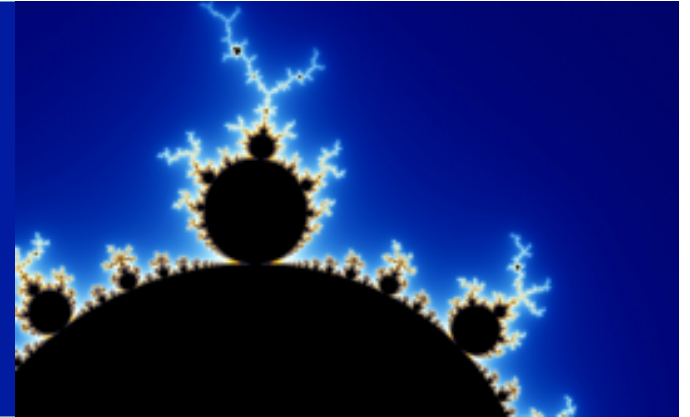
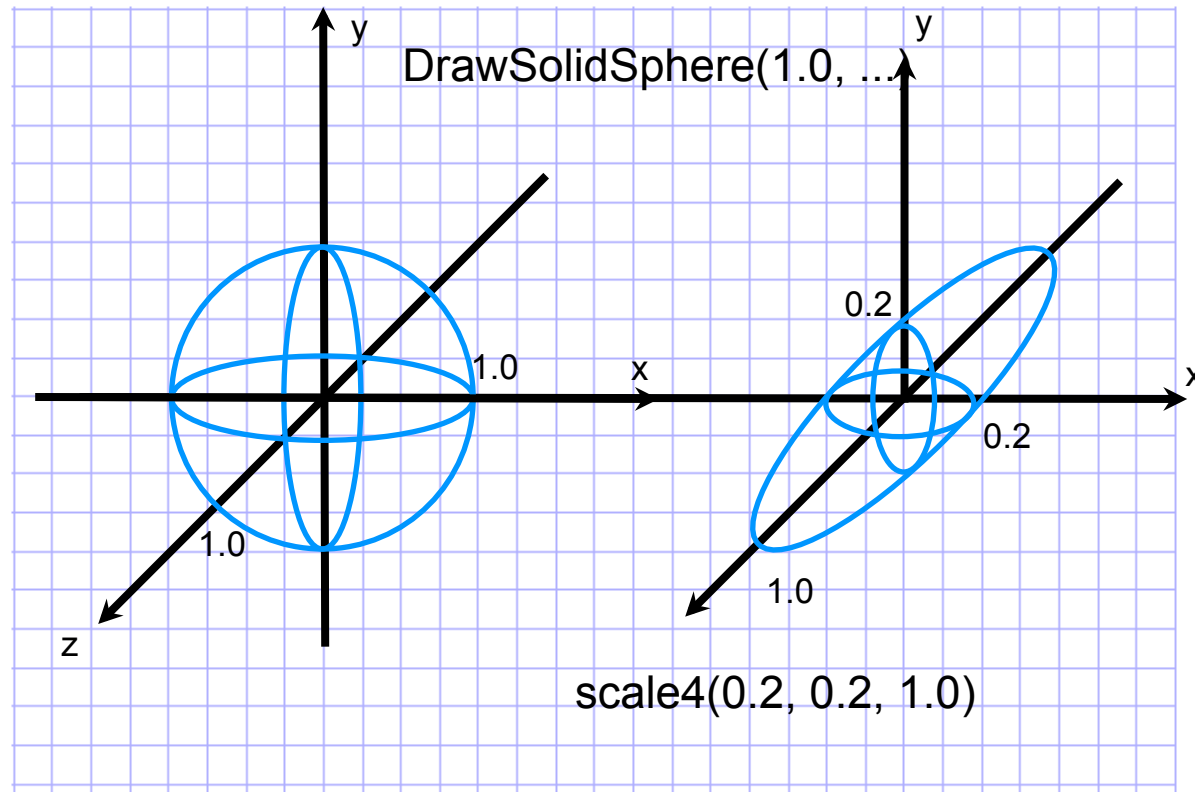


