

# SGN-11006. Basic Course in Signal Processing.

## Exercise #9. Solutions.

I  $y[n] = a_1 x[n+k+1] + a_2 x[n+k] + a_2 x[n+k-2] + a_1 x[n+k-3]$

$$Y(e^{j\omega}) = a_1 X(e^{j\omega}) e^{(k+1)j\omega} + a_2 X(e^{j\omega}) e^{kj\omega} + a_2 X(e^{j\omega}) e^{(k-2)j\omega} + a_1 X(e^{j\omega}) e^{(k-3)j\omega}$$

$$H(e^{j\omega}) = \frac{Y(e^{j\omega})}{X(e^{j\omega})} = a_1 e^{(k+1)j\omega} + a_2 e^{kj\omega} + a_2 e^{(k-2)j\omega} + a_1 e^{(k-3)j\omega}$$

If  $H(e^{j\omega})$  is a real function of  $\omega$  then  $H(e^{j\omega}) = H^*(e^{j\omega}) \Rightarrow$   
 $\Rightarrow H(e^{j\omega}) = H(e^{-j\omega}) \Rightarrow$

$$\begin{aligned} \Rightarrow a_1 e^{(k+1)j\omega} + a_2 e^{kj\omega} + a_2 e^{(k-2)j\omega} + a_1 e^{(k-3)j\omega} &= a_1 e^{-(k+1)j\omega} + a_2 e^{-kj\omega} + \\ &+ a_2 e^{-(k-2)j\omega} + a_1 e^{-(k-3)j\omega} \\ e^{(k-1)j\omega} (a_1 e^{2j\omega} + a_2 e^{j\omega} + a_2 e^{-j\omega} + a_1 e^{-2j\omega}) &= e^{-(k-1)j\omega} (a_1 e^{-2j\omega} + a_2 e^{-j\omega} + \\ &+ a_2 e^{j\omega} + a_1 e^{2j\omega}) \\ e^{(k-1)j\omega} &= e^{-(k-1)j\omega} \end{aligned}$$

$$k-1 = -k+1$$

$$2k = 2$$

$$k = 1$$

II  $H(z) = \frac{(5z+6)(2z-3)}{(z-0.3)(z+0.2)} = \frac{10z^2(1+\frac{6}{5}z^{-1})(1-\frac{3}{2}z^{-1})}{z^2(1-0.3z^{-1})(1+0.2z^{-1})} \quad \text{ROC} \equiv |z| > 0.3$

Poles:  $z = 0.3$  and  $z = -0.2$  are inside the unit circle  $\Rightarrow$   
 $\Rightarrow H(z)$  is stable.

} A causal stable TF with all zeroes inside/outside the unit circle is called a minimum/maximum-phase TF

Zeroes:  $z = -6/5$  and  $z = 3/2$  are outside the unit circle  $\Rightarrow$   
 $\Rightarrow H(z)$  is a maximum-phase TF.

For a maximum-phase TF  $H(z)$  corresponding minimum-phase TF  $G(z)$  such that  $|H(e^{j\omega})| = |G(e^{j\omega})|$  can be found from the following equation:  $H(z) = G(z)A(z)$ . (\*)

where  $A(z)$  is a causal stable all pass TF.

} All pass TF of degree  $N$  is defined as follows:  
 $A_N(z) = \pm \frac{z^{-N}(D_N(z^{-1}))}{D_N(z)}$  where  $D_N(z) = 1 + d_1 z^{-1} + \dots + d_{N-1} z^{-N+1} + d_N z^{-N}$   
 $z^{-N}(D_N(z^{-1}))$  is called a mirror-image polynomial.

