Statistics 452: Statistical Learning and Prediction

Chapter 5: Resampling Methods

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Resampling Methods

- Cross-validation and bootstrap.
- Grouped together because they involve random sampling of subsets of the data.
- ▶ But purpose is different: CV estimates the test error, bootstrap is used to estimate the variance of estimators.

Test Error

The test error is based on the average squared prediction error over test observations (not used to train the model):

$$Ave(y_0 - \hat{f}(x_0))^2,$$

where the average is over future x_0 's.

- We then average this average over repeated samples of training data.
- Picture this as repeating the following:
 - 1. Sample training and test data
 - 2. Train the model, and use on the test data to obtain the average squared error

and averaging the average from step 2.

With just one training and test set we can get an estimate of the test error.

Validation

- ▶ This is what we have already been doing.
- ▶ We split our data into two parts, a training set and a validation, or hold-out set.
 - Use the training set for fitting and the validation set for estimating the test error.

Validation on the Auto Data

Split the Auto data in half.

```
library(tidyverse)
library(ISLR)
data(Auto)
Auto <- dplyr::select(Auto,mpg,horsepower)</pre>
n <- nrow(Auto)
set.seed(42)
# Split in half
train <- sort(sample(1:n,size=n/2)) # sorting not necessary</pre>
head(train)
## [1] 1 2 3 7 11 14
validn <- setdiff(1:n,train)</pre>
head(validn)
## [1] 4 5 6 8 9 10
Auto.train <- Auto[train.]
Auto.validn <- Auto[validn,] # same as Auto[-train,]
```

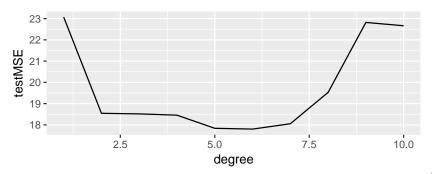
- Use the train half to train a polynomial model in horsepower and then estimate the test MSE on the validn half.
 - Software note: poly() returns polynomials and is useful in a model formula to save typing

```
afit <- lm(mpg ~ poly(horsepower,2),data=Auto.train)
yhat.v <- predict(afit,newdata=Auto.validn)
tMSE <- with(Auto.validn,mean((mpg - yhat.v)^2))
tMSE</pre>
```

[1] 18.54359

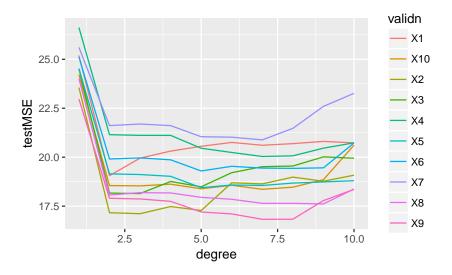
Validation to Select the Degree of Polynomial

```
testMSE <- function(dd,train,validn) {
   afit <- lm(mpg ~ poly(horsepower,dd),data=train)
   yhat.v <- predict(afit,newdata=validn)
   return(with(validn,mean((mpg - yhat.v)^2)))
}
nd <- 10; dd <- (1:nd); tm <- rep(NA,nd)
for(i in dd) {
   tm[i] <- testMSE(i,Auto.train,Auto.validn)
}
dMSE <- data.frame(degree=dd,testMSE= tm)
ggplot(dMSE,aes(x=degree,y=testMSE)) + geom_line()</pre>
```



Validation with Different Validation Sets

```
nValid <- 10
valid <- function() {</pre>
  n <- nrow(Auto)
  train <- sample(1:n,size=n/2)</pre>
  Auto.train <- Auto[train,]</pre>
  Auto.validn <- Auto[-train,]
  tm <- rep(NA,nd)
  for(i in dd) {
    tm[i] <- testMSE(i,Auto.train,Auto.validn)</pre>
  tm
tMSE <- replicate(nValid, valid())</pre>
tMSE <- data.frame(degree=dd,tMSE)</pre>
tMSE <- gather(tMSE, validn, testMSE, X1:X10, -degree)</pre>
```



▶ Note the variability in the estimated test MSE.

Cross-Validation (CV)

- Rather than a single data split, do multiple splits into "folds" of approximately equal size.
 - ▶ Common numbers of folds are k = n, 10 and 5.
- ► Train on all but one hold-out fold, and test on the hold-out to get MSE_i; i = 1,..., k.
- ▶ Repeat for each fold and average the estimated test MSEs:

$$CV_{(k)} = \frac{1}{k} \sum_{i=1}^{k} MSE_i.$$

Leave-Out-One CV (LOOCV)

- ▶ Break the data into *n* folds, with one observation in each fold.
- Computational trick for a linear model fit by least squares:

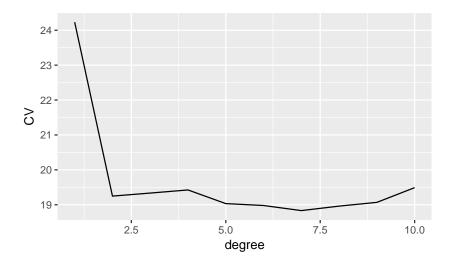
$$CV_{(n)} = \frac{1}{n} \sum_{i=1}^{n} \left(\frac{y_i - \hat{y}_i}{1 - h_i} \right)^2,$$

where \hat{y}_i is the fitted value from the least squares fit and h_i is the leverage of the *i*th observation.

