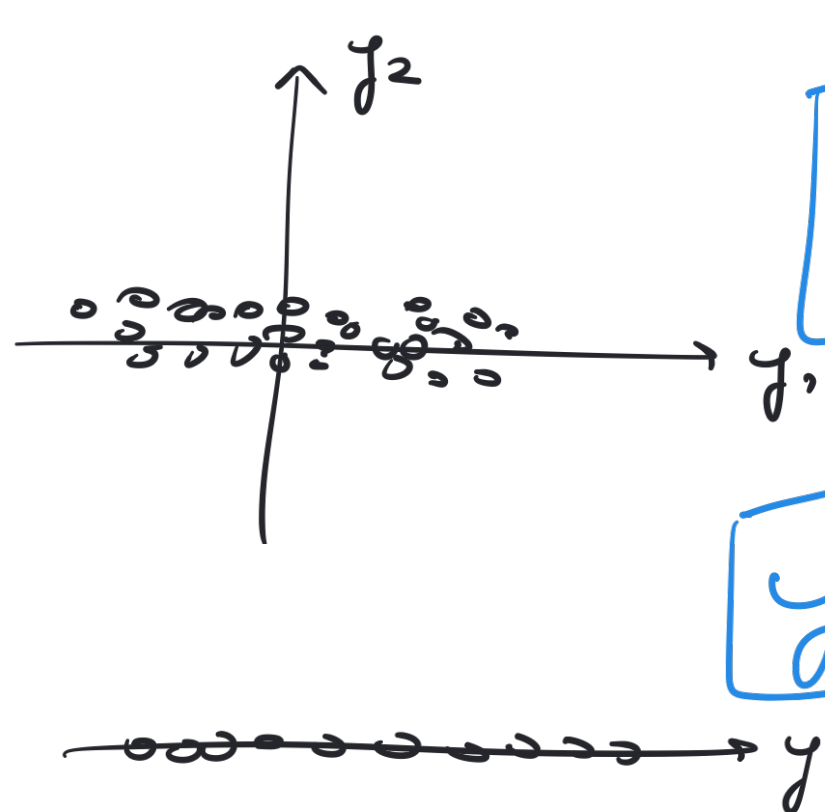


NOTE:  
 DEMEANING  
 OR  
 STANDARDIZATION  
 ARE METHODS  
 for  
 preprocessing  
 while  
 using PCA.



$$Y = A \cdot \tilde{X}$$

$2 \times N$     $2 \times 2$     $2 \times N$

$$Y = A_2 \cdot \tilde{X}$$

$1 \times N$     $1 \times 2$     $2 \times N$

Apply a  
 change of  
 basis (rotation)

Dimensionality  
 reduction  
 keeps direction  
 that explains the  
 most variance

Linear transformation:  $y = A \cdot \tilde{x}$

where  $\tilde{x} = x - \mu_x$

and  $\tilde{x}$  is a  $D \times N$  matrix

$A$  is a  $M \times D$  matrix ( $M \leq D$ )

$$A = \begin{bmatrix} a_1^T \\ a_2^T \\ \vdots \\ a_N^T \end{bmatrix} \quad \text{where } a_i \text{ is a } D \times 1$$

Goal: Find  $A$  such that

①  $\text{cov}(y_i, y_j) = 0$ ,  $\forall y_i \neq y_j$

②  $\text{cov}(y_i, y_i) = \text{var}(y_i)$  is maximum,  $\forall y_i$

Covariance of  $Y$ :  $K_Y$   
 $M \times N$

$$K_Y = E[(Y - \mu_Y)(Y - \mu_Y)^T]$$

$M \times M$

$$= E[YY^T]$$

$$\mu_Y = 0$$

$$= E[A \tilde{X} (A \tilde{X})^T]$$

$$= E[A \tilde{X} \tilde{X}^T A^T]$$

$$= A \cdot E[\tilde{X} \tilde{X}^T] \cdot A^T$$

$E[\cdot]$  is a  
linear operator

$K_{\tilde{X}} \equiv$  covariance of  $\tilde{X} = X - \mu_X$

$$= A \cdot K_{\tilde{X}} \cdot A^T$$

$$K_Y = A \cdot K_{\tilde{X}} \cdot A^T$$

$$= \begin{bmatrix} a_1^T \\ a_2^T \end{bmatrix}_{2 \times 2} \cdot K_{\tilde{X}}_{2 \times 2} \cdot \begin{bmatrix} a_1 & a_2 \end{bmatrix}_{2 \times 2}$$

