

**Homework 8 (Due: beginning of class, Monday Oct 24<sup>th</sup>)**

1. Transformation applied to points
  - a. Write out the following 4x4 matrices and label each with the following names:  
T0: Translate in x by 4 and in y by 3  
R: Rotate about the z axis by  $\pi/4$  (45 degrees)  
T1: Translate in x by -4 and in y by -3  
S: Scale in x by a factor of 2 and y by a factor of 4 (z is unchanged)
  - b. Assume you have an object you want to rotate by  $\pi/4$  around a z-axis centered at (4, 3, 0). Using the symbols T0, R, and T1, show the correct order of composition of these matrices to perform the desired rotation.
  - c. Find the composite matrix M by multiply out your answer from question 1.b.
  - d. Apply the transformation matrix M to the 3D point  $P=(7, 5, 7)$  to find the transformed point Q by multiply it out.
2. Coordinate Transformation
  - a. Assume you have an object you want to rotate by  $\pi/4$  around a z-axis centered at (4, 3, 0). How should the coordinate system be transformed? Compute the Current Transformation (CT) matrix as a result of that transformation.
  - b. For a 3D point  $P'=(4, 3, 4)$  in the transformed coordinate system, what is its coordinates in the original coordinate system?

< you may use Matlab or other software for the matrix computations >

3. Read the handout on Display Lists