Computer Graphics



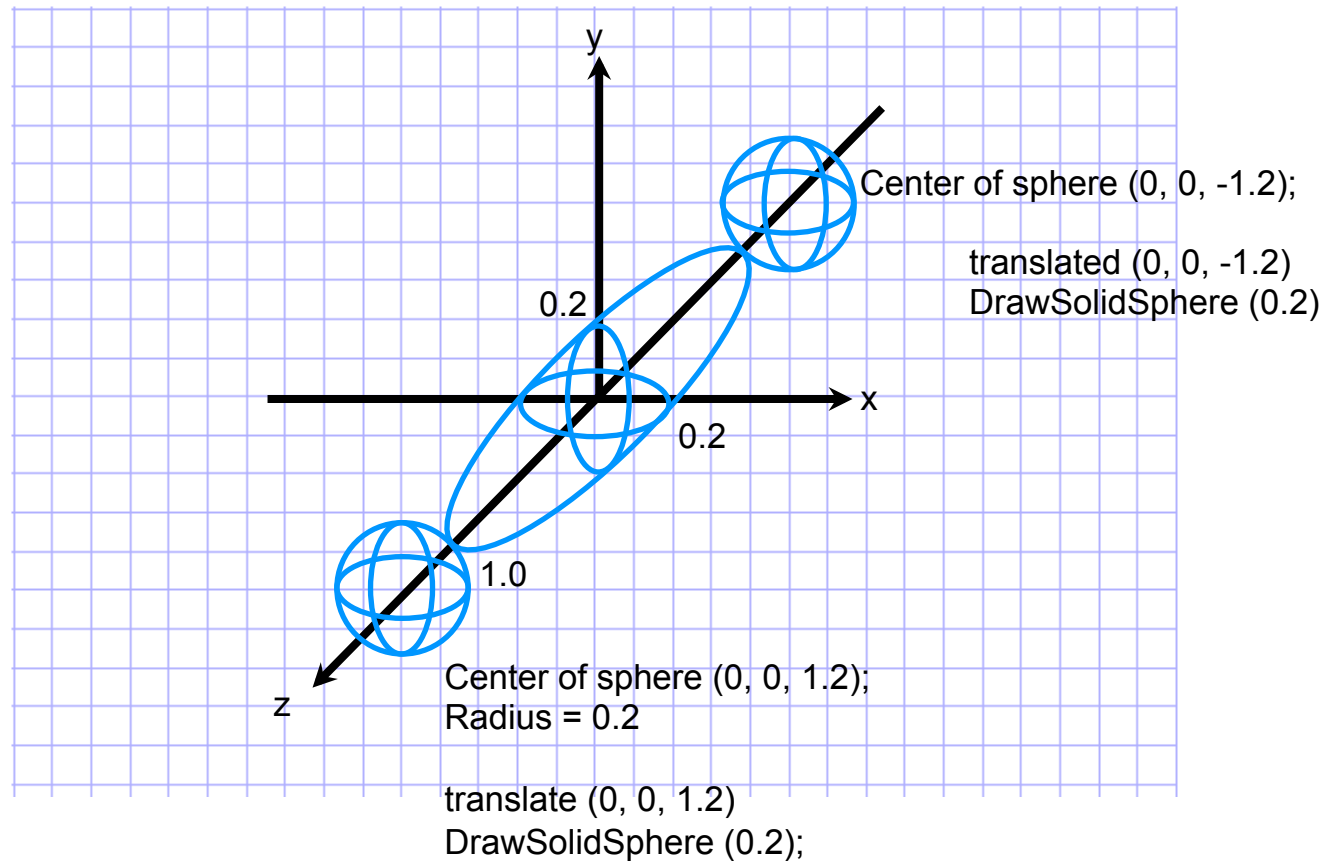
Build 3D objects Using 3D Primitives

Jack Construction



