Data Mining



Classification Naïve Bayes Classifier

A Quick Review of Probability

- The Axioms of Probability
 - $-0 \le P(A) \le 1$
 - -P(A or B) = P(A) + P(B) P(A and B)
 - $-P(not A) = P(^{\sim}A) = 1 P(A)$
 - $-P(A) = P(A \text{ and } B) + P(A \text{ and } ^B)$

Multivalued Random Variables

- Suppose A can take on more than 2 values
- A is a random variable with arity k if it can take on exactly one value out of $\{v_1, v_2, ... v_k\}$
- Thus...

$$P(A = v_i \text{ and } A = v_i) = 0 \text{ if } i \neq j$$

$$P(A = v_1 \text{ or } A = v_2 \text{ ... or } A = v_k) = 1$$

An easy fact about Multivalued Random Variables • Using the axioms of probability...

$$P(A \text{ or } B) = P(A) + P(B) - P(A \text{ and } B)$$

• And assuming that A obeys...

$$P(A = v_i \text{ and } A = v_i) = 0 \text{ if } i \neq j$$

$$P(A = v_1 \text{ or } A = v_2 \text{ or ... or } A = v_k) = 1$$

• It can be proved that:

$$P(A = v_1 \text{ or } A = v_2 \text{ or ... or } A = v_i) = \sum_{j=1}^{i} P(A = v_j)$$

Thus:

Thus:

$$\sum_{i=1}^{k} P(A = v_j) = 1$$

Another fact about Multivalued Random Variables:

• Using the axioms of probability...

$$0 \le P(A) \le 1$$

P(A or B) = P(A) + P(B) - P(A and B)

• And assuming that A obeys...

$$P(A = v_i \text{ and } A = v_j) = 0 \text{ if } i \neq j$$

 $P(A = v_1 \text{ or } A = v_2 \text{ or } A = v_k) = 1$

• It can be proved that

$$P(B \text{ and } [A = v_1 \text{ or } A = v_2 \text{ or } A = v_i]) = \sum_{j=1}^{t} P(B \text{ and } (A = v_j))$$

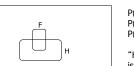
• Thus

$$P(B) = \sum_{j=1}^{k} P(B \text{ and } A = v_j)$$

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Conditional Probability

• P(A|B) = Fraction of worlds in which B is true that also have A true



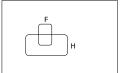
H = "Have a headache" F = "Coming down with Flu"

P(H) = 1/10 P(F) = 1/40P(H|F) = 1/2

"Headaches are rare and flu is rarer, but if you' re coming down with flu there's a 50-50 chance you'll have a headache."

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Conditional Probability



H = "Have a headache" F = "Coming down with Flu"

P(H) = 1/10 P(F) = 1/40P(H|F) = 1/2 P(H|F) = Fraction of flu-inflicted worlds in which you have a headache

= #worlds with flu and headache ------#worlds with flu

= Area of "H and F" region

Area of "F" region

= P(H and F) ------P(F)

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Definition of Conditional Probability

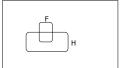
$$P(A|B) = P(A \text{ and } B)$$

 $P(B)$

Corollary: The Chain Rule P(A and B) = P(A|B) P(B)

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Probabilistic Inference



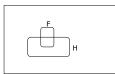
H = "Have a headache" F = "Coming down with

P(H) = 1/10 P(F) = 1/40 P(H|F) = 1/2

One day you wake up with a headache. You think: "Drat! 50% of flus are associated with headaches so I must have a 50-50 chance of coming down with flu"

Is this reasoning correct?

Probabilistic Inference



H = "Have a headache" F = "Coming down with

P(H) = 1/10 P(F) = 1/40 P(H|F) = 1/2

P(F and H) = ...

P(F|H) = ...

What we just did...is the Bayes Rule

Bayes, Thomas (1763) An essay towards solving a problem in the doctrine of chances. *Philosophical Transactions of the Royal Society of London,* 53:370-418



More General Forms of Bayes Rule

$$P(A|B) = \frac{P(B|A)P(A)}{P(B|A)P(A) + P(B|\sim A)P(\sim A)}$$

$$P(A = v_i | B) = \frac{P(B | A = v_i)P(A = v_i)}{\sum_{k=1}^{n_A} P(B | A = v_k)P(A = v_k)}$$

Useful Easy-to-prove facts

$$P(A | B) + P(\neg A | B) = 1$$

$$\sum_{k=1}^{n_A} P(A = v_k | B) = 1$$

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...

