## **TestVector**

## Outline

We will proceed as follows. First, we will write a program to test if a given test *vector* can be produced by a seed vector combination, according to the function given. Then, we shall write a program that checks the compatibility of test *cubes* with test *vectors*. Finally, we may write a program that reads a sequence of test cubes and checks if it matches with one or more test vectors.

## I. Testing if a given test *vector* can be produced from some a, b.

The title of this section is somewhat misleading- in addition to checking if a certain test vector can be compressed directly, we will also produce the a and b which decompress to the given vector. To understand the general plan of action, we will first take note of some theory.

The partial products of the multipliers correspond to the given equations: (taken from the code in MATLAB)

```
t11 = v11;
t12 = v12;
t13 = v13;
t14 = v14;
t21 = xor(v12,v21);
t22 = xor(v12,v23);
t23 = xor(v13,v24);
t24 = v24;
t31 = xor(v12, xor(v23, v31));
t32 = xor(v13, xor(v24, v32));
t33 = xor(v23, v34);
t34 = v34:
t41 = xor(xor(v14,v22),xor(v33,v41));
t42 = xor(v23, xor(v34, v42));
t43 = xor(v34, v43);
t44 = v44;
```

where the variables  $v_{ij}$  are obtained from a, b as:

$$v_{ij} := a_i \wedge b_j$$

with the indices on a and b signifying the bit number under current consideration. The equivalence of the XOR operation and multiplication modulo 2 means that all the operations involved in the evaluation of  $t_{ij}$  from a,b can be regarded as operations in a finite field, more specifically, the field  $F_2$ . This means that we may ignore, for now, the operation by which we obtain  $v_{ij}$  from a and b, and treat the mapping of the matrix  $[v_{ij}]$  to  $[t_{ij}]$  as that of a linear operator acting on  $F_2^{-16}$ , in which we replace  $[v_{ij}]$  and  $[t_{ij}]$  by the vectors V and T respectively, with the definition of their components taken in the row-major convention:

$$t_{ij} = T_{4i + j - 4}$$

and similarly for v and V. In order to test, now, whether a given test vector can be compressed directly, we must first analyse the form of this linear operator.

Writing it out in matrix form we get:

```
1\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0
0\; 0\; 1\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0
0\ 0\ 0\ 1\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0
0\ 1\ 0\ 0\ 1\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0
0\ 1\ 0\ 0\ 0\ 0\ 1\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0
0\ 0\ 1\ 0\ 0\ 0\ 0\ 1\ 0\ 0\ 0\ 0\ 0\ 0\ 0
0\ 0\ 0\ 0\ 0\ 0\ 0\ 1\ 0\ 0\ 0\ 0\ 0\ 0\ 0
0\; 1\; 0\; 0\; 0\; 0\; 1\; 0\; 1\; 0\; 0\; 0\; 0\; 0\; 0\; 0
0\; 0\; 1\; 0\; 0\; 0\; 0\; 1\; 0\; 1\; 0\; 0\; 0\; 0\; 0\; 0
0\; 0\; 0\; 0\; 0\; 0\; 1\; 0\; 0\; 0\; 0\; 1\; 0\; 0\; 0\; 0
0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 1\; 0\; 0\; 0\; 0
0\ 0\ 0\ 1\ 0\ 1\ 0\ 0\ 0\ 0\ 1\ 0\ 1\ 0\ 0\ 0
0\ 0\ 0\ 0\ 0\ 0\ 1\ 0\ 0\ 0\ 1\ 0\ 1\ 0\ 0
0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 1\ 0\ 1\ 0
```

We'll call this matrix A. The rest of the analysis is very simple and apparent immediately:

- 1) Check if the given 16-bit data (T) is in the column space of A.
- 2) Find the V which corresponds to T, if the first step allows for it.
- 3) Find a and b from V according to the multiplier equations.

To perform 1), we analyse A a little. While performing computation in  $F_2$ , the operator is non-invertible if it has an *odd* determinant. The above matrix has determinant 0. It can be seen that its rank is 14- by simply *looking* at each column from the rightmost (i.e. column #16), we find that the linear independence of the columns is broken by the fact that:  $C_6 = C_{11} = C_{13}$ . That is why, on elimination of these columns, row reduction gives us a very simple formula for the partial inversion of the operation. The formulae we get by reducing the block matrix  $[A \mid T]$ , is as below.

```
egin{aligned} V_1 &= T_1 \ V_2 &= T_2 \ V_3 &= T_3 \ V_4 &= T_4 \ V_5 &= T_5 - T_2 \ V_6 &= T_6 - T_2 \ V_7 &= T_7 - T_3 \ V_8 &= T_9 - T_6 \ V_9 &= T_{10} - T_7 \ V_{10} &= T_{11} - T_6 + T_2 \ V_{11} &= T_{13} - T_4 \end{aligned}
```

```
egin{array}{ll} V_{12} = & T_{14} 	ext{ - } T_{11} \ V_{13} = & T_{15} 	ext{ - } T_{11} + & T_6 	ext{ - } T_2 \ V_{14} = & T_{16} \ V_{15} = & T_8 	ext{ - } T_7 + & T_3 \ V_{16} = & T_{12} 	ext{ - } T_{11} + & T_6 	ext{ - } T_2 \end{array}
```

