

CS 305 Computer Networks

Chapter 6 Link Layer and LANs (I)

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Chapter 6: Link layer and LANs

our goals:

- understand principles behind link layer services:
 - error detection, correction
 - sharing a broadcast channel: multiple access
 - link layer addressing
 - local area networks: Ethernet, VLANs
- instantiation, implementation of various link layer technologies

Link layer, LANs: outline

6.1 introduction, services

6.2 error detection,
correction

6.3 multiple access
protocols

6.4 LANs

- addressing, ARP
- Ethernet
- switches
- VLANs

6.5 link virtualization:
MPLS

6.6 data center
networking

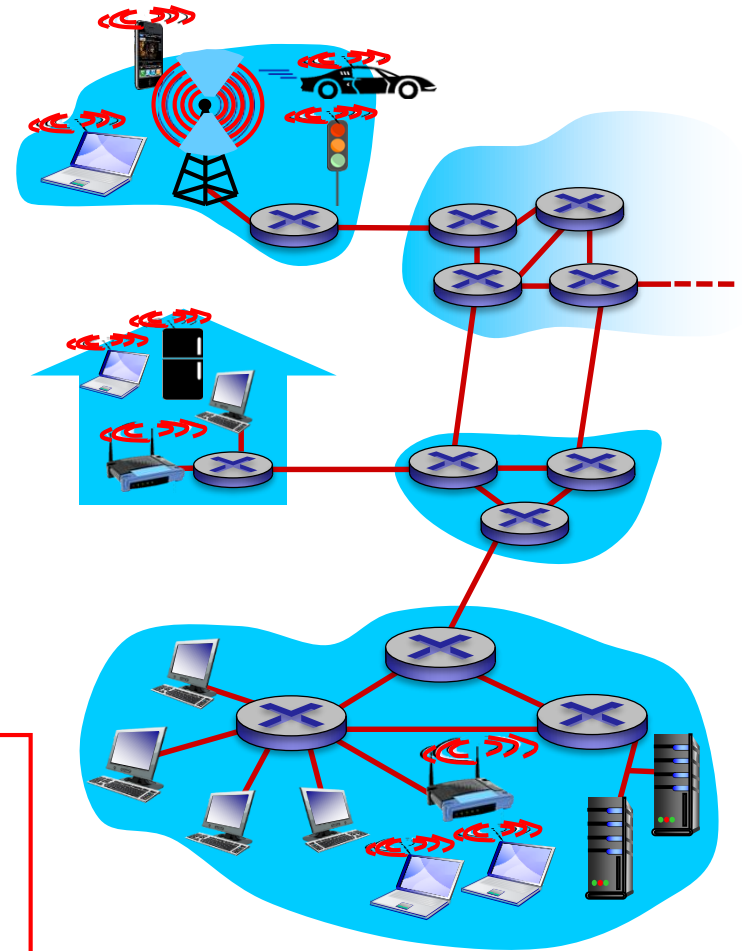
6.7 a day in the life of a
web request

Link layer: introduction

terminology:

- hosts and routers: **nodes**
- communication channels that connect adjacent nodes along communication path: **links**
 - wired links
 - wireless links
- layer-2 packet: **frame**, encapsulates datagram

link layer has responsibility of transferring datagram from one node to *physically adjacent* node over a link



Link layer: context

- datagram transferred by different link protocols over different links:
 - e.g., Ethernet on first link, PPP on intermediate links, 802.11 on last link
- each link protocol provides different services
 - e.g., may or may not provide rdt over link

transportation analogy:

- trip from Princeton to Lausanne
 - limo: Princeton to JFK
 - plane: JFK to Geneva
 - train: Geneva to Lausanne
- tourist = **datagram**
- transport segment = **communication link**
- transportation mode = **link layer protocol**
- travel agent = **routing algorithm**

Link layer services

- *framing, link access:*

- encapsulate datagram into frame, adding header, trailer
- channel access if shared medium
- “MAC” addresses used in frame headers to identify source, destination
 - different from IP address!