The Joint Distribution

Recipe for making a joint distribution of M variables:

Example: Boolean variables A, B, C

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The Joint Distribution

Recipe for making a joint distribution of M variables:

 Make a truth table listing all combinations of values of your variables (if there are M Boolean variables then the table will have 2^M rows). Example: Boolean variables A, B, C

A	В	С
0	0	0
0	0	1
0	1	0
0	1	1
1	0	0
1	0	1
1	1	0
1	1	1

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The Joint Distribution

Recipe for making a joint distribution of M variables:

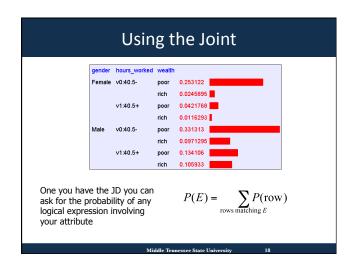
- Make a truth table listing all combinations of values of your variables (if there are M Boolean variables then the table will have 2^M rows).
- 2. For each combination of values, say how probable it is.

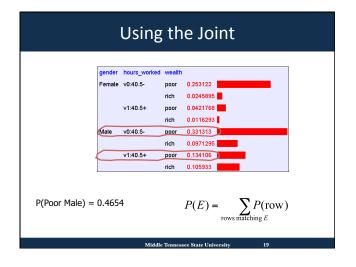
Example: Boolean variables A, B, C

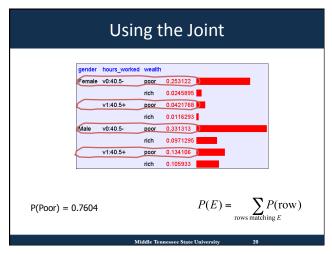
M	В	J	PIUD
0	0	0	0.30
0	0	1	0.05
0	1	0	0.10
0	1	1	0.05
1	0	0	0.05
1	0	1	0.10
1	1	0	0.25
1	1	1	0.10

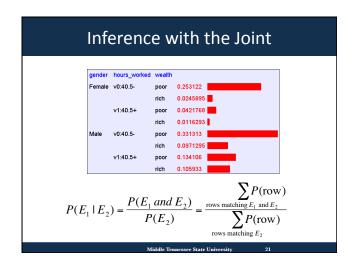
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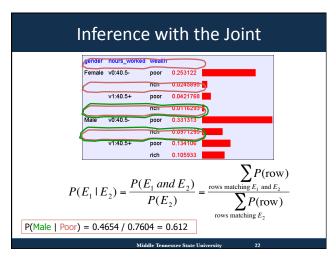
The Joint Distribution Prob Recipe for making a joint distribution 0.30 of M variables: 0.05 0.10 1. Make a truth table listing all 0.05 combinations of values of your 0.05 variables (if there are M Boolean 0.10 variables then the table will have 0.25 2^{M} rows). For each combination of values, say how probable it is. 3. If you subscribe to the axioms of 0.10 0.05 0.25 probability, those numbers must sum to 1. 0.05 0.10 0.30











Inference is a big deal

- I' ve got this evidence. What's the chance that this conclusion is true?
 - I've got a sore neck: how likely am I to have meningitis?
 - I see my lights are out and it's 9pm. What's the chance my spouse is already asleep?
- There's a thriving set of industries growing based around Bayesian Inference. Highlights are: Medicine, Pharma, Help Desk Support, Engine Fault Diagnosis

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Where do Joint Distributions come from?