$$= \begin{bmatrix} a_1^T \cdot K_{\tilde{X}} \\ a_2^T \cdot K_{\tilde{X}} \end{bmatrix} \cdot \begin{bmatrix} a_1 & a_2 \end{bmatrix}$$

$$= \begin{bmatrix} \underbrace{a_1^T \cdot K_{\tilde{X}} \cdot a_1}_{=0} & \underbrace{a_1^T \cdot K_{\tilde{X}} \cdot a_2}_{=0} \\ \underbrace{a_2^T \cdot K_{\tilde{X}} \cdot a_1}_{=0} & \underbrace{a_2^T \cdot K_{\tilde{X}} \cdot a_2}_{2 \times 2} \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

we want to find  $a_1$  and  $a_2$  such

that ①  $a_1^T \cdot K_{\tilde{X}} \cdot a_2 = 0 = a_2^T \cdot K_{\tilde{X}} \cdot a_1$

②  $a_1^T \cdot K_{\tilde{X}} \cdot a_1 > a_2^T \cdot K_{\tilde{X}} \cdot a_2$

If we are projecting onto a 1-D  
space,

$$Y = a_1^T \cdot \tilde{X}$$

$1 \times N$        $1 \times D$        $D \times N$

$$\arg \max_{\vec{a}_1} a_1^T \cdot K \cdot a_1$$

Such that  $\|a_1\|^2 = 1$

$$\Leftrightarrow a_1^T \cdot a_1 = 1$$

because  
we only  
care about  
the direction  
of  $\vec{a}_1$  not  
its magnitude.

Lagrangian function :

$$\mathcal{L}(a_1, \lambda) = a_1^T \cdot K_{\tilde{x}} \cdot a_1 + \lambda (1 - a_1^T a_1)$$

$$\left( \text{or } \mathcal{L}(a_1, \lambda) = -a_1^T \cdot K_{\tilde{x}} \cdot a_1 - \lambda (1 - a_1^T a_1) \right)$$

minimization formulation

$$\frac{\partial \mathcal{L}}{\partial a_1} = 0 \Leftrightarrow 2 \cdot K_{\tilde{x}} \cdot a_1 - 2 \lambda \cdot a_1 = 0$$

$$\Leftrightarrow K_{\tilde{x}} \cdot a_1 = \lambda \cdot a_1$$

this is the  
generalized  
eigenvector eq.

$\therefore a_1$  is an eigenvector of  
 $K_{\tilde{x}}$  with eigenvalue  $\lambda$

Since, in this example,  $K_{\tilde{x}}$  has 2 eigenvectors,  
we pick the one with largest eigenvalue.

Pseudo-code:

- ① Subtract the mean:  $\tilde{X} = X - \mu_X$
- ② Compute the covariance of  $\tilde{X}$ ,  $K_{\tilde{X}}$ .
- ③ Compute the Eigenvectors and eigenvalues of  $K_{\tilde{X}}$ .  
and store the eigenvectors in decreasing order of their eigenvalues

$$U = \begin{bmatrix} E_1 & E_2 & \dots & E_D \end{bmatrix}_{D \times D}$$

MODAL  
MATRIX

$$\Lambda = [\lambda_1, \lambda_2, \dots, \lambda_D], \lambda_1 > \lambda_2 > \dots > \lambda_D$$

- ④ Apply rotation or dimensionality reduction

$$Y = A \cdot \tilde{X}, \text{ where } A = U^T$$

4.1) For dimensionality reduction  $A = [E_1 | E_2 | \dots | E_N]^T$

Explained Variance Ratio

M - dimensional space explains

$$\frac{\lambda_1 + \lambda_2 + \dots + \lambda_M}{\sum_{i=1}^D \lambda_i} \% \text{ of variance in the data}$$