- *reliable delivery between adjacent nodes*

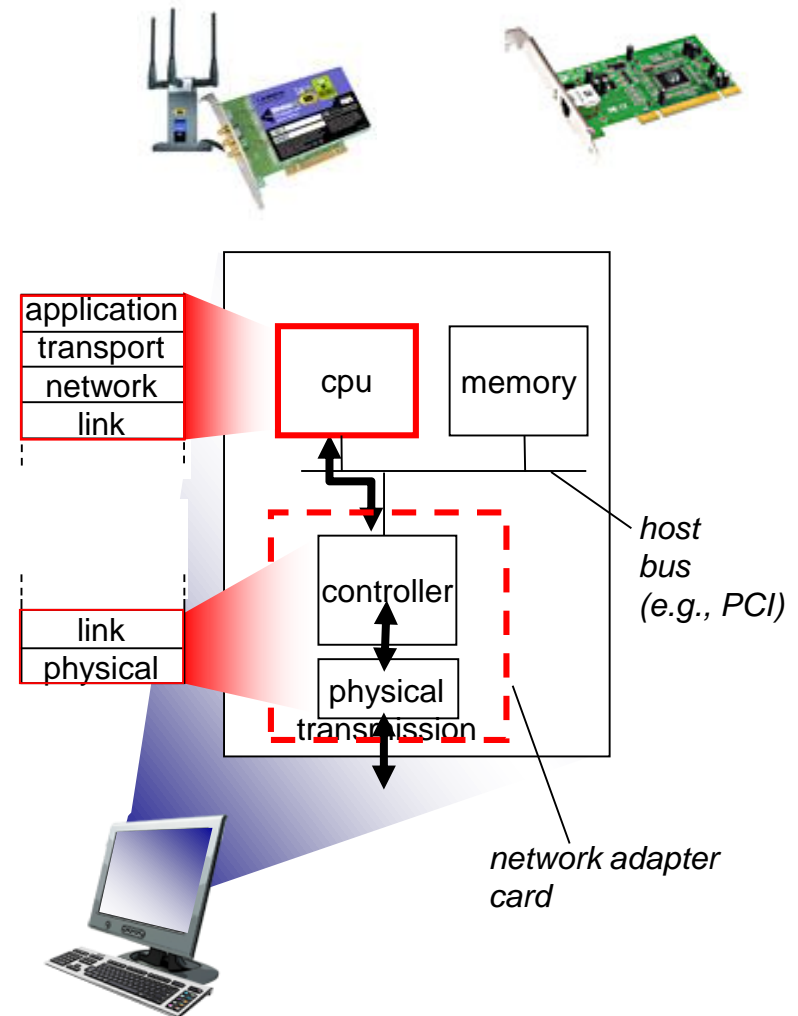
- we learned how to do this already (chapter 3)!
- seldom used on low bit-error link (fiber, some twisted pair)
- wireless links: high error rates
 - *Q*: why both link-level and end-end reliability?

Link layer services (more)

