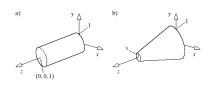




#### Generic Tapered Cylinder

- Axis coincides with z-axis; circular cross section of radius 1 at base, s when z = 1; extends in z from 0 to 1.
- The tapered cylinder with an arbitrary value of *s* provides formulas for the generic cylinder and cone by setting *s* to 1 or 0, respectively.



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#### Generic Tapered Cylinder (2)

• The wall of the tapered cylinder is given by the implicit form  $F(x, y, z) = x^2 + y^2 - (1 + (s - 1)z)^2 \quad 0 < z < 1$  for 0 < z < 1, and by the parametric form

$$P(u,v) = ((1+(s-1)v)\cos(u), (1+(s-1)v)\sin(u), v)$$
  
0 \le u \le 2\pi 0 \le v \le 1

• When the tapered cylinder is a solid object, we add two circular discs at its ends: a **base** and a **cap**. The cap is a circular portion of the plane z = 1, characterized by the inequality  $x^2 + y^2 < s^2$ , or given parametrically by  $P(u, v) = (v \cos(u), v \sin(u), 1)$  for v in [0, s].

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## Generic Tapered Cylinder (3)

The normal vector to the wall of the tapered cylinder is
 n(x, y, z) = (x, y, -(s - 1)(1+ (s - 1)z)),
 or in parametric form

 $\mathbf{n}(u, v) = (\cos(u), \sin(u), 1 - s).$ 

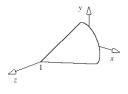
- For the generic cylinder the normal is simply (cos(u), sin(u), 0).
- The normal is directed radially away from the axis of the cylinder. For the tapered cylinder it is also directed radially, but shifted by a constant z-component.

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#### **Generic Cone**

 A cone whose axis coincides with the z-axis, has a circular cross section of maximum radius 1, and extends in z from 0 to 1. It is a tapered cylinder with small radius of s = 0.



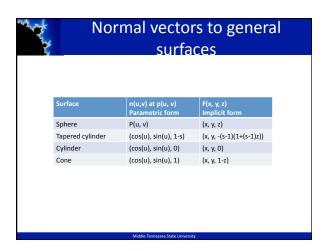
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## Generic Cone (2)

- Wall:  $F(x, y, z) = x^2 + y^2 (1 z)^2 = 0$  for 0 < z < 1; parametric form P(u, v) = ((1-v) cos(u), (1-v) sin(u), v) for azimuth u in  $[0, 2\pi]$  and v in [0, 1].
- Using the results for the tapered cylinder again, the normal vector to the wall of the cone is (x, y, 1-z).

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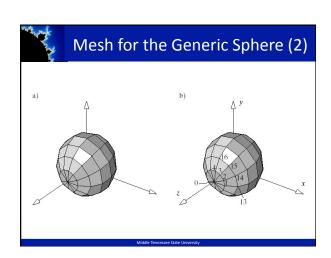




#### Mesh for the Generic Sphere

- We slice the sphere along azimuth lines and latitude lines.
- We slice the sphere into nSlices slices around the equator and nStacks stacks from the South Pole to the North Pole.
- The figure (next slide) shows the example of 12 slices and 8 stacks.
- The larger nSlices and nStacks are, the better the mesh approximates a true sphere.

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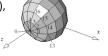




#### Mesh for the Generic Sphere (3)

- To make slices we need nSlices values of u around the equator between 0 and  $2\pi$ . Usually these are chosen to be equal-spaced:  $u_i = i^*(2\pi/n\text{Slices}), i = 0, 1, ..., n\text{Slices} -1$ .
- We put half of the stacks above the equator and half below. The top and bottom stacks will consist of triangles; all other faces will be quadrilaterals.

This requires we define (nStacks + 1) values of latitude:  $v_j = \pi - j*(\pi / nStacks)$ , j = 0, 1, ..., nStacks.



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#### Mesh for the Generic Sphere (4)

- The vertex list: put the north pole in pt[0], the bottom points of the top stack into the next 12 vertices, etc. There will be 86 points.
- The normal vector list: norm[k] is the normal for the sphere at vertex pt[k] in parametric form; n(u,v) is evaluated at (u,v) used for the points.
  - For the sphere this is particularly easy since norm[k] is the same as pt[k].

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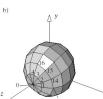
#### Mesh for the Generic Sphere (5)

- The face list: Put the top triangles in the first 12 faces, the 12 quadrilaterals of the next stack down in the next 12 faces, etc.
- The first few entries in the face list will contain the data

 number of vertices:
 3
 3
 ...

 vertex indices:
 0 1 2
 0 2 3
 0 3 4
 ...

 normal indices:
 0 1 2
 0 2 3
 0 3 4
 ...



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#### **General Meshes**

- Ultimately we need a method, such as makeSurfaceMesh(), that generates appropriate meshes for a given surface P(u, v).
- Some graphics packages have routines that are highly optimized for triangles, making triangular meshes preferable to quadrilateral ones.
- We can use the same vertices, but alter the face list by replacing each quadrilateral with two triangles.
  - For instance, a face that uses vertices 2, 3, 15, 14 might be subdivided into two triangles, one using 2, 3, 15 and the other using 2, 15, 14.

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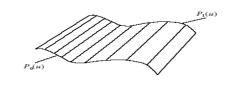
## Mesh for the Tapered Cylinder

- We use nSlices = 10 and nStacks = 1.
- A decagon is used for the cap and base.
- If you prefer to use only triangles, the walls, the cap, and the base could be dissected into triangles.



# Ruled Surfaces through every point, these

- Ruled Surface: through every point, there passes at least one straight line lying entirely on the surface.
- Made by moving the ends of a straight line along curves.

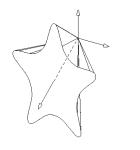


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## Ruled Surfaces (2)

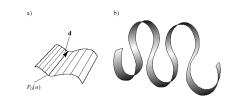
 A cone is a ruled surface for which one of the curves, say, P<sub>0</sub>(u), is a single point P<sub>0</sub>(u) = P<sub>0</sub>, the apex of the cone.



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## Ruled Surfaces (3)

 A cylinder is a ruled surface for which P<sub>1</sub>(u) is a translated version of P<sub>0</sub>(u): P<sub>1</sub>(u) = P<sub>0</sub>(u) + d, for some vector d.

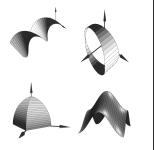


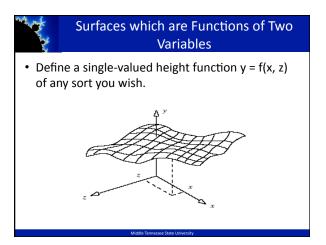
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## Ruled Surfaces (5)

- Double helix:  $P_0(u)$  and  $P_1(u)$  are both helixes that wind around each other.
- Möbius strip (has only one edge).
- Vaulted roof made up of four ruled surfaces.
- Coons patch named after the legendary graphicist Steven Coons.

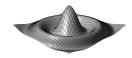






## Surfaces which are Functions of Two Variables (2)

- Parametric form: P(u, v) = (u, f(u, v), v)
- Normal vector  $\mathbf{n}(\mathbf{u}, \mathbf{v}) = -\left(\frac{\partial f}{\partial u}, -1, \frac{\partial f}{\partial v}\right)$
- Thus *u*-contours lie in planes of constant *x*, and *v*-contours lie in planes of constant *z*.



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