LOOCV on Auto Data

```
loocv <- function(dd) {
   CVn <- rep(NA,length(dd))
   for(i in dd) {
     fit <- lm(mpg ~ poly(horsepower,i),data=Auto)
        hh <- hatvalues(fit)
        ff <- fitted.values(fit)
        CVn[i] <- with(Auto,mean(((mpg-ff)/(1-hh))^2))
   }
   CVn
}
cv.err <- loocv(dd)
cv.err <- data.frame(degree=dd,CV=cv.err)</pre>
```

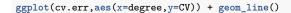
ggplot(cv.err,aes(x=degree,y=CV)) + geom_line()

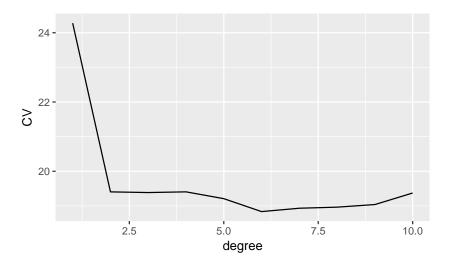


10-Fold CV on Auto Data

- ► Can use a function cv.glm() from the boot package.
 - ▶ Uses output from glm().
 - ▶ glm default is normal errors; i.e., lm().

```
library(boot)
cv.err <- rep(NA,nd)
set.seed(123)
for(i in dd) {
   fit <- glm(mpg ~ poly(horsepower,i),data=Auto)
   cc <- cv.glm(Auto,fit,K=10)
   cv.err[i] <- cc$delta[1]
}
cv.err <- data.frame(degree=dd,CV=cv.err)</pre>
```





Bias-Variance Trade-Off for k-Fold CV

- ▶ In general, computation of *k*-fold CV increases with *k*.
- ▶ But more important is the accuracy of the CV estimator as a function of *k*.
- ▶ There are two components to accuracy, bias and variance.
 - ► It can be shown that the bias of the CV estimator of the test error *decreases* as *k* increases.
 - It can be shown that the variance of the CV estimator increases with k.

Bias

- If data splitting results in a training set that is small, the error of the statistical learning method will be larger than if we fit to all data.
- ▶ Implies an upward bias in the estimate of the test error.
- ➤ On the other extreme, LOOCV uses almost all the data to train, and so will have almost no bias.

Variance

- This is harder to reason through.
- ► The LOOCV estimate is an average of many squared errors that are (i) highly variable, and (ii) positively correlated.
 - Averaging many things is good.
 - ► The positive correlation arrises from using mostly the same data to fit the model each time.
- ► For k-fold CV with smaller k, we average fewer MSEs that are (i) less variable and
- 2. less correlated.
- Which "wins"? Turns out that k = 5 or 10 have been shown to work well empirically.

Simulation Example

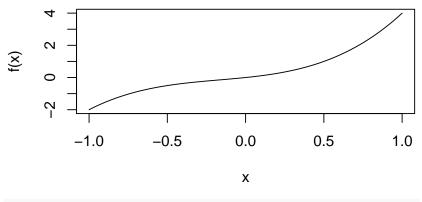
- We can illustrate the bias and variance of the CV estimator of the test error with one similation model.
- Simulate from the model

$$Y = X + X^2 + 2X^3 + \epsilon$$

for $\epsilon \sim N(0,1)$ and a fixed grid of X-values.

- Fit a linear regression.
- ▶ View the contributions to $CV_{(n)}$ and $CV_{(10)}$ and the variance of these two estimators.

```
n <- 100
x <- seq(-1,1,length=n)
plot(x,x+x^2+2*x^3,ylab="f(x)",type="l")</pre>
```

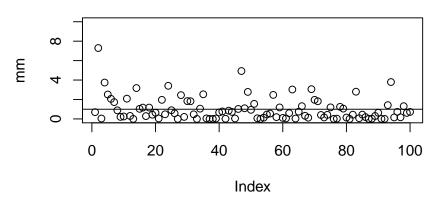


```
simdat <- function() {
  y<-rnorm(n,mean=x+x^2+2*x*3,sd=1)
  data.frame(y=y,x=x)
}</pre>
```

```
# LOOCV contributions for data set of size 100
loocv.contrib <- function() {
    MSE <- rep(NA,n)
    dat <- simdat()
    for(i in 1:n) {
        fit <- lm(y~x,data=dat,subset=(-i))
        newdat <- data.frame(x=dat$x[i])
        pp <- predict(fit,newdata=newdat)
        MSE[i] <- (dat$y[i] - pp)^2
    }
    MSE
}</pre>
```