Solid sphere centered at origin

Jack Construction



Jack Construction

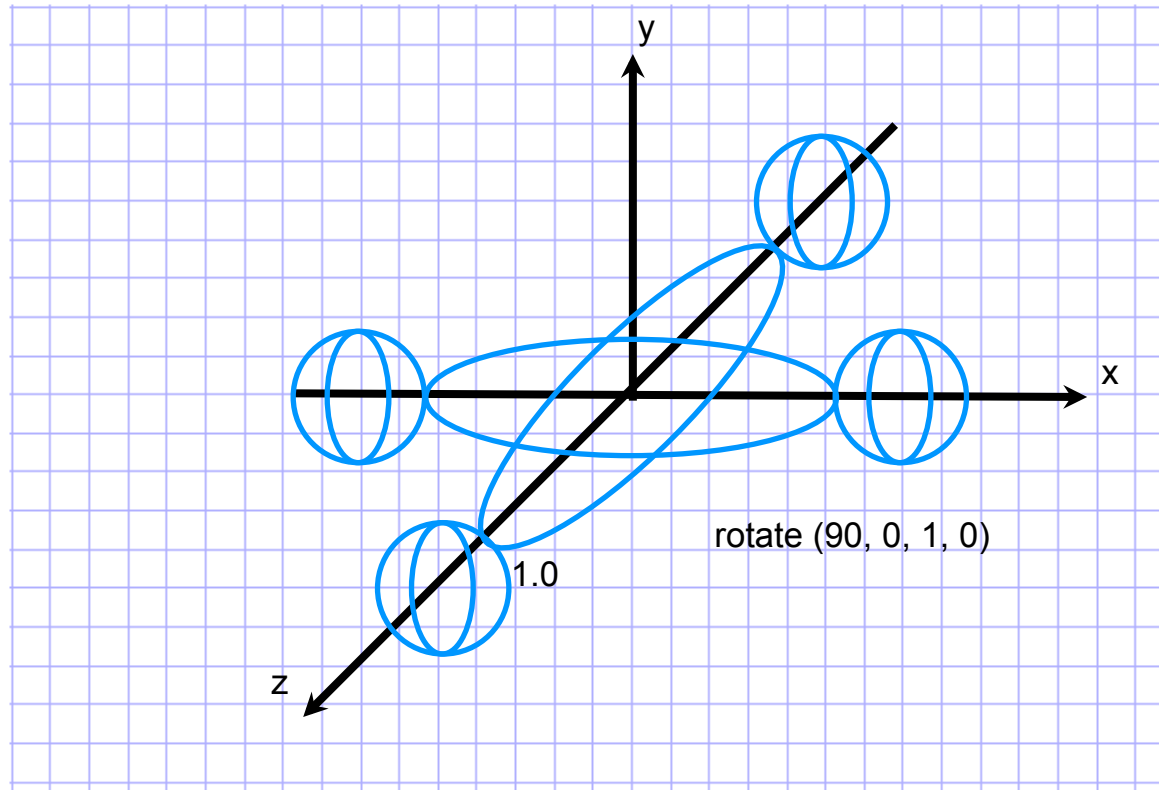


Table Construction

