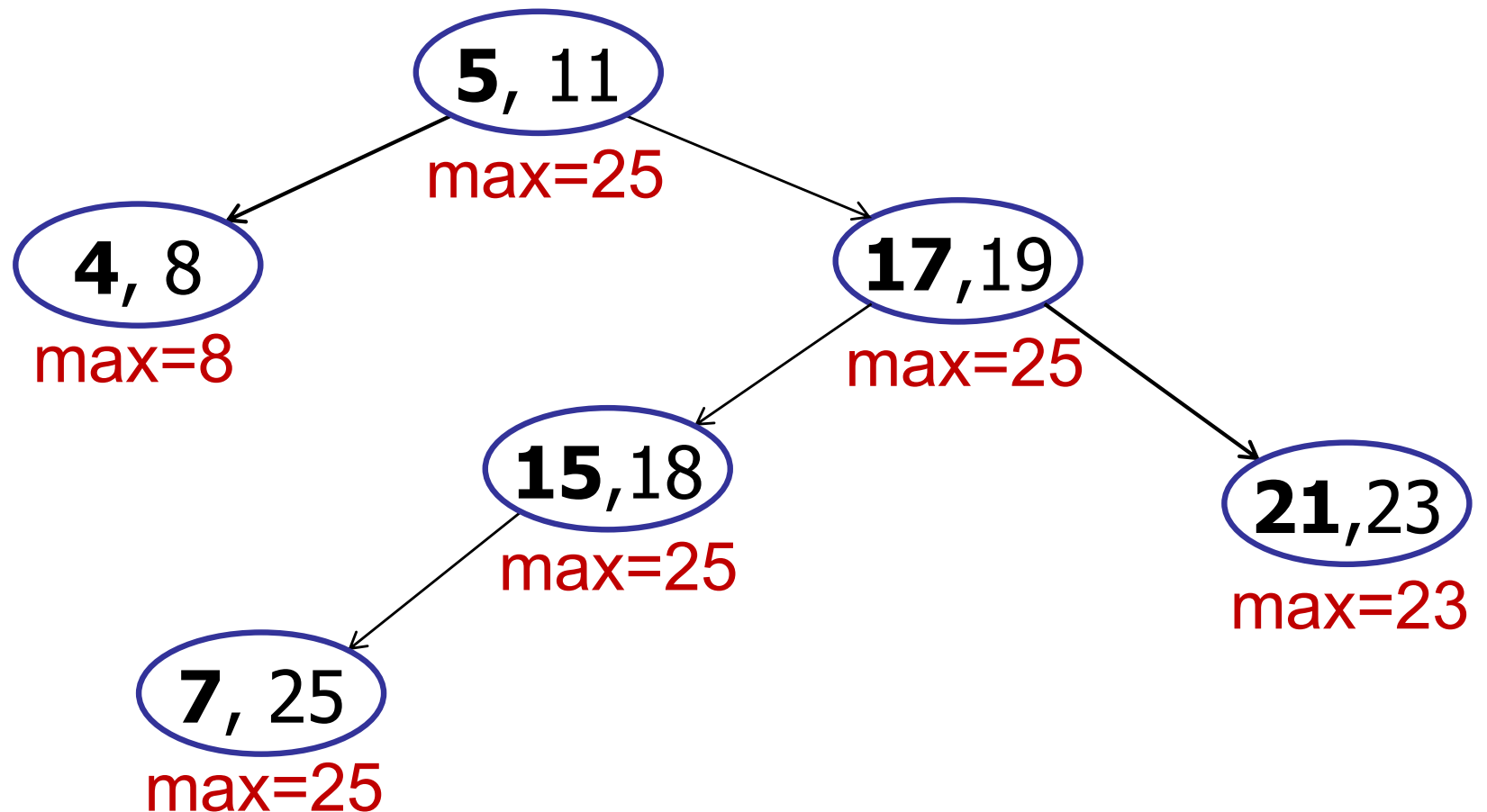
<input checked="" type="radio"/> Yes	or	<input type="radio"/> No	on Zoom.
--------------------------------------	----	--------------------------	----------



# Interval Trees

---

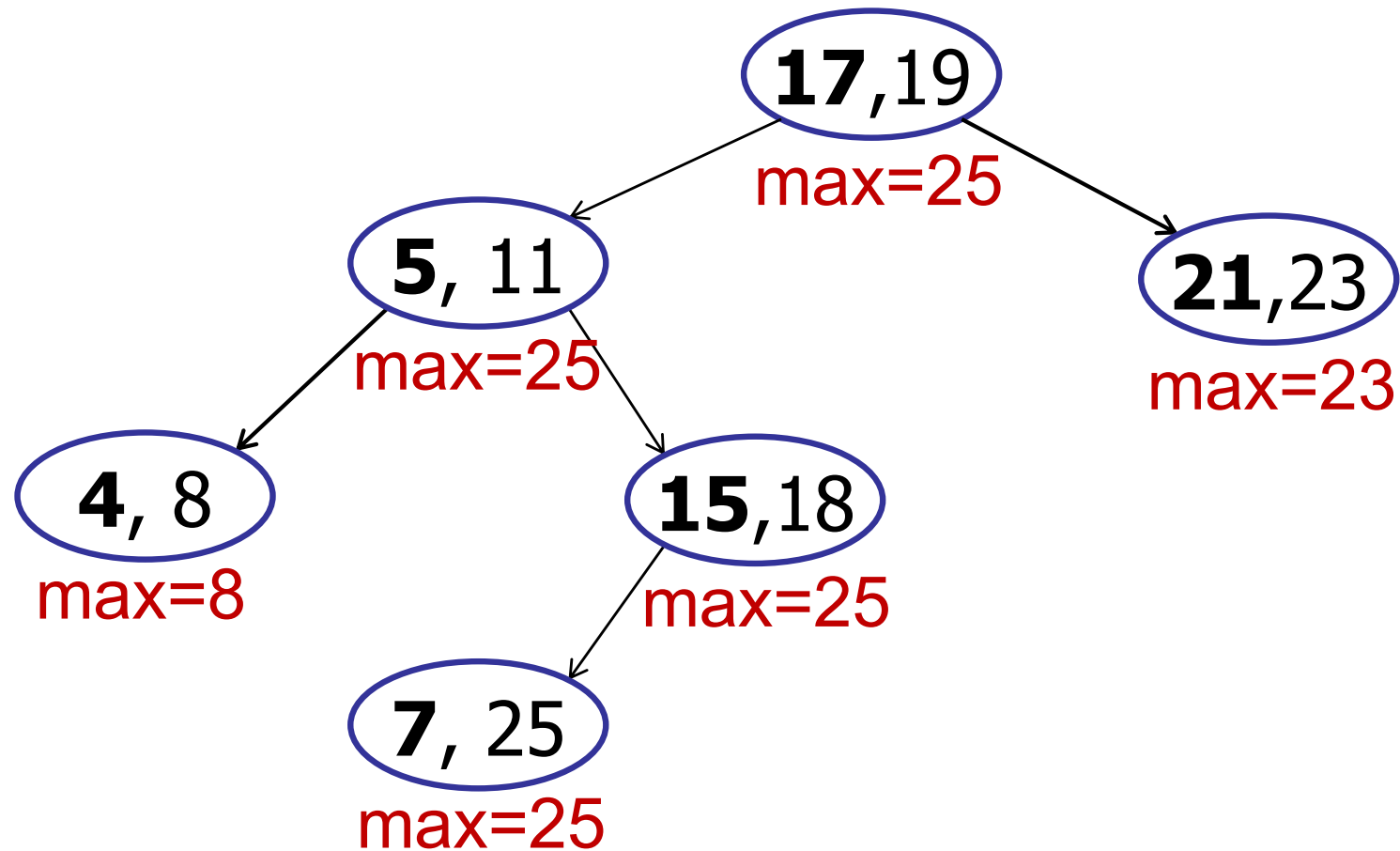
Insertion: *right-rotate* (17, 19), **OOPS!**



# Interval Trees

---

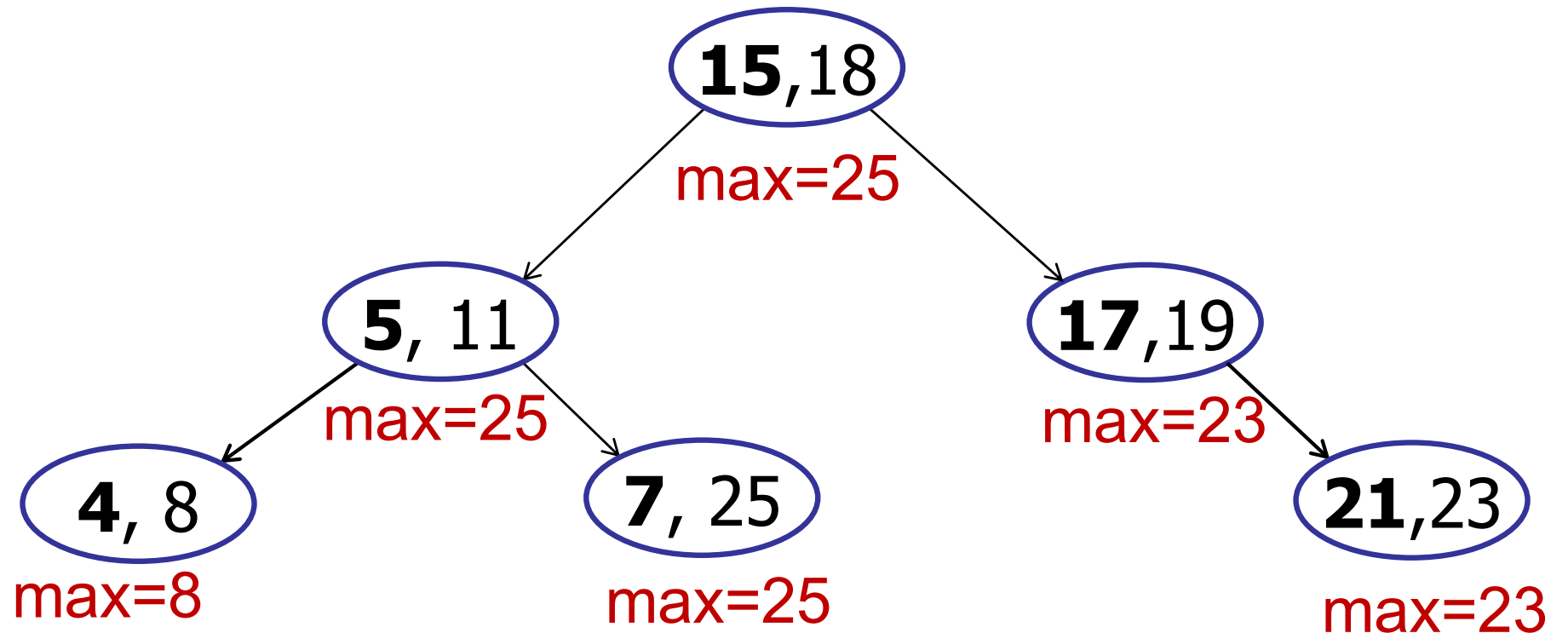
Insertion: *out-of-balance*



# Interval Trees

---

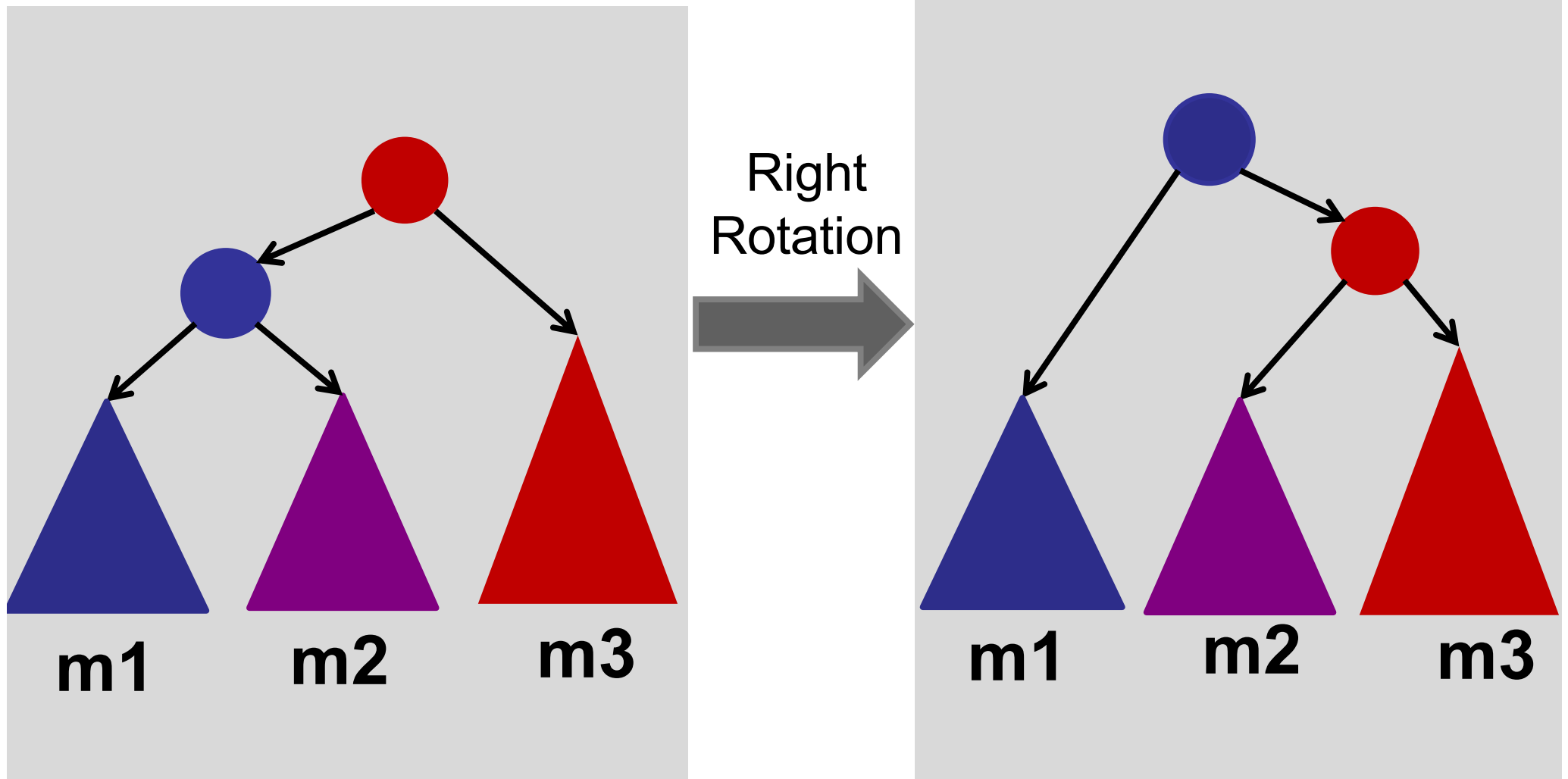
Insertion: left-rotate, right-rotate



# Interval Trees

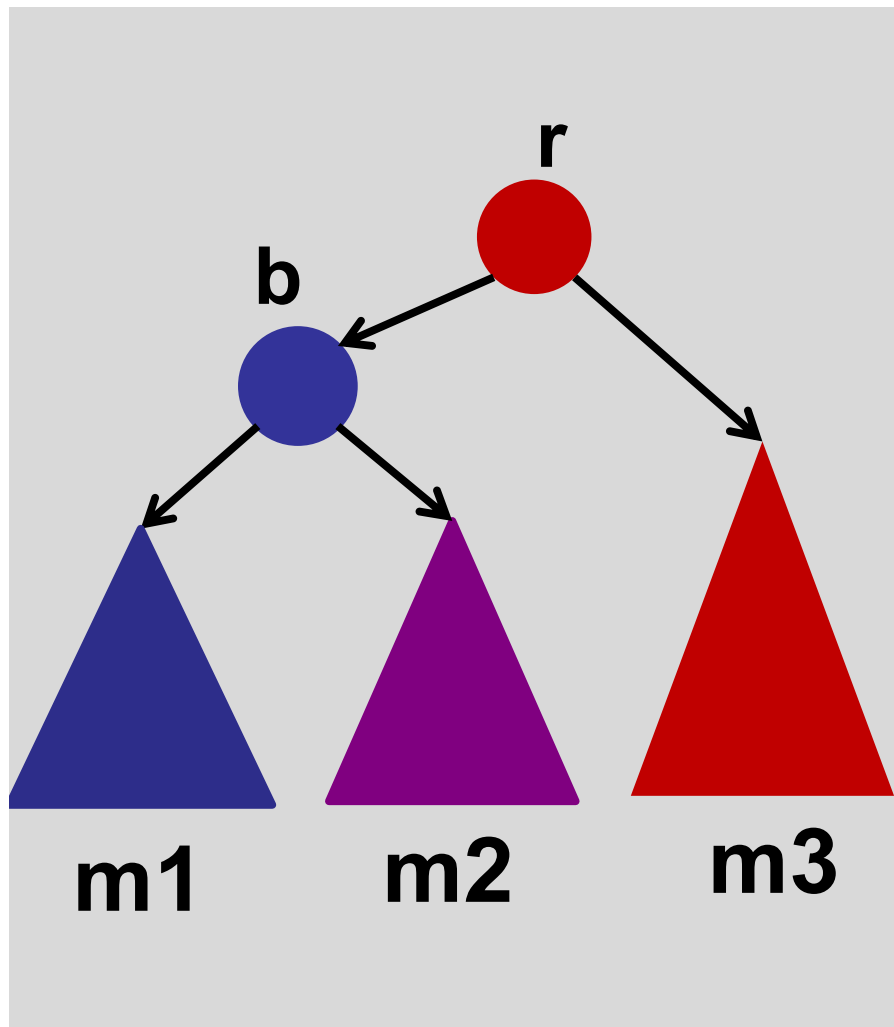
---

Maintain MAX during rotations:

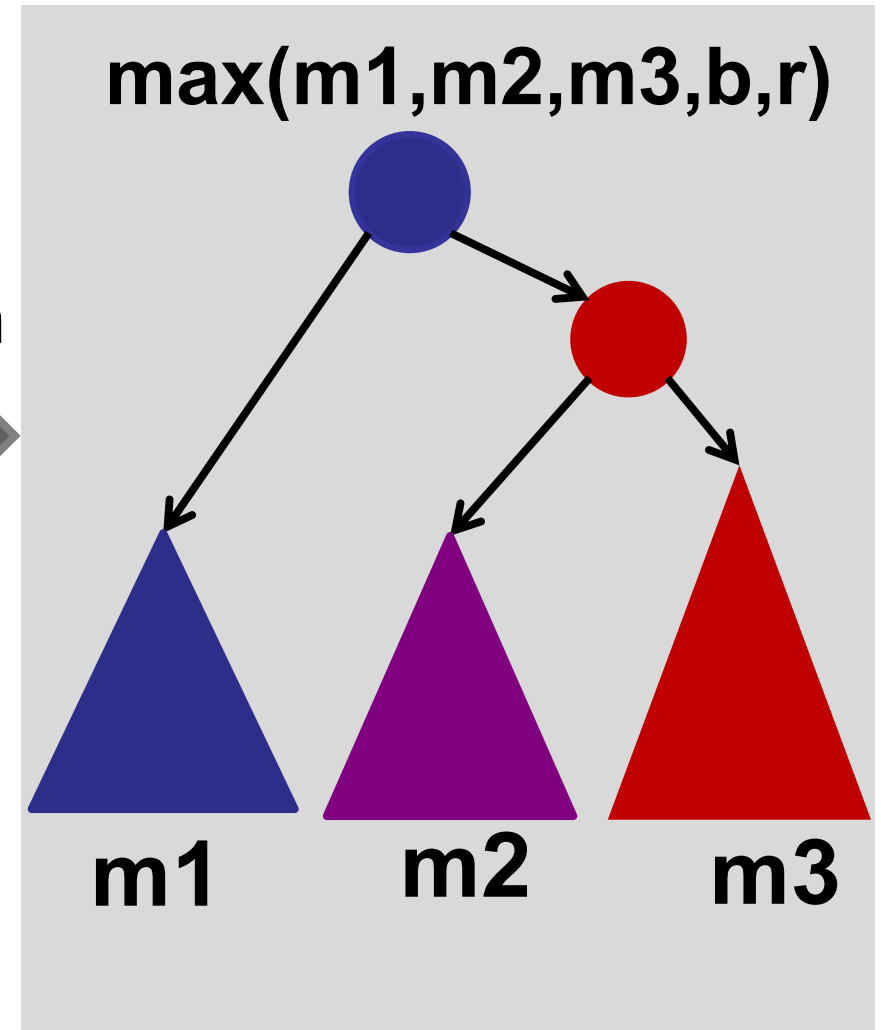


# Interval Trees

Maintain MAX during rotations:

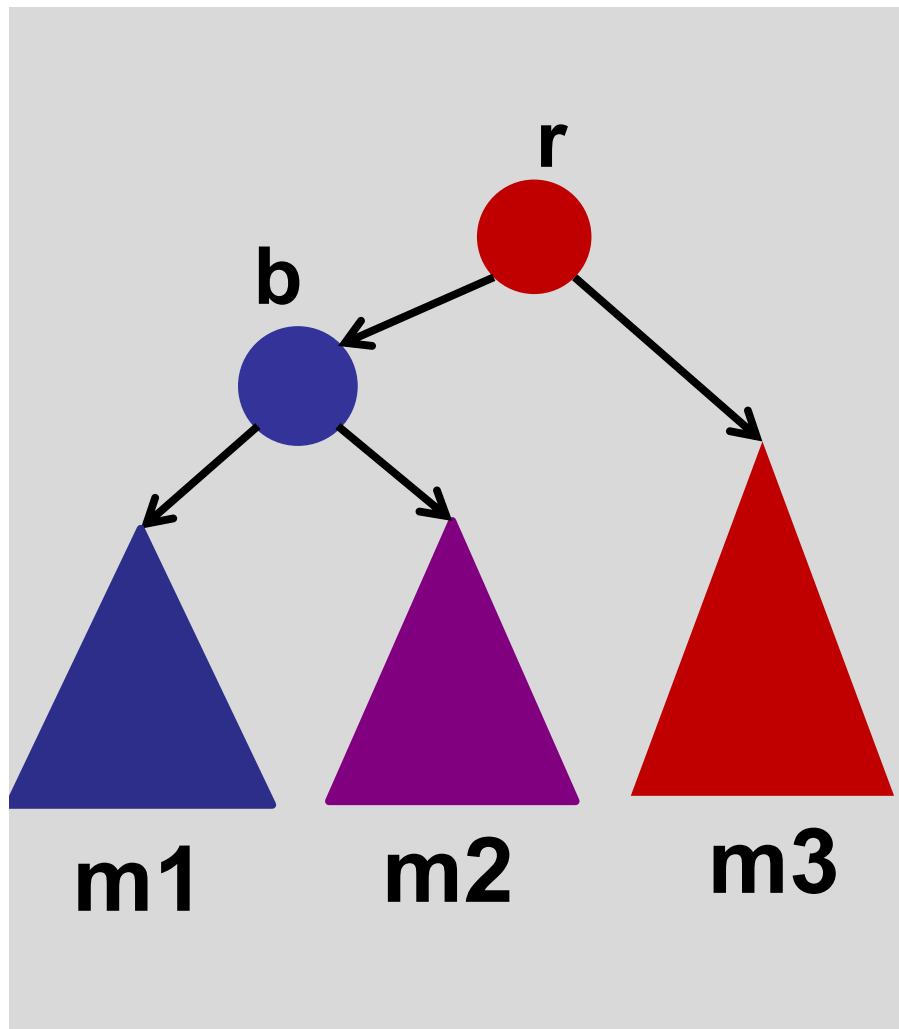


Right  
Rotation

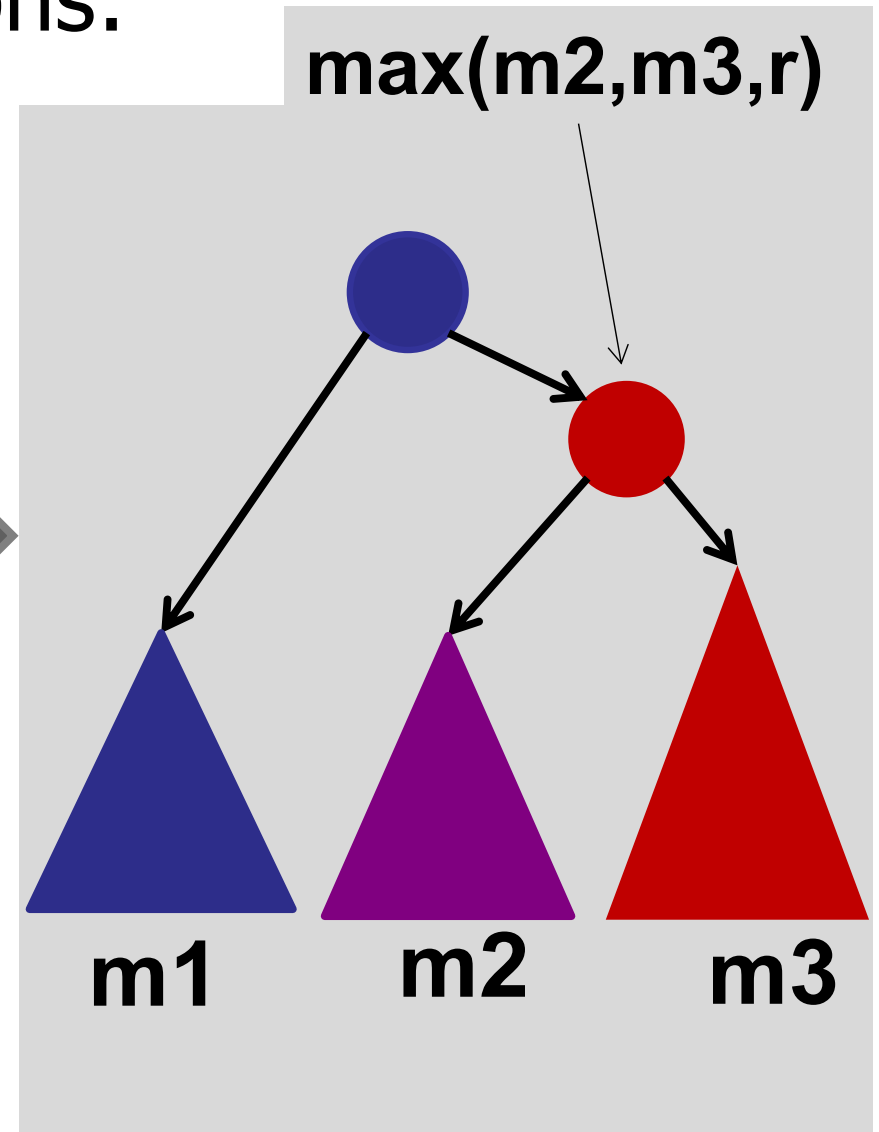


# Interval Trees

Maintain MAX during rotations:



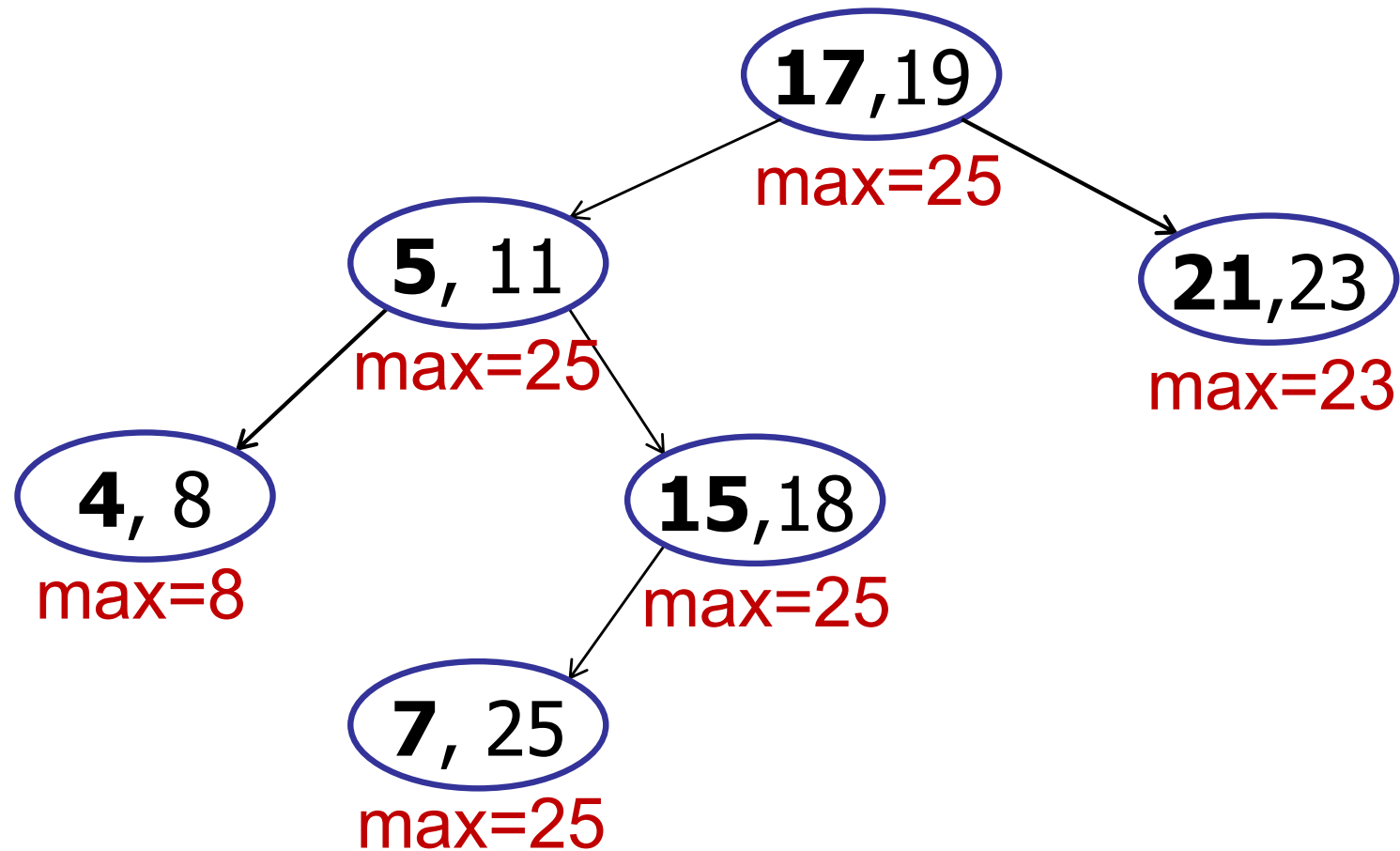
Right  
Rotation



# Interval Trees

---

Searching: **interval-search(22)**

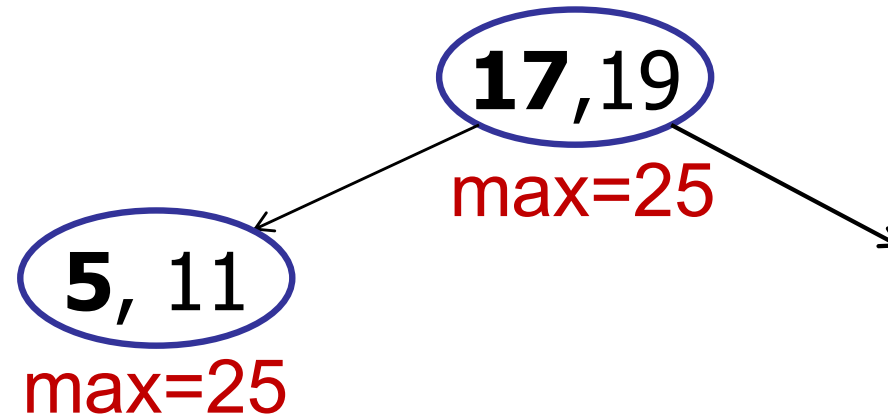




# Interval Trees

---

Searching: **interval-search(22)**



It is possible that 22 is covered in the left subtree.

