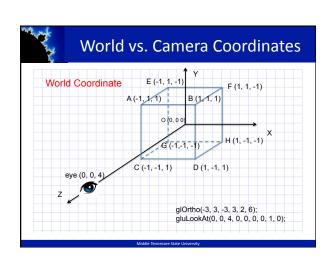
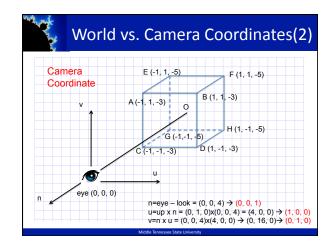


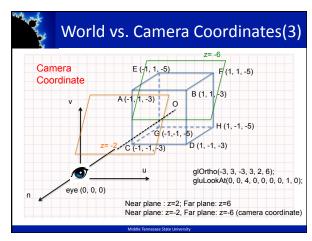
Projections of 3-D Objects (2)

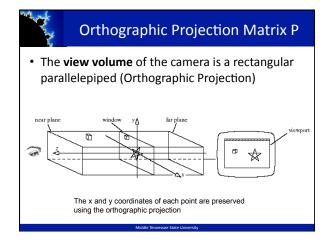
- Each vertex v is multiplied by the modelview matrix (VM), containing all of the modeling transformations for the object; the viewing part (V) accounts for the transformation set by the camera's position and orientation. When a vertex emerges from this matrix it is in **eye coordinates**, that is, in the coordinate system of the eye.
- The figure shows this system: the eye is at the origin, and the near plane is perpendicular to the z-axis, located at z = -N.

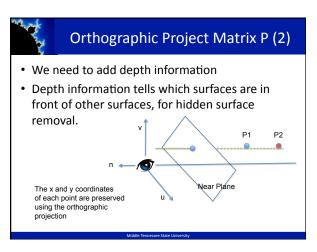
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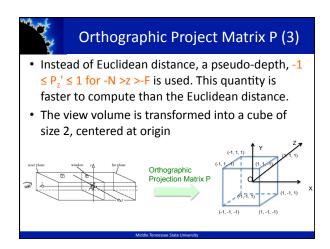