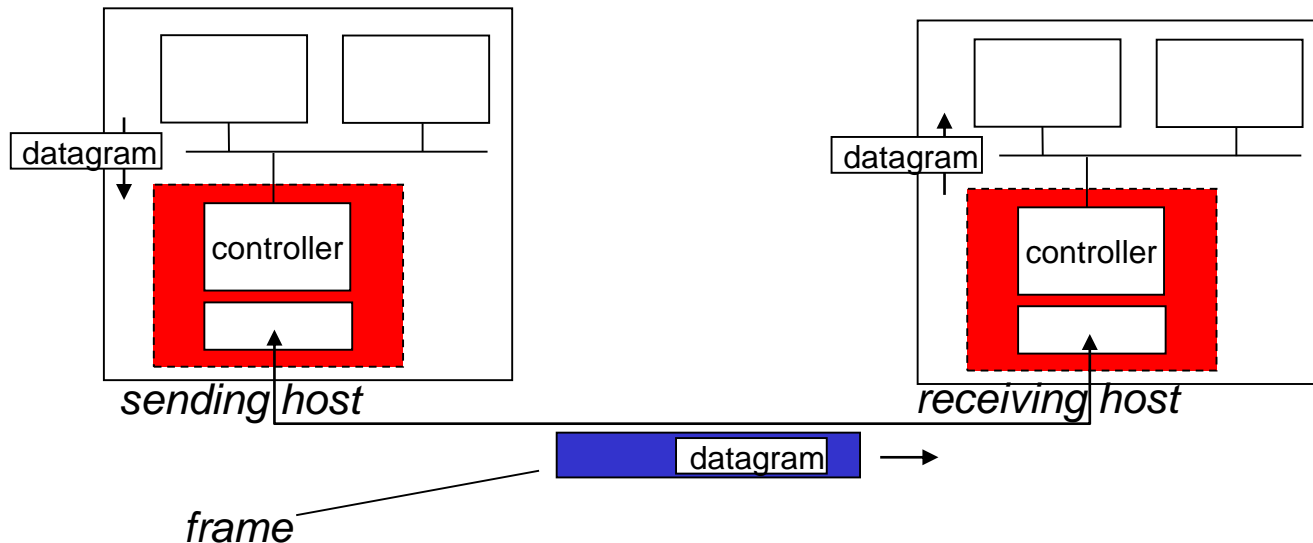
- *flow control:*
 - pacing between adjacent sending and receiving nodes
- *error detection:*
 - errors caused by signal attenuation, noise.
 - receiver detects presence of errors:
 - signals sender for retransmission or drops frame
- *error correction:*
 - receiver identifies *and corrects* bit error(s) without resorting to retransmission
- *half-duplex and full-duplex*
 - with half duplex, nodes at both ends of link can transmit, but not at same time

Where is the link layer implemented?

- in each and every host
- link layer implemented in “adaptor” (aka *network interface card* NIC) or on a chip
 - Ethernet card, 802.11 card; Ethernet chipset
 - implements link, physical layer
- attaches into host's system buses
- combination of hardware, software, firmware



Adaptors communicating



- sending side:
 - encapsulates datagram in frame
 - adds error checking bits, rdt, flow control, etc.
- receiving side
 - looks for errors, rdt, flow control, etc.
 - extracts datagram, passes to upper layer at receiving side

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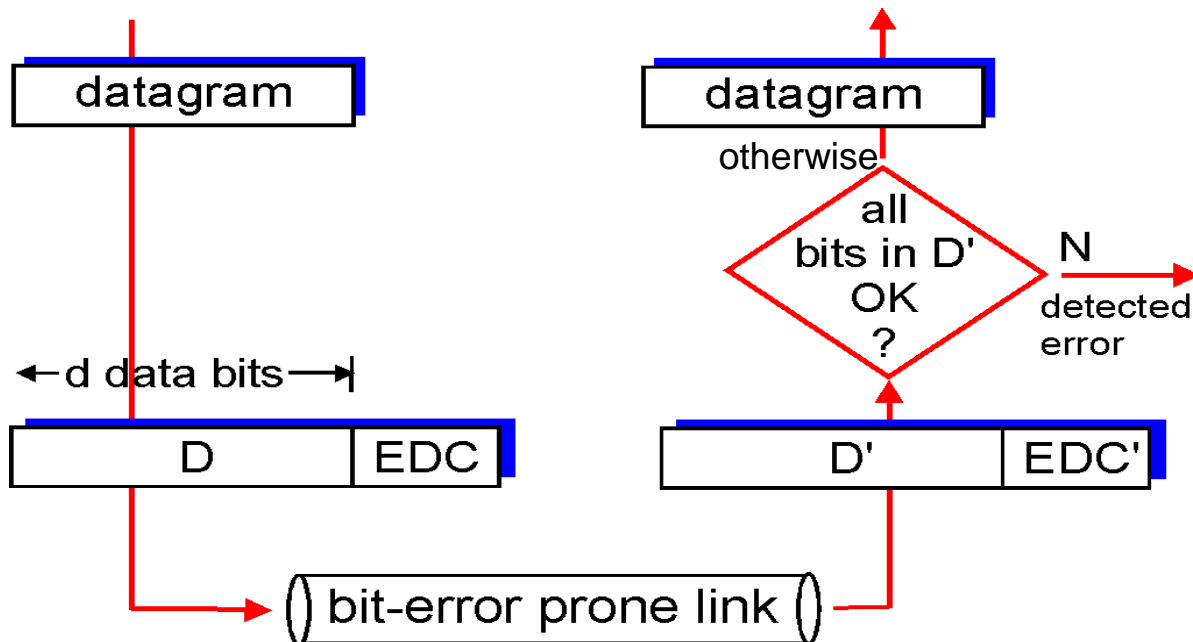
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Error detection