Do we know *\*for sure\** that going left will work?

# Interval Trees

---

interval-search(x) : find interval containing x

interval-search(x)

c = root;

**while** (c != null **and** x is not in c.interval) **do**

**if** (c.left == null) **then**

        c = c.right;

**else if** (x > c.left.max) **then**

        c = c.right;

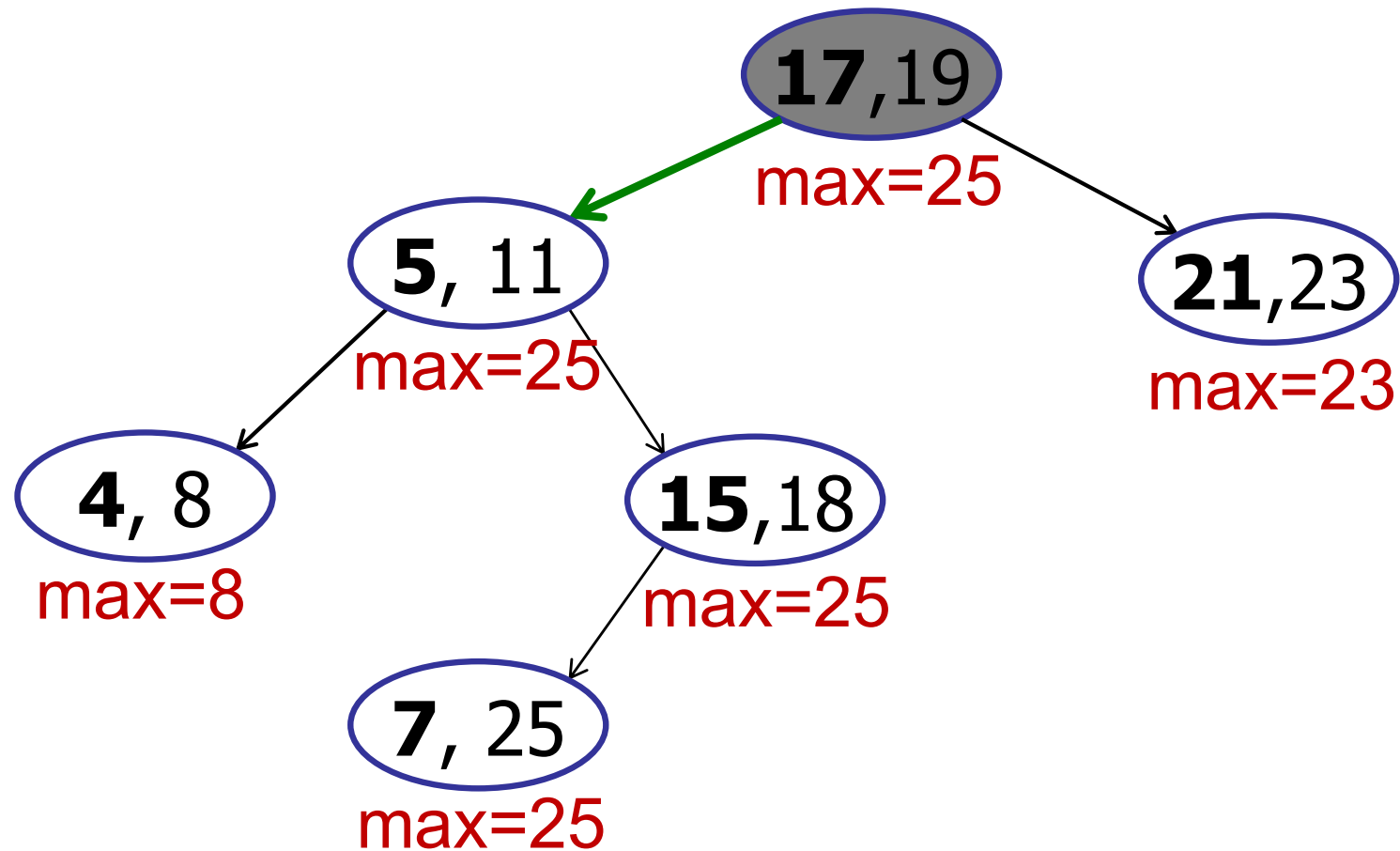
**else** c = c.left;

return c.interval;

# Interval Trees

---

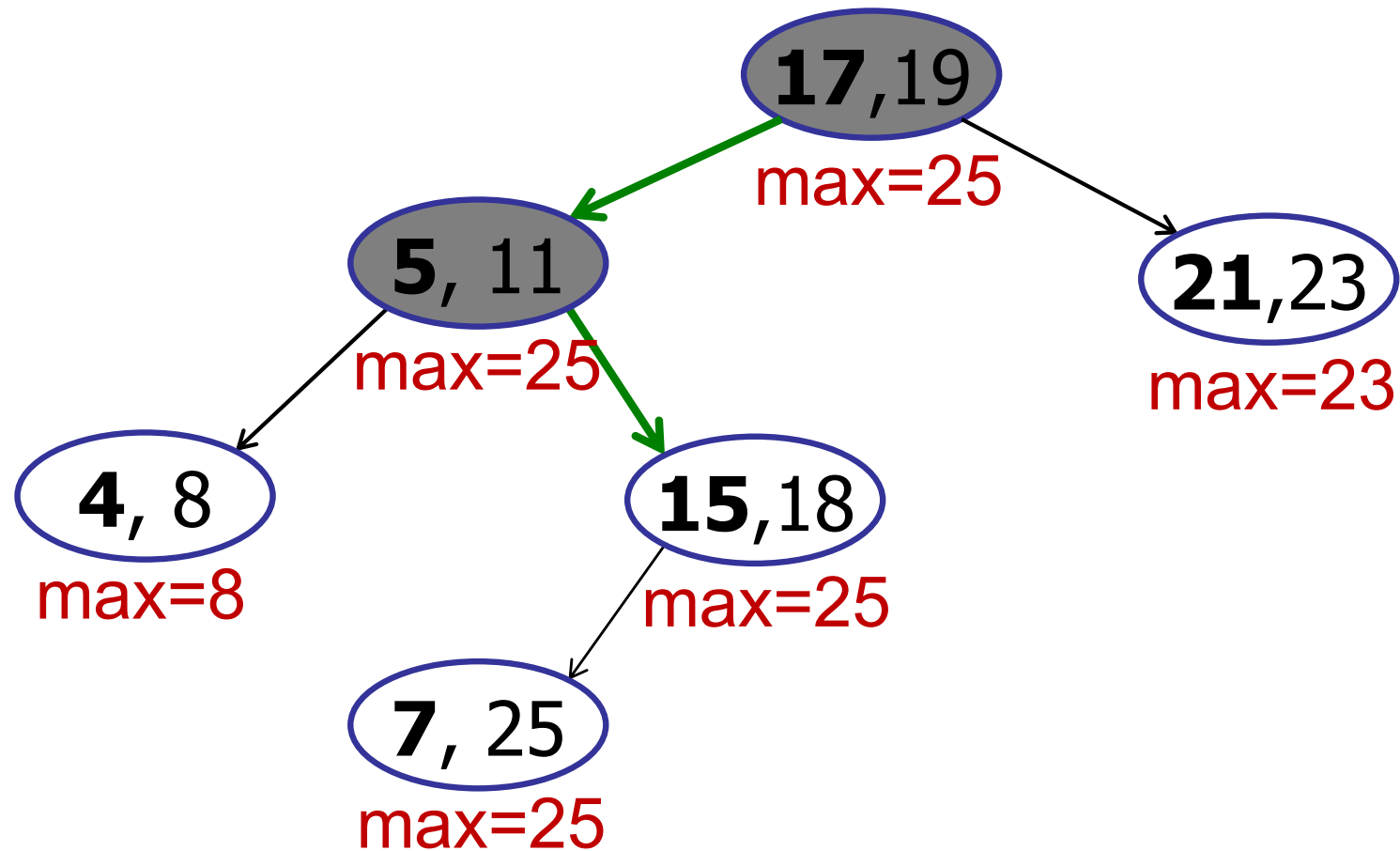
Searching: **interval-search(22)**



# Interval Trees

---

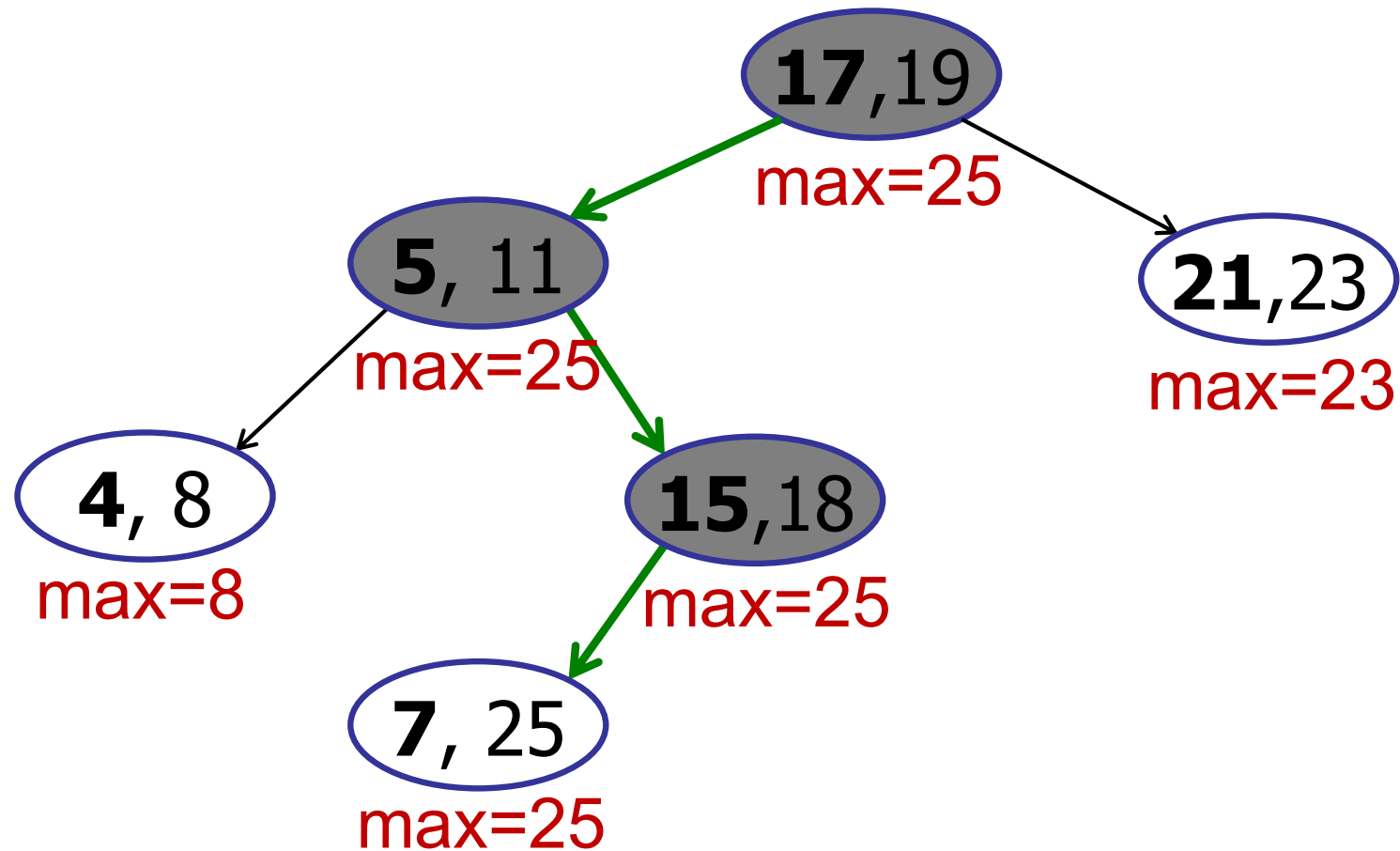
Searching: **interval-search(22)**



# Interval Trees

---

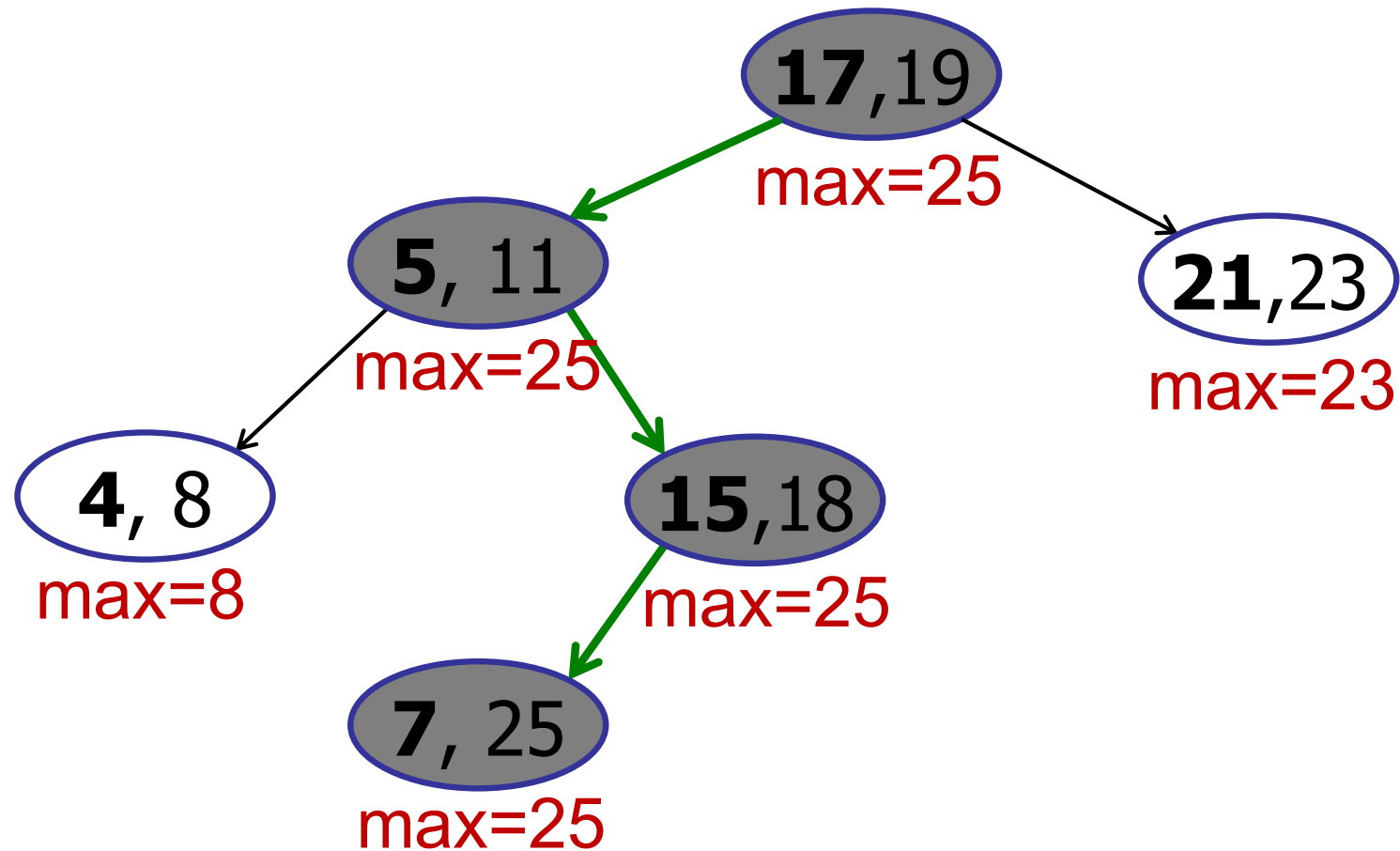
Searching: **interval-search(22)**



# Interval Trees

---

Searching: **interval-search(22)**



# Interval Trees

---

interval-search(x) : find interval containing x

interval-search(x)

c = root;

**while** (c != null **and** x is not in c.interval) **do**

**if** (c.left == null) **then**

        c = c.right;

**else if** (x > c.left.max) **then**

        c = c.right;

**else** c = c.left;

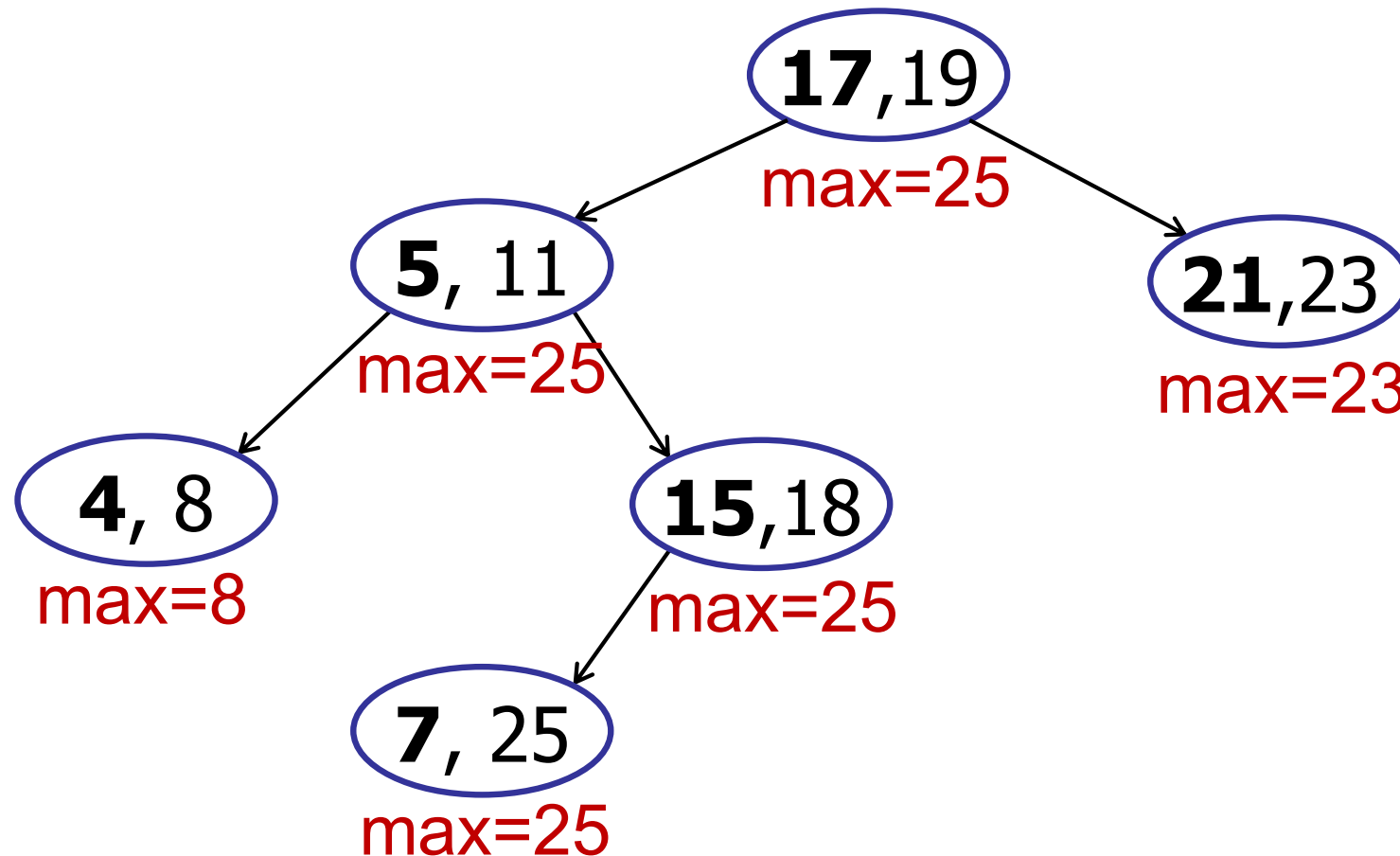
return c.interval;

# Interval Trees

---

Will any search find (21, 23)?

<input checked="" type="radio"/> Yes	or	<input type="radio"/> No	on Zoom.
--------------------------------------	----	--------------------------	----------

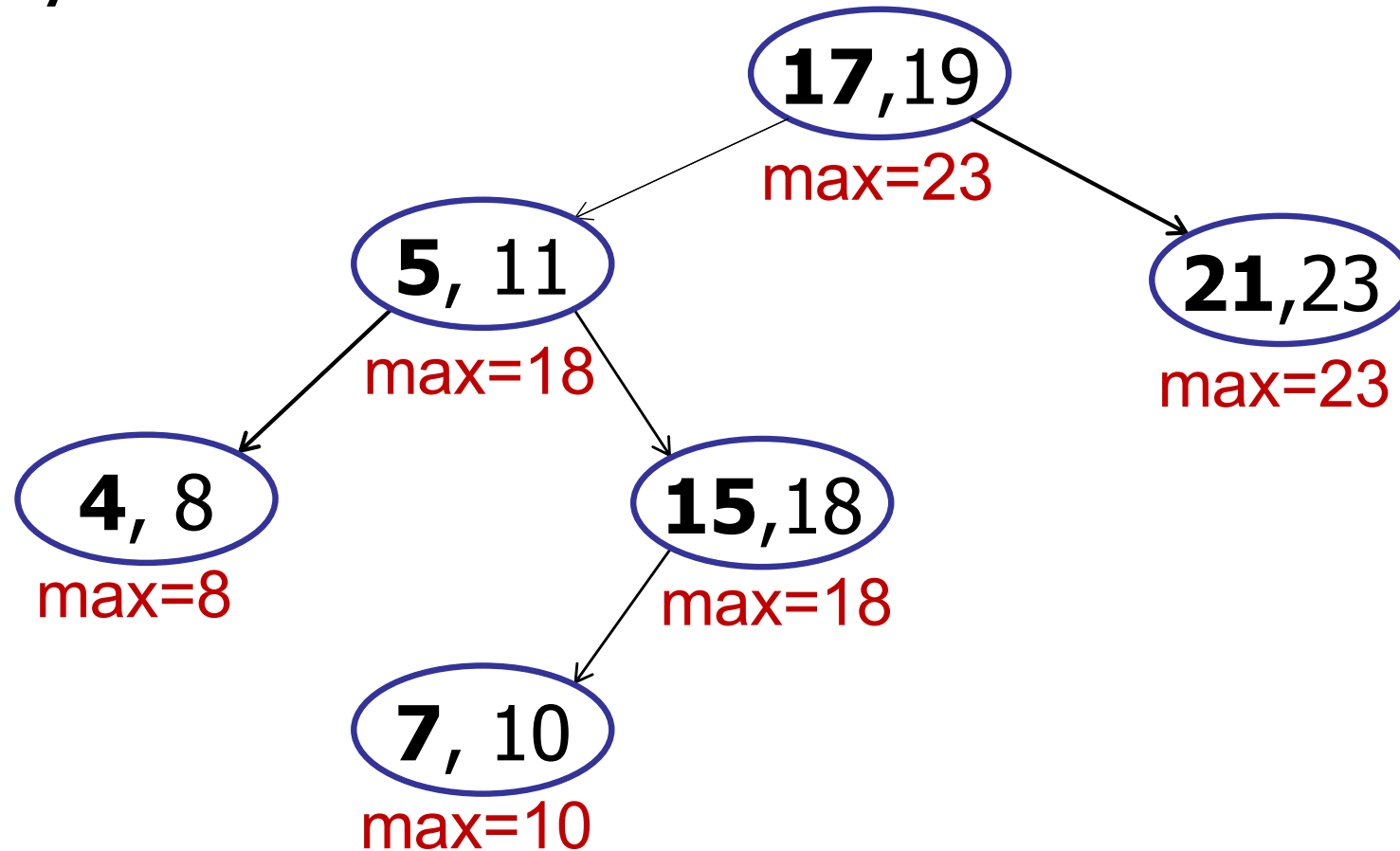




# Interval Trees

---

Why does it work?

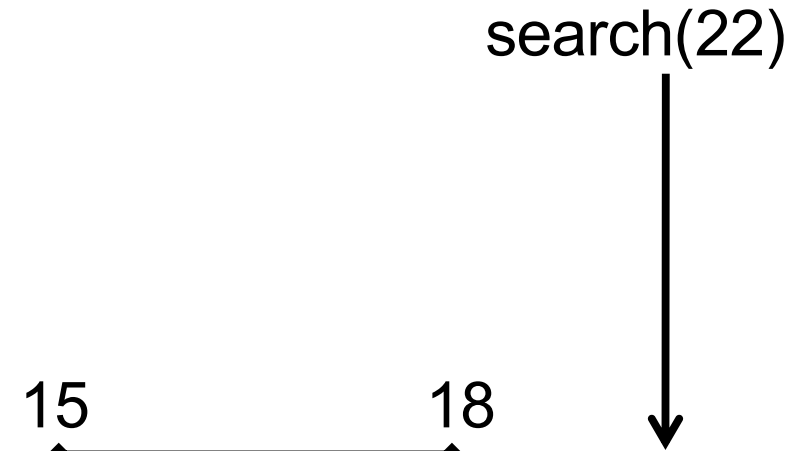
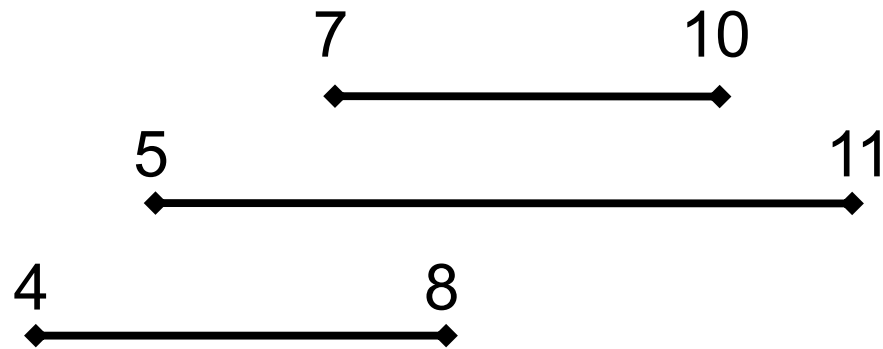


**Claim:** If search goes right, then no overlap in left subtree.

# Interval Trees

---

Max in "left sub-tree" is 18:

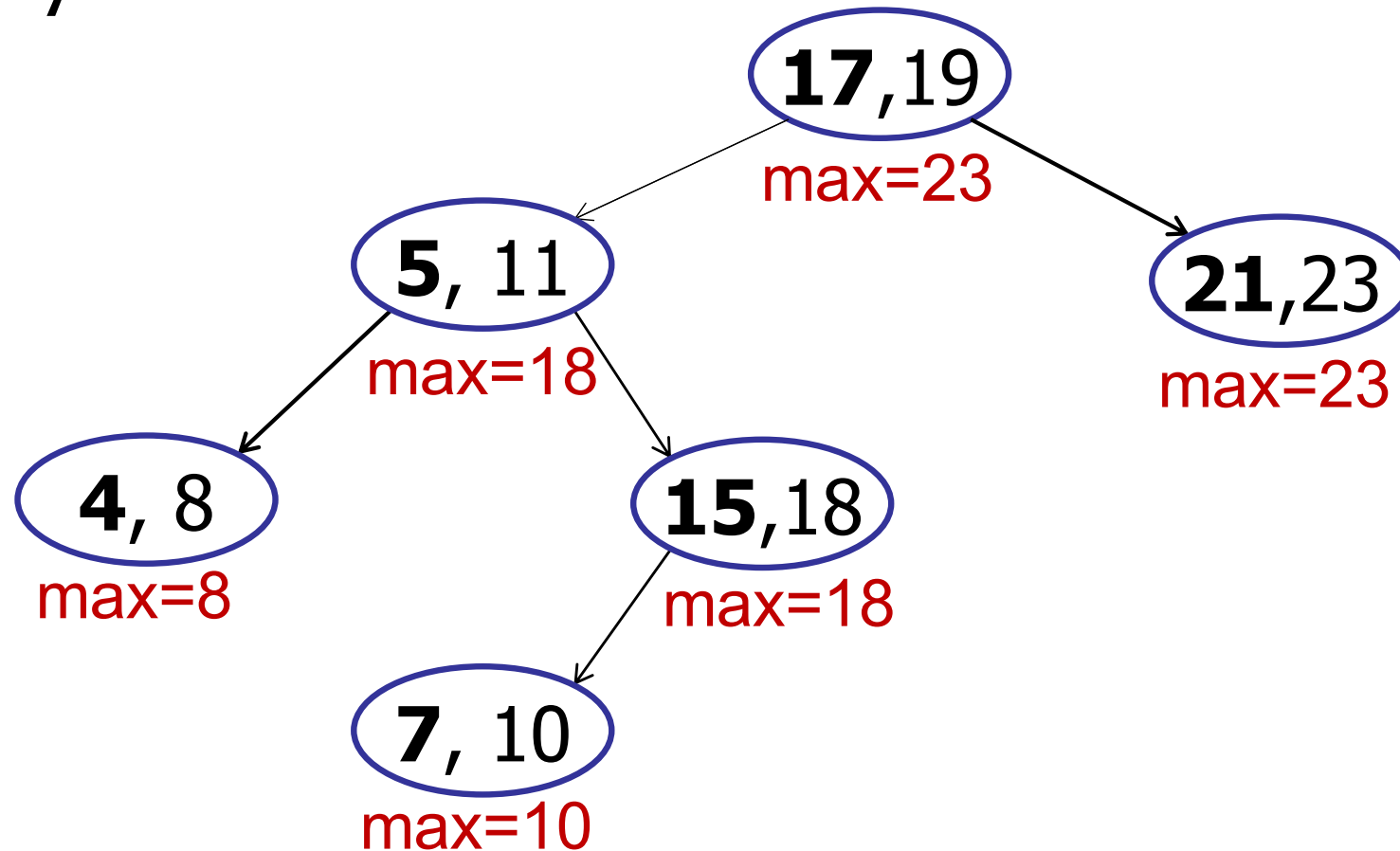


Safe to go right: 22 is not in the left sub-tree.

