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|  | **Vehicle** | **Intersection Manager** |
| **Requests** | 1. Sents REQUEST signal | 1. Accepts the signal |
|  |  | 1. Arranged in First Ready Out |
| **Prioritization** |  | 1. EV detected |
|  |  | 1. Asks vehicle in front to remove itself out of way (YIELD signal) |
|  | 1. Vehicle removes itself and prepares to send MOVED\_REQUEST, at a random time it chooses |  |
| **Normal Movement** | 1. After the EV passes, other vehicles follow the normal traffic intersection, one node at a time | 1. IM keeps track of exited vehicles |