Let's define  $D(z^{-1})$  as  $(5z+6)(2z-3)$  then  
 $D(z) = (5z^{-1}+6)(2z^{-1}-3)$  and  $A(z) = \frac{z^{-2}(5z+6)(2z-3)}{(5z^{-1}+6)(2z^{-1}-3)}$

Then  $G(z) = \frac{H(z)}{A(z)} = \frac{\cancel{(5z+6)}\cancel{(2z-3)}(5z^{-1}+6)(2z^{-1}-3)}{(2-0.3)(2+0.2)z^{-2}\cancel{(5z+6)}\cancel{(2z-3)}} =$   
 $= \frac{(5+6z)(2-3z)}{(2-0.3)(2+0.2)} = \frac{-18z^2(1+\frac{5}{6}z^{-1})(1-\frac{3}{2}z^{-1})}{2^2(1-0.3z^{-1})(1+0.2z^{-1})} \quad \text{ROC} \equiv |z| > 0.3$

Let  $X(z) = \frac{1}{(1-0.3z^{-1})(1+0.2z^{-1})} = \frac{P_1}{1-0.3z^{-1}} + \frac{P_2}{1+0.2z^{-1}} \quad \text{ROC} \equiv |z| > 0.3$

$P_1 = \frac{1}{1+0.2z^{-1}} \Big|_{z=0.3} = \frac{3}{5} \quad P_2 = \frac{1}{1-0.3z^{-1}} \Big|_{z=-0.2} = \frac{2}{5}$

$X(z) = \frac{3/5}{1-0.3z^{-1}} + \frac{2/5}{1+0.2z^{-1}} \quad \text{ROC} \equiv |z| > 0.3 \xrightarrow{z}$   
 $\xrightarrow{z} x[n] = 0.6(0.3)^n \mu[n] + 0.4(-0.2)^n \mu[n].$

$H(z) = 10(1 + \frac{6}{5}z^{-1} - \frac{3}{2}z^{-1} - \frac{9}{5}z^{-2})X(z) = (10 - 3z^{-1} - 18z^{-2})X(z) \xrightarrow{z}$

$\xrightarrow{z} h[n] = 10x[n] - 3x[n-1] - 18x[n-2] = 6(0.3)^n \mu[n] + 4(-0.2)^n \mu[n] -$   
 $- 1.8(0.3)^{n-1} \mu[n-1] - 1.2(-0.2)^{n-1} \mu[n-1] - 10.8(0.3)^{n-2} \mu[n-2] - 7.2(-0.2)^{n-2} \mu[n-2].$

$G(z) = -18(1 + \frac{5}{6}z^{-1} - \frac{2}{3}z^{-1} - \frac{10}{18}z^{-2})X(z) = (-18 + 3z^{-1} + 10z^{-2})X(z) \xrightarrow{z}$   
 $\xrightarrow{z} g[n] = -18x[n] + 3x[n-1] + 10x[n-2] = -10.8(0.3)^n \mu[n] - 7.2(-0.2)^n \mu[n] +$   
 $+ 1.8(0.3)^{n-1} \mu[n-1] + 1.2(-0.2)^{n-1} \mu[n-1] + 6(0.3)^{n-2} \mu[n-2] + 4(-0.2)^{n-2} \mu[n-2].$

III Group delay can be computed from the phase shift as follows:  $\tau(\omega) = -\frac{d}{d\omega} [\theta(\omega)]$  where  $\theta(\omega)$  is the phase function.

If  $\tau(\omega) = \text{const}$ , then  $\theta(\omega)$  must be a linear function of  $\omega$ :  $\theta(\omega) = c\omega + \beta$ .