# Interval Trees

---

Why does it work?

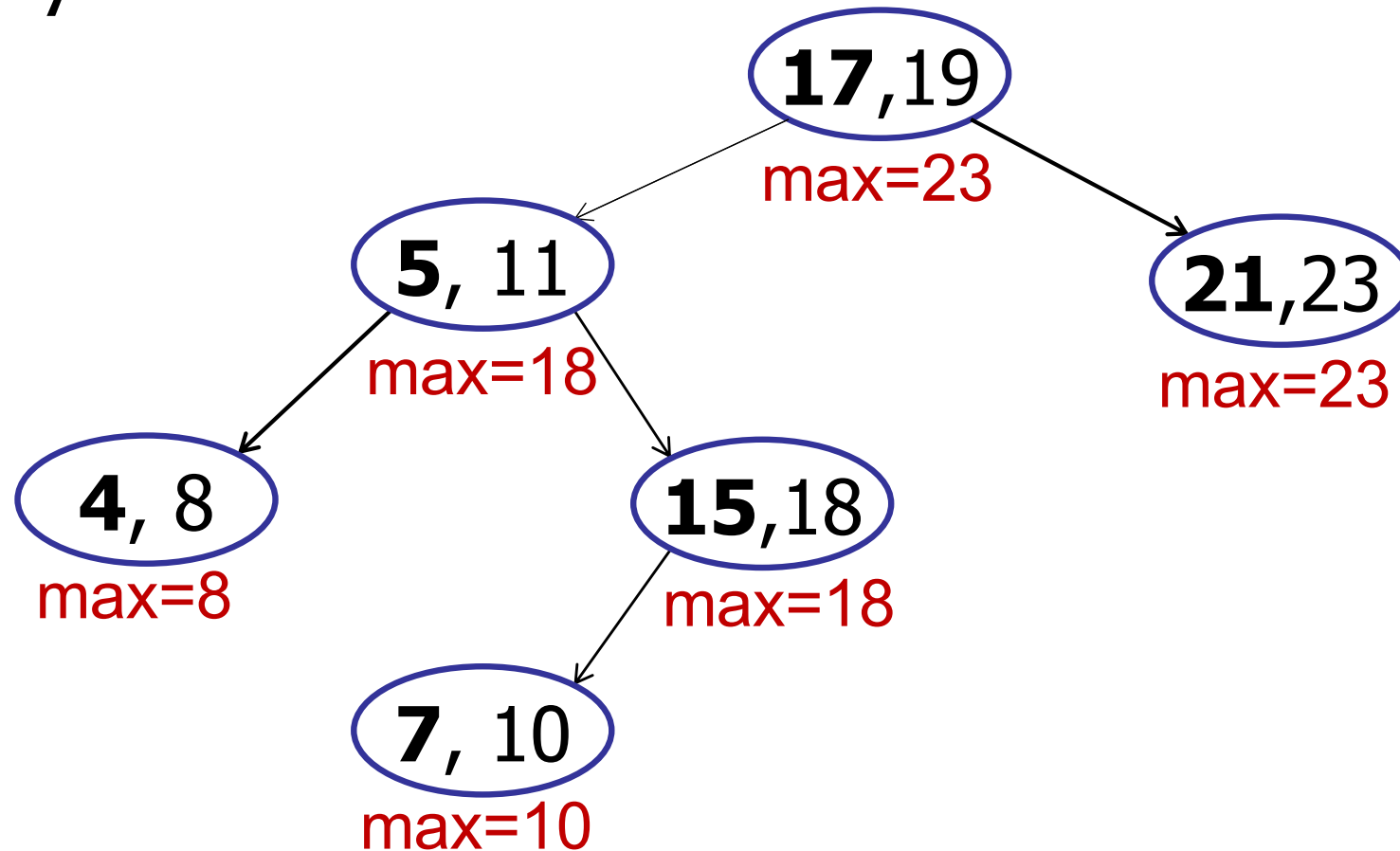


**Claim:** If search goes left and there is no overlap in the left subtree...

# Interval Trees

---

Why does it work?



**Claim:** If search goes left, then safe to go left.

# Interval Trees

---

Max in “left sub-tree” is 18:

search(13)



15



18

Left  
subtree

Right  
subtree

Assume we go to left subtree.

Assume search fails!

# Interval Trees

---

Max in "left sub-tree" is 18:

search(13)



15

18



Left  
subtree

Right  
subtree

Go left:  $\text{search}(13) < 18$

# Interval Trees

---

Max in "left sub-tree" is 18:

search(13)



15

18



Left  
subtree

Right  
subtree

Go left:  $\text{search}(13) < 15 < 18$

# Interval Trees

---

Max in "left sub-tree" is 18:

search(13)



15

18



Left  
subtree

Right  
subtree

Go left:  $\text{search}(13) < 15 < 18$

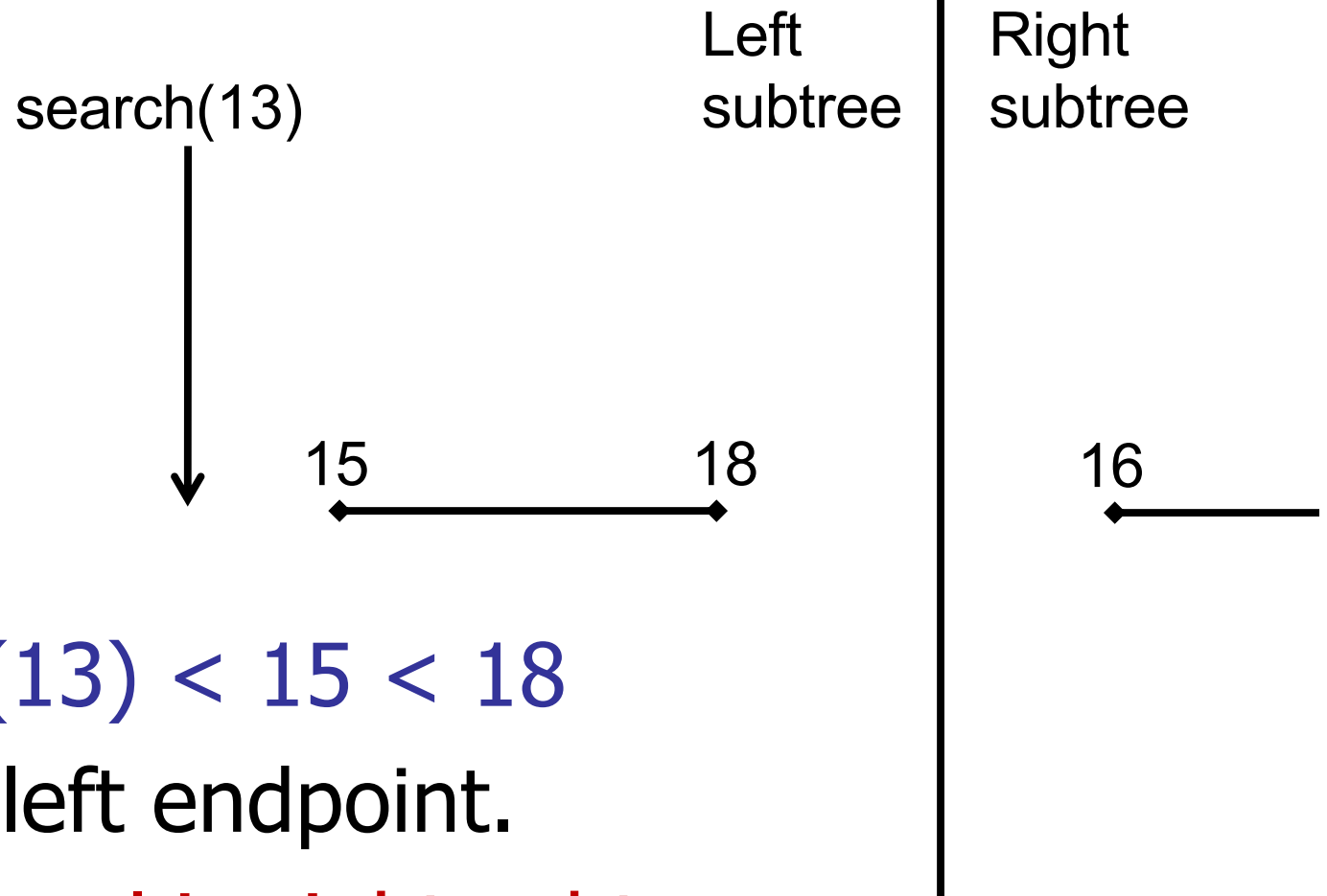
Tree sorted by left endpoint.



# Interval Trees

---

Max in “left sub-tree” is 18:



Go left:  $\text{search}(13) < 15 < 18$

Tree sorted by left endpoint.

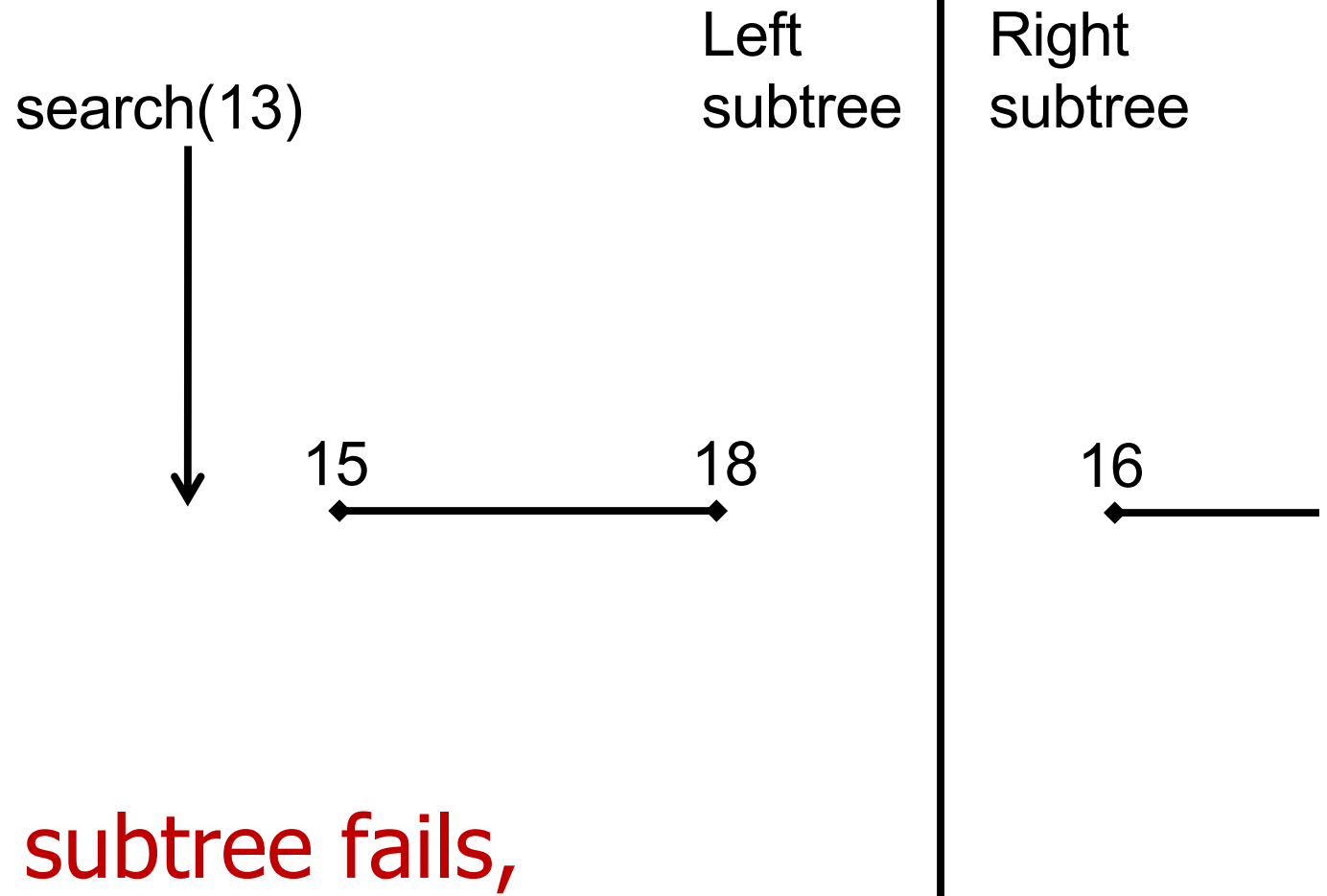
$13 < \text{every interval in right subtree}$

➔ Search also would fail in right subtree

# Interval Trees

---

Max in "left sub-tree" is 18:

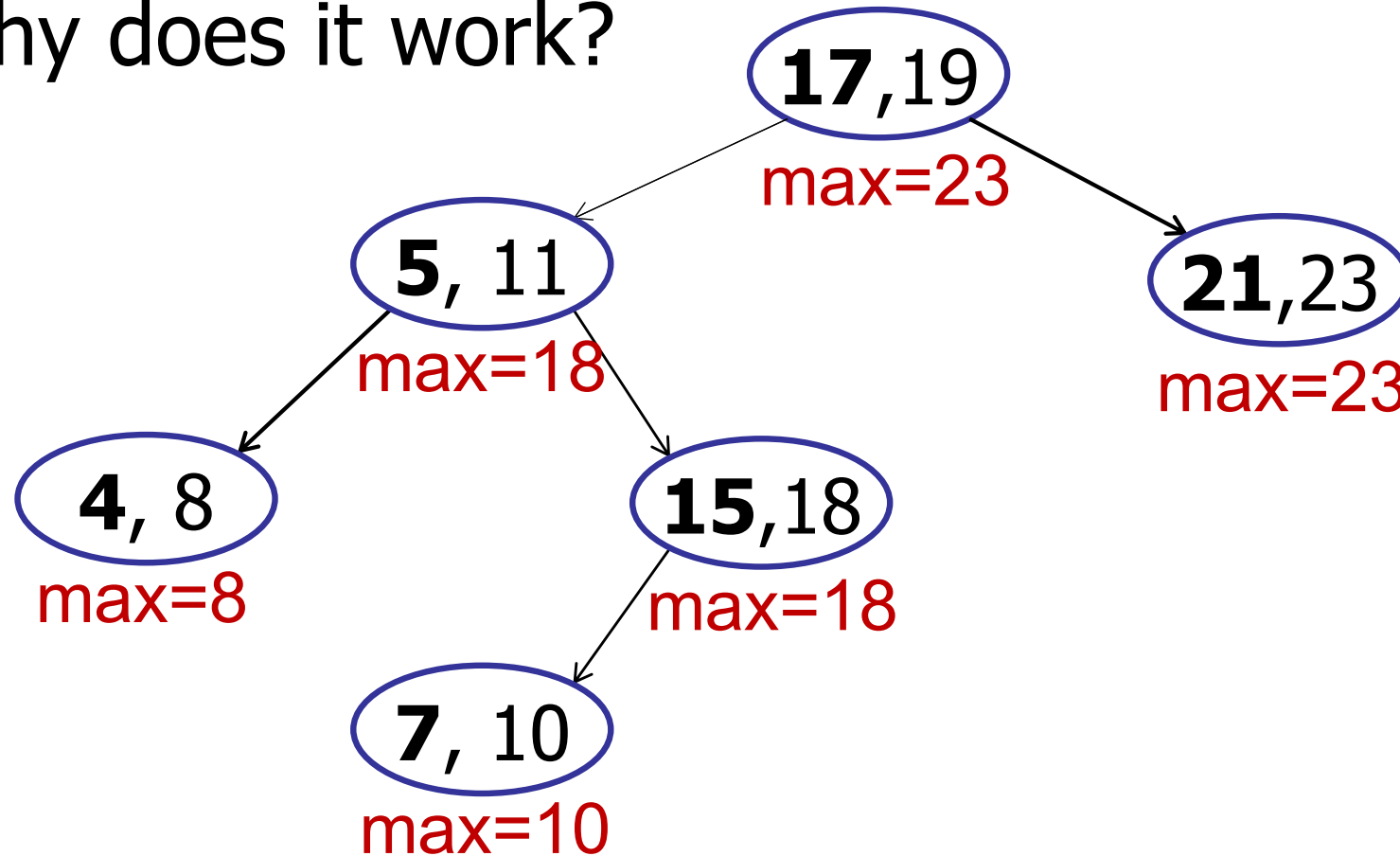


If search in left subtree fails,  
Then search also would fail in right subtree!

# Interval Trees

---

Why does it work?



**Claim:** If search goes left and fails, then  
key < every interval in right sub-tree.

# Interval Trees

---

If search goes right: then no interval in left subtree.

→ Either search finds key in right subtree or it is not in the tree.

If search goes left: if there is no interval in left subtree, then there is no interval in right subtree either.

→ Either search finds key in left subtree or it is not in the tree.

Conclusion: search finds an overlapping interval, if it exists.

The running time of interval-search is:

1.  $O(1)$
2.  $O(\log n)$
3.  $O(n)$
4.  $O(n \log n)$
5.  $O(n^2)$
6. Can't say.

ARCHIPELAGO

is open

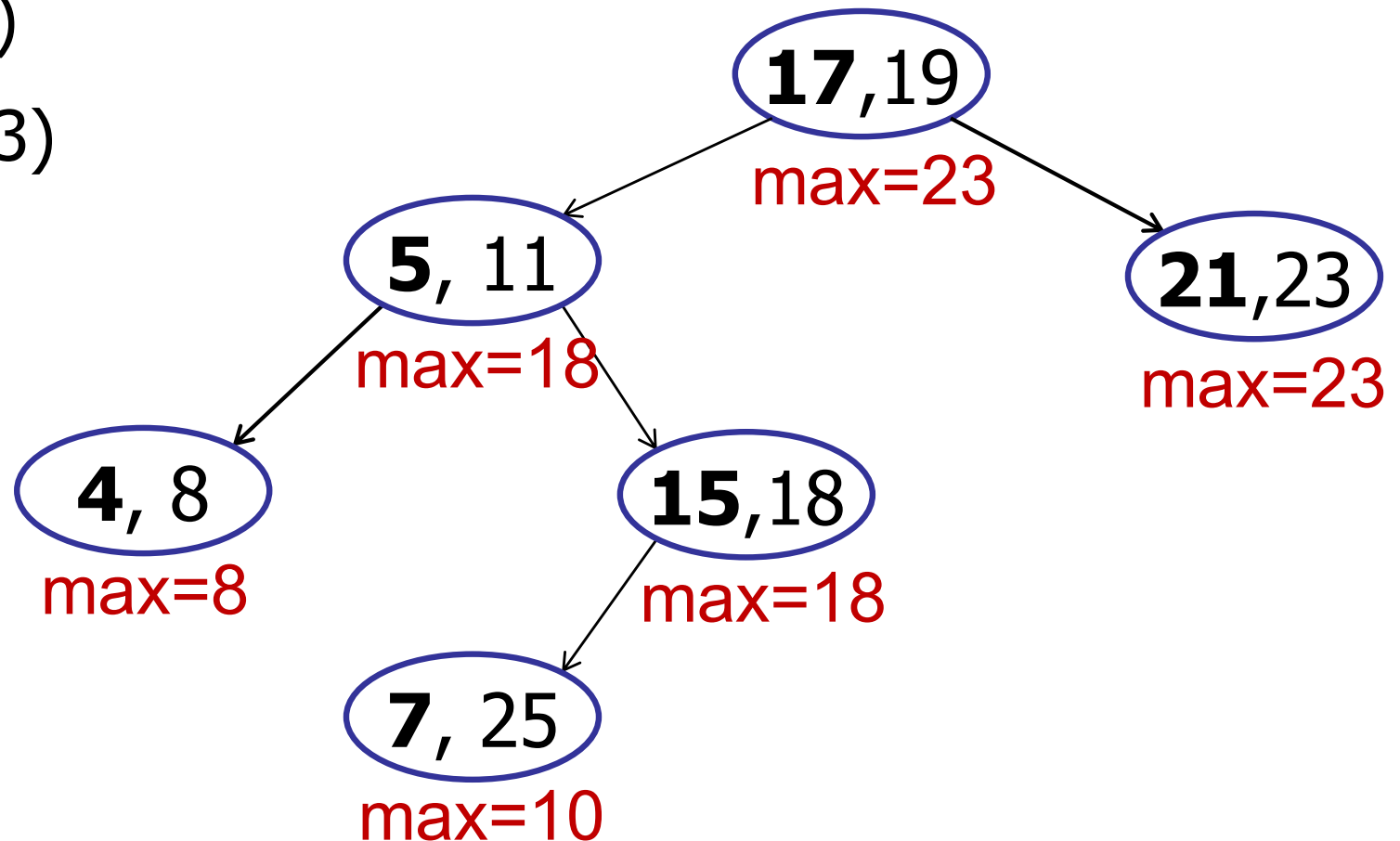
# Interval Trees

---

Extension: List all intervals that overlap with point?

E.g.: `search(22)` returns:

- (7,25)
- (21,23)



# Interval Trees

---

Extension: List all intervals that overlap with point?

## All-Overlaps Algorithm:

**Repeat** until no more intervals:

- Search for interval.
- Add to list.
- Delete interval.

**Repeat** for all intervals on list:

- Add interval back to tree.

The running time of All-Overlaps, if there are  $k$  overlapping intervals?

1.  $O(1)$
2.  $O(k)$
3.  $O(k \log n)$
4.  $O(k + \log n)$
5.  $O(kn)$
6.  $O(kn \log n)$

ARCHIPELAGO

is open



# Interval Trees

---

Extension: List all intervals that overlap with point?

All-Overlaps Algorithm:  $O(k \log n)$

**Repeat** until no more intervals:

- Search for interval.
- Add to list.
- Delete interval.

**Repeat** for all intervals on list:

- Add interval back to tree.

Best known solution:  $O(k + \log n)$

# Today

---

Three examples of augmenting BSTs

~~1. Order Statistics~~

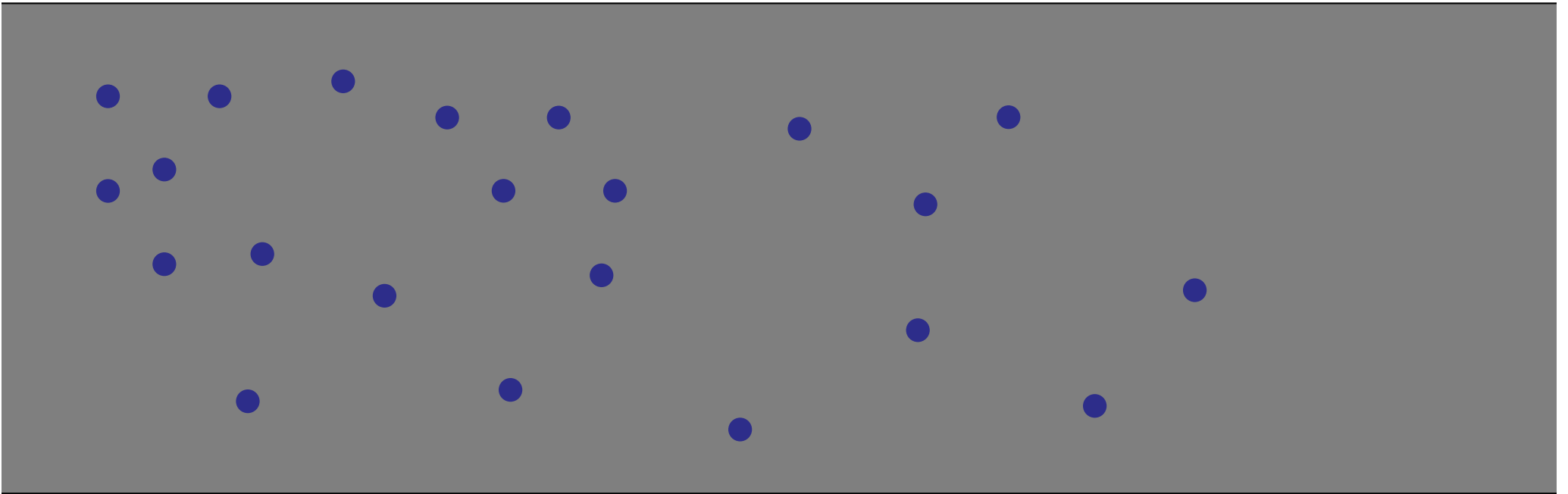
~~2. Intervals~~

3. Orthogonal Range Searching

# Orthogonal Range Searching

---

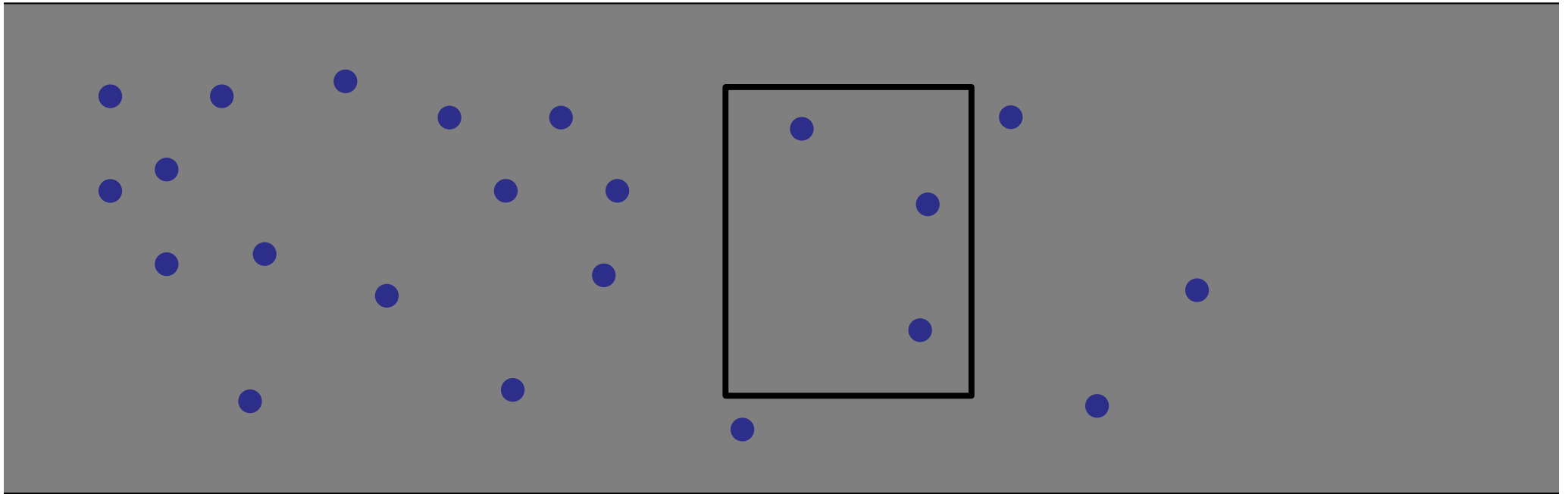
Input:  $n$  points in a 2d plane



# Orthogonal Range Searching

---

Input:  $n$  points in a 2d plane



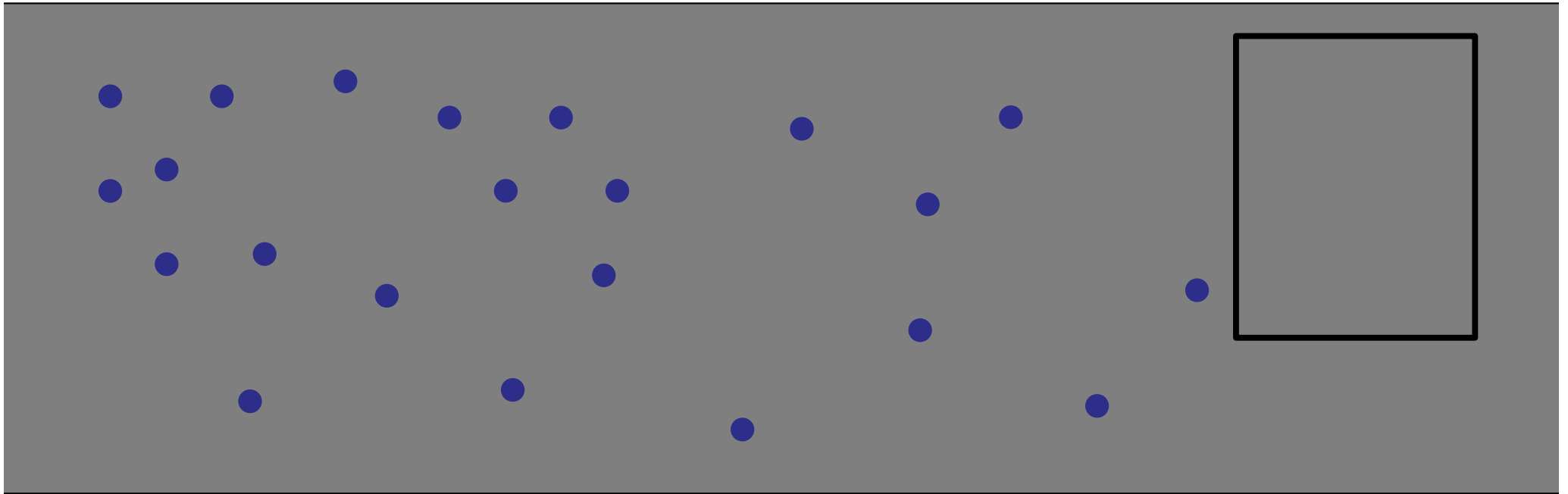
Query: Box

- Contains at least one point?
- How many?