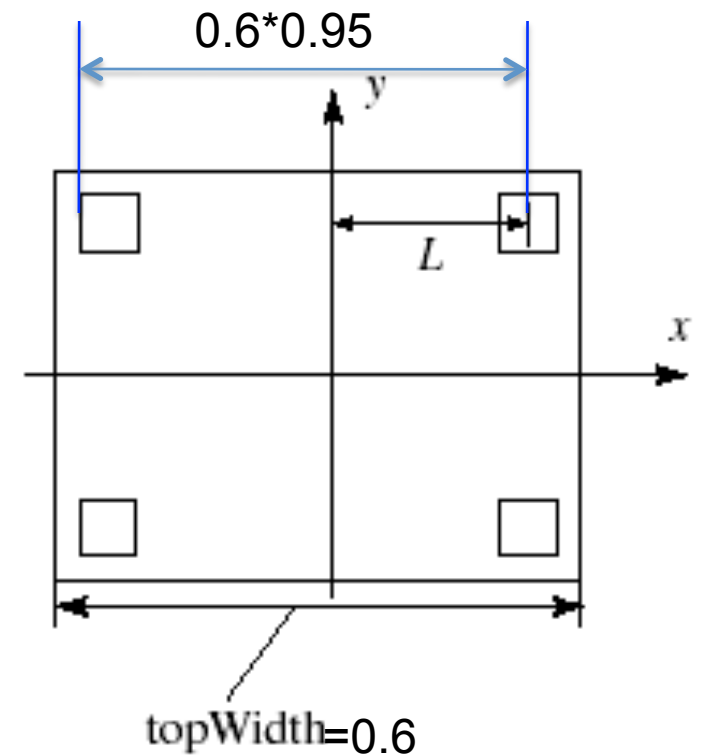
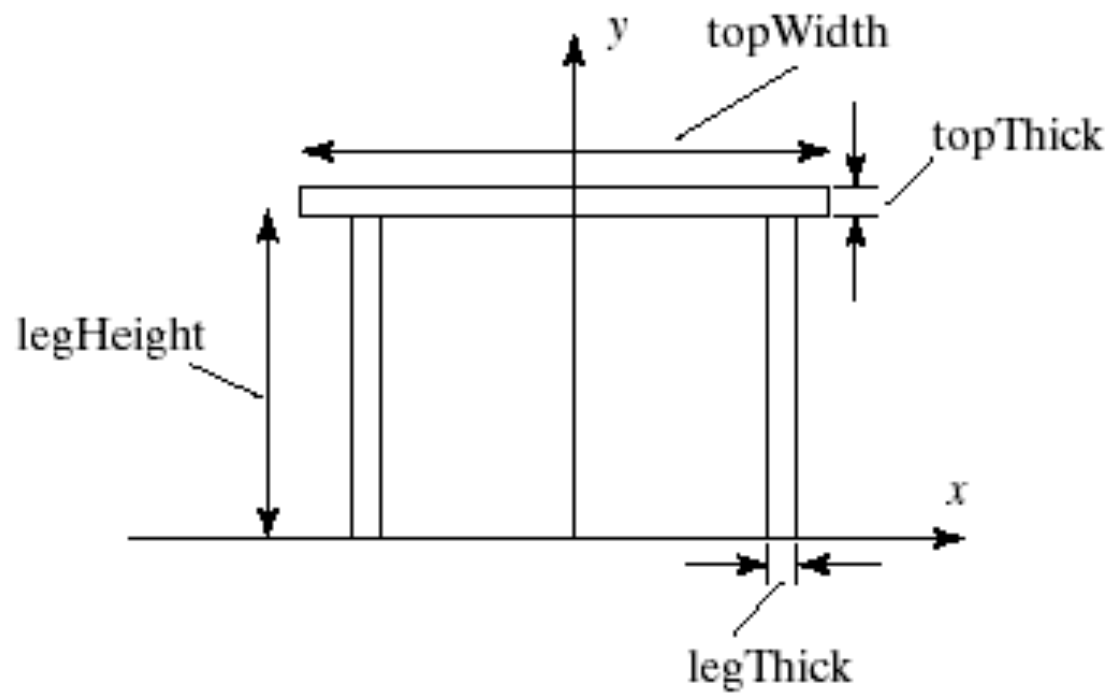
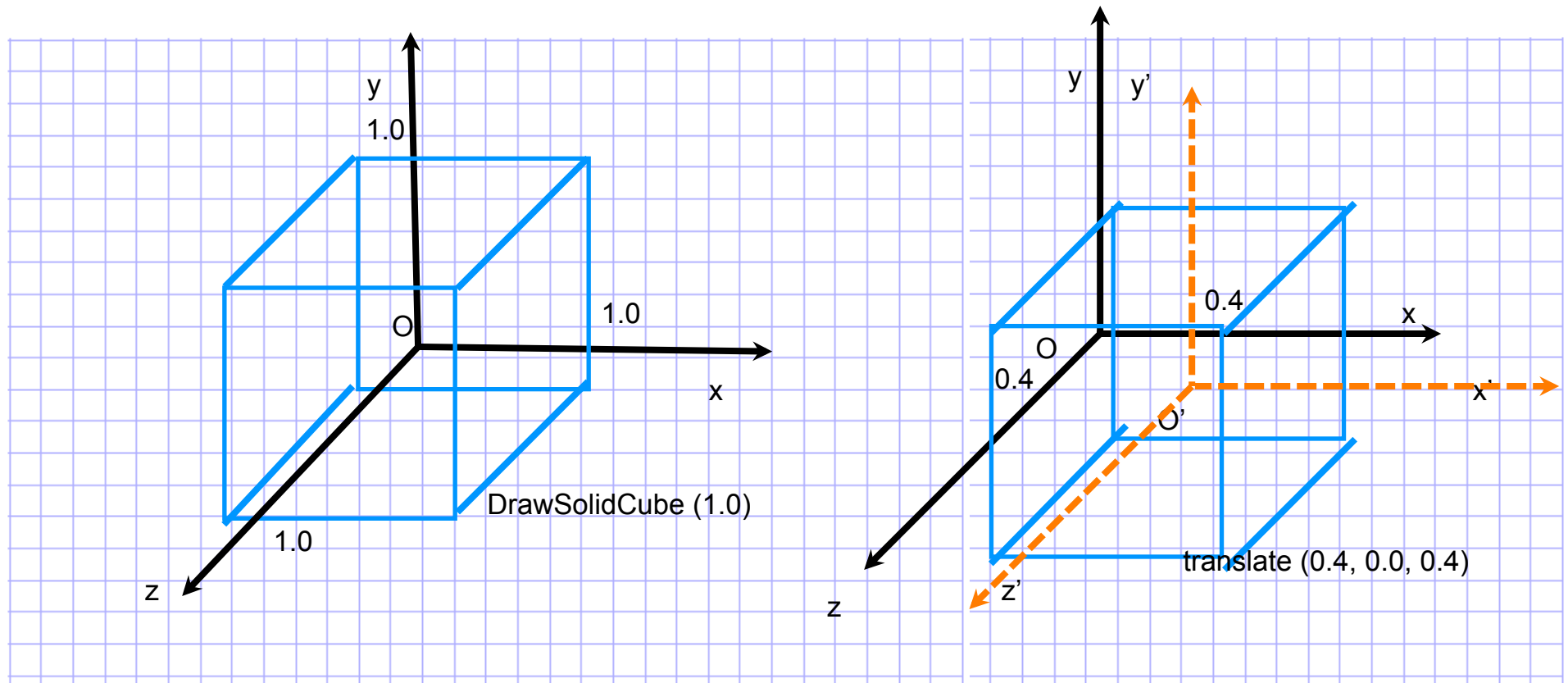