• Idea One: Expert Humans

 Idea Two: Simpler probabilistic facts and some algebra

Example: Suppose you knew

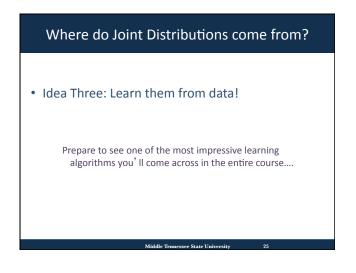
 $\begin{array}{ll} P(A) = 0.7 & P(C|A \text{ and } B) = 0.1 \\ P(C|A \text{ and } \sim B) = 0.2 \\ P(B|A) = 0.2 & P(C|\sim A \text{ and } B) = 0.3 \\ P(B|\sim A) = 0.1 & P(C|\sim A \text{ and } \sim B) = 0.1 \\ \end{array}$

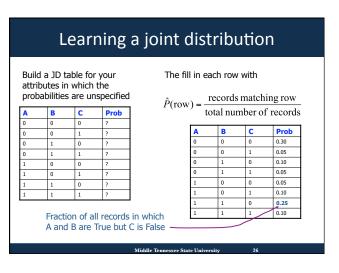
Then you can automatically compute the JD using the chain rule

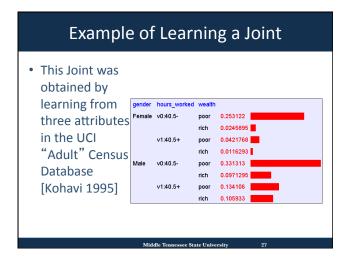
 $P(A=x \text{ and } B=y \text{ and } C=z) = P(C=z|A=x \text{ and } B=y) \ P(B=y|A=x) \ P(A=x)$

What is P(A, B, ∼C)?

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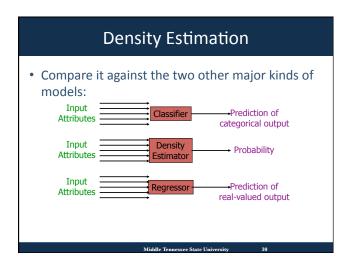


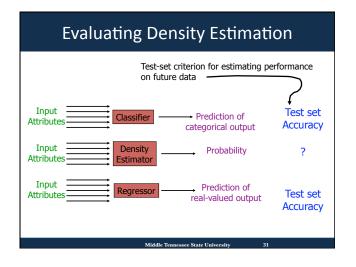




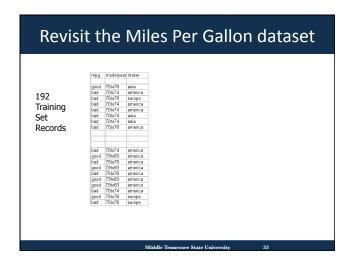
Where are we? We have recalled the fundamentals of probability We have become content with what JDs are and how to use them We know how to learn JDs from data.

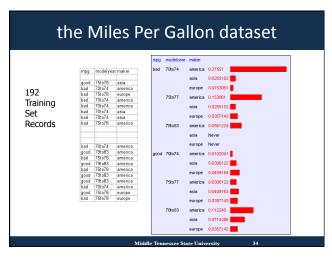
Our Joint Distribution learner is our first example of something called Density Estimation A Density Estimator learns a mapping from a set of attributes to a Probability Input Attributes Density Estimator Probability Middle Tennessee State University 29

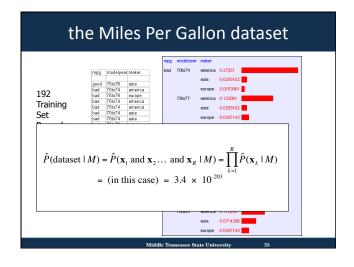


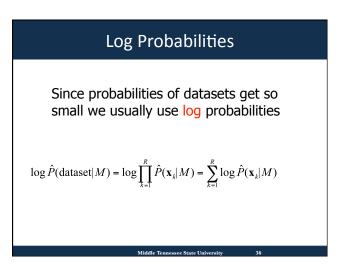


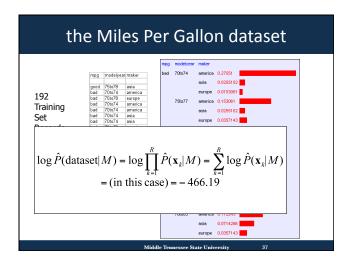
Evaluating a density estimator • Given a record \mathbf{x} , a density estimator M can tell you how likely the record is: $\hat{P}(\mathbf{x}|M)$ • Given a dataset with R records, a density estimator can tell you how likely the dataset is: (Under the assumption that all records were independently generated from the Density Estimator's JD) $\hat{P}(\text{dataset} \mid M) = \hat{P}(\mathbf{x}_1 \text{ and } \mathbf{x}_2 \dots \text{ and } \mathbf{x}_R \mid M) = \prod_{k=1}^R \hat{P}(\mathbf{x}_k \mid M)$