EDC= Error Detection and Correction bits (redundancy)

D = Data protected by error checking, may include header fields

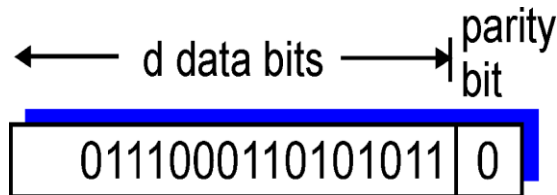
- Error detection not 100% reliable!
 - protocol may miss some errors, but rarely
 - larger EDC field yields better detection and correction



Parity checking

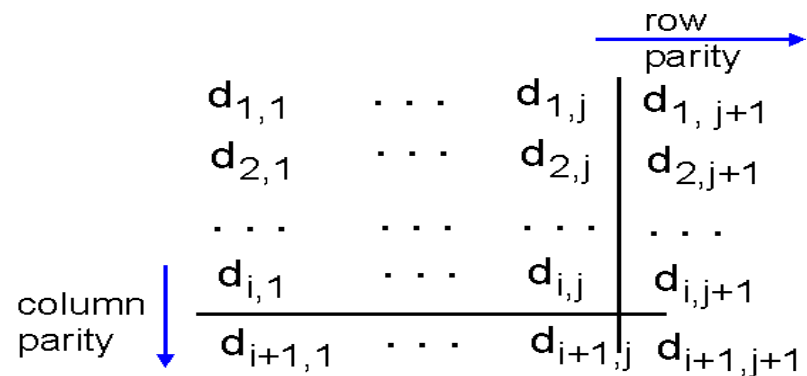
single bit parity:

- detect single bit errors



two-dimensional bit parity:

- detect and correct single bit errors



1	0	1	0	1	1
1	1	1	1	0	0
0	1	1	1	0	1
0	0	1	0	1	0

no errors

1	0	1	0	1	1
1	1	1	1	0	0
0	1	1	1	0	1
0	0	1	0	1	0

parity error

*correctable
single bit error*

* Check out the online interactive exercises for more examples: http://gaia.cs.umass.edu/kurose_ross/interactive/

Internet checksum (review)

goal: detect “errors” (e.g., flipped bits) in transmitted packet
(note: used at transport layer only)

sender:

- treat segment contents as sequence of 16-bit integers
- checksum: addition (1's complement sum) of segment contents
- sender puts checksum value into UDP checksum field

receiver:

- compute checksum of received segment
- check if computed checksum equals checksum field value:
 - NO - error detected
 - YES - no error detected.
But maybe errors nonetheless?

Cyclic redundancy check

- more powerful error-detection coding
- view data bits, **D**, as a binary number
- choose $r+1$ bit pattern (generator), **G**
- goal: choose r CRC bits, **R**, such that
 - $\langle D, R \rangle$ exactly divisible by G (modulo 2)
 - receiver knows G , divides $\langle D, R \rangle$ by G . If non-zero remainder: error detected!
 - can detect all burst errors less than $r+1$ bits
- widely used in practice (Ethernet, 802.11 WiFi, ATM)

← d bits → ← r bits →



*bit
pattern*

$$D * 2^r \text{ XOR } R$$

*mathematical
formula*

CRC example

want:

$$D \cdot 2^r \text{ XOR } R = nG$$

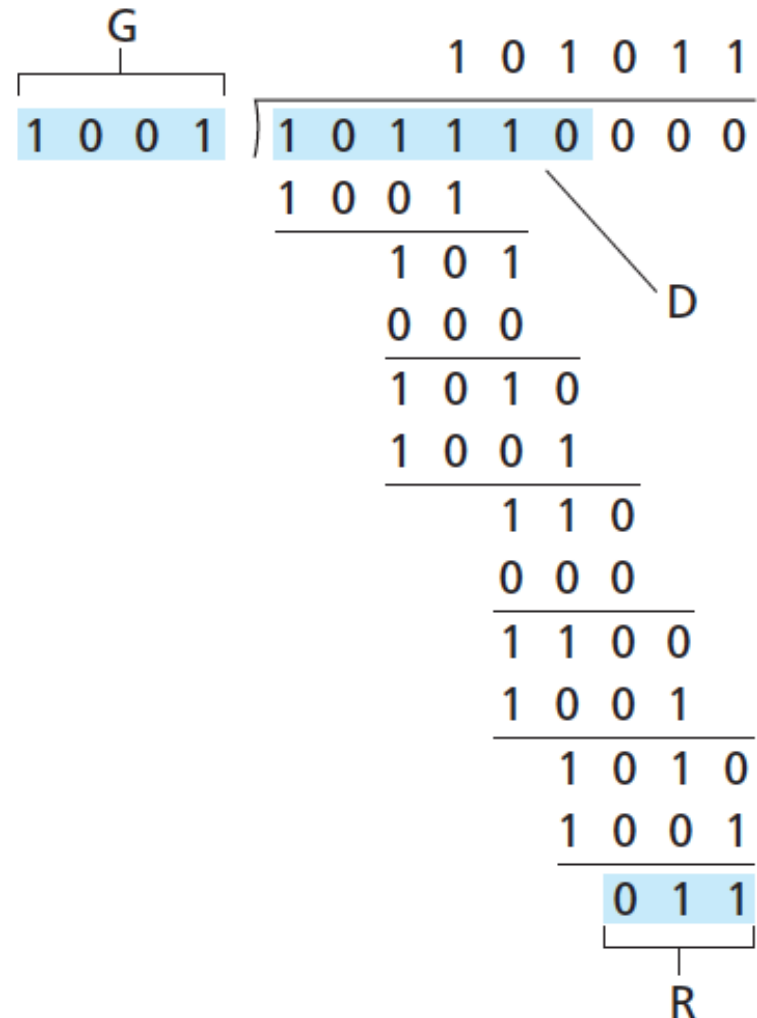
equivalently:

$$D \cdot 2^r = nG \text{ XOR } R$$

equivalently:

if we divide $D \cdot 2^r$ by G , want remainder R to satisfy:

$$R = \text{remainder}\left[\frac{D \cdot 2^r}{G}\right]$$



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Multiple access links, protocols

two types of “links”:

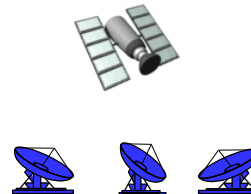
- point-to-point
 - PPP for dial-up access
 - point-to-point link between Ethernet switch, host
- *broadcast (shared wire or medium)*
 - old-fashioned Ethernet
 - upstream HFC
 - 802.11 wireless LAN



shared wire (e.g.,
cabled Ethernet)



shared RF
(e.g., 802.11 WiFi)



shared RF
(satellite)



humans at a
cocktail party
(shared air, acoustical)

Multiple access protocols

- single shared broadcast channel
- two or more simultaneous transmissions by nodes:
interference
 - *collision* if node receives two or more signals at the same time

multiple access protocol

- distributed algorithm that determines how nodes share channel, i.e., determine when node can transmit
- communication about channel sharing must use channel itself!
 - no out-of-band channel for coordination

An ideal multiple access protocol

given: broadcast channel of rate R bps

Desired properties:

1. when one node wants to transmit, it can send at rate R .
2. when M nodes want to transmit, each can send at average rate R/M
3. fully decentralized:
 - no special node to coordinate transmissions
 - no synchronization of clocks, slots
4. simple

MAC protocols: taxonomy

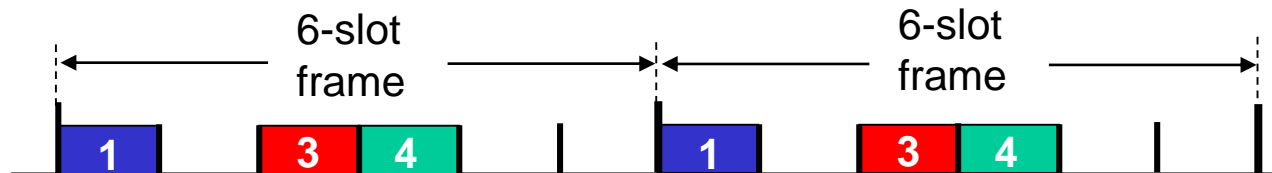
three broad classes:

- *channel partitioning*
 - divide channel into smaller “pieces” (time slots, frequency, code)
 - allocate piece to node for exclusive use
- *random access*
 - channel not divided, allow collisions
 - “recover” from collisions
- *“taking turns”*
 - nodes take turns, but nodes with more to send can take longer turns

Channel partitioning MAC protocols: TDMA

TDMA: time division multiple access

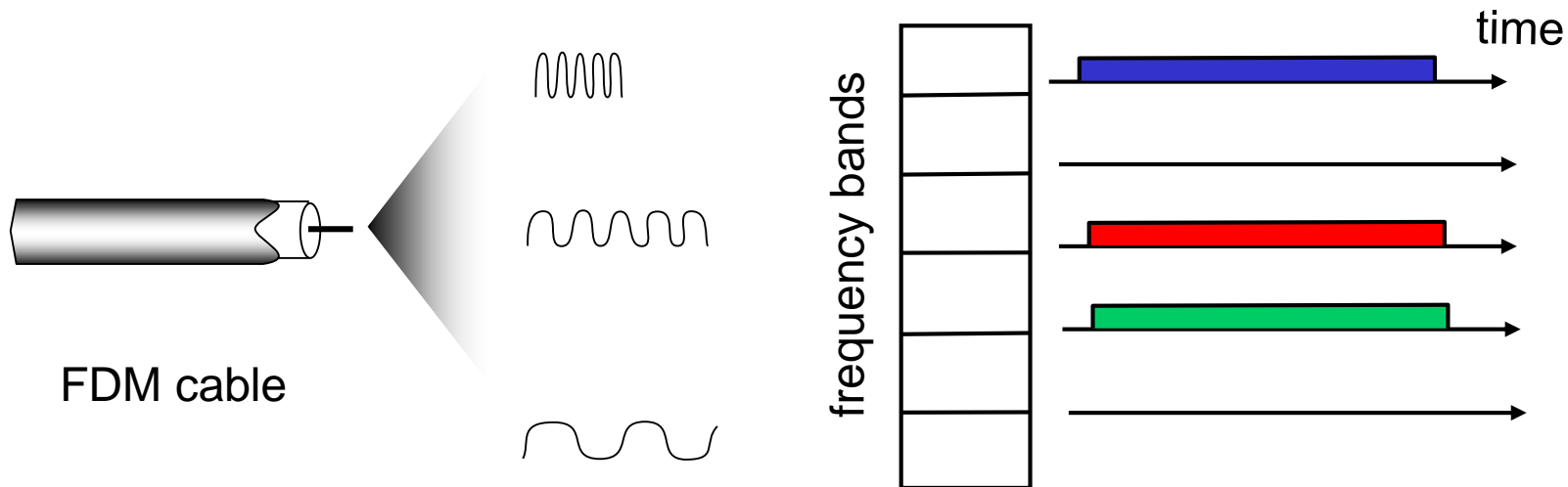
- access to channel in "rounds"
- each station gets fixed length slot (length = packet transmission time) in each round
- unused slots go idle
- example: 6-station LAN, 1,3,4 have packets to send, slots 2,5,6 idle



Channel partitioning MAC protocols: FDMA

FDMA: frequency division multiple access

- channel spectrum divided into frequency bands
- each station assigned fixed frequency band
- unused transmission time in frequency bands go idle
- example: 6-station LAN, 1,3,4 have packet to send, frequency bands 2,5,6 idle



Random access protocols

- when node has packet to send
 - transmit at full channel data rate R .
 - no *a priori* coordination among nodes
- two or more transmitting nodes → “collision”,
- **random access MAC protocol** specifies:
 - how to detect collisions
 - how to recover from collisions (e.g., via delayed retransmissions)
- examples of random access MAC protocols:
 - slotted ALOHA
 - ALOHA
 - CSMA, CSMA/CD, CSMA/CA

Slotted ALOHA

