Building modules in ${\tt SpaDES}$

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1 Introduction

1.1 Module overview

SpaDES modules are event-based, meaning that different actions are performed on data objects based on the order of scheduled events. Basically, a module consists of a collection of events which are scenduled depending on the rules of your simulation. Each event may evaluate or modify a simulation data object.

1.2 Events

1.2.1 Simulation event list

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1.2.2 Module events

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1.2.3 Dependencies

Typically, each module schedules its own events (e.g., a "fire" module may schedule "burn" events) and only uses its own data objects. Modules that behave in this way are indepedent of each other, and this is generally the prefered way to design and implement modules. A module that schedules events from another module is said to depend on that module.

Module event dependencies complicate the construction of simulation models, and hinder the ability to develop and deploy models with modularity. If two modules are actually depedent on each others' events, then you should consider whether they really are separate modules or should be merged into a single module.

1.3 Objects

As you build your module / simulation, you can use any of R's data types to store your objects / data. In particular, matrices (including vectors) and lists work well for this purpose because they are pass-by-reference, which reduces your model's memory footprint and speeds up your codes execution. Other useful datatypes include Raster* and SpatialPoints* objects.

1.3.1 Global objects

Use the superassignment operator (<<-) to assign global objects to reduce copying large objects (such as maps), which slows model execution.

1.3.2 Module object dependencies

As noted above, modules can depend on one another for event scheduling. Modules can also be design to rely on outputs (data objects) from other modules. A module that relies on a global simulation data object that is also used by another module is said to be dependent on that other module. It is often useful to develop collections of modules that interact indirectly and are dependent on shared data objects.

Note that modules need not be inter-dependent on one another: module B may depend on module A (for example to initialize a data object), without module A depending on module B.

1.4 Parameters

The parameter list in the simList object are used to pass parameters to modules. The nested named list structure allows passing as many parameters as needed for your simulation. We suggest passing a list of all the parameters needed for a single module together.

2 Default SpaDES modules

There are a number of built-in modules that provide useful functionality. These modules have their names prefaced with a dot to indicate they are "special".

2.1 .checkpoint module

Schedule automatic simulation checkpointing to allow you to resume a previously saved simulation. All objects in the global environment including the state of the random number generator are saved and can be reloaded. Checkpoint frequency and filename can be passed as parameters to the simulation object as illustrated below. By befault, checkpointing is not used unless the interval parameter is provided; the simulation checkpoint file (if one exists) is loaded if the file parameter is specified.

2.2 .progress module

Schedule updates to the simulation progress bar.

2.3 .load and .save modules

Schedule object save and file load events by passing parameters to the save and load parameters for each module. Unlike the default modules above, loading and saving is designed to be scheduled by the user from within a module.

Loading files can be done be passing a simulation parameter called .loadFileList which can be a list or a data.frame and consists minimally of a column called files listing the filepaths of the files to be loaded. Additional columns can also be provided:

- objs: a character string indicating the name of the object once the file is loaded.
- funs: a character string indicating the function to be used to load the file.
- intervals: a numeric indicating the interval between repeated loading of the same file. This should be NA or the column absent if the file is only loaded once.

- loadTime: a numeric indicating when the file should be loaded. Defaults to simTime = 0, but this can be any time. The loading will be scheduled to occur at the "loadTime", whatever that is. If the same file is to loaded many times, but not at a regular interval, then there should be separate line, with a unique loadTime for each.
- args: a list of lists of named arguments, one list for each loading function. For example, if raster is a loading function, args = list(native = TRUE). If there is only one list, then it is assumed to apply to all load attempts and will be repeated for each load function.

Saving objects to file can be done by passing the appropriate arguments as parameters. The key values to include are:

- .saveObjects: a character vector naming the objects to be saved.
- .savePath: A path to which the object will be saved.
- .saveInitialTime: the time at which the first save is scheduled.
- .saveInterval: the interval at which objects will be saved. Used to schedule save events.

```
> # initialize a new simulation, setting the load and save parameters
> mySim <- simInit(times=list(start=0.0, stop=100),
                   params=list(
                     .loadFileList=data.frame(files=dir(pattern="tif"), stringsAsFactors=FALSE),
                     habitat=list(nx=1e2, ny=1e2,
                                   .saveObjects=c("habitat"),
                                  .savePath=file.path("output", "habitat"),
                                  .saveInitialTime=0,
                                  .saveInterval=10),
                     ),
                   modules=list("habitat"),
+
                   path="SAMPLE"
+ )
> # retrieve the load and save params from the simulation object
> simParams(mySim)$.loadFileList
> simParams(mySim)$habitat$.saveObjects
> simParams(mySim)$habitat$.savePath
> simParams(mySim)$habitat$.saveInitialTime
> simParams(mySim)$habitat$.saveInterval
> # schedule a recurring save event [WITHIN A MODULE]
> nextSave <- simCurrentTime(sim) + simParams(sim) $habitat$.saveInterval
> sim <- scheduleEvent(sim, nextSave, "habitat", "save")
```

3 Creating a new module

3.1 Module design considerations

perhaps a bit about design phlosophy, relating back to dependencies and how to carefully build modules that actually retain modularity.

As noted above, modules should function as independently as possible so that they retain their modularity. While it may be useful for modules to exhibit indirect dependence on each other via shared data objects (such as maps), modules should not depend directly on each other via event scheduling.

3.2 Using the module template

Code for new modules can be developed quickly using the template generator function newModule which accepts as arguments the name of the new module, a directory path in which to create the new module, and a logical indicating whether to open the newly created module code file for editing.

```
> # create a new module called "randomLandscape" in the "custom-modules" subdirectory
> # and open the resulting file immediately for editing.
> newModule(name="randomLandscapes", path="custom-modules", open=TRUE)
```

The newly created file can now be modified in the identified sections and customized to your module. However, it is very important that you do not edit portions of the file outside of the designated sections or your module may fail to work properly within a simulation.

3.2.1 Plotting

Plotting events can also be scheduled similarly to save events, by passing module-specific parameters indicating when to schedule the first plot event and how often to rescheduling recurring plot events.

- .saveObjects: a character vector naming the objects to be saved.
- .savePath: A path to which the object will be saved.
- .saveInitialTime: the time at which the first save is scheduled.
- .saveInterval: the interval at which objects will be saved. Used to schedule save events.

3.2.2 Saving

See Section 2.3 above for more details.

Appendix

- A Generate random landscapes (randomLandscapes)
- B Simulate fire spread on a landscape (fireSpread)
- $C\quad Agent\ based\ model\ of\ caribou\ movement\ (\texttt{caribouMovement})$

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