Table Top



Coordinate system translated to the new origin O'

Draw Table Top

Table Top

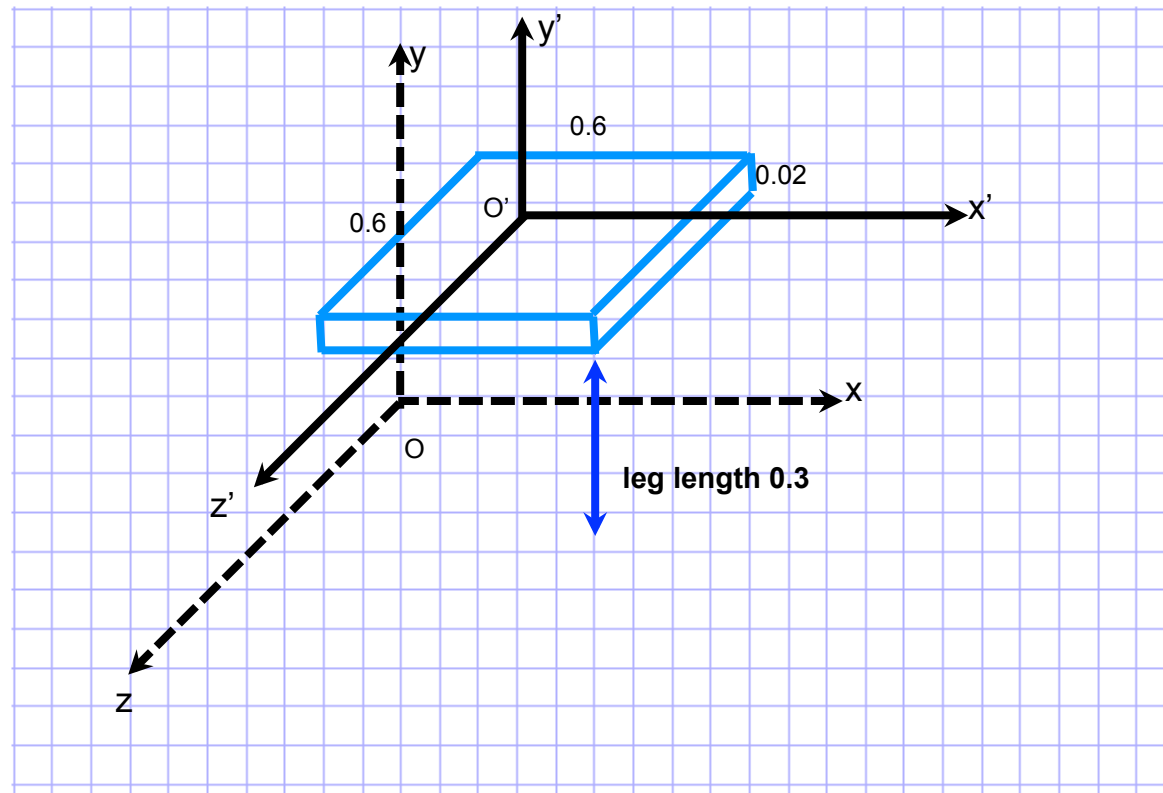


Table Width = 0.6
Table Thickness = 0.02

Table Top

```
modelViewMatrix.push()
```

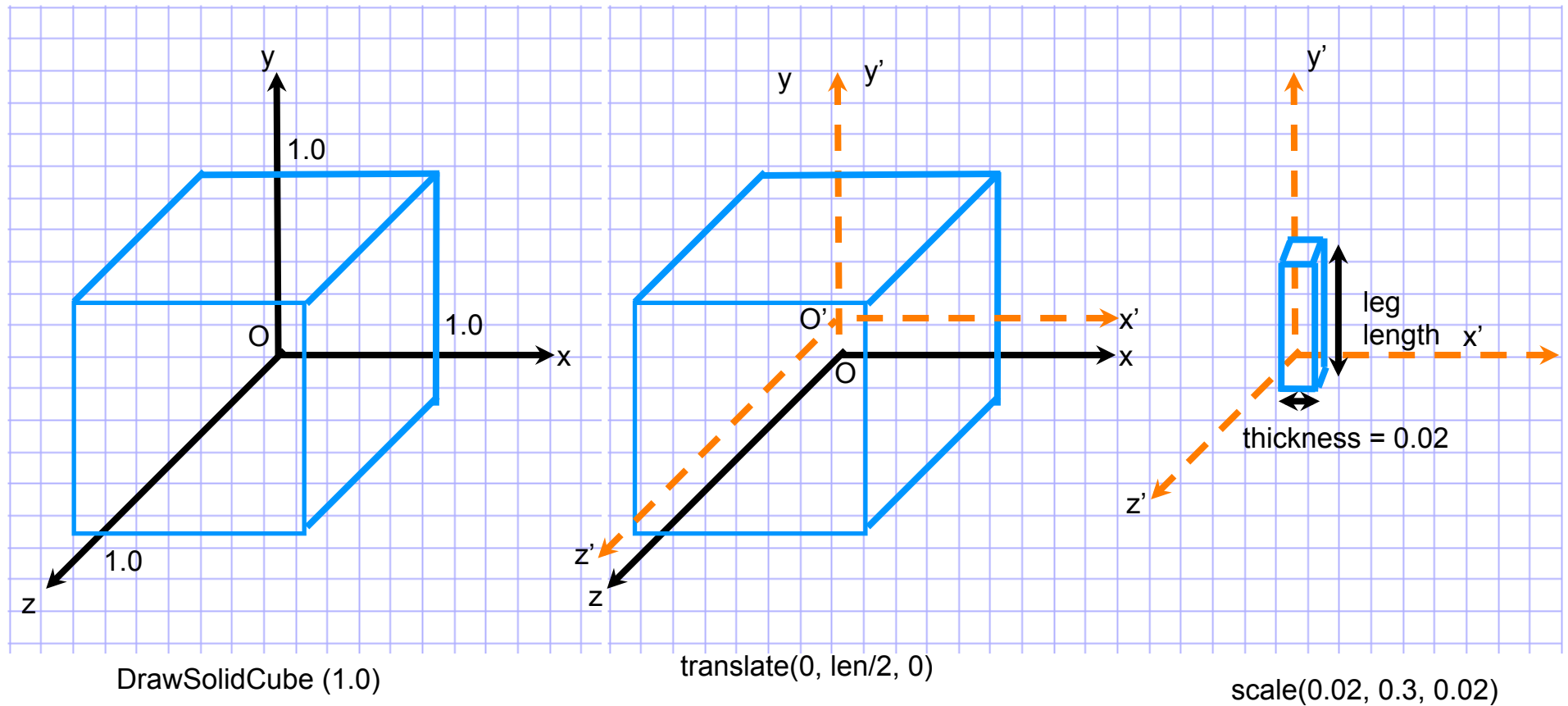
```
translate (0, 0.3, 0) // O' raised 0.3 from 0 along y
```

```
scale(0.6, 0.02, 0.6) // O' (0.4, 0.3, 0.4)
```

```
DrawSolidCube (1.0)
```

```
modelviewMatrix.pop()
```