Further, row reduction on the 14-column version of A gives the last two rows zero, as expected. This means that a given T cannot lie in the column space of A if the last two expressions above (for  $V_{15}$  and  $V_{16}$ ) evaluate to zero. This gives us step number one in the operation to get V from T:

The above equations also allow us to complete step (2) of our analysis easily.

```
\langle 2. \text{ Find } V \text{ from } T. \rangle:-
V[1] \leftarrow (T[1]) \mod 2;
V[2] \leftarrow (T[2]) \mod 2;
V[3] \leftarrow (T[3]) \mod 2;
V[4] \leftarrow (T[4]) \mod 2;
V[5] \leftarrow (T[5] - T[2]) \mod 2;
V[6] \leftarrow (T[6] - T[2]) \mod 2;
V[7] \leftarrow (T[7] - T[3]) \mod 2;
V[8] \leftarrow (T[9] - T[6]) \mod 2;
V[9] \leftarrow (T[10] - T[7]) \mod 2;
V[10] \leftarrow (T[11] - T[6] + T[2]) \mod 2;
V[11] \leftarrow (T[13] - T[4]) \mod 2;
V[12] \leftarrow (T[14] - T[11]) \mod 2;
V[13] \leftarrow (T[15] - T[11] + T[6] - T[2]) \mod 2;
V[14] \leftarrow (T[16]) \mod 2;
V[15] \leftarrow (T[8] - T[7] + T[3]) \mod 2;
V[16] \leftarrow (T[12] - T[11] + T[6] - T[2]) \mod 2;
```

Step (3) is also simple, and hinges on one basic insight. Let us look at the rectangular array representation of  $v_{ij}$ , and use its definition in therms of a and b.

```
a_1b_1 a_1b_2 a_1b_3 a_1b_4

a_2b_1 a_2b_2 a_2b_3 a_2b_4

a_3b_1 a_3b_2 a_3b_3 a_3b_4

a_4b_1 a_4b_2 a_4b_3 a_4b_4
```

It is clear that if any entry is zero, one of three cases holds:

- 1) Every other entry in its row is zero
- 2) Every other entry in its column is zero
- 3) Both 1) and 2) holds

That is because of the repitition of one of the (bit-) multiplicands along each row and column. Given the interpretation of V as being the row-major reading of v, we can implement this easily. We simply have to search for a zero, in V, then check if every entry along either its row or column is also zero. If not, the given vector *cannot* be compressed. If it can, then identifying that row, or column will immediately identify a bit as being zero. If all the  $a_i$ 's and  $b_i$ 's were intitialised to '1', repeating this will identify all the bits of the multiplicand.

Here, we shall:

- 1) Get v from V.
- 2) Search for a zero in the result.
- 3) Check if the entire row vanishes.
- 4) Check if the entire column vanishes.
- 5) Error handling- if *neither* row nor column vanishes.

```
\langle 3. \text{ Find } a, b \text{ from } V. \rangle:-
for( i \leftarrow 1; i \le 16; i \leftarrow i + 1 )
{
     I \leftarrow (\text{int})i/4 + 1;
     J \leftarrow (i \mod 4) + 1;
     v [I][J] \leftarrow V [i];
}
for( I \leftarrow 1; I \leq 4; I \leftarrow I + 1)
{
    for (J \leftarrow 1; J \leq 4; J \leftarrow J + 1)
         if(v [I][J] = 0)
              for (k \leftarrow 1; k \leq 4; k \leftarrow k + 1)
                   row \quad sum \leftarrow row \quad sum + v [I][k];
              if (row \ sum = 0) \ a \ [I] \leftarrow 0;
              for (k \leftarrow 1; k \leq 4; k \leftarrow k + 1)
                    column \quad sum \leftarrow column \quad sum + v [k][J];
              if (column \ sum = 0) \ b \ [J] \leftarrow 0;
```

Finally, there is a lot of work in the initialisation. Immediately, we note that we must:

- 1) The seed vectors (i.e. a, b) must be initialised to 1111,1111.
- 2) Resolve the symbol "mod" according to the language ("%" in C.)
- 3) Read T from the command line arguments.

```
⟨ Initialise. ⟩:-
int I \leftarrow 1, J \leftarrow 1, i \leftarrow 1, k \leftarrow 1;
int row\_sum \leftarrow 0, column\_sum \leftarrow 0;
int V [16], T [16], v [4][4];
int a [5] \leftarrow { 1, 1, 1, 1, 1}, b [5] \leftarrow { 1, 1, 1, 1, 1};

for( i \leftarrow 1; i \leq 16; i \leftarrow i + 1 )
{ T [ i ] \leftarrow argv [1][ i - 1 ] - '0'; }
```

In C, this requires further resolution to head it off,

That takes care of determining a, b from T. The procedure is, therefore, as:

```
⟨ Begin. ⟩

⟨ Initialise. ⟩

⟨ 1. Check if the given T \in \text{column-space of } A. ⟩

⟨ 2. Find V from T. ⟩

⟨ 3. Find a, b from V. ⟩

⟨ Finish. ⟩
```