# Orthogonal Range Searching

---

Input:  $n$  points in a 2d plane

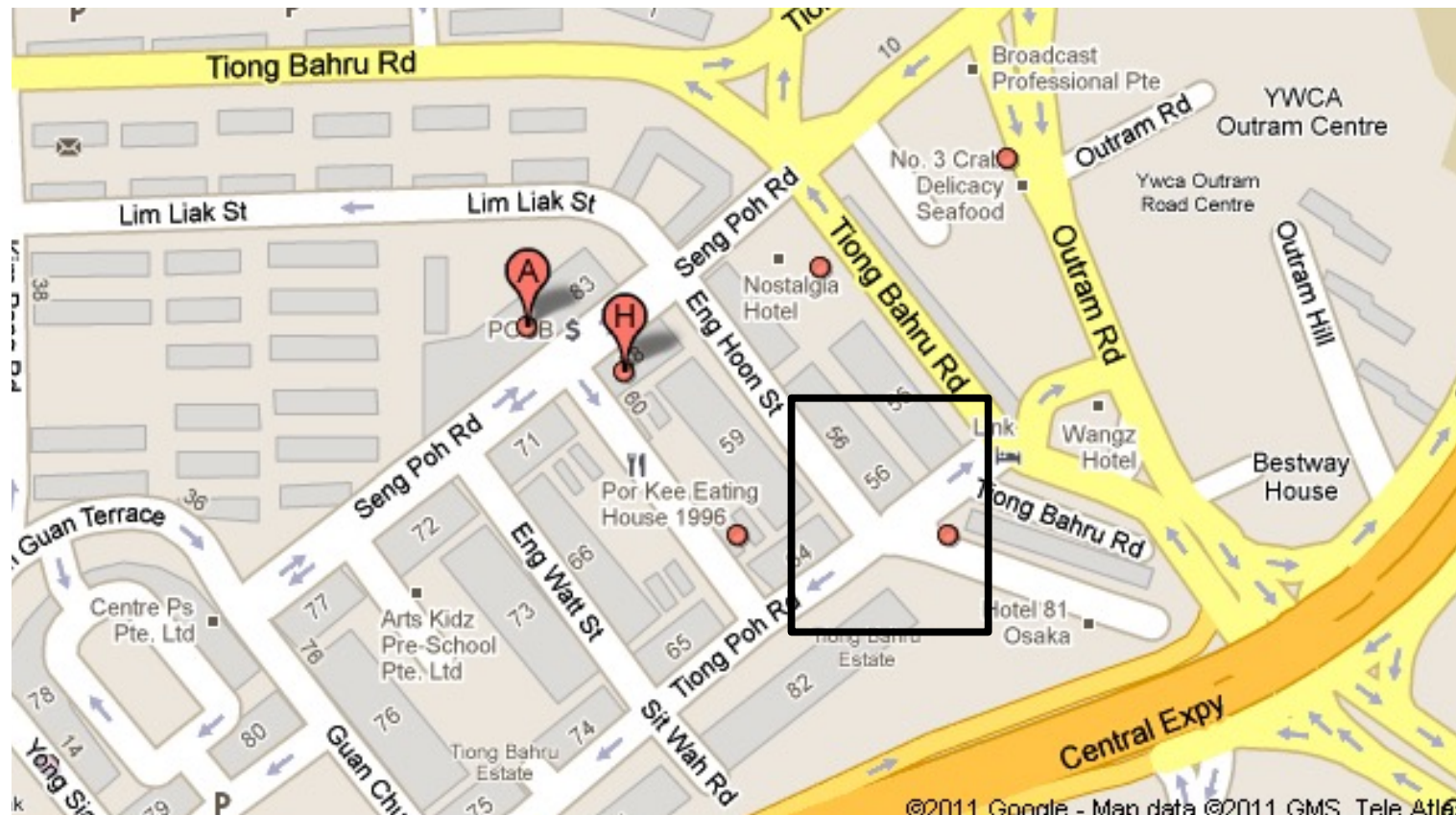


Query: Box

- Contains at least one point?
- How many?

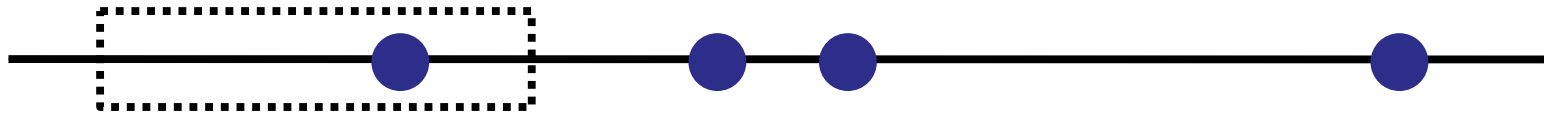
# Practical Example

Are there any good restaurants within one block of me?



# One Dimension

---

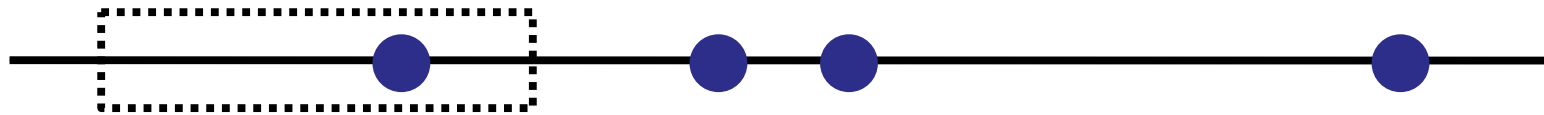


# One Dimension

---

## Range Queries

- Important in databases
- “Find me everyone between ages 22 and 27.”





# One Dimension

---

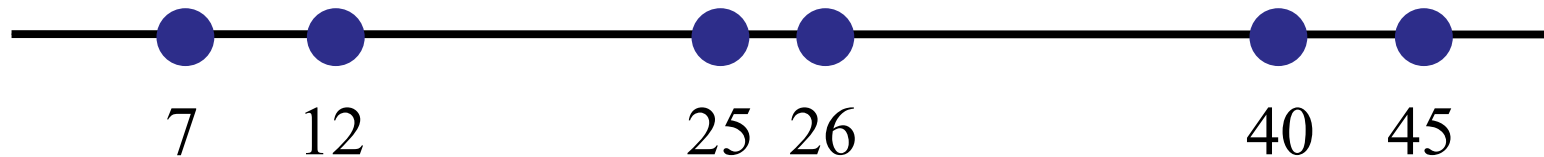
## Strategy:

1. Use a binary search tree.
2. Store all points in the leaves of the tree.  
(Internal nodes store only copies.)
3. Each internal node  $v$  stores the MAX of any leaf in the left sub-tree.

# Example: what is the root?

---

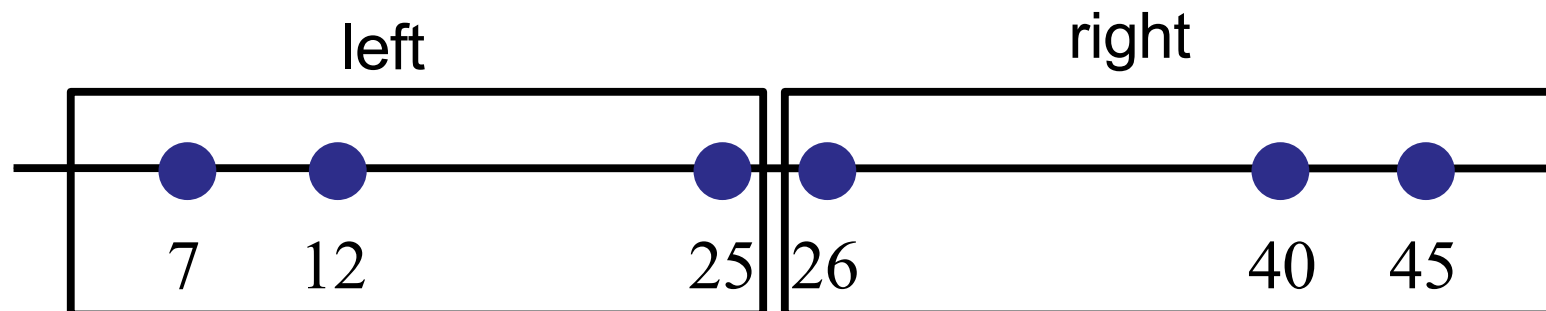
**ARCHIPELAGO**  
is open



# Example

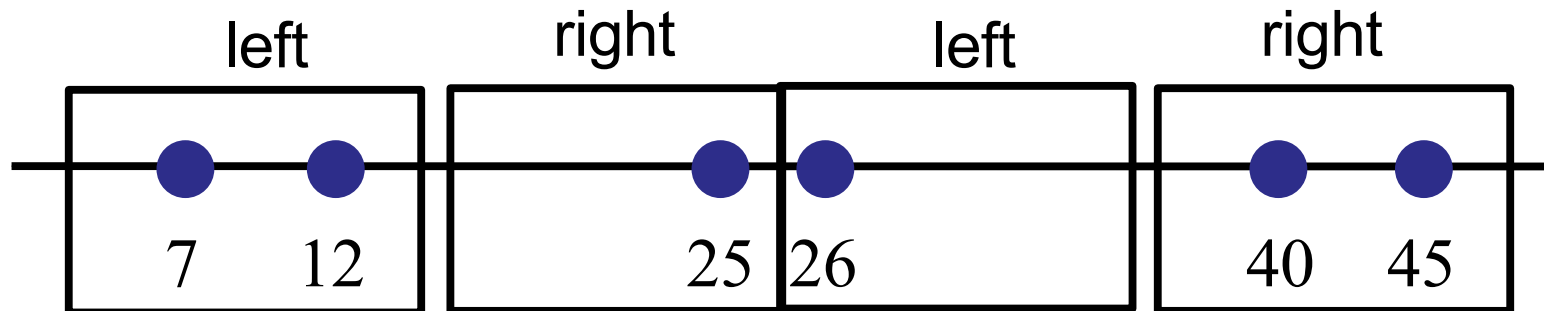
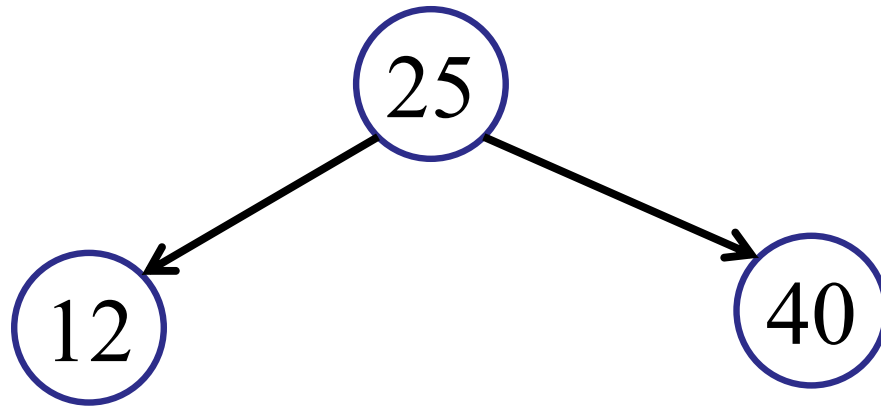
---

25



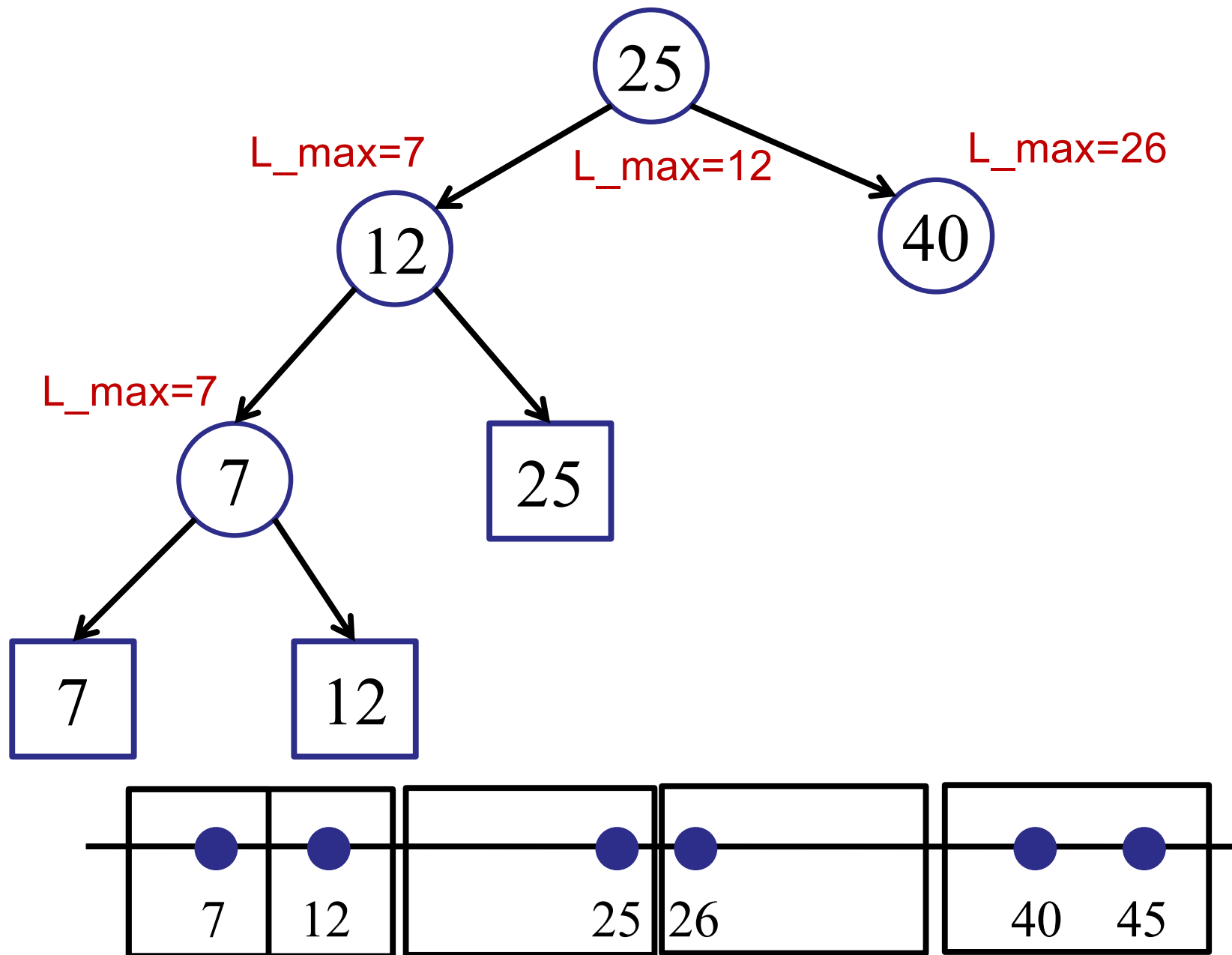
# Example

---



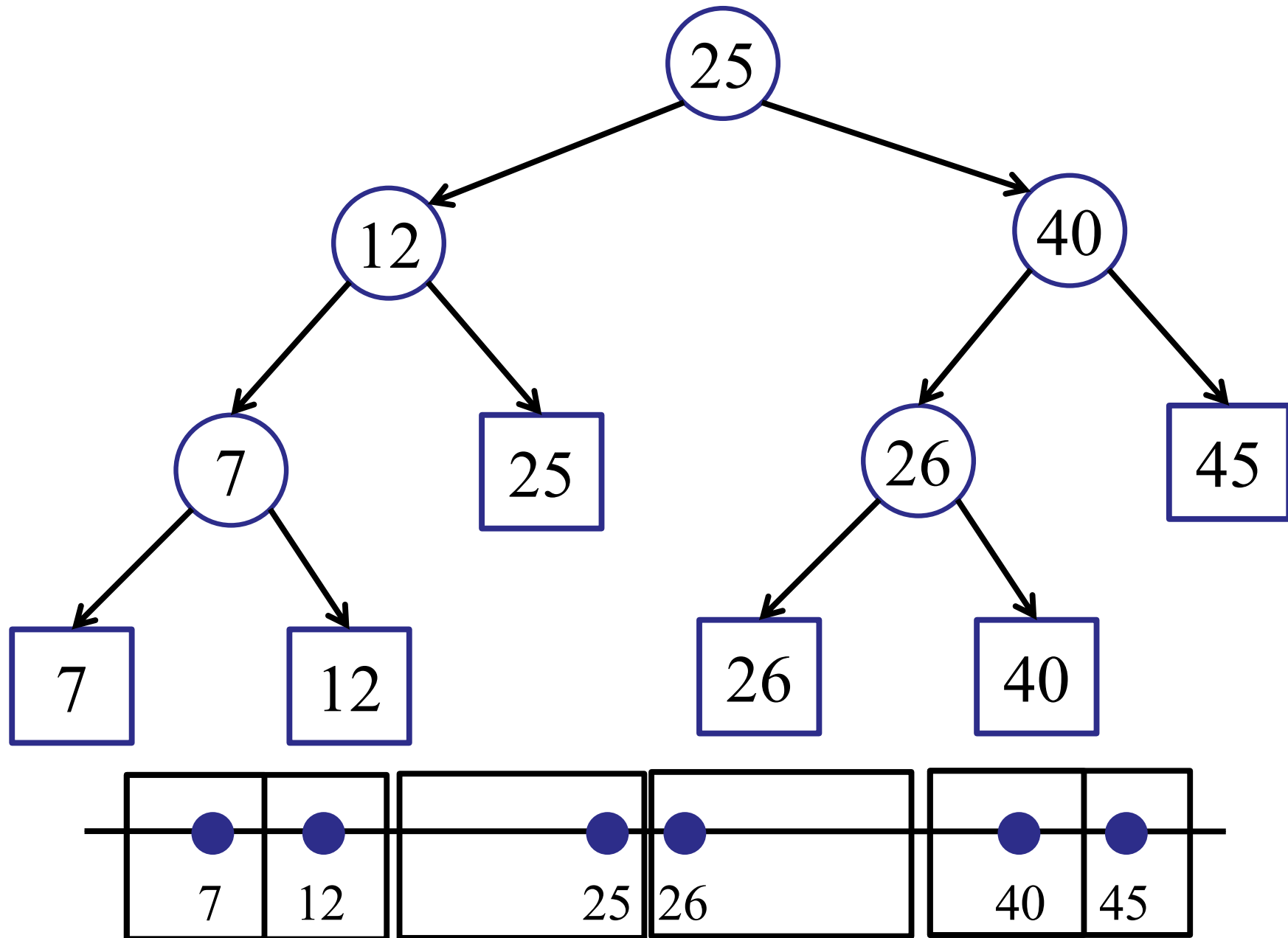
# Example

---



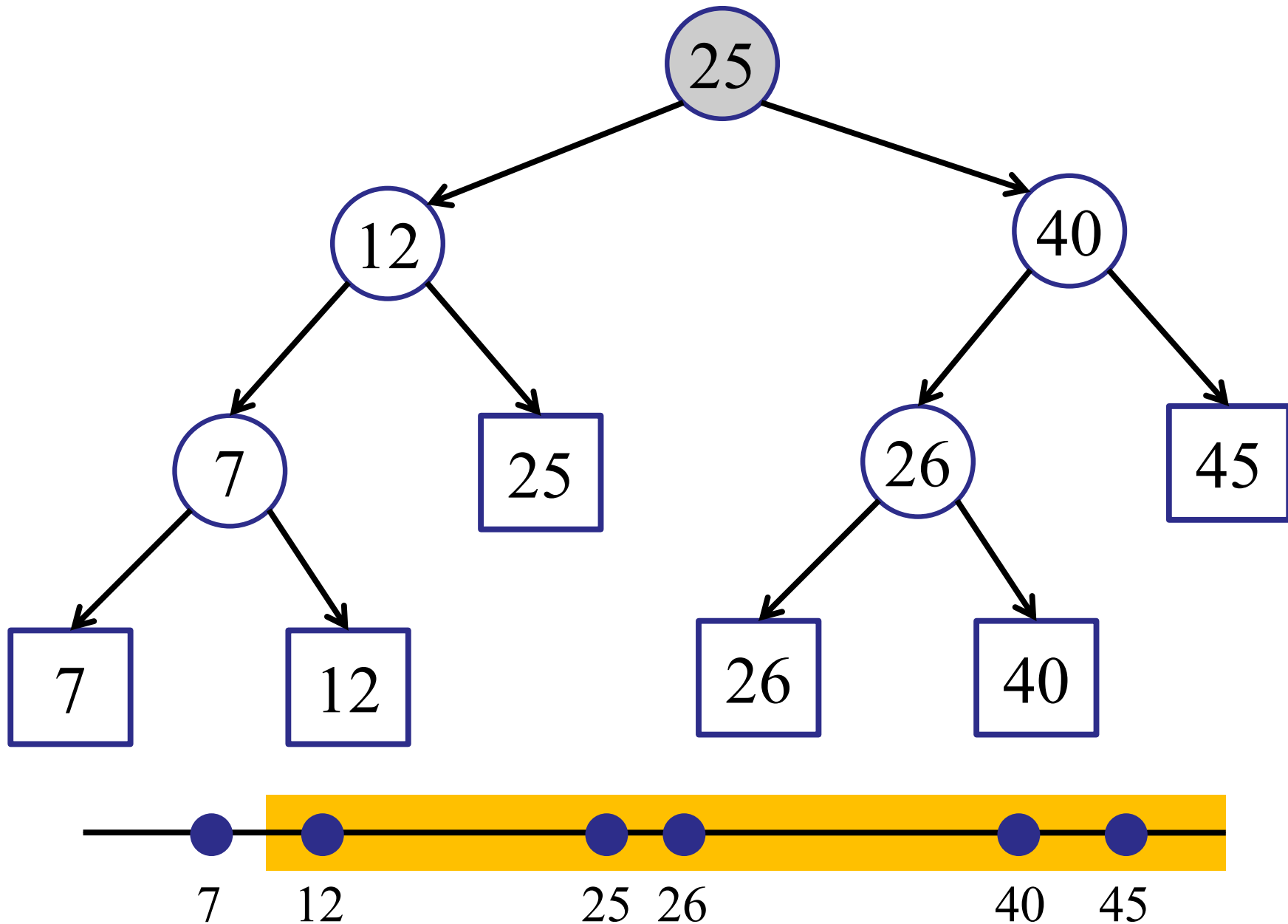
# Note: BST Property

---



# Example: query(10, 50)

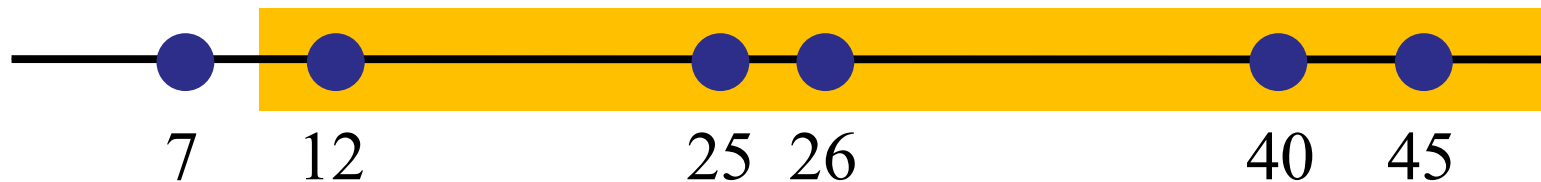
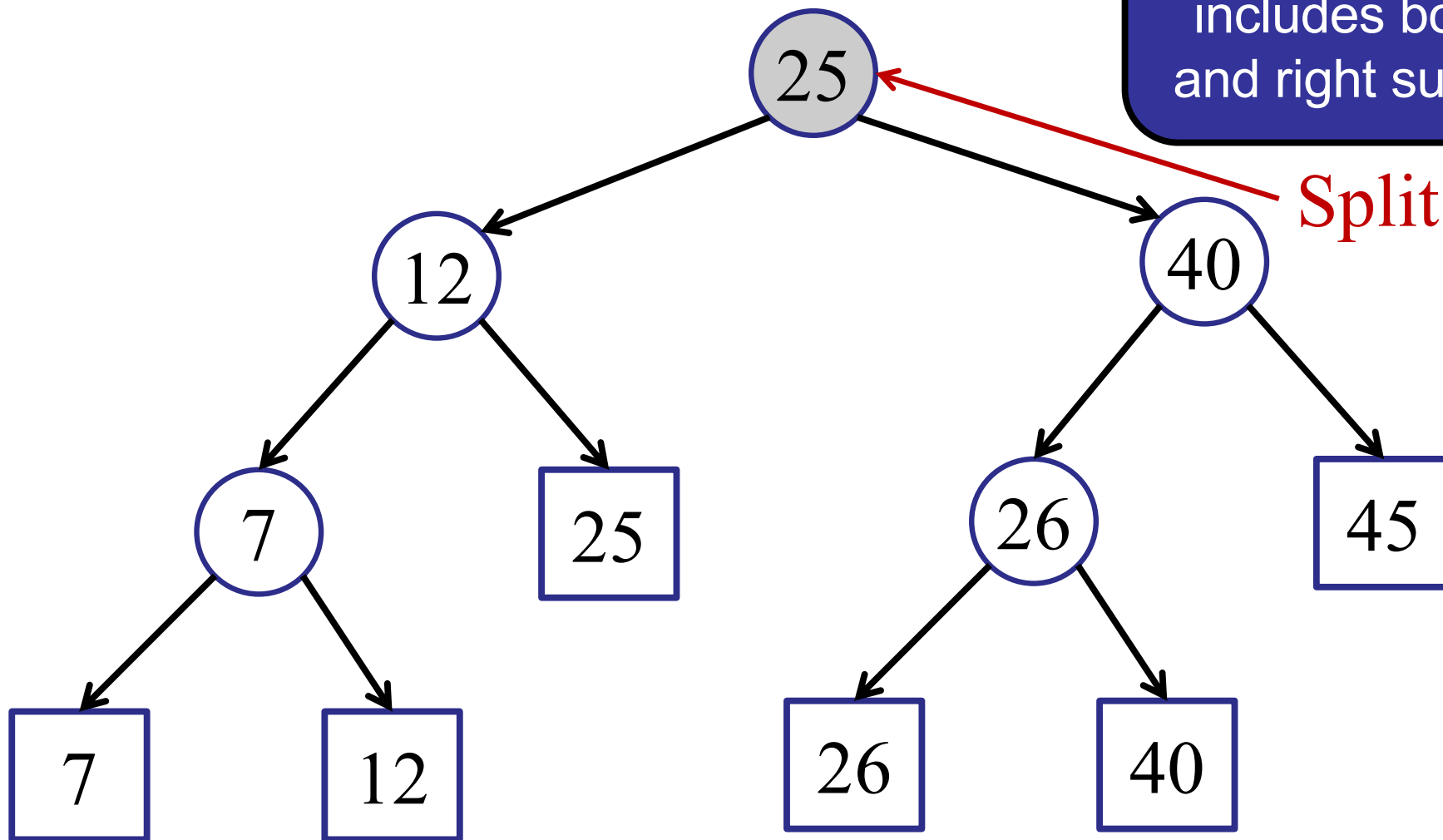
---



# Example: query(10, 50)

Highest node where search includes both left and right subtrees.