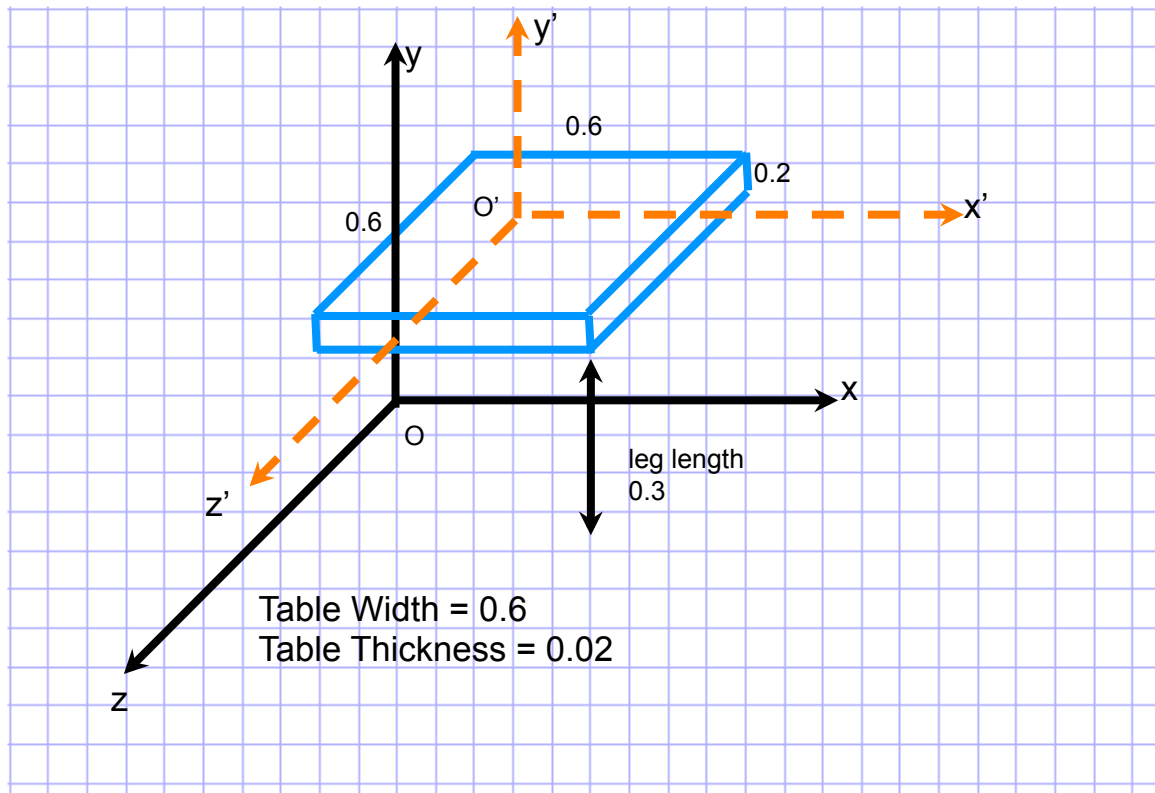
Table Leg



Leg Thickness = 0.02
Leg Length = 0.3

Draw Table Leg

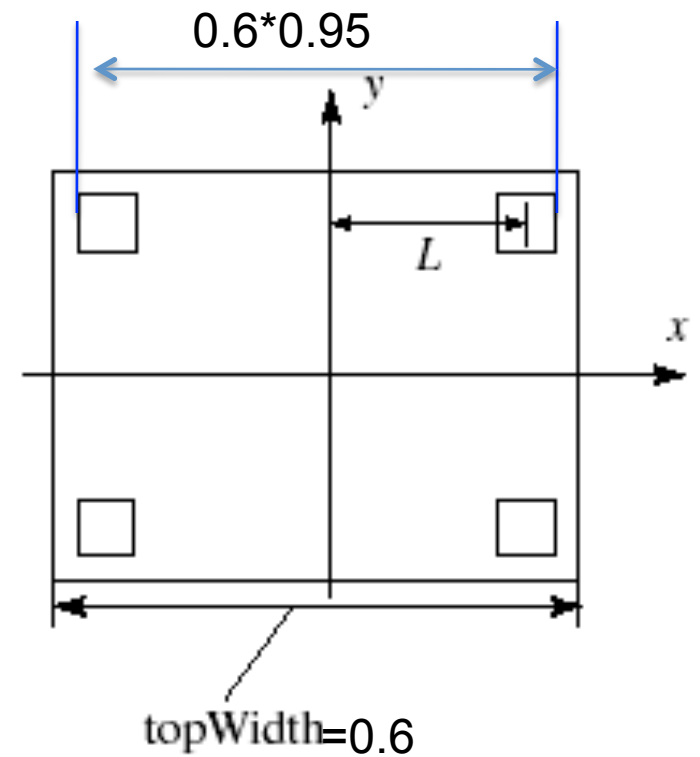
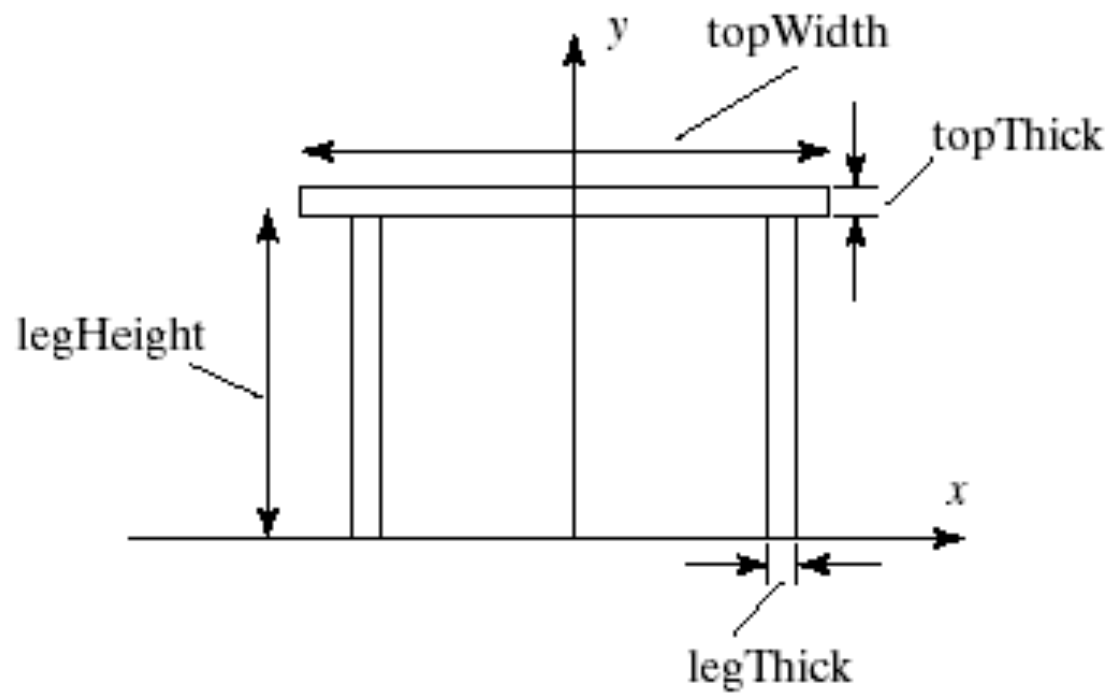