Summary: The Good News

- We have a way to learn a Density Estimator from data.
- Density estimators can do many good things...
 - Can sort the records by probability, and thus spot weird records (anomaly detection)
 - Can do inference: P(E1 | E2)
 Automatic Doctor / Help Desk etc
 - Can perform classification, e.g., p(C_k | A₁, A₂, ... A_n)
 - Ingredient for Bayes Classifiers (see later)

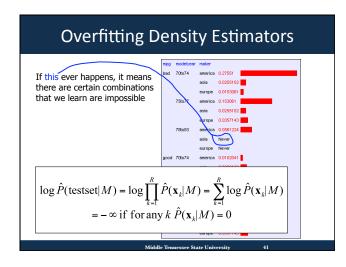
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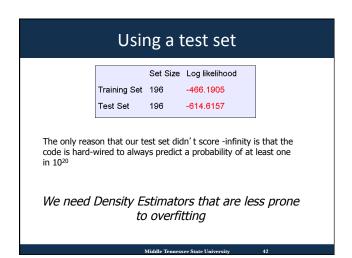
Summary: The Bad News

• Density estimation by directly learning the joint is trivial, mindless and dangerous

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Set Size Log likelihood Training Set 196 -466.1905 Test Set 196 -614.6157 An independent test set with 196 cars has a worse log likelihood (actually it's a billion quintillion quintillion quintillion times less likely)Density estimators can overfit. And the full joint density estimator is the overfittiest of them all!





Naïve Density Estimation

The problem with the Joint Estimator is that it just mirrors the training data.

We need something which generalizes more usefully.

The naïve model generalizes strongly:

Assume that each attribute is distributed independently of any of the other attributes.

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Independently Distributed Data

- Let x[i] denote the i th field of record x.
- The independent distribution assumption says that for any i,v, u_1 u_2 ... u_{i-1} u_{i+1} ... u_M

$$\begin{split} P(x[i] = v \mid x[1] = u_1, x[2] = u_2, \dots x[i-1] = u_{i-1}, x[i+1] = u_{i+1}, \dots x[M] = u_M) \\ = P(x[i] = v) \end{split}$$

- Or in other words, x[i] is independent of {x[1],x[2],..x[i-1], x[i+1],...x[M]}
- This is often written as

 $x[i] \perp \{x[1], x[2], \dots x[i-1], x[i+1], \dots x[M]\}$

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A note about independence

- Assume A and B are Boolean Random Variables. Then
 - "A and B are independent" if and only if P(A|B) = P(A)
- "A and B are independent" is often notated as

$$A \perp B$$

Independence Theorems

 Assume P(A|B) = P(A) Then

P(A and B) = P(A) P(B)

 Assume P(A|B) = P(A) Then

 $P(^A|B) = P(^A)$

- Assume P(A|B) = P(A) Then P(B|A) = P(B)
- Assume P(A|B) = P(A) Then $P(A|^B) = P(A)$

Multivalued Independence

For multivalued Random Variables A and B,

$$A \perp B$$

if and only if

$$\forall u, v : P(A = u \mid B = v) = P(A = u)$$

from which you can then prove things like...

$$\forall u, v : P(A = u \text{ and } B = v) = P(A = u)P(B = v)$$

$$\forall u, v : P(B = v \mid A = v) = P(B = v)$$

Back to Naïve Density Estimation

- Let x[i] denote the i'th field of record x:
- Naïve DE assumes x[i] is independent of ${x[1],x[2],..x[i-1], x[i+1],...x[M]}$
- Example:
 - Suppose that each record is generated by randomly shaking a green dice and a red dice
 - Dataset 1: A = red value, B = green value
 - Dataset 2: A = red value. B = sum of values
 - Dataset 3: A = sum of values, B = difference of values
 - Which of these datasets violates the naïve assumption?