Split node

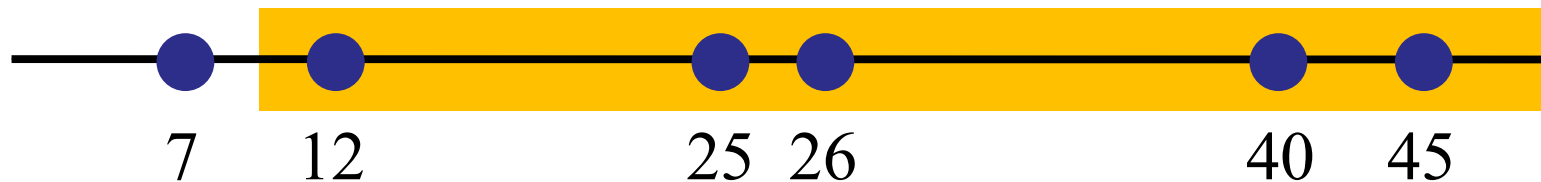
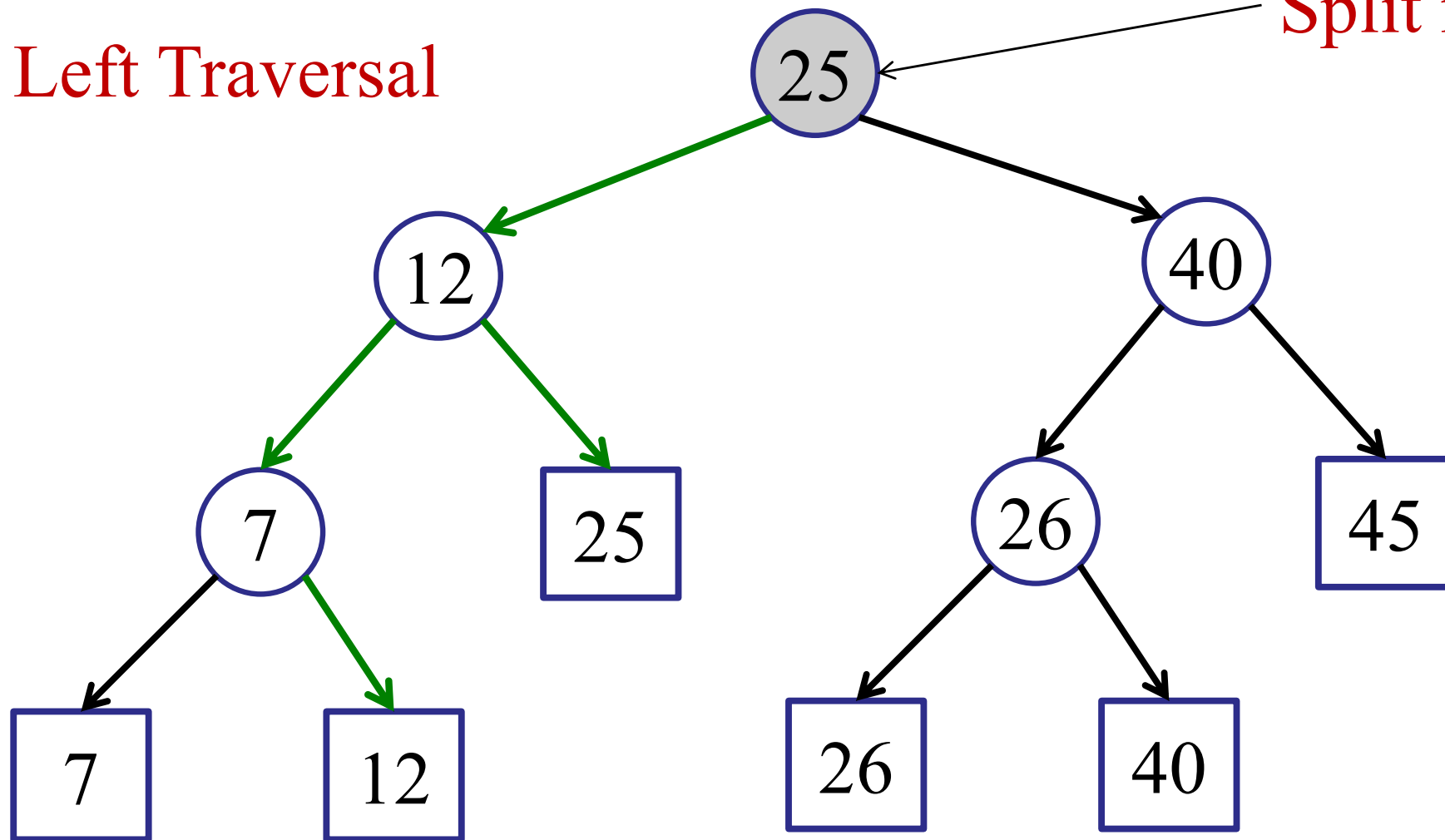




# Example: query(10, 50)

Left Traversal

Split node

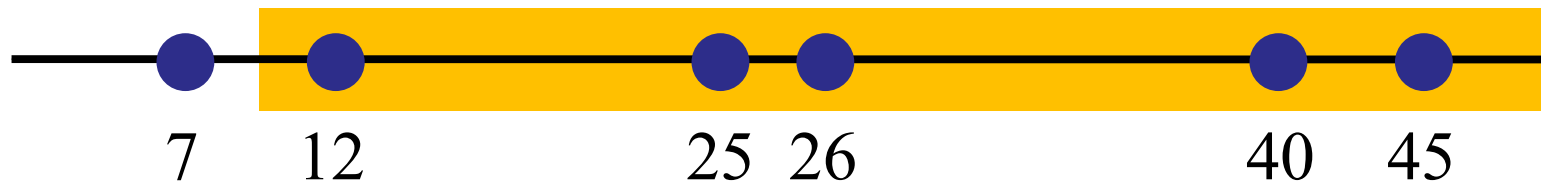
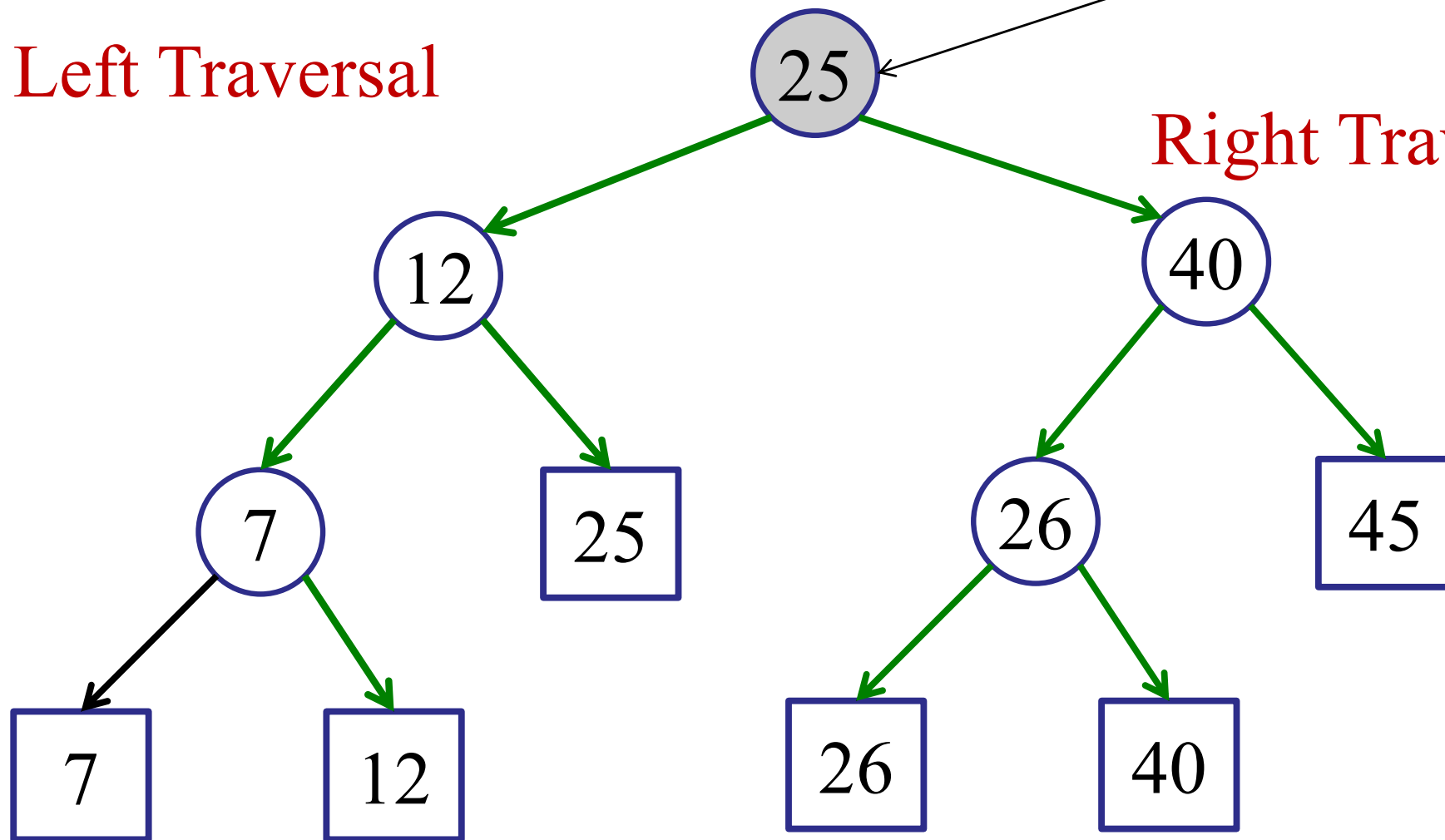


# Example: query(10, 50)

Left Traversal

Split node

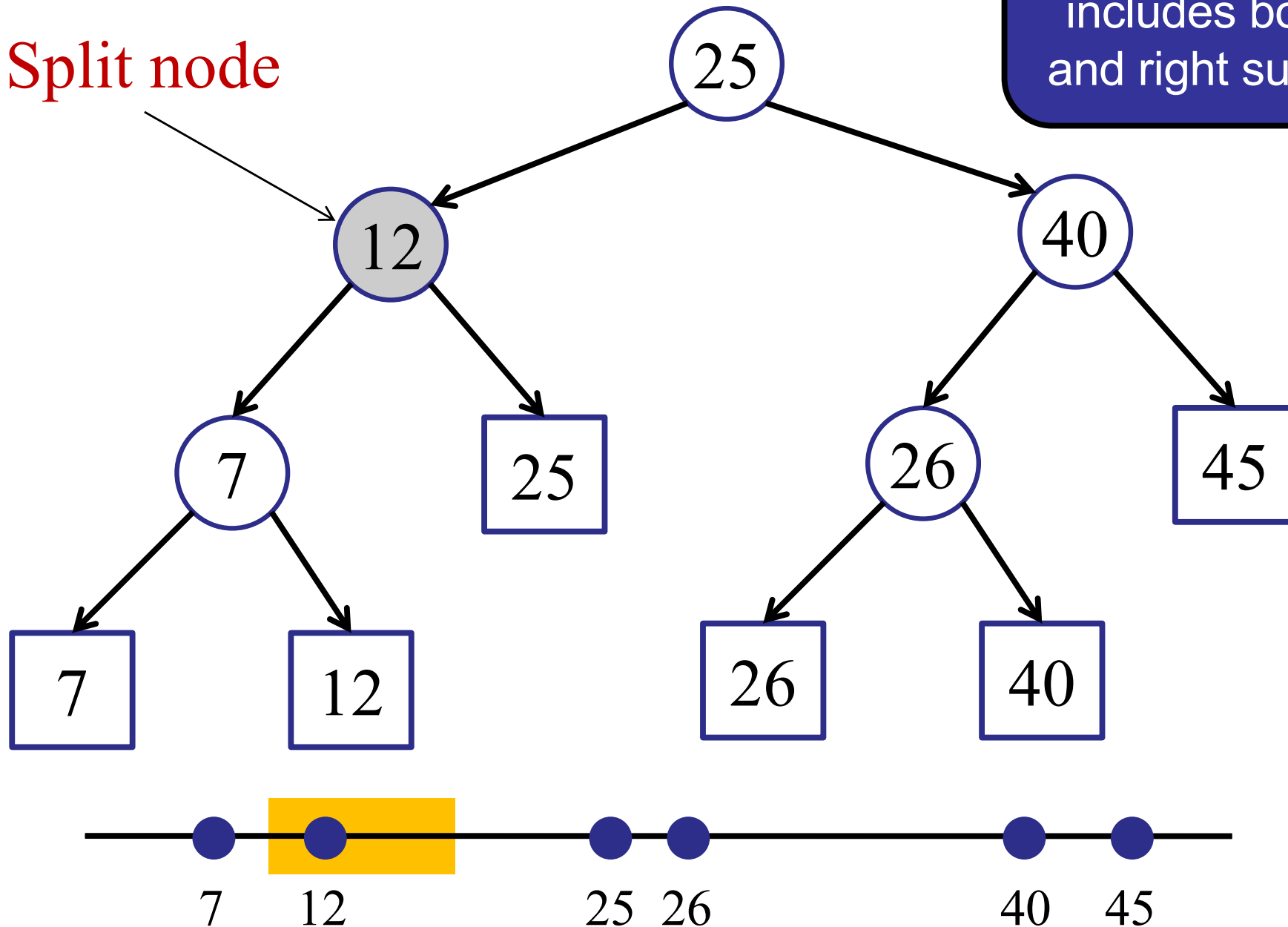
Right Traversal



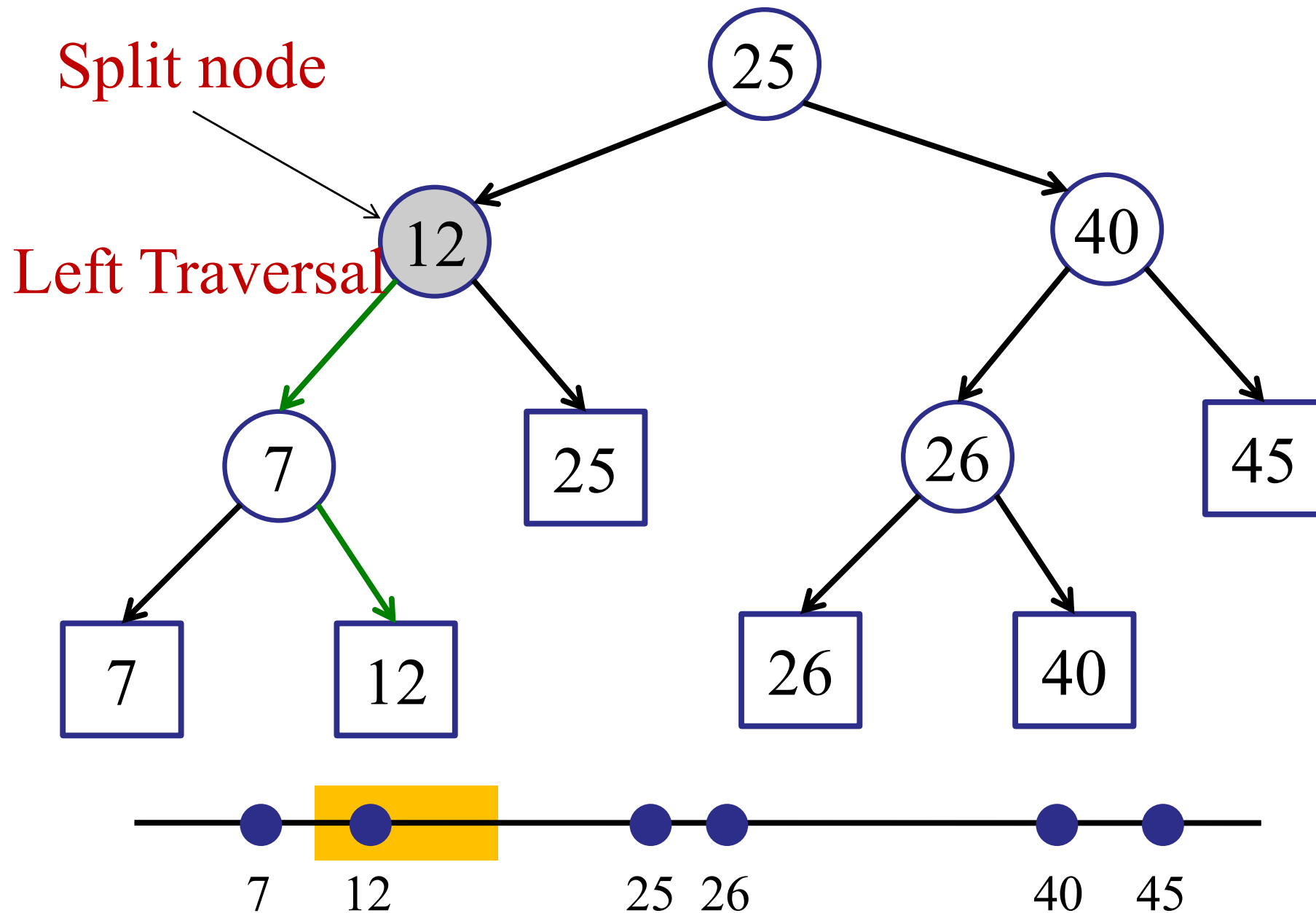
# Example: query(8, 20)

Highest node where search includes both left and right subtrees.

Split node



# Example: query(8, 20)

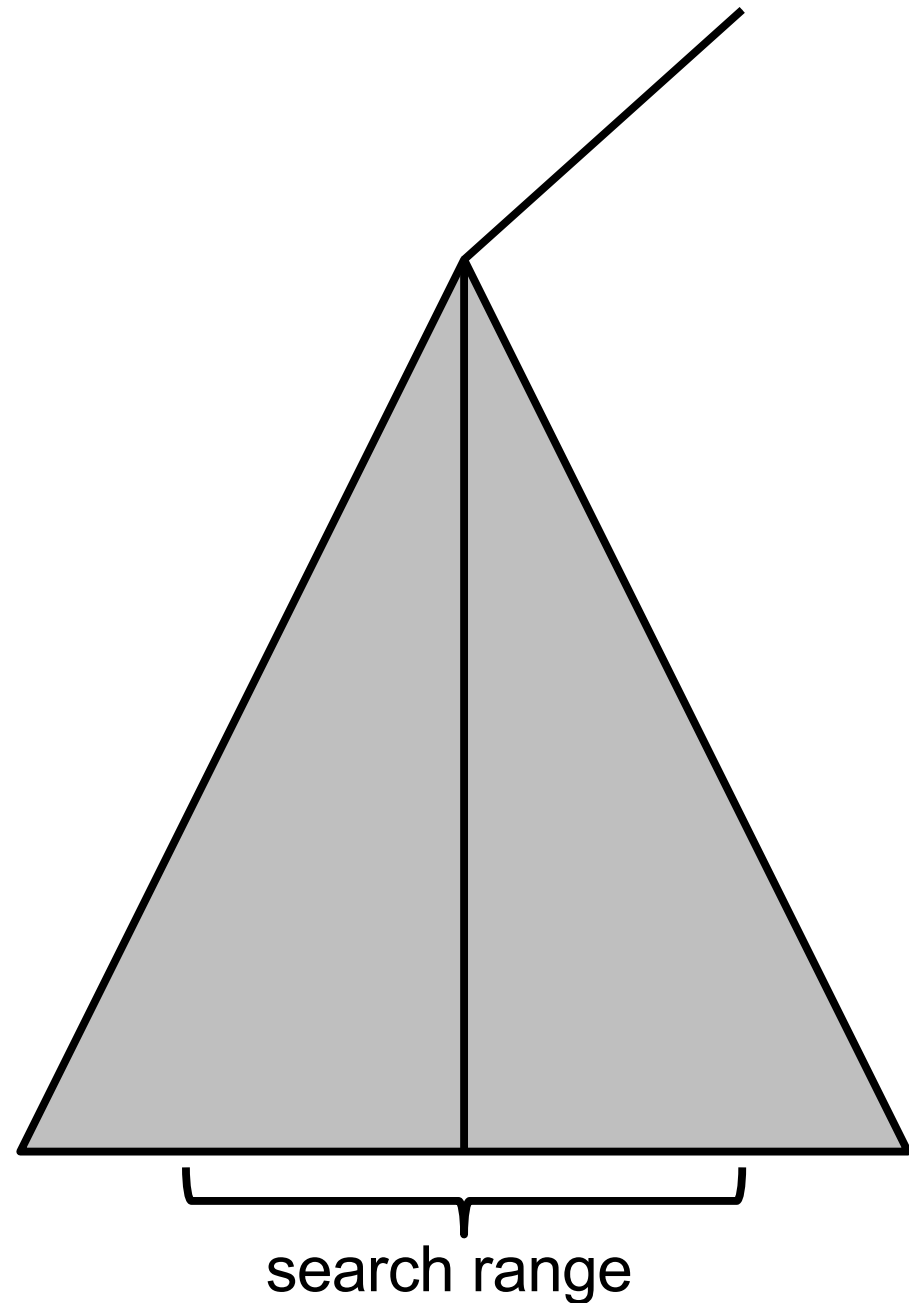


# One Dimensional Range Queries

---

Algorithm:

- Find “split” node.
- Do left traversal.
- Do right traversal.

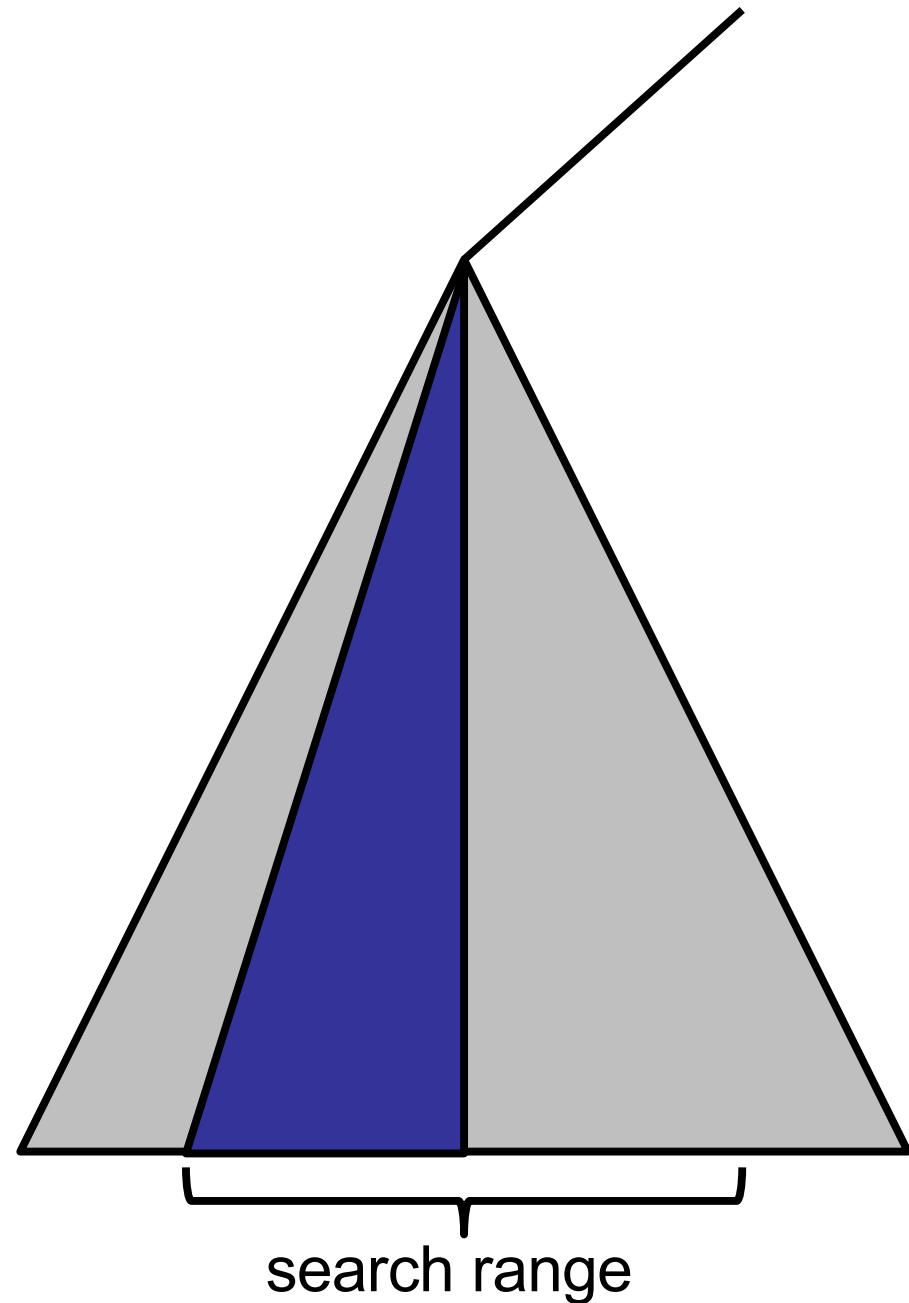


# One Dimensional Range Queries

---

Algorithm:

- Find “split” node.
- Do left traversal.
- Do right traversal.

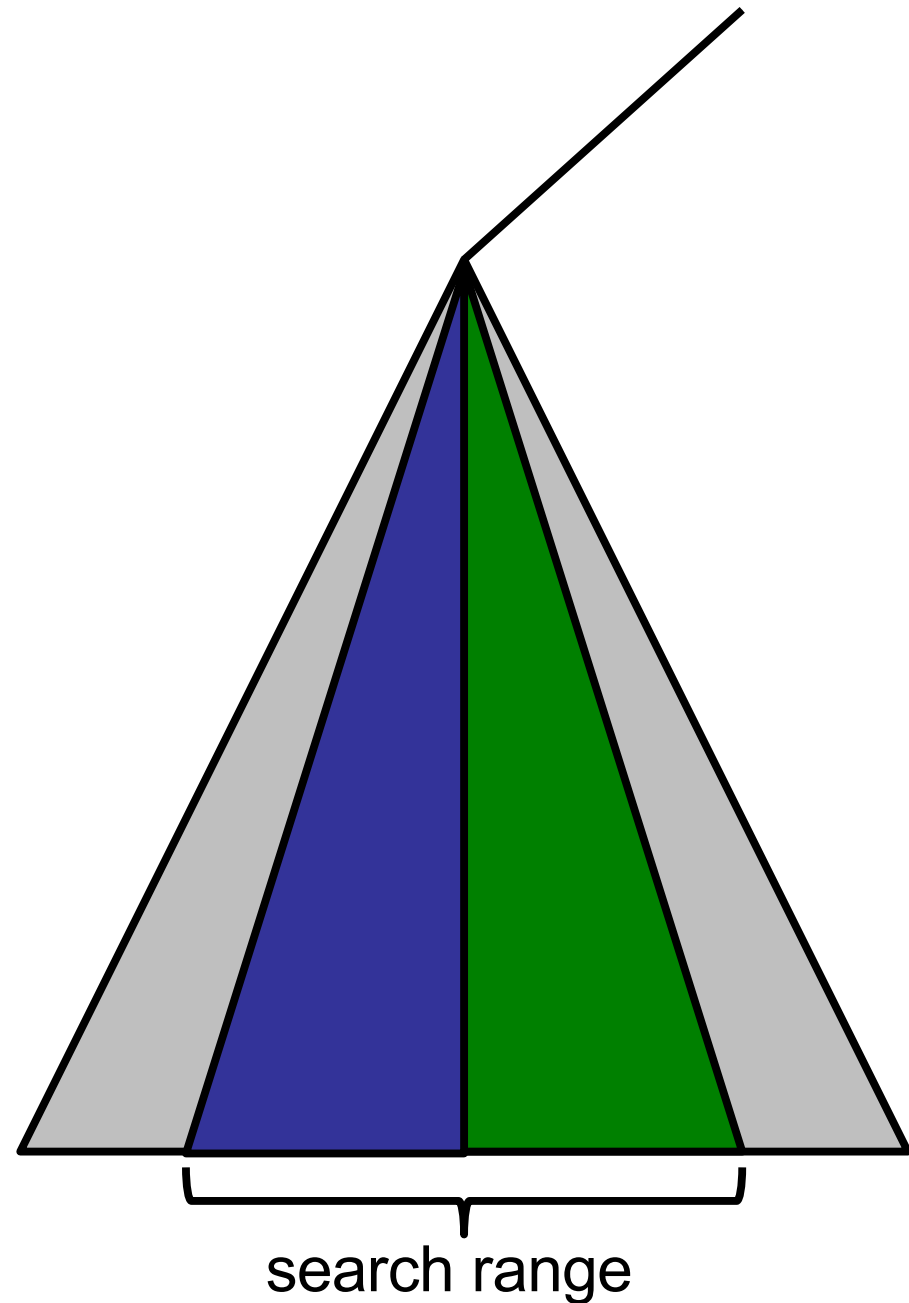


# One Dimensional Range Queries

---

Algorithm:

- Find “split” node.
- Do left traversal.
- Do right traversal.