Place Table Leg



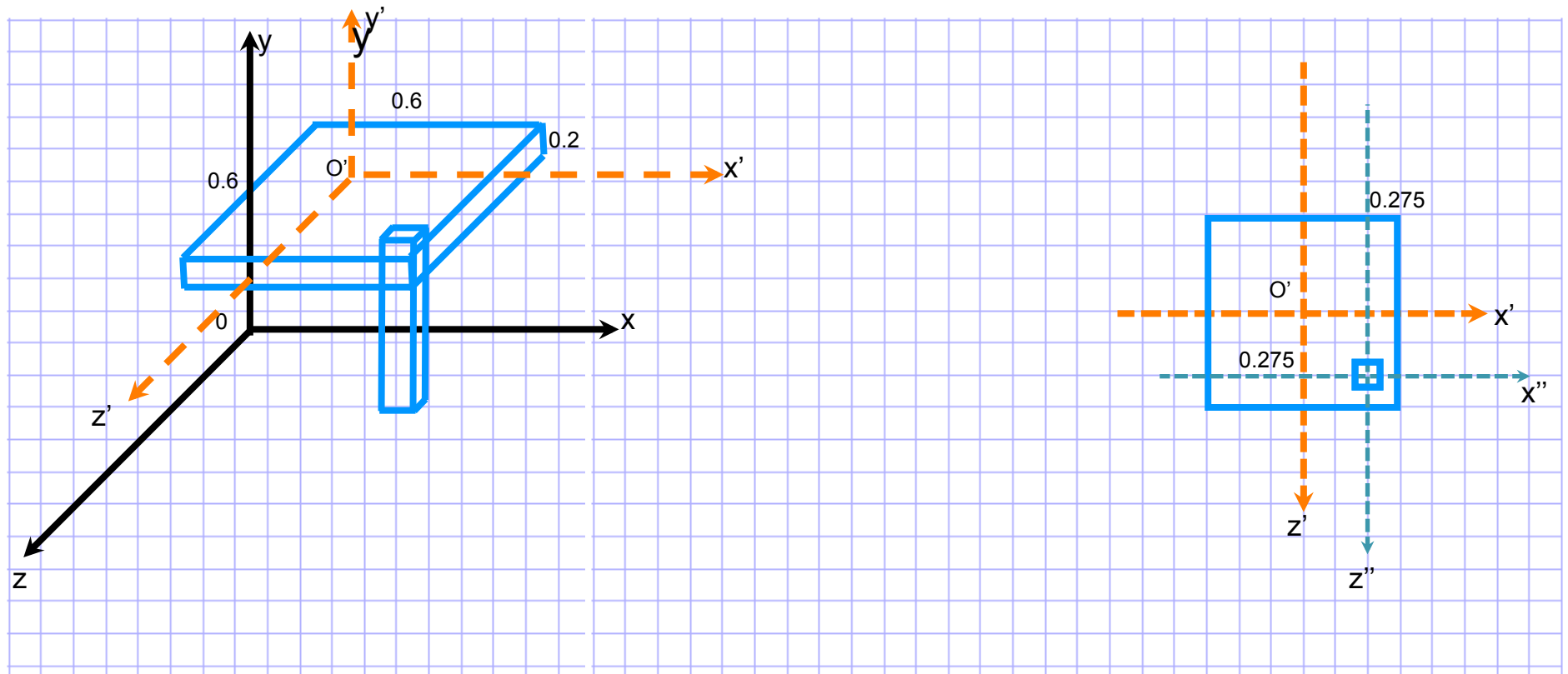
```
modelViewMatrix.push()
translate(0, 0.3, 0)
scale(0.6, 0.02, 0.6)
DrawSolidCube (1.0)
modelViewMatrix.pop()
```