Using the Naïve Distribution

- Once you have a Naïve Distribution you can easily compute any row of the joint distribution.
- Suppose A, B, C and D are independently distributed. What is P(A and ~B and C and ~D)?

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Using the Naïve Distribution

- Once you have a Naïve Distribution you can easily compute any row of the joint distribution.
- Suppose A, B, C and D are independently distributed.
 What is P(A and ~B and C and ~D)?

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Naïve Distribution General Case

• Suppose x[1], x[2], ... x[M] are independently

$$P(x[1] = u_1, x[2] = u_2, \dots x[M] = u_M) = \prod^M P(x[k] = u_k)$$

- So if we have a Naïve Distribution we can construct any row of the implied Joint Distribution on demand.
- So we can do any inference
- But how do we learn a Naïve Density Estimator?

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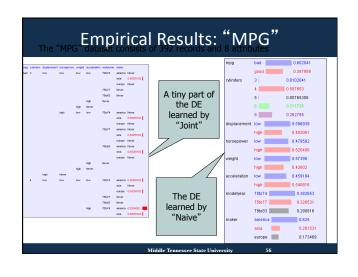
Learning a Naïve Density Estimator

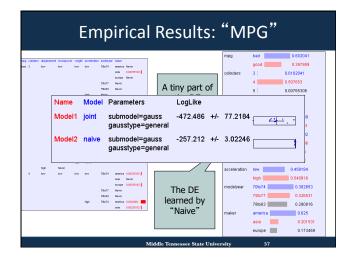
 $\hat{P}(x[i] = u) = \frac{\text{\#records in which } x[i] = u}{\text{total number of records}}$

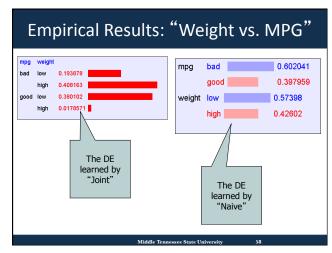
Another trivial learning algorithm!

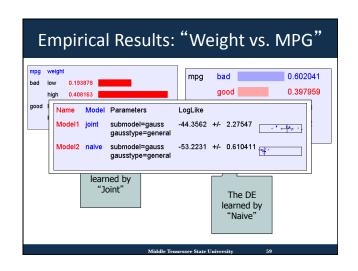
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Joint DE	Naïve DE
Can model anything	Can model only very boring distributions
No problem to model "C is a noisy copy of A"	Outside Naïve's scope
Given 100 records and more than 6 Boolean attributes will screw up badly	Given 100 records and 10,000 multivalued attributes will be fine

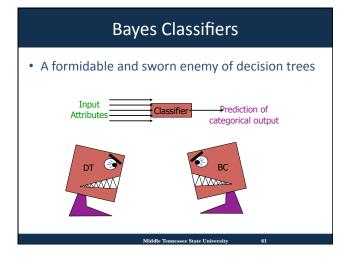


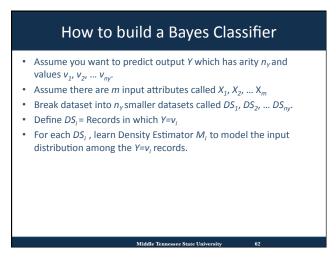






Reminder: The Good News • We have two ways to learn a Density Estimator from data. • Other, vastly more impressive Density Estimators developed - Mixture Models, Bayesian Networks, Density Trees, Kernel Densities and many more • Density estimators can do many good things... - Anomaly detection - Can do inference: P(E1|E2) Automatic Doctor / Help Desk etc - Ingredient for Bayes Classifiers





How to build a Bayes Classifier

- Assume you want to predict output Y which has arity n_y and values $v_1, v_2, ... v_{nv}$.
- Assume there are m input attributes called $X_1, X_2, ... X_m$
- Break dataset into n_{γ} smaller datasets called DS_{1} , DS_{2} , ... $DS_{n\gamma}$.
- Define DS_i = Records in which $Y=v_i$
- For each DS_i , learn Density Estimator M_i to model the input distribution among the $Y=v_i$ records.
- M_i estimates $P(X_1, X_2, ... X_m \mid Y=v_i)$