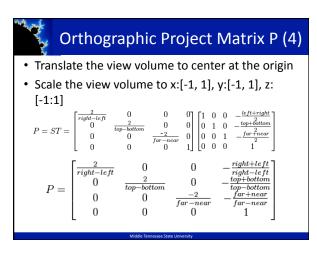


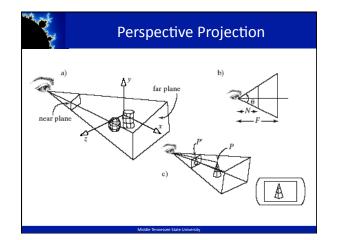


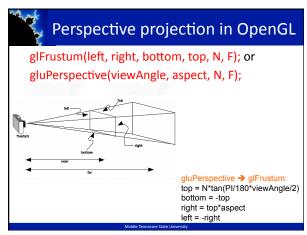


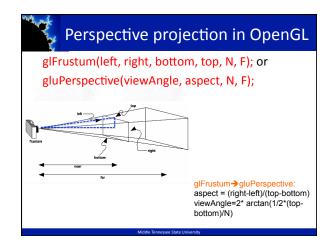


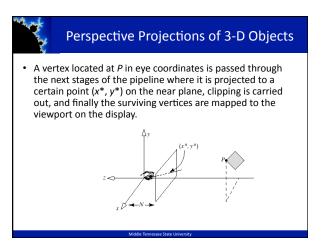


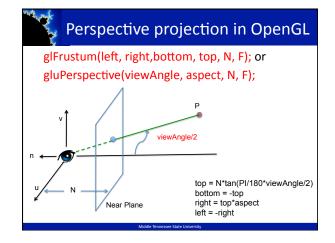


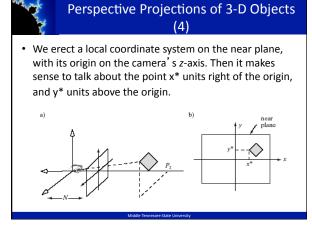


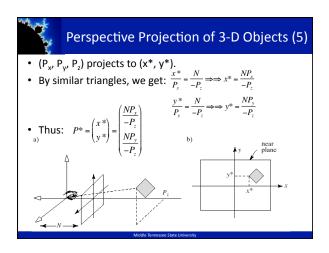


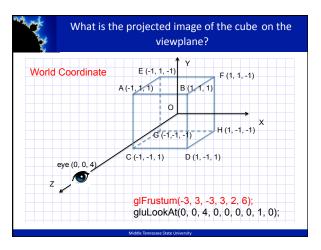


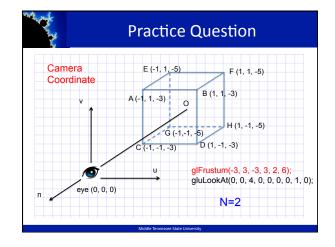


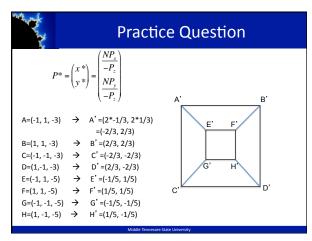














Perspective Projection Properties

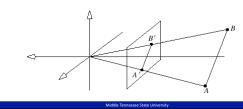
- |P_z| is larger for points further away from the eye, and, because we divide by it, causes objects further away to appear smaller (perspective foreshortening).
- We do not want P_z ≥ 0; generally these points (at or behind eye) are clipped.
- Projection to a plane other than N simply scales P*; since the viewport matrix will scale anyway, we might as well project to N.

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Perspective Projection Properties (2)

- Straight lines project to straight lines. Consider the line between A and B. A projects to A' and B projects to B'.
- In between: consider the plane formed by A, B, and the origin.
 Since any two planes intersect in a straight line, this plane intersects the near plane in a straight line. Thus line segment AB projects to line segment A'B'.



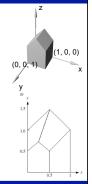


Barn Example

• View #1: gluPerspective(30, 1.5, 1, 2); gluLookAt(0, 0, 2, 0, 0, 0, 0, 1, 0);

The near plane coincides w/ the front of the barn.

- In camera coordinates all points on the front wall of the barn have $P_z=-1$ and those on the back wall have $P_z=-2$. So any point (P_w,P_y,P_z) on the front wall projects to $P'=(P_x,P_y)$ and any point on the back wall projects to $P'=(P_x,P_y)$
- The foreshortening factor is two for points on the back wall. Note that edges on the rear wall project at half their true length. Also note that edges of the barn that are actually parallel in 3D need not project as parallel.



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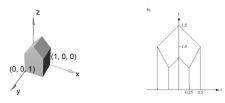


Barn Example (2)

• In view #2, the camera has been moved right, but everything else is the same:

gluPerspective(30, 1.5, 1, 2);

gluLookAt(0.5, 0, 2, 0, 0, 0, 0, 1, 0);

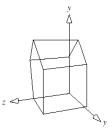


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Example (3)

 In part c, we look down from above and right on the barn.



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Perspective Projection of Lines

- · Straight lines are transformed to straight lines.
- Lines that are parallel in 3D project to lines, but not necessarily parallel lines. If not parallel, they meet at some vanishing point.
- If P_z ≥ 0, lines that pass through the camera undergo a catastrophic "passage through infinity"; such lines must be clipped.
- Perspective projections usually produce geometrically realistic pictures. But realism is strained for very long lines parallel to the viewplane.

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Projection of Straight Lines (2)

• For any line in 3D: P = A + ct, its projected line on viewplane:

$$P_{x}'(t) = \frac{N * P_{x}(t)}{-P_{z}(t)} = -\frac{N * (A_{x} + c_{x} * t)}{A_{z} + c_{z} * t}$$

$$P_{y}'(t) = \frac{N * P_{y}(t)}{-P_{z}(t)} = -\frac{N * (A_{y} + c_{y} * t)}{A_{z} + c_{z} * t}$$

The projected Point A is P'(0) = - N/A₂ (A_x, A_v).