Repeat the following a few times

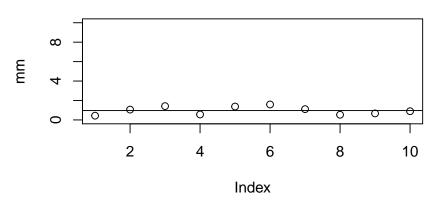
```
mm <- loocv.contrib()
plot(mm,ylim=c(0,10))
abline(h=mean(mm)) # LOOCV estimate of test error</pre>
```



```
# 10-fold CV contributions for data set of size 100
cv.contrib <- function(n=100,k=10) {
    MSE <- rep(NA,k)
    dat <- simdat()
    inds <- sample(1:n)
    for(i in 1:(n/k)) {
        ss <- inds[(i-1)*k + (1:(n/k))]
        fit <- lm(y-x,data=dat,subset=(-ss))
        newdat <- data.frame(x=dat$x[ss])
        pp <- predict(fit,newdata=newdat)
        MSE[i] <- mean((dat$y[ss] - pp)^2)
    }
    MSE
}</pre>
```

▶ Repeat the following a few times

```
mm <- cv.contrib()
plot(mm,ylim=c(0,10))
abline(h=mean(mm)) # Estimate of test error</pre>
```



► Hard to see how the CV estimates (horzontal lines) vary over samples, so record them over many simulations.

```
set.seed(123)
NREPS <- 1000
LOOCVres <- CVres <- rep(NA, NREPS)
for(i in 1:NREPS) {
  LOOCVres[i] <- mean(loocv.contrib())
  CVres[i] <- mean(cv.contrib())</pre>
mean(LOOCVres): var(LOOCVres):mean(CVres): var(CVres)
## [1] 1.122344
## [1] 0.02634004
## [1] 1.124939
## [1] 0.02689808
```

 Can see suggestion of lower bias from LOOCCV, but not lower variance of 10-fold CV for this scenario.

CV on Classification Problems

- ▶ We have illustrated the idea behind CV when the response is quantitative.
- ▶ We then use the MSE (mean squared error) to quantify test error.
- ► For classification problems we measure the error of a procedure by the misclassification error.
- For example,

$$CV_{(n)} = \frac{1}{n} \sum_{i=1}^{n} I(y_i \neq \hat{y}_i)$$

See the text for examples.

The Bootstrap

► The bootstrap uses resampling to quantify uncertainty in an estimator.

Assumptions and sampling distributions

- Under model assumptions, the sampling distribution of the statistics used for inference are known.
 - Sampling distribution: Distribution of a statistic over repeated samples of data from the population.
 - For regression coefficients, the sampling distribution leads to t-tests and Cls
- The bootstrap is a data-driven approach to approximating the sampling distribution of inferential statistics.
 - ► Find the distribution of a statistic over repeated samples of data from the original sample.
 - ▶ Reasonable if original sample is representative of the population.
 - ▶ Base inference on the bootstrap approximate distribution.

Advantages

- ▶ Bootstrap may give reasonable uncertainty estimates when assumptions for traditional inference don't hold.
- ▶ We can expand the definition of the procedure used to obtain the estimates to include variable selection and/or other smoothing (more on this later).

Resampling

- Resampling means drawing samples, with replacement, from the original sample.
 - ▶ E.G., drawing cars, with replacement.

```
set.seed(42)
n <- nrow(Auto)
Autos <- data.frame(index=1:n,Auto)
resamAuto <- sample_n(Auto,size=n,replace=TRUE)
head(resamAuto)</pre>
```

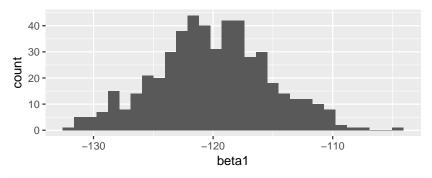
```
## mpg horsepower
## 364 22.4 110
## 373 27.0 90
## 114 21.0 107
## 328 36.4 67
## 254 20.5 95
## 206 28.0 75
```

Bootstrap Standard Errors

- Resample some number B times.
- For each resample compute the estimates.
- ► Take the sample SD of the bootstrap estimates.

```
B <- 500; beta1Boot <- rep(NA,B)
for(i in 1:B) {
    rAuto <- sample_n(Auto, size=n, replace=TRUE)
    fit <- lm(mpg-poly(horsepower,2), data=rAuto)
    beta1Boot[i] <- coefficients(fit)[2]
}
beta1Boot <- data.frame(beta1=beta1Boot)</pre>
```

ggplot(beta1Boot,aes(x=beta1)) + geom_histogram()



```
with(beta1Boot,sd(beta1))
```

```
## [1] 4.72912
```

```
fit <- lm(mpg~poly(horsepower,2),data=Auto)
round(summary(fit)$coefficients[2,],4)</pre>
```

```
## Estimate Std. Error t value Pr(>|t|)
## -120.1377 4.3739 -27.4668 0.0000
```