# One Dimensional Range Queries

---

FindSplit(low, high)

v = root;

done = false;

while !done {

    if (high <= v.key) then v=v.left;

    else if (low > v.key) then v=v.right;

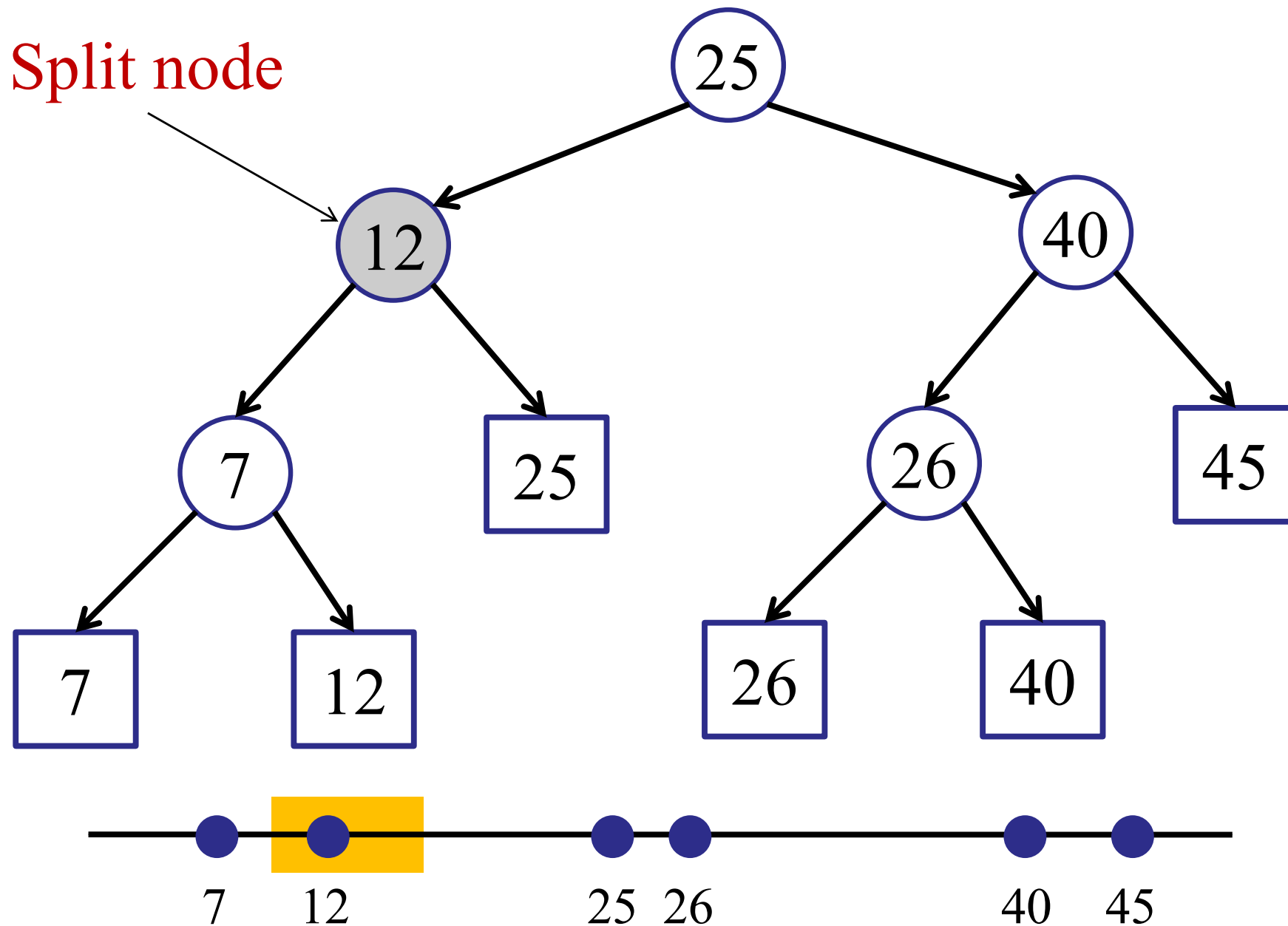
    else (done = true);

}

return v;



# Example: query(8, 20)



# One Dimensional Range Queries

---

Algorithm:

- $v = \text{FindSplit}(\text{low}, \text{high});$
- $\text{LeftTraversal}(v, \text{low}, \text{high});$
- $\text{RightTraversal}(v, \text{low}, \text{high});$

# One Dimensional Range Queries

---

LeftTraversal(v, low, high)

if (low <= v.key) {

all-leaf-traversal(v.right);

LeftTraversal(v.left, low, high);

}

else {

LeftTraversal(v.right, low, high);

}

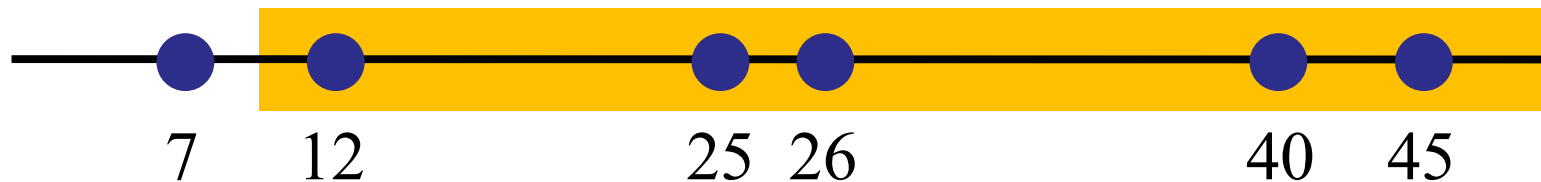
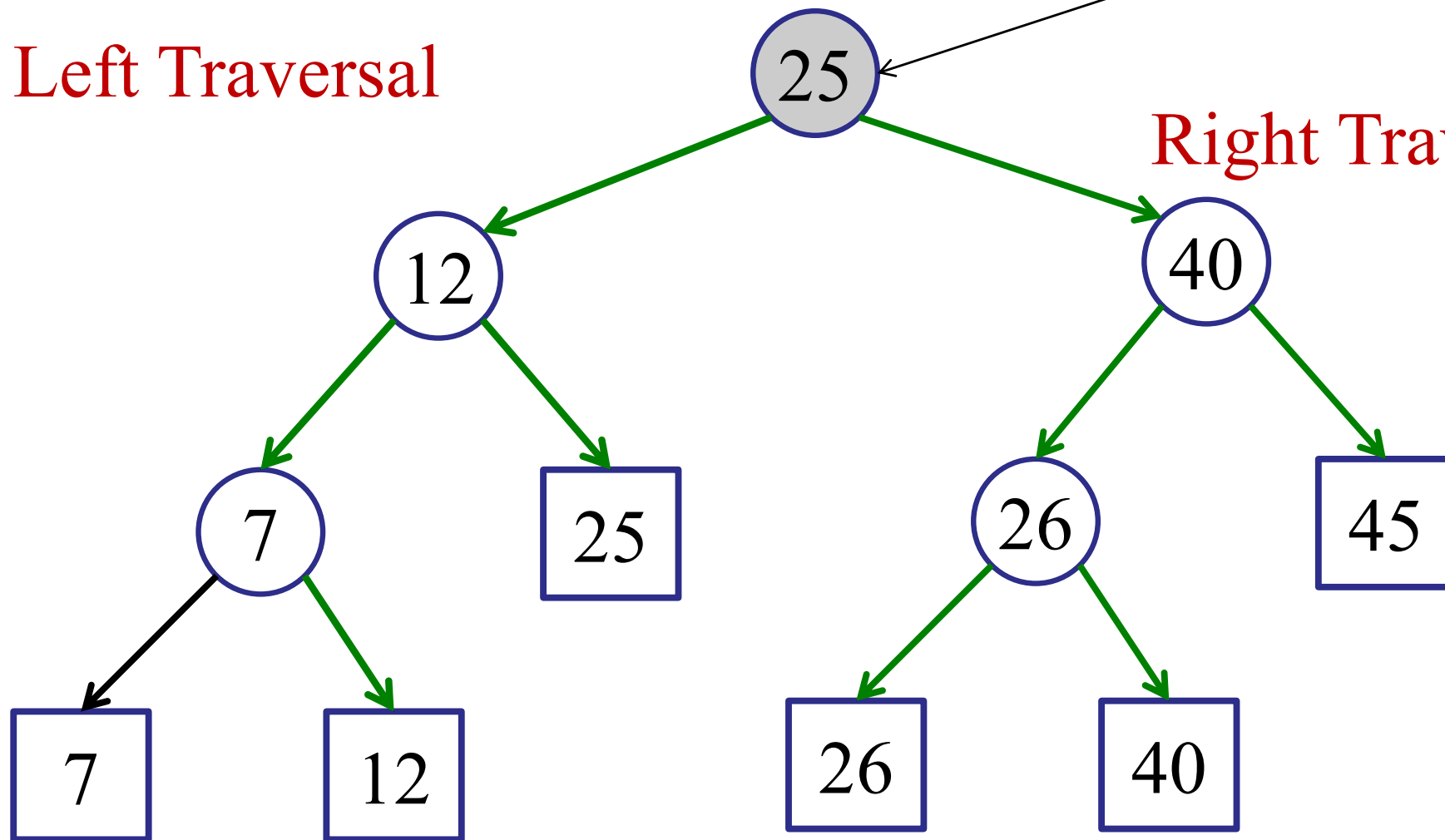
}

# Example: query(10, 50)

Left Traversal

Split node

Right Traversal

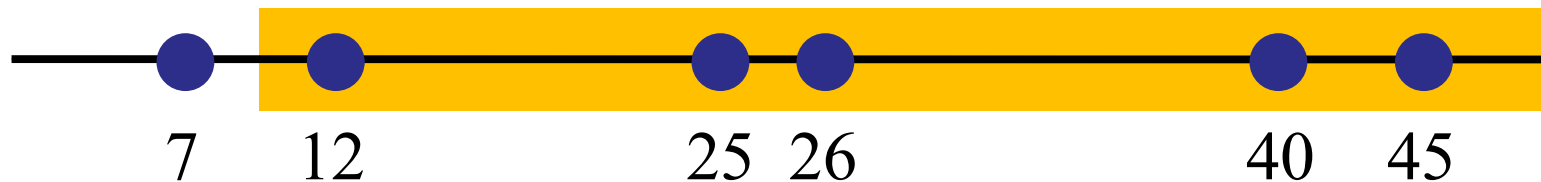
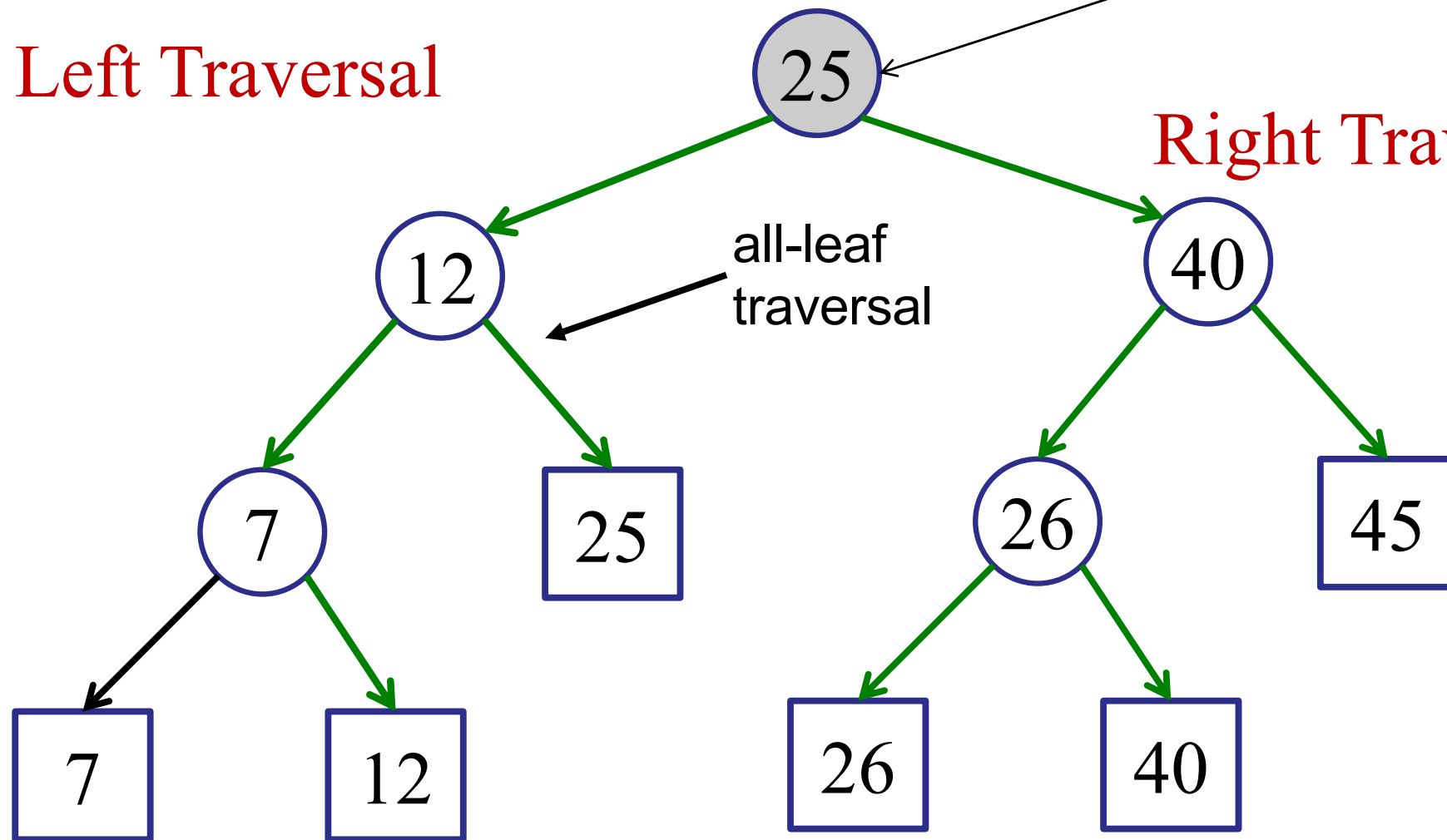


# Example: query(10, 50)

Left Traversal

Split node

Right Traversal

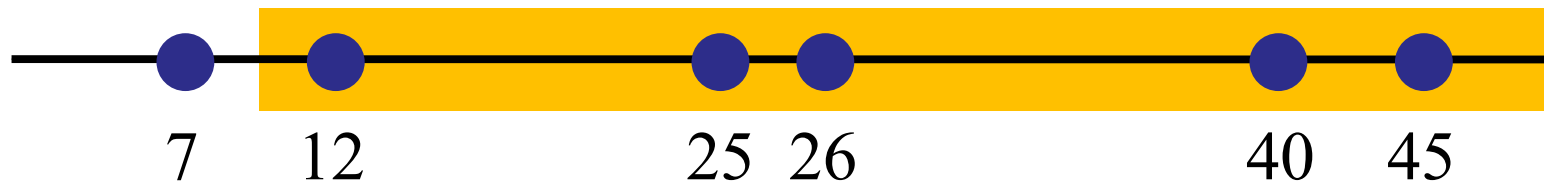
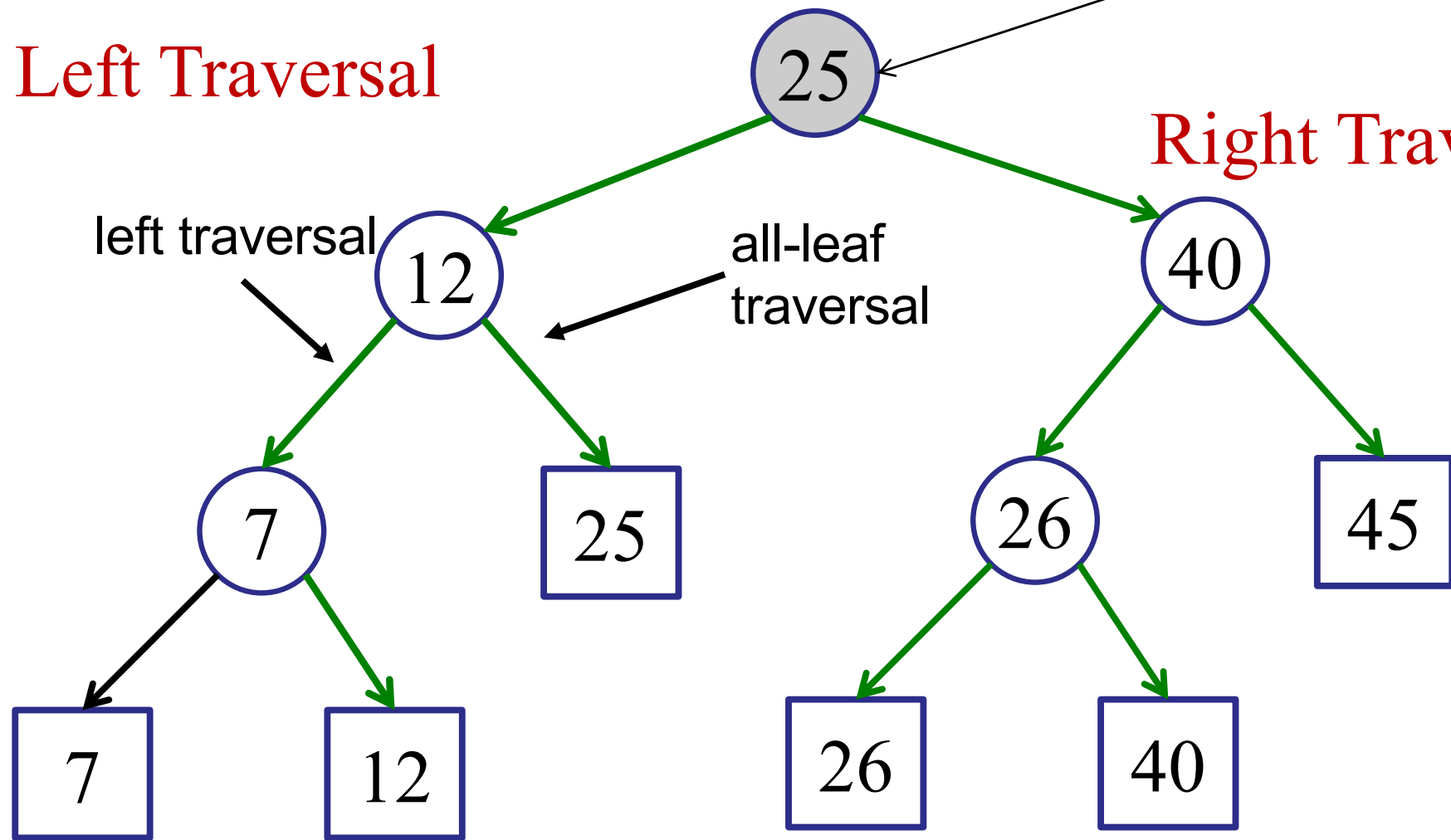


# Example: query(10, 50)

Split node

Left Traversal

Right Traversal



# One Dimensional Range Queries

---

Invariant:

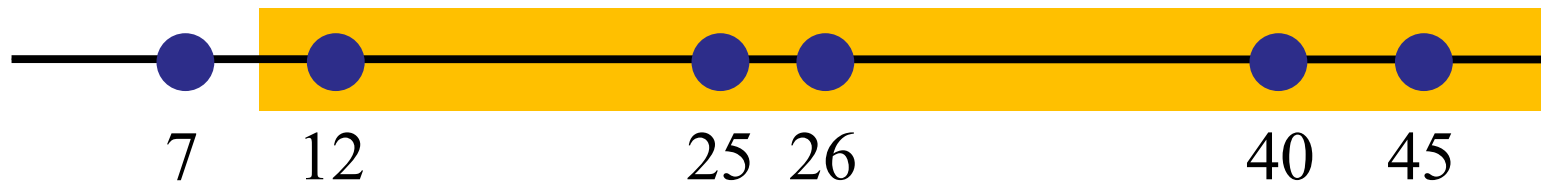
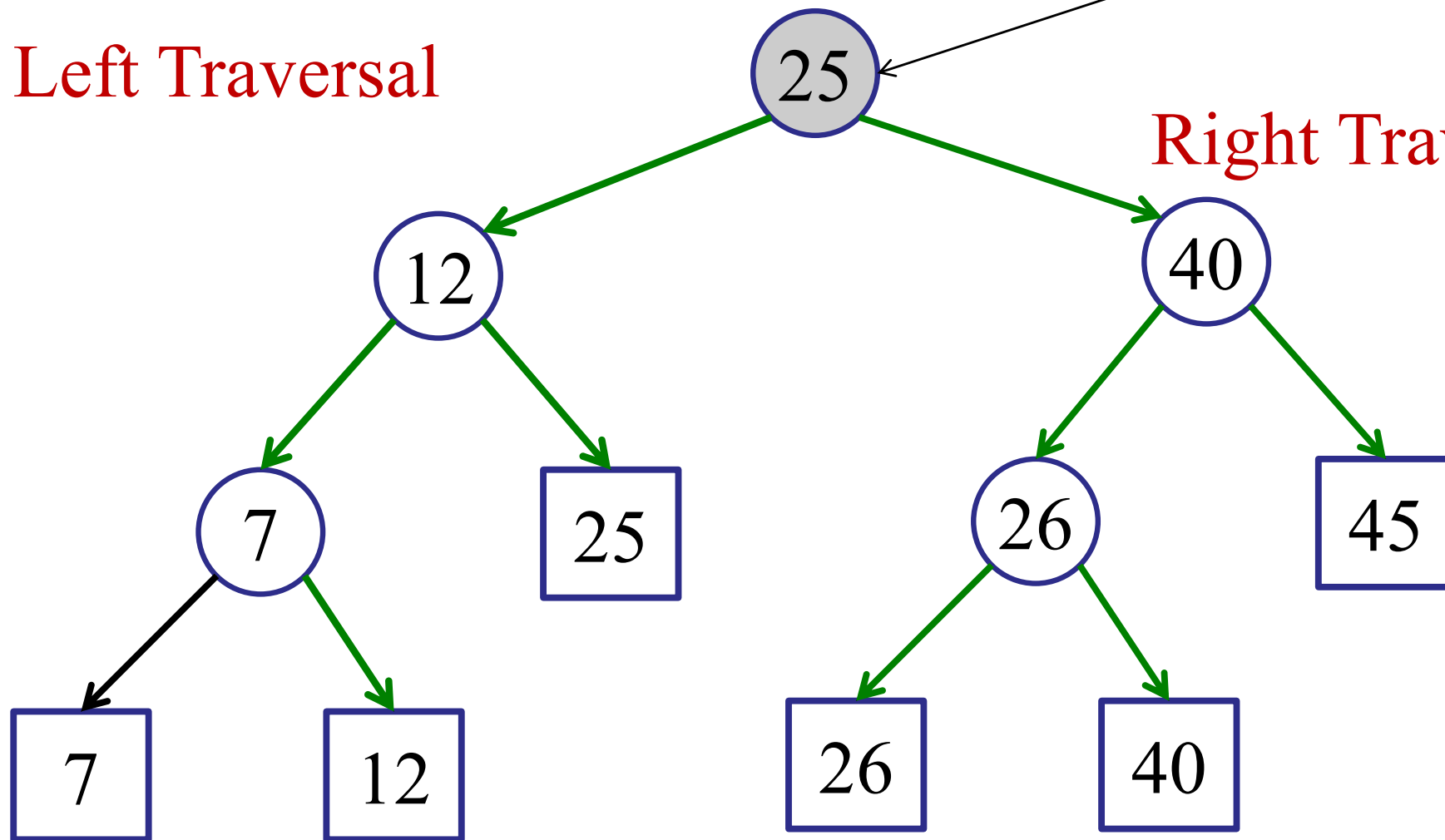
The search interval for a left-traversal at node  $v$  includes the maximum item in the subtree rooted at  $v$ .

# Example: query(10, 50)

Left Traversal

Split node

Right Traversal





# One Dimensional Range Queries

---

LeftTraversal(v, low, high)

if (low <= v.key) {

all-leaf-traversal(v.right);

LeftTraversal(v.left, low, high);

}

else {

LeftTraversal(v.right, low, high);

}

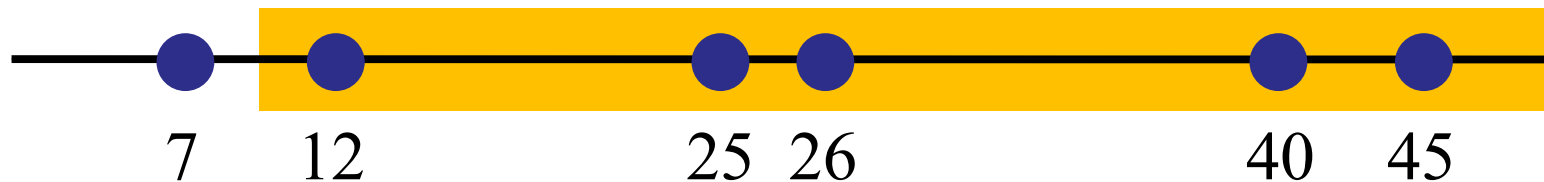
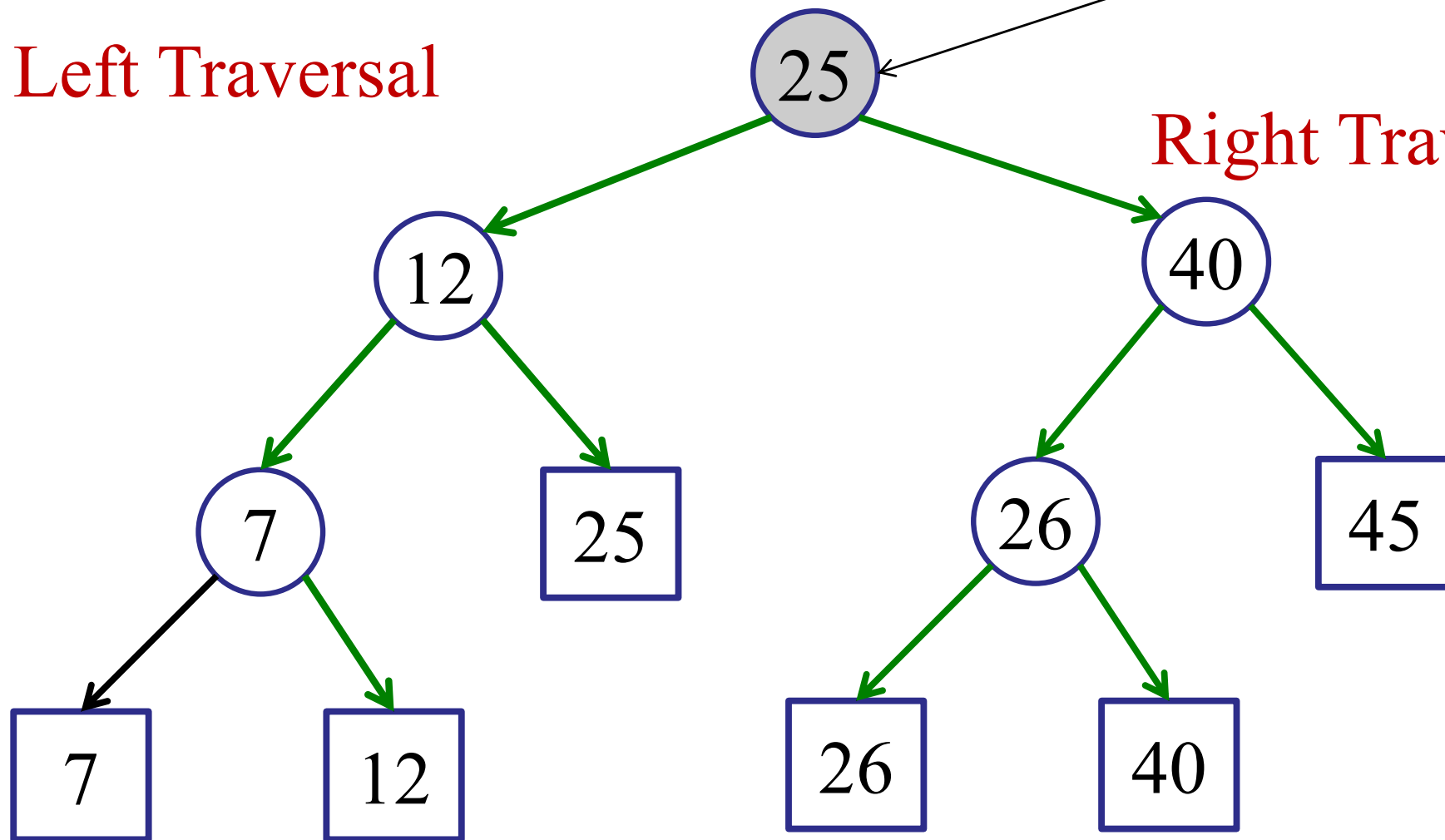
}

# Example: query(10, 50)

Left Traversal

Split node

Right Traversal



# One Dimensional Range Queries

---

```
RightTraversal(v, low, high)
```

```
    if (v.key <= high) {
```

```
        all-leaf-traversal(v.left);
```

```
        RightTraversal(v.right, low, high);
```

```
    }
```

```
    else {
```

```
        RightTraversal(v.left, low, high);
```

```
    }
```

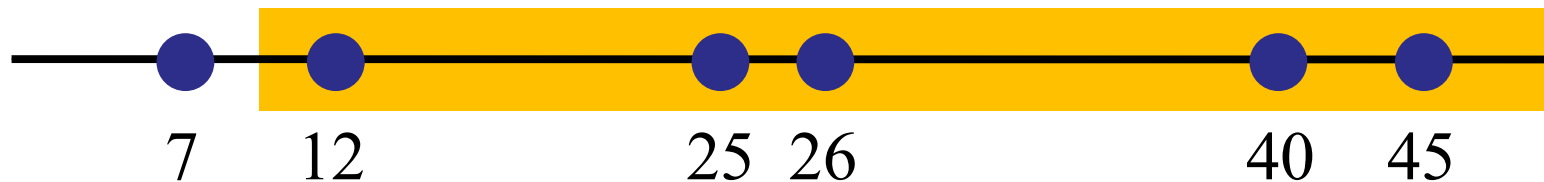
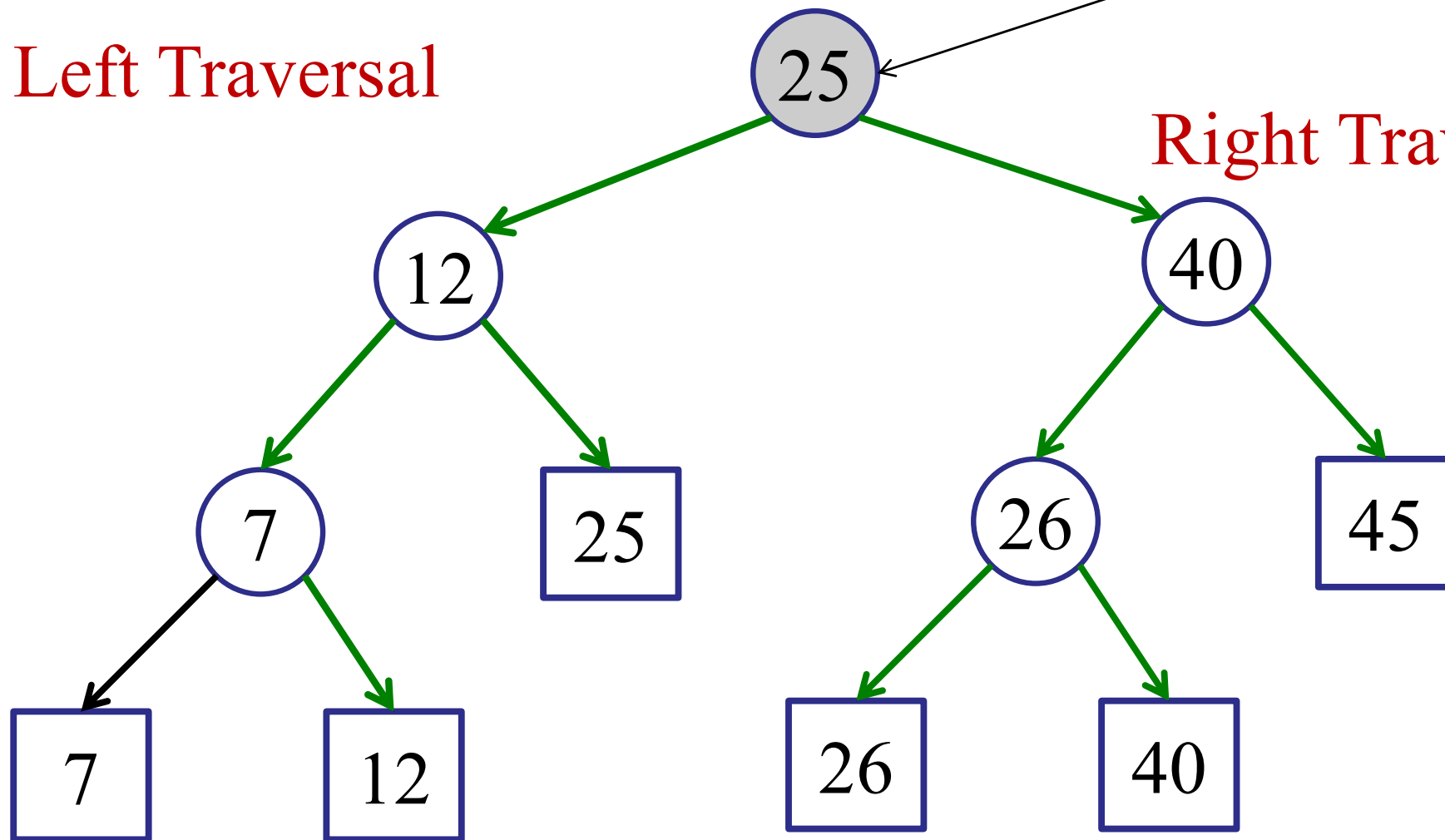
```
}
```