Projection of Straight Lines (3)

- Effect of projection → on parallel lines:
- If the line is parallel to the near plane N, c, = 0:
- Thus

$$P_{x}'(t) = \frac{N * P_{x}(t)}{-P_{z}(t)} = -\frac{N * (A_{x} + c_{x} * t)}{A_{z} + c_{z} * t} = -\frac{N}{A_{z}} (A_{x} + c_{x} * t)$$

$$P_{y}'(t) = \frac{N * P_{y}(t)}{-P_{z}(t)} = -\frac{N * (A_{y} + c_{y} * t)}{A_{z} + c_{z} * t} = -\frac{N}{A_{z}} (A_{y} + c_{y} * t)$$

- Thus if two lines in 3D are parallel to each other and to the viewplane, they project to two parallel lines.

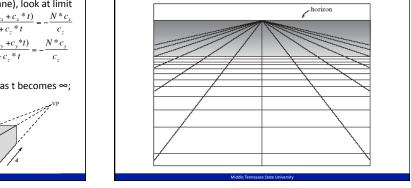
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Projection of Straight Lines (3)

- If the line is not parallel to plane N (near plane), look at limit as t becomes ∞ for $P_x(t) = \frac{N^* P_x(t)}{-P_z(t)} = -\frac{N^* (A_x + c_x * t)}{A_z + c_z * t} = -\frac{N^* c_x}{c_z}$ $P_z(t) = \frac{N^* P_y(t)}{-P_z(t)} = -\frac{N^* (A_y + c_y * t)}{-P_z(t)} = -\frac{N^* c_y}{-P_z(t)}$
- \rightarrow p(t)=-N/c_z (c_x, c_y), a constant.
 - All lines with direction c reach this point as t becomes ∞; it is called the vanishing point.
- Thus all parallel lines share the same vanishing point.
- In particular, these lines project to lines that are not parallel.

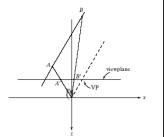
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Projection of Straight Lines (≤)

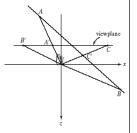
- Geometry of vanishing point: A projects to A', B projects to B', etc.
 Very remote points on the line project to VP as shown.
- Line from eye to VP must be parallel to line AB. (why?)



Projection of Straight Lines (5)

Example: horizontal grid in perspective

- Lines that pass behind the eye have a different geometry for the vanishing point; as C moves from A to B, and approaches the eye plane, its projection moves infinitely far to the right.
- When it reaches the eye plane, it jumps infinitely far to the left.



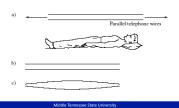
Normally, all parts of the line closer to the eye than the near plane are clipped off before the projection is attempted.

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Eye Effects

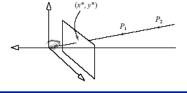
 Note that technically the eye is not a planar surface, but a curved one. This fact results in anomalies such as a slight curve appearing in the view of very long parallel lines.





Incorporating Perspective in the Graphics Pipeline

- We need to add depth information (destroyed by projection).
- Depth information tells which surfaces are in front of other surfaces, for hidden surface removal.



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Incorporating Perspective in the Graphics Pipeline (2)

and choose a and b so that

$$P_z$$
* = -1 when P_z = -N and 1 when P_z = -F.

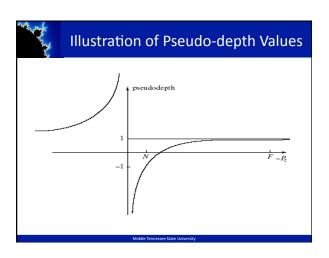
• Result:

$$a = -(F + N)/(F - N),$$

 $b = -2FN/(F - N).$

 P_z* increases (becomes more positive) as P_z decreases (becomes more negative, moves further away).

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Incorporating Perspective in the Graphics Pipeline (3)

- Pseudodepth values bunch together as -P_z gets closer to F, causing difficulties for hidden surface removal.
- When N is much smaller than F, as it normally will be, pseudodepth can be approximated by

$$pseudodepth \approx 1 + \frac{2N}{P_z}$$

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