

SGN-12007 Introduction to Image and Video Processing

EXERCISE 7

20.11.2017-21.11.2017

The tasks should be completed and presented to TA during the lab session. Questions about exercises should be addressed to the TA personally or via email: (firstname.surname@tut.fi).

Task 1. Noise generation and restoration

Load 'lena.jpg' and separately add the following noises to it:

- Gaussian noise (Hint: Use `imnoise` function)
- Salt & pepper noise (Hint: Use `imnoise` function)
- Rayleigh noise:
 - If there are multiple independent Gaussian random variables, the magnitude of their combination will follow the Rayleigh distribution. For example: if the image is taken in complex domain and has independent instances of Gaussian noise in both its real part and its imaginary part, the magnitude image will have a Rayleigh noise component.
 - MATLAB: `noise = sqrt(-b*log((1-rand(height,width))))`
 - Add the generated noise to the image to obtain the noisy image.

Select the noise parameters so that image quality deterioration is noticeable and the image quality approximately is same in each case.

Task 2. Restoration of Noisy Images

Filter the image using the following filters. Use 3x3 as the size of the filter. Present your resulting images in four 2-by-2 subplots. The first subplot contains the original image and three types of noisy images. From the second to the fourth subplot, you should have the noisy image of one type on the top left and images filtered with different filters in the other positions.

- Arithmetic mean filter:

$$\hat{f}(x, y) = \frac{1}{mn} \sum_{(s,t) \in S_{xy}} g(s, t)$$

MATLAB: `f = imfilter(g, fspecial('average', [m n]));`

- Geometric mean filter:

$$\hat{f}(x, y) = \left(\prod_{(s,t) \in S_{xy}} u(s, t) \right)^{\frac{1}{mn}},$$

MATLAB: `f = exp(imfilter(log(g), ones(m, n), 'replicate')) .^(1/(m*n))`

(Note: $\log(a*b*c...) = \log(a) + \log(b) + \log(c) + \dots$)

- Harmonic mean filter:

$$\hat{f}(x, y) = \frac{mn}{\sum_{(s,t) \in S_{xy}} \frac{1}{u(s, t)}},$$

MATLAB: `f = (m*n) ./ imfilter(1 ./ (g + eps), ones(m, n), 'replicate');`

Which filtering method is the most suitable for each specific type of the noise? Describe the effects of the filters on each noisy image.

Task 3. Noise cleaning with Weighted Median Filter.

An extension of median filter, which we learned last week, is the **weighted median filter (WMF)**. Besides having the same strengths such as edge preserving and removing the impulse noise, WMF has a better **detail preserving property over the original median filter**¹. In this exercise, we implement a simple WMF and identify its strengths.

- Load the `baboon.png`, and add salt and pepper noise with a variance of 0.02.
- Implement the WMF with a window of 5 by 5. The output of weighted median is presented in the equation below. Fill the center of weight kernel with 5 and keep the rest with 1.

$$y(n) = \text{MEDIAN}[W_1 \diamond x_1(n), W_2 \diamond x_2(n), \dots, W_N \diamond x_N(n)],$$

- Show the original image, noisy image, original median filtered image and the one by WMF in a 2-by-2 subplot.

¹ *More details can be found in Yang, et al., "Optimal Weighted Median Filtering Under Structural Constraints", IEEE Transactions on Signal Processing, 1994.