# Example: query(10, 50)

Left Traversal

Split node

Right Traversal



# One Dimensional Range Queries

---

Algorithm:

- $v = \text{FindSplit}(\text{low}, \text{high});$
- $\text{LeftTraversal}(v, \text{low}, \text{high});$
- $\text{RightTraversal}(v, \text{low}, \text{high});$

# Analysis

---

Query time:

- Finding split node:  $O(\log n)$
- Left Traversal:

At every step, we either:

1. Output all right sub-tree and recurse left.
2. Recurse right.

- Right Traversal:

At every step, we either:

1. Output all left sub-tree and recurse right.
2. Recurse left.

# Analysis

---

## Left Traversal:

At every step, we either:

1. Output all right sub-tree and recurse left.
2. Recurse right.

## Counting:

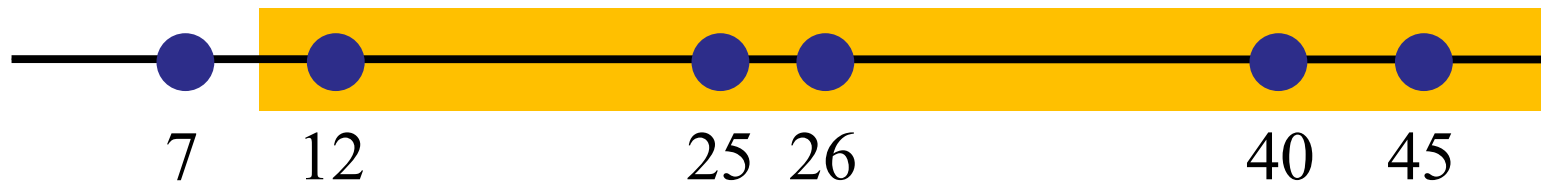
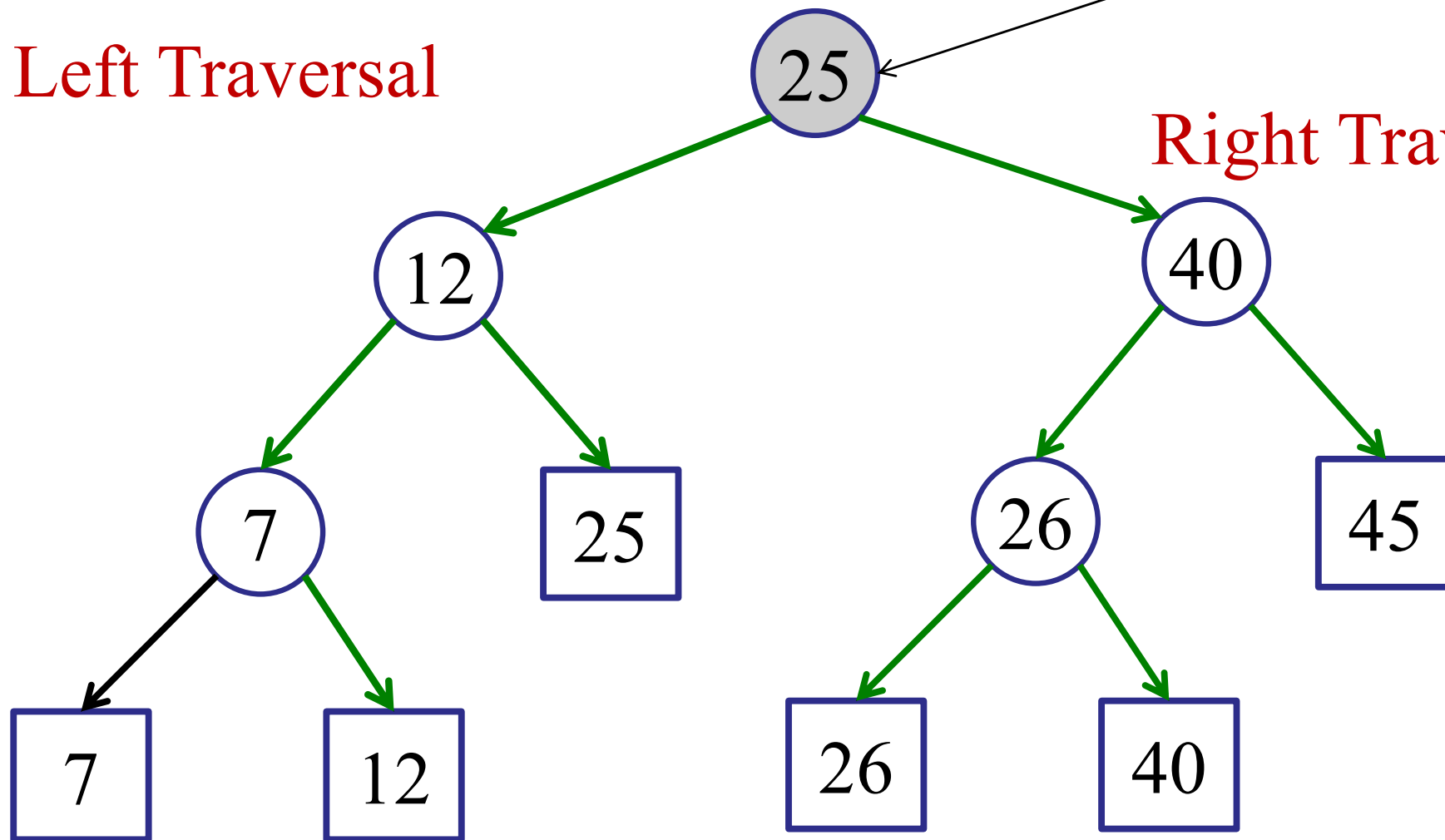
1. Recurse at most  $O(\log n)$  times (i.e., option 2).
2. How expensive is “output all sub-tree” (i.e., option 1)?

# Example: query(10, 50)

Left Traversal

Split node

Right Traversal





# Analysis

---

## Left Traversal:

At every step, we either:

1. Output all right sub-tree and recurse left.
2. Recurse right.

## Counting:

1. Recurse at most  $O(\log n)$  times (i.e., option 2).
2. How expensive is “output all sub-tree” (i.e., option 1)?  
→  $O(k)$ , where  $k$  is number of items found.

# Analysis

---

Query time complexity:

$$O(k + \log n)$$

where  $k$  is the number of points found.

Preprocessing (buildtree) time complexity:

$$O(n \log n)$$

Total space complexity:

$$O(n)$$

# One Dimensional Range Queries

---

What if you just want to know *how many* points are in the range?

# One Dimensional Range Queries

---

What if you just want to know *how many* points are in the range?

- Augment the tree!
- Keep a count of the number of nodes in each sub-tree.
- Instead of walking entire sub-tree, just remember the count.

# One Dimensional Range Queries

---

LeftTraversal(v, low, high)

if (low <= v.key) {

~~all-leaf-traversal(v.right);~~

total += v.right.count;

LeftTraversal(v.left, low, high);

}

else {

LeftTraversal(v.right, low, high);

}

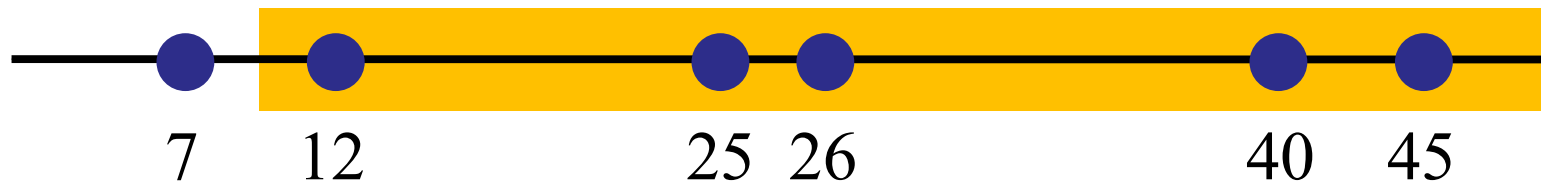
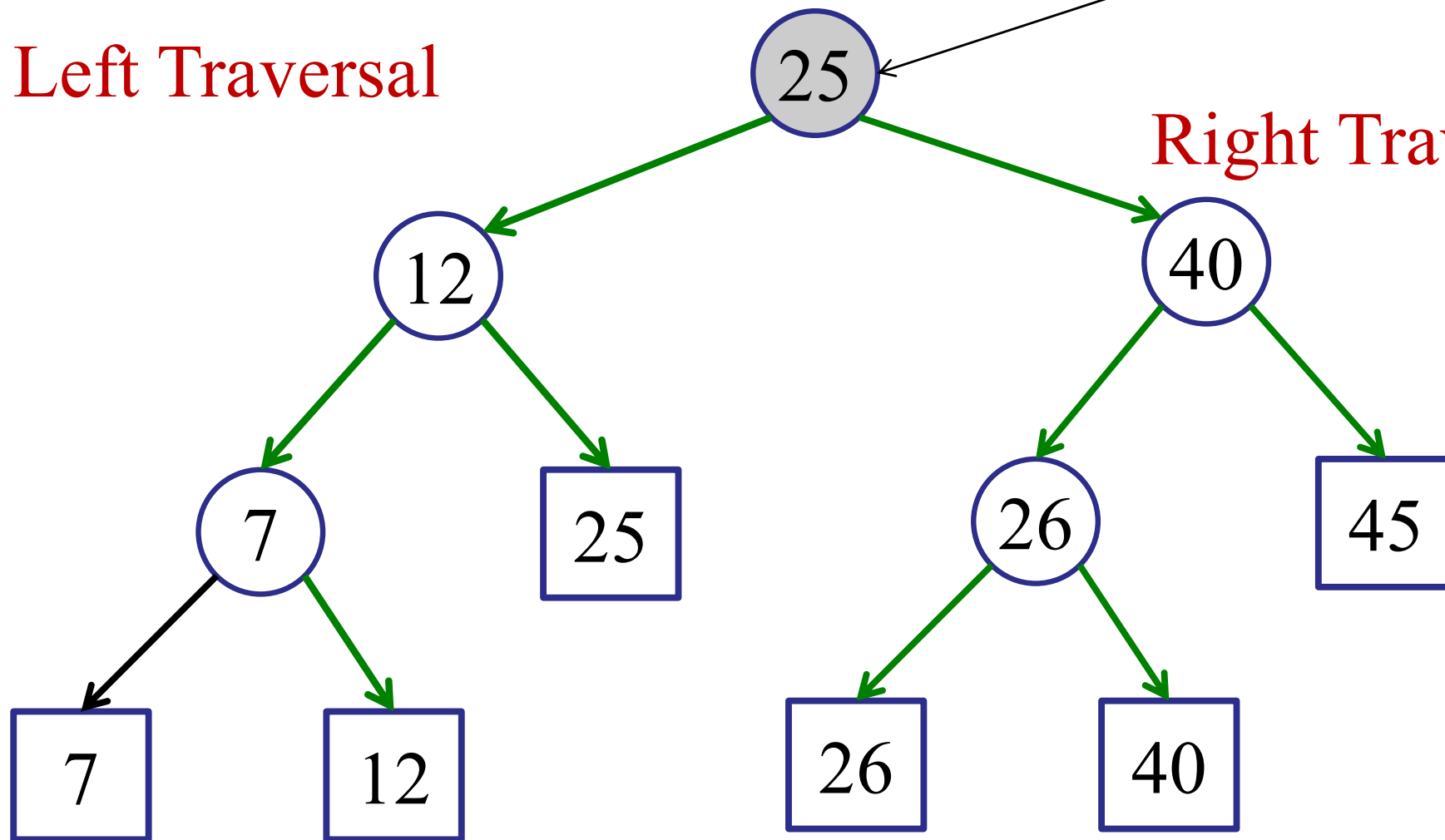
}

# Example: query(10, 50)

Left Traversal

Split node

Right Traversal



# 1D Range Tree

---

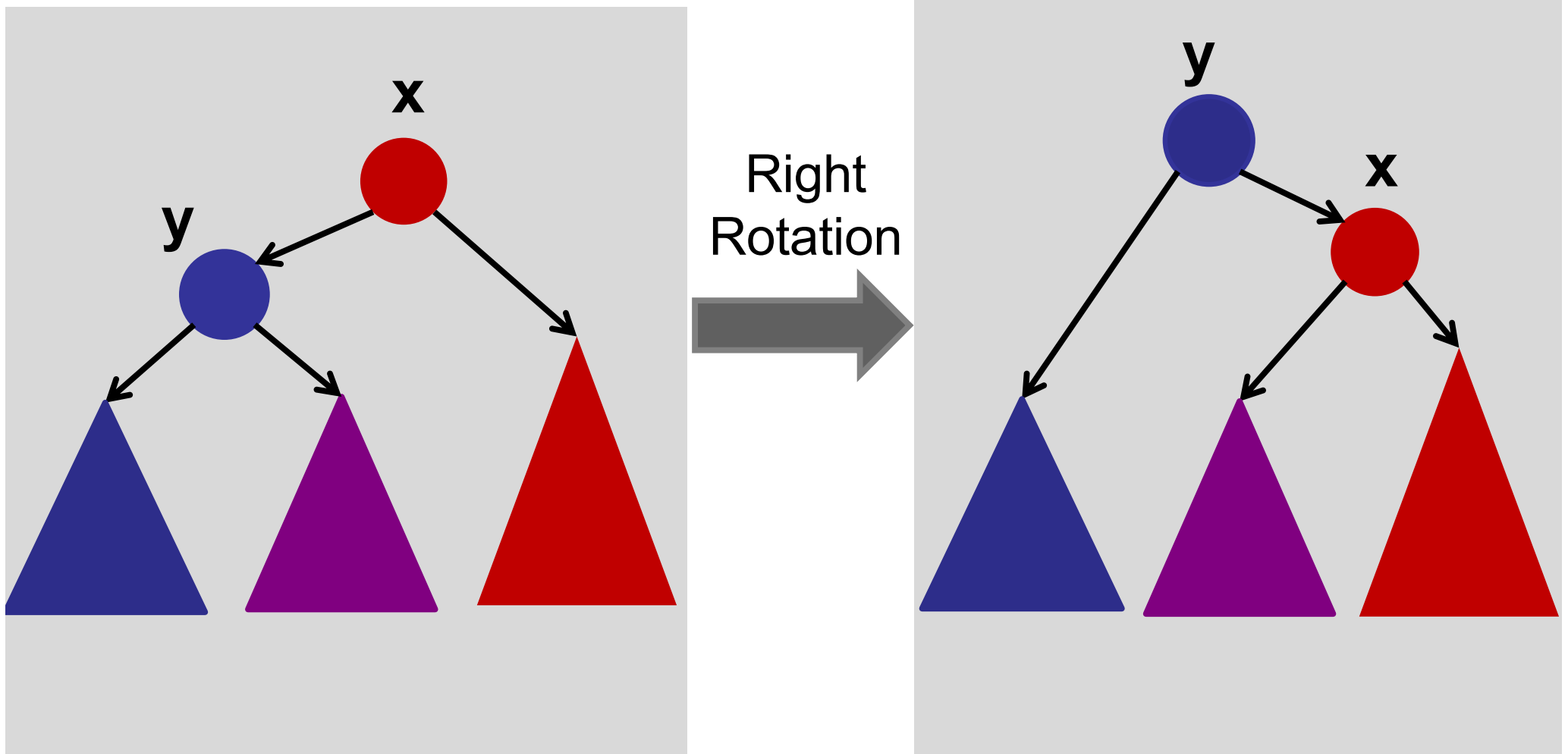
Done??

# One Dimensional Range Queries

---

What about dynamic updates?

- Need to fix rotations! Any changes needed?

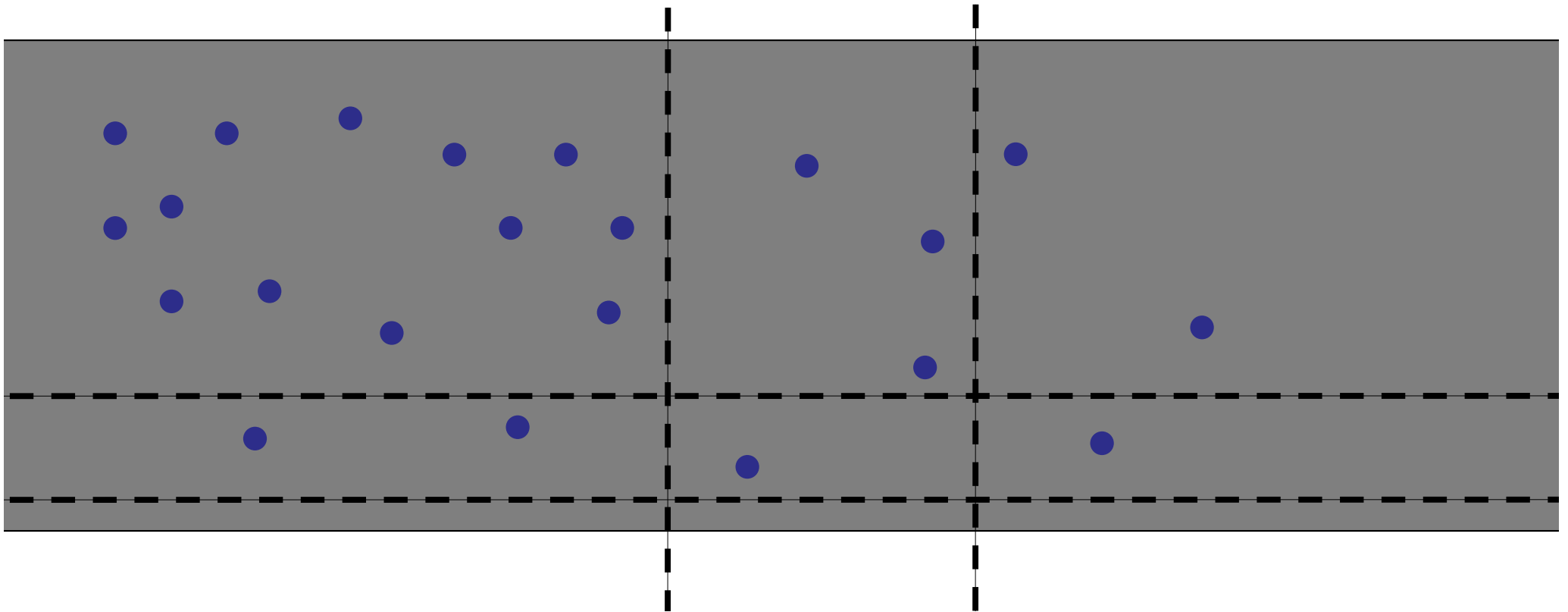




# Two Dimensional Range Tree

---

Ex: search for all points between dashed lines.



# Two Dimensional Range Tree

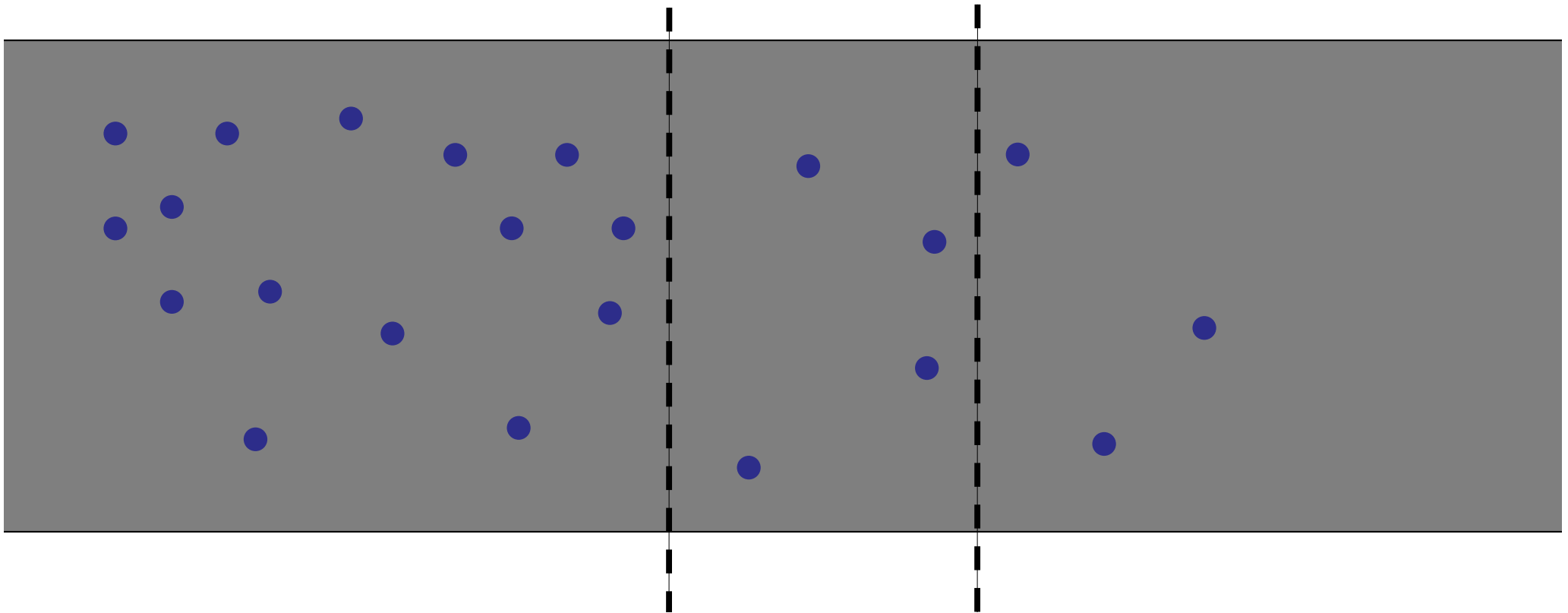
---

Idea:

Step 1: Create a 1d-range-tree on the x-coords.

Step 2: Enumerate all points in range, sort.

Step 3: Return only points in the y-range.



# Two Dimensional Range Tree

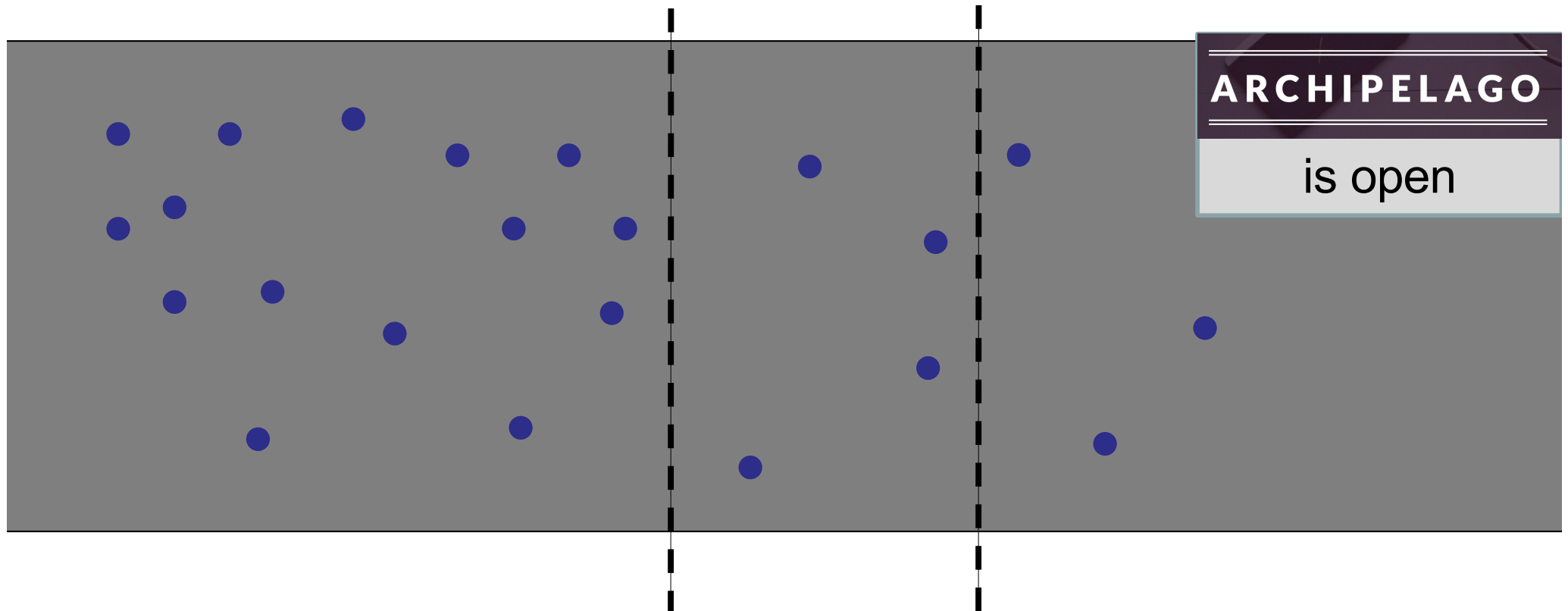
---

Idea:

Step 1: Create a 1d-range-tree on the x-coords.

Step 2: Enumerate all points in range, sort.

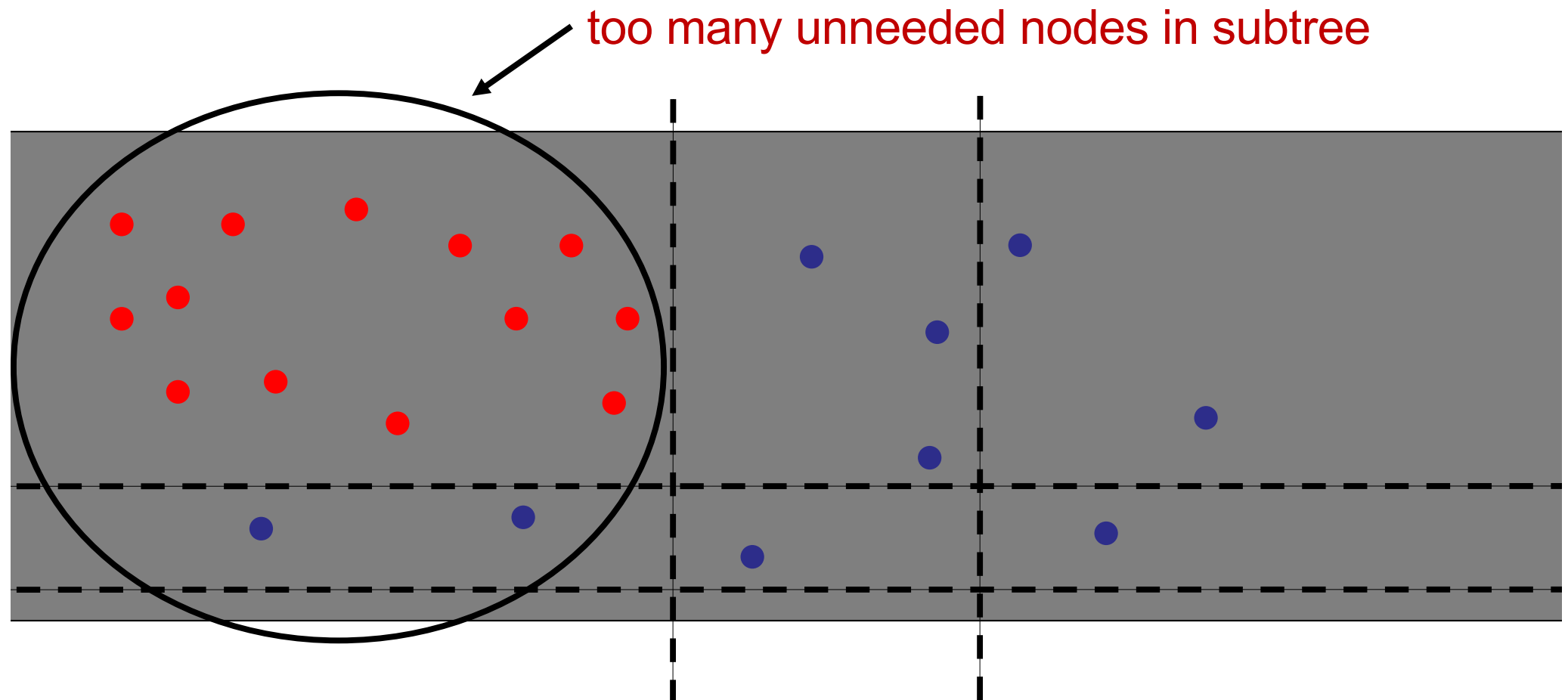
Step 3: Return only points in the y-range.