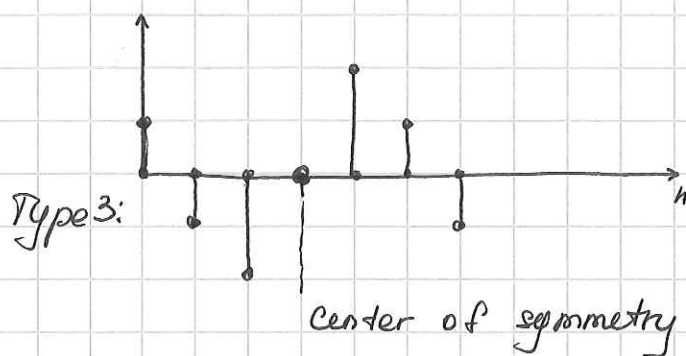
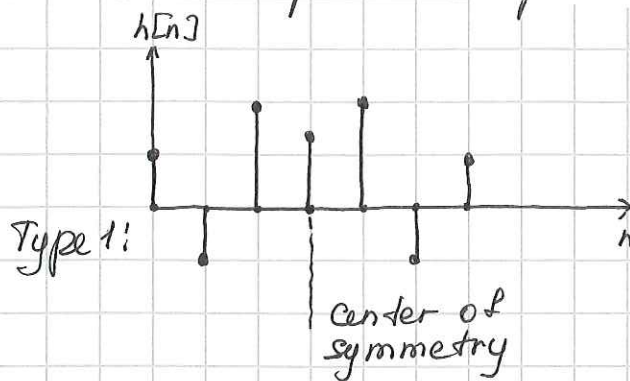
If  $H(z)$  has a linear-phase, its frequency response must be of the form  $H(e^{j\omega}) = e^{j(c\omega + \beta)} \tilde{H}(\omega)$  where  $\tilde{H}(\omega)$  is amplitude response.

For  $h[n] = a_0 \delta[n] + \dots + a_6 \delta[n-6] \xrightarrow{\text{DTFT}} H(e^{j\omega}) = a_0 + a_1 e^{-j\omega} + a_2 e^{-2j\omega} + \dots + a_6 e^{-6j\omega} = e^{j(c\omega + \beta)} \tilde{H}(\omega)$



$h[n]$  is a real impulse response of length 7.  $\Rightarrow$

$\Rightarrow$  Linear phase response is possible in this two cases:



Type 1: Symmetric impulse response with odd length

Because of symmetry:  $h[0] = h[6]$ ,  $h[1] = h[5]$ ,  $h[2] = h[4]$   $\Rightarrow$

$$\Rightarrow \begin{cases} a_0 = a_6 \\ a_1 = a_5 \\ a_2 = a_4 \\ a_3 \text{ any real number} \end{cases}$$

$$\begin{aligned} \Rightarrow H(e^{j\omega}) &= a_0(1 + e^{-j6\omega}) + a_1(e^{-j\omega} + e^{-j5\omega}) + \\ &+ a_2(e^{-j2\omega} + e^{-j4\omega}) + a_3 e^{-j3\omega} = \\ &= e^{-j3\omega} (a_0(e^{j3\omega} + e^{-j3\omega}) + a_1(e^{j2\omega} + e^{-j2\omega}) + \\ &+ a_2(e^{j\omega} + e^{-j\omega}) + a_3) = \\ &= e^{-j3\omega} (2a_0 \cos(3\omega) + 2a_1 \cos(2\omega) + \\ &+ 2a_2 \cos(\omega) + a_3) \end{aligned}$$

$\nwarrow$  real function of  $\omega$ .  
amplitude response

$$\Rightarrow \begin{cases} \theta(\omega) = -3\omega \\ \text{or } \theta(\omega) = -3\omega \pm \pi \end{cases} \Rightarrow \underline{\underline{\tau(\omega) = -\frac{d\theta(\omega)}{d\omega} = 3}}$$

$\left\{ \text{for the case when amplitude is negative, then } -1 = e^{\pm j\pi} \right\}$

Type 2: Antisymmetric impulse response with odd length:  $h[0] = -h[6]$ ,  
 $h[1] = -h[5]$ ,  $h[2] = -h[4]$ ,  $h[3] = -h[3] = 0$ .  $\Rightarrow$

$$\Rightarrow \begin{cases} a_0 = -a_6 \\ a_1 = -a_5 \\ a_2 = -a_4 \\ a_3 = 0 \end{cases} \Rightarrow H(e^{j\omega}) = e^{-j3\omega} e^{j\pi/2} (2a_0 \sin(3\omega) + 2a_1 \sin(2\omega) + 2a_2 \sin(\omega))$$

$$\Rightarrow \begin{cases} \theta(\omega) = -3\omega + \pi/2 \\ \text{or } \theta(\omega) = -3\omega + \frac{3\pi}{2} \end{cases} \Rightarrow \underline{\underline{\tau(\omega) = -\frac{d\theta(\omega)}{d\omega} = 3}}$$