Assemble The Table (draw table)

Assemble Table



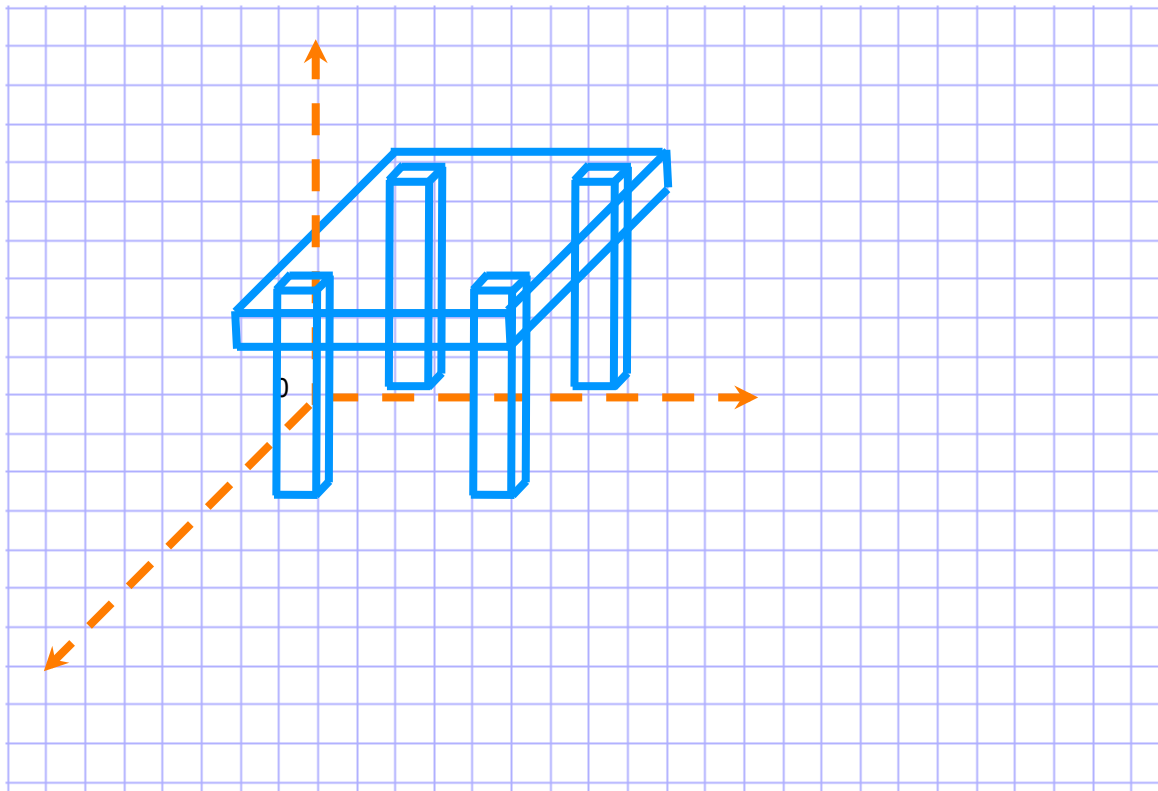
Assemble Table



```
modelViewMatrix.push()  
dist = 0.6 * 0.95 / 2 - 0.02 / 2.0 = 0.275  
translate(0.275, 0, 0.275)  
DrawTableLeg(0.02, 0.3)
```

```
modelViewMatrix.push()  
translate(0, len/2, 0)  
scale(0.02, len, 0.02)  
DrawSolidCube(1.0)  
modelViewMatrix.pop()
```

Assemble Table



Assembled Table

dist = 0.275

```
translate(0, 0, -2*dist)  
DrawTableLeg(0.02, 0.3)
```

```
translate(-2*dist, 0, 2*dist)  
DrawTableLeg(0.02, 0.3)
```

```
translate(0, 0, -2*dist)  
DrawTableLeg(0.02, 0.3)
```



Example Code

- The code to draw each object is imbedded in a `modelViewMatrix.push(), modelViewMatrix.pop()` pair.
- To draw the x -axis, the z -axis is rotated 90° about the y -axis to form a rotated system, and the axis is redrawn in its new orientation.
- This axis is drawn without immersing it in a pair `modelViewMatrix.push(), modelViewMatrix.pop()` , so the rotation to produce the y -axis takes place in the already rotated coordinate system.