# Two Dimensional Range Tree

---

**Problem:** can't enumerate entire sub-trees, since there may be too many nodes that don't satisfy the y-restriction.



# One Dimensional Range Queries

---

```
LeftTraversal(v, low, high)
```

```
    if (v.key >= low) {
```

```
        all-leaf-traversal(v.right);
```

```
        LeftTraversal(v.left, low, high);
```

```
    }
```

```
    else {
```

```
        LeftTraversal(v.right, low, high);
```

```
    }
```

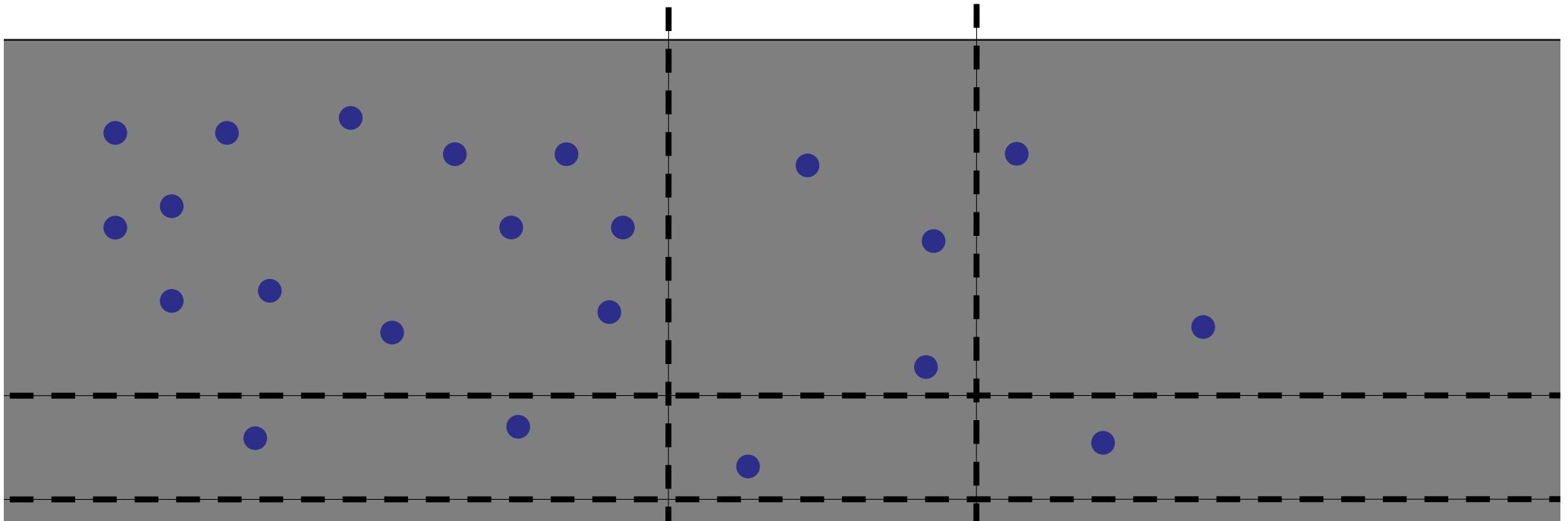
```
}
```

# Two Dimensional Range Tree

---

**Solution:** Augment!

- Each node in the x-tree has a set of points in its sub-tree.
- Store a y-tree at each x-node containing all the points in the sub-tree.

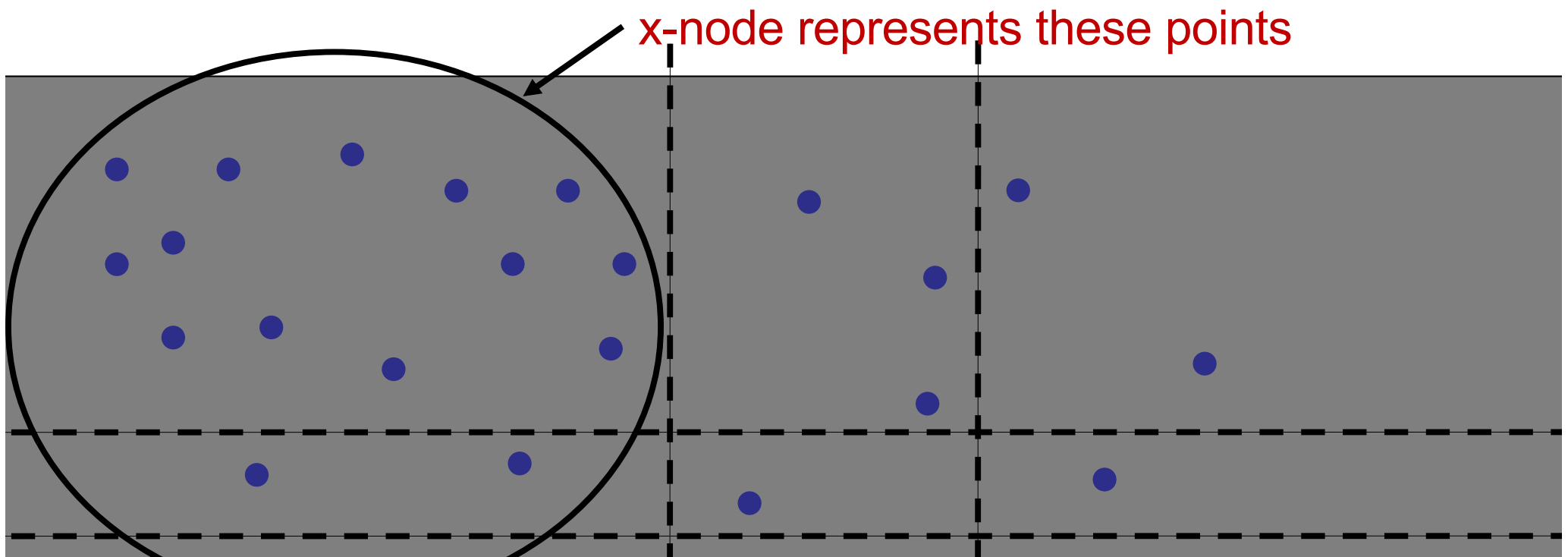


# Two Dimensional Range Tree

---

**Solution:** Augment!

- Each node in the x-tree has a set of points in its sub-tree.
- Store a y-tree at each x-node containing all the points in the sub-tree.

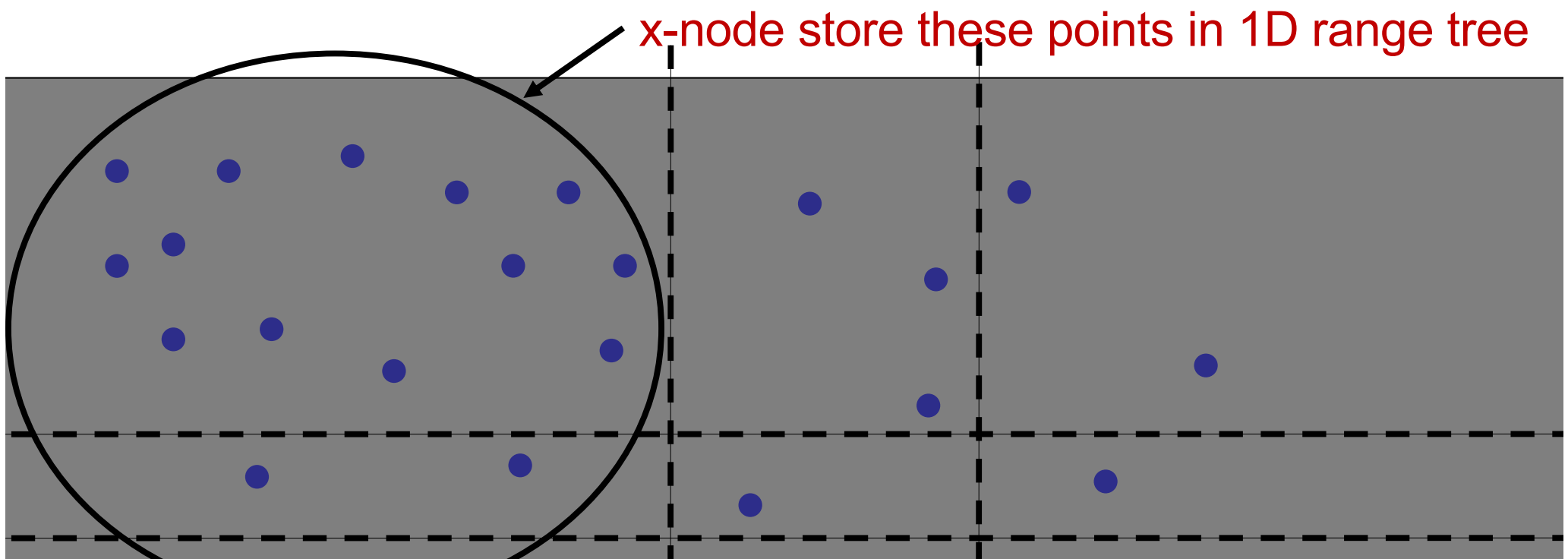


# Two Dimensional Range Tree

---

**Solution:** Augment!

- Each node in the x-tree has a set of points in its sub-tree.
- Store a y-tree at each x-node containing all the points in the sub-tree.





# One Dimensional Range Queries

---

```
LeftTraversal(v, low, high)
```

```
    if (v.key.x >= low.x) {
```

```
        ytree.search(low.y, high.y);
```

```
        LeftTraversal(v.left, low, high);
```

```
    }
```

```
    else {
```

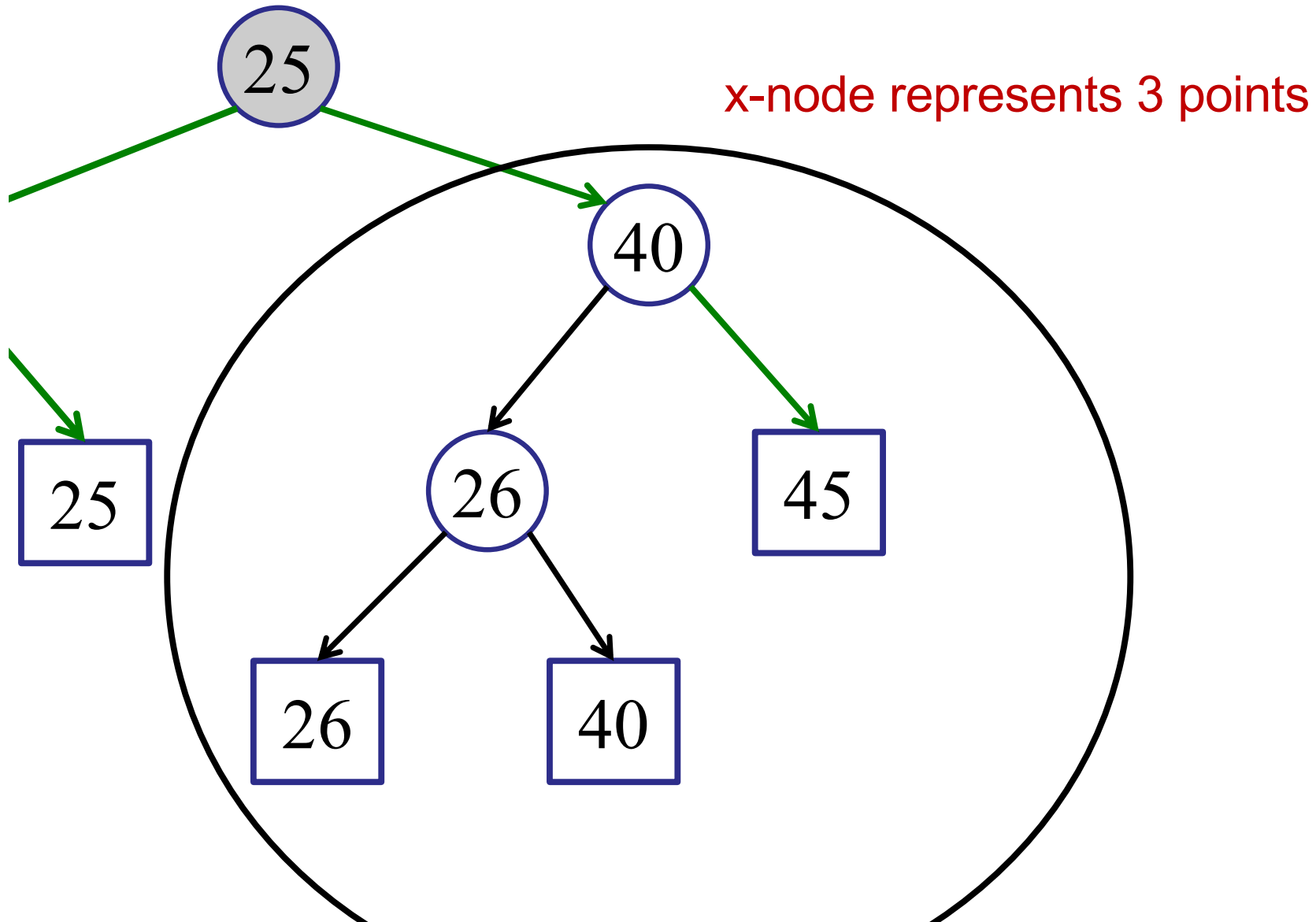
```
        LeftTraversal(v.right, low, high);
```

```
    }
```

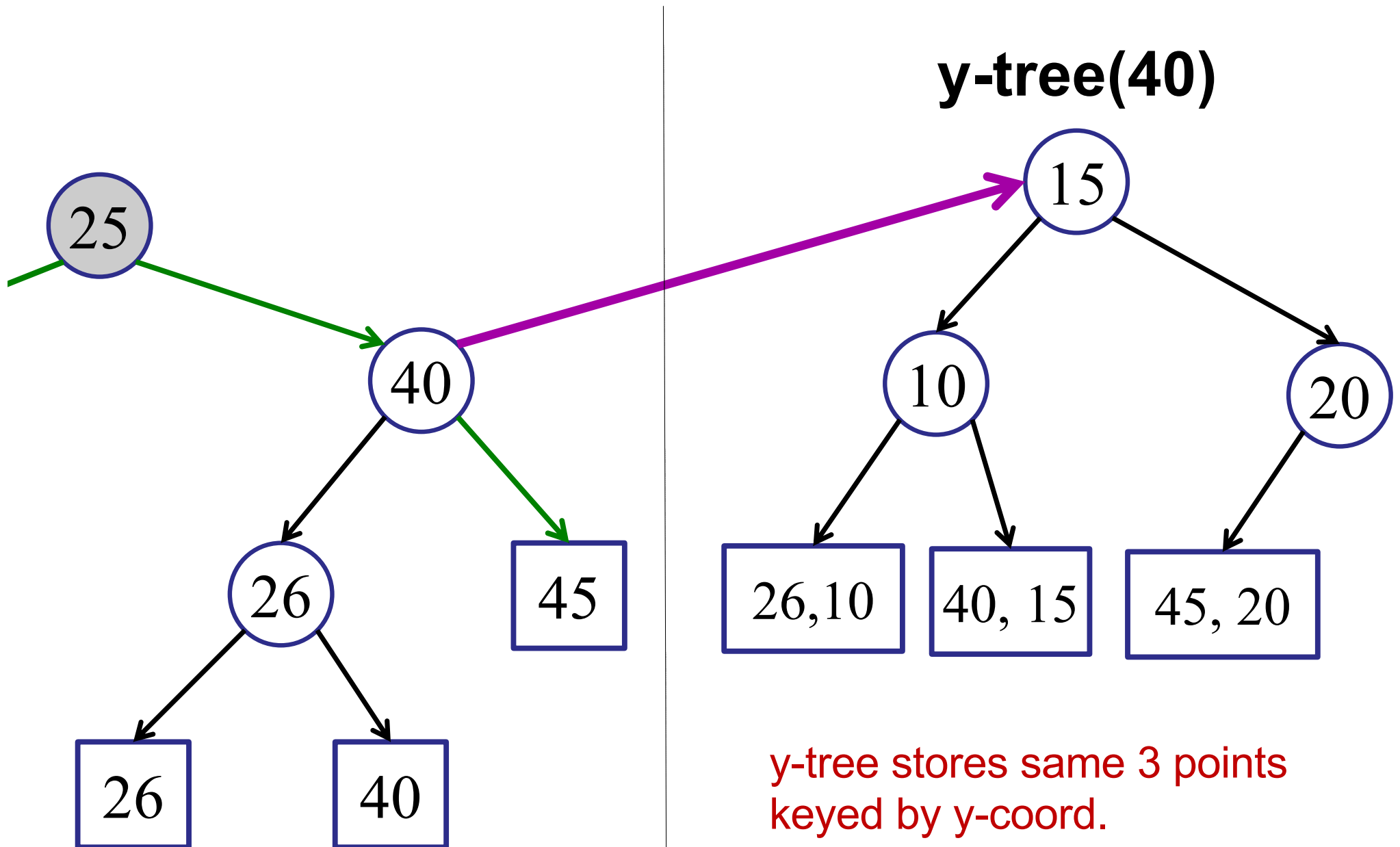
```
}
```

# Example:

---



# Example:

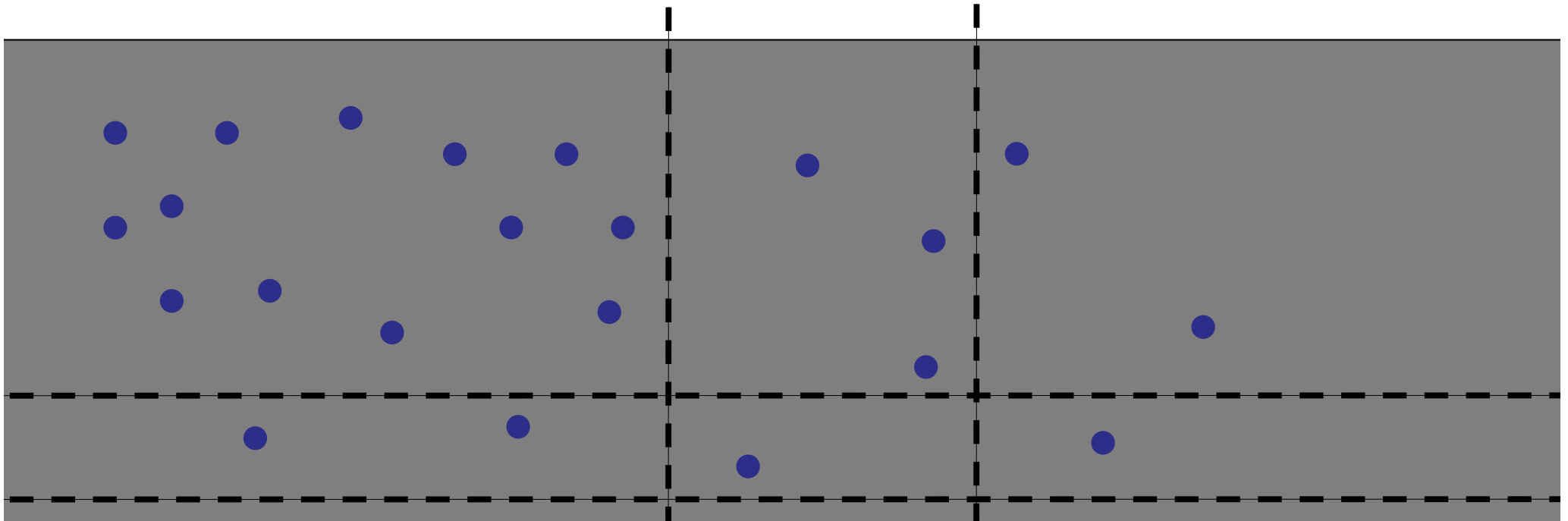


# Two Dimensional Range Tree

---

## Idea:

- Build an **x-tree** using only x-coordinates.
- For every node in the x-tree, build a **y-tree** out of nodes in subtree using only y-coordinates.



# Analysis

---

Query time:  $O(\log^2 n + k)$

- $O(\log n)$  to find split node.
- $O(\log n)$  recursing steps
- $O(\log n)$  y-tree-searches of cost  $O(\log n)$
- $O(k)$  enumerating output

# Analysis

---

Space complexity:  $O(n \log n)$

- Each point appears in at most one y-tree per level.
- There are  $O(\log n)$  levels.
- ➔ Each node appears in at most  $O(\log n)$  y-trees.
- The rest of the x-tree takes  $O(n)$  space.

# Analysis

---

Building the tree:  $O(n \log n)$

- Tricky...
- Left as a puzzle... 😊

Challenge of the Day...

# Dynamic Trees

---

What about inserting/deleting nodes?

**ARCHIPELAGO**

is open



# Dynamic Trees

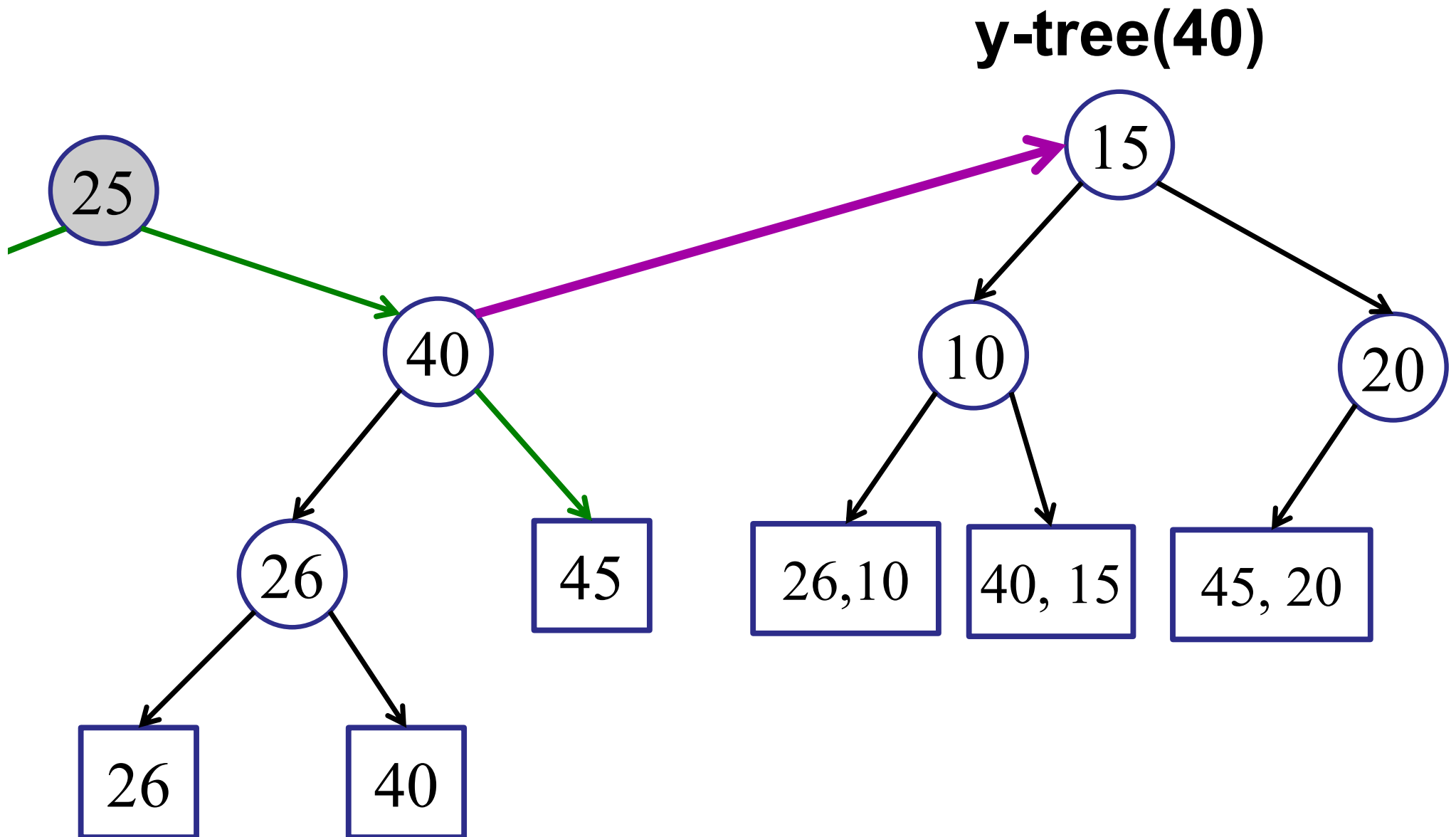
---

What about inserting/deleting nodes?

- Hard!
- How do you do rotations?
- Every rotation you may have to entirely rebuild the y-trees for the rotated nodes.
- Cost of rotate:  $O(n)$  !!!!

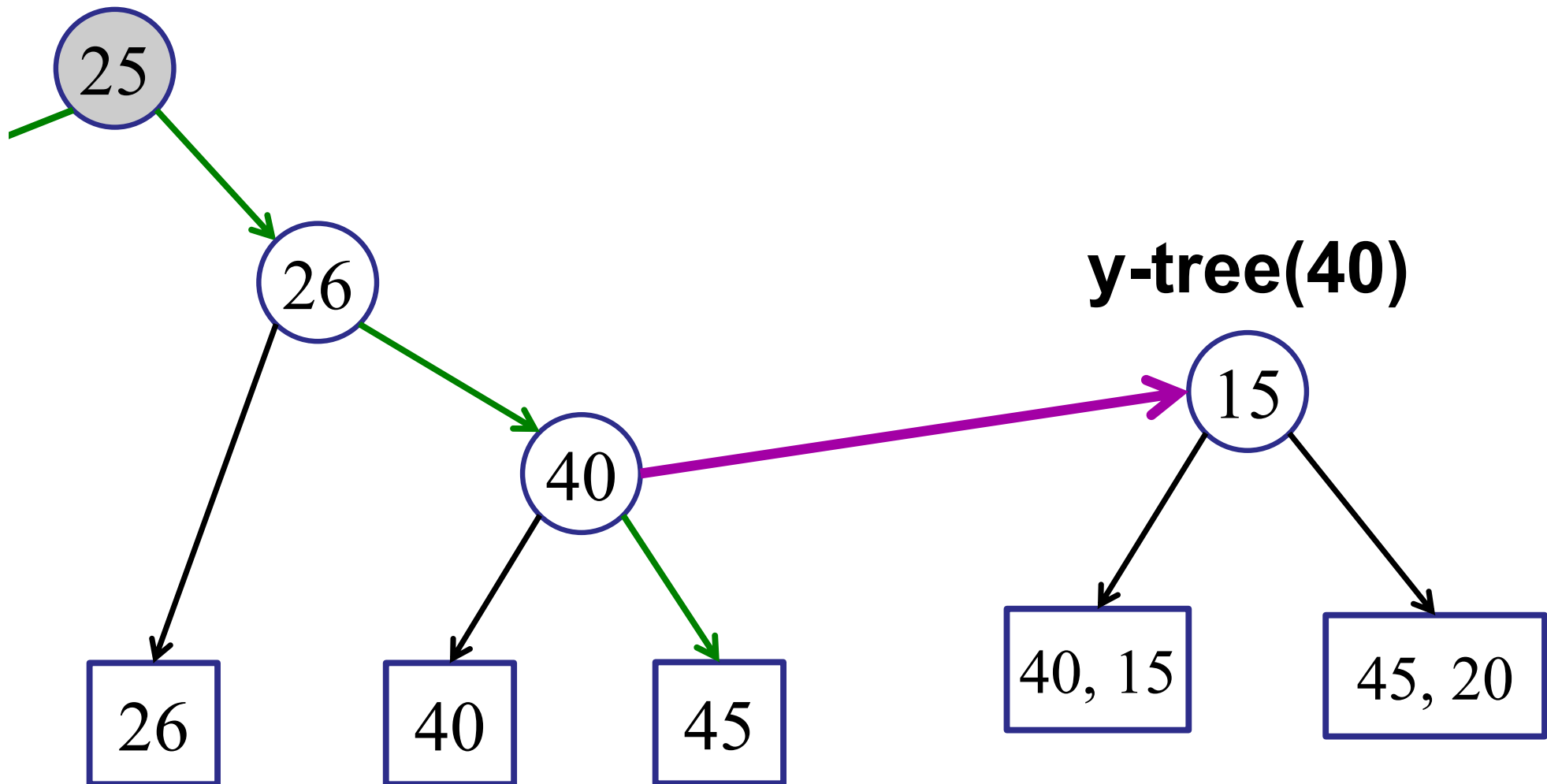
# Example:

---



# Example:

---



# Dynamic Trees

---

## Moral:

- Static 2d-range trees support efficient operations.
- We do not support insert/delete operations in 2d-range trees because rotations would be too expensive.

Augmenting data structures has to be done carefully!

Many useful augmentations cannot be supported efficiently!

# d-dimensional

---

What if you want high-dimensional range queries?

- Query cost:  $O(\log^d n + k)$
- buildTree cost:  $O(n \log^{d-1} n)$
- Space:  $O(n \log^{d-1} n)$

Idea:

- Store  $d-1$  dimensional range-tree in each node of a 1D range-tree.
- Construct the  $d-1$ -dimensional range-tree recursively.

# Curse of Dimensionality

---

What if you want high-dimensional range queries?

- Query cost:  $O(\log^d n + k)$
- buildTree cost:  $O(n \log^{d-1} n)$
- Space:  $O(n \log^{d-1} n)$

Idea:

- Store  $d-1$  dimensional range-tree in each node of a 1D range-tree.
- Construct the  $d-1$ -dimensional range-tree recursively.

# Real World (aside)

---

## kd-Trees

- Alternate levels in the tree:
  - vertical
  - horizontal
  - vertical
  - horizontal
- Each level divides the points in the plane in half.
- Supports more efficient updates
- Often better in practice.
- Good for a variety of queries (e.g., nearest neighbor).

# Augmented BSTs

---

Three examples of augmenting BSTs

1. Order Statistics
2. Intervals
3. Orthogonal Range Searching