How to build a Bayes Classifier

- Assume you want to predict output Y which has arity n_Y and values $V_1, \ V_2, \ ... \ V_{ny}.$
- Assume there are m input attributes called $X_1, X_2, ... X_m$
- Break dataset into n_Y smaller datasets called DS_1 , DS_2 , ... DS_{n_Y} .
- Define DS_i = Records in which $Y=v_i$
- For each DS_i , learn Density Estimator M_i to model the input distribution among the $Y=v_i$ records.
- M_i estimates $P(X_1, X_2, ... X_m | Y=v_i)$
- Idea: When a new set of input values (X₁ = u₁, X₂ = u₂, X_m = u_m) come along to be evaluated predict the value of Y that makes P(X₁, X₂, ... X_m | Y=v_i) most likely

$$Y^{\text{predict}} = \underset{v}{\operatorname{argmax}} P(X_1 = u_1, X_2 = u_2, \dots X_m = u_m \mid Y = v)$$

Is this a good idea?

How to build a Bayes Classifier

very unlikely

- Assume you want to predict output This is a Maximum Likelihood .. Vny • Assume there are *m* input attribute classifier.
- Break dataset into n_{γ} smaller dataset
- It can get silly if some Ys are • Define DS_i = Records in which $Y=v_i$
- For each DS_i , learn Density Estimat records.
- M_i estimates P(X₁, X₂, ... X_m | Y=v_i)
- $= u_1, X_2 = u_2, \dots, X_m = u_m$) come along Idea: When a new set of input values (X.) to be evaluated predict the value of Y that makes $P(X_1, X_2, ... X_m \mid Y = v_i)$ most

$$Y^{\text{predict}} = \underset{v}{\operatorname{argmax}} P(X_1 = u_1, X_2 = u_2, \dots X_m = u_m \mid Y = v)$$

Is this a good idea?

How to build a Bayes Classifier

- Assume you want to predict output Y which Assume there are *m* input attributes called *b*
- Break dataset into n_v smaller datasets called n
- Define DS_i = Records in which Y=v_i
- For each DS_i, learn Density Estimator M_i to n
- M_i estimates $P(X_1, X_2, ... X_m \mid Y=v_i)$
- Idea: When a new set of input value $y=u_1, X_2=u_2, \dots, X_m=u_m$) come along to be evaluated predict the value of Y that makes $\mathbf{P}(\mathbf{Y}=\mathbf{v_j}\mid \mathbf{X_1}, \mathbf{X_2}, \dots \mathbf{X_m})$ most

 $Y^{\text{predict}} = \operatorname{argmax} P(Y = v \mid X_1 = u_1, X_2 = u_2, \dots X_m = u_m)$

Much Better Idea

Terminology

• MLE (Maximum Likelihood Estimator):

$$Y^{\text{predict}} = \underset{v}{\operatorname{argmax}} P(X_1 = u_1 \cdots X_m = u_m \mid Y = v)$$

• MAP (Maximum A-Posteriori Estimator):

$$Y^{\text{predict}} = \operatorname{argmax} P(Y = v \mid X_1 = u_1 \cdots X_m = u_m)$$

Computing a posterior probability

$$Y^{\text{predict}} = \underset{v}{\operatorname{argmax}} P(Y = v \mid X_1 = u_1 \cdots X_m = u_m)$$

$$P(Y = v \mid X_1 = u_1 \cdots X_m = u_m)$$

$$= \frac{P(X_1 = u_1 \cdots X_m = u_m | Y = v)P(Y = v)}{P(X_1 = u_1 \cdots X_m = u_m)}$$

$$= \frac{P(X_1 = u_1 \cdots X_m = u_m \mid Y = v)P(Y = v)}{\sum_{j=1}^{n_y} P(X_1 = u_1 \cdots X_m = u_m \mid Y = v_j)P(Y = v_j)}$$

Bayes Classifiers in a nutshell

- 1. Learn the distribution over inputs for each value Y.
- 2. This gives $P(X_1, X_2, ... X_m / Y=v_i)$.
- 3. Estimate $P(Y=v_i)$ as fraction of records with $Y=v_i$.
- 4. For a new prediction:

$$Y^{\text{predict}} = \underset{v}{\operatorname{argmax}} P(Y = v \mid X_1 = u_1 \cdots X_m = u_m)$$

$$= \underset{v}{\operatorname{argmax}} P(X_1 = u_1 \cdots X_m = u_m \mid Y = v) P(Y = v)$$

Bayes Classifiers in a nutshell

- Step 1. Learn the distribution over inputs for each value Y.
- Step 2. This gives $P(X_1, X_2, ...)$ We can use our favorite Density Estimator here.

• Step 3. Estimate $P(Y=v_i)$. as Right now we have two with $Y=v_i$.

• Step 4. For a new prediction • Joint Density Estimator • Naïve Density Estimator

$$\begin{split} Y^{\text{predict}} &= \underset{v}{\operatorname{argmax}} \ P(Y = v \mid X_1 = u_1 \cdots X_m = u_m) \\ &= \underset{v}{\operatorname{argmax}} \ P(X_1 = u_1 \cdots X_m = u_m \mid Y = v) P(Y = v) \end{split}$$

Joint Density Bayes Classifier

$$Y^{\text{predict}} = \operatorname{argmax} P(X_1 = u_1 \cdots X_m = u_m \mid Y = v) P(Y = v)$$

- In the case of the joint Bayes Classifier this degenerates to a very simple rule:
- $Y^{predict}$ = the most common value of Y among records in which $X_1 = u_1, X_2 = u_2, \dots, X_m = u_m$.
- Note that if no records have the exact set of inputs X₁ = u₁, X₂ = u₂, X_m = u_m, then P(X₁, X₂, ... X_m / Y=v₁) = 0 for all values of Y.
- In that case we just have to guess Y's value

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Naïve Bayes Classifier

$$Y^{\text{predict}} = \operatorname{argmax} P(X_1 = u_1 \cdots X_m = u_m \mid Y = v) P(Y = v)$$

• In the case of the naive Bayes Classifier this can be simplified:

$$Y^{\text{predict}} = \underset{v}{\operatorname{argmax}} P(Y = v) \prod_{j=1}^{n_{y}} P(X_{j} = u_{j} \mid Y = v)$$

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An Example Temperature Humidity D1 hot high weak sunny no D2 sunny hot high strong D3 overcast hot high weak D4 high weak yes normal weak yes D6 rain normal cool strong no D7 overcast normal strong D8 D9 sunny cool normal weak yes D10 rain mild normal weak yes D11 sunnv mild normal strong strong D12 mild high normal weak high strong

To Learn a Naïve Bayes Classifier from this data

Two classes: $y=v_1$: play golf=no

y=v2: play golf=yes

four attributes:

x₁: three values (sunny, overcast, rain)

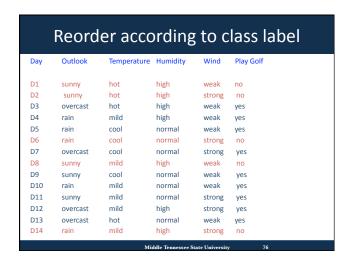
x₂: three values (hot, mild, cool)

x₃: two values (high, normal)

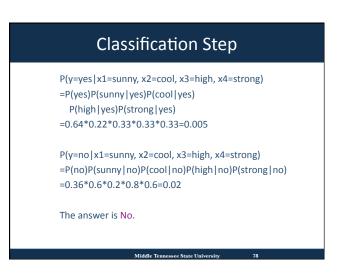
x₄: two values (weak, strong)

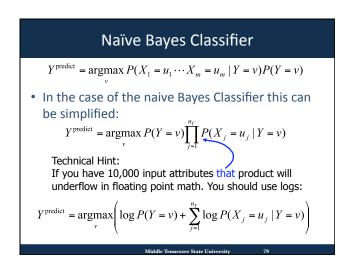
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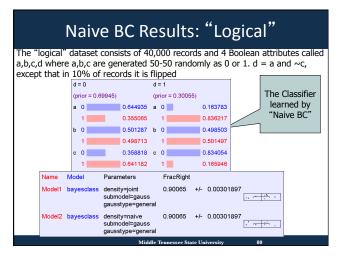
Which probabilities do we need to compute? • P(class1 = yes) P(class2=no) P(a1=sunny|y=yes) P(a1=overcast|y=yes) P(a1=sunny|y=no) P(a1=overcast|y=no) P(a1=rain|y=no) P(a1=rain|y=yes) P(a2=hot|y=yes) P(a2=hot|y=no)P(a2=mild|y=no) P(a2=mild|y=yes) P(a2=cool|y=no) P(a2=cool|y=yes) P(a3=high|y=yes) P(a3=high|y=no) P(a3=normal|y=no) P(a3=normal|y=yes) P(a4=weak|y=yes) P(a4=weak|y=no) P(a4=strong|y=yes) P(a4=strong|y=no)

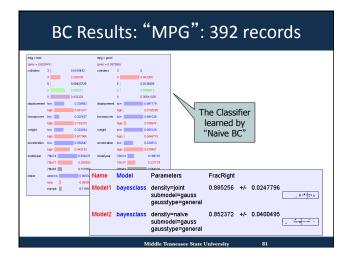


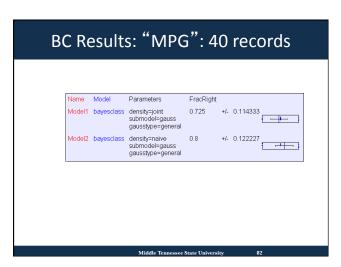
Given a new case/object: outlook=sunny, temperature=cool, humid=high, wind = strong Question: whether to play or not to play golf?











Classify text with naïve Bayes classifier

- Why?
 - Learn which news articles are of interest
 - Learn to classify web pages by topic
 - Spam control...
- Naïve Bayes is among the most effective algorithms

What attributes shall we use to represent text documents?

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Text Classification – data formulation

• Class label:

Target concept Interesting?

Document → {class1=yes, class2=no}

- represent each document by vector of words (one attribute per word position in document)
 - Remove stopwords, numbers, tags, single letters, ...
 - Change all words to lower case
 - Stemming (only retain roots)
 - Remove words appeared only once

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Naïve Bayes Classifier for Text Classification

Build classifier: estimate

P(class1=yes), P(class2=no),
P(doc|class1=yes), P(doc|class2=no)

conditional independence assumption:

$$P(doc \mid class_{j}) = \prod_{i=1}^{length(doc)} P(a_{i} = w_{k} \mid class_{j})$$
Probability word in position *i* is w_{k} for class_j

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Naïve Bayes Classifier for Text Classification

 Additional assumption: positional independence assumption

drop word positioning

 $P(a_i=w_k|class_j) = P(a_m=w_k|class_j)$, for all i, mTherefore,

$$P(doc \mid class_{j}) = \prod_{i=1}^{length(doc)} P(a_{i} = w_{k} \mid class_{j})$$
$$= \prod_{i}^{length(doc)} P(w_{i} \mid class_{j})$$

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Steps in Learning Naïve Bayes Text Classifier

- Collect all words and other tokens that occur in examples
- Vocabulary = all distinct words and other tokens in the examples
- Calculate P(class_j) and P(w_k | class_j) for each target value class_i:
 - doc_j = subset of document examples for which the target value is class_i
 - $-P(class_i) = |doc_i| / |all document examples|$
 - text_j ← a single document created by concatenating all members of doc_i

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Steps in Learning Naïve Bayes Text Classifier

- n = total number of words in Text_j (counting duplicate words multiple times)
- for each word w_k in Vocabulary

 n_k = number of times word w_k occurs in Text_i

$$P(w_k \mid class_j) = \frac{(n_k + 1)}{n + \mid vocabulary \mid}$$

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Steps in Classifying a Document using the Naïve Test Classifier

- Positions = all word positions in the document that contain tokens found in Vocabulary
- Return v_{NB} , where

$$v_{NB} = \underset{j}{\operatorname{arg\,max}} P(class_j) \prod_{i \in positions} P(w_i \mid class_j)$$

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Example Application: Classify newsgroup documents

Given 1000 training documents from each group, learn to classify new documents according to which newsgroup it came from:

 comp.graphics
 misc.forsale

 comp.os.ms-windows.misc
 rec.autos

 comp.sys.ibm.pc.hardware
 rec.motorcycles

 comp.sys.mac.hardware
 rec.sport.hockey

....

Result: Naïve Bayes obtained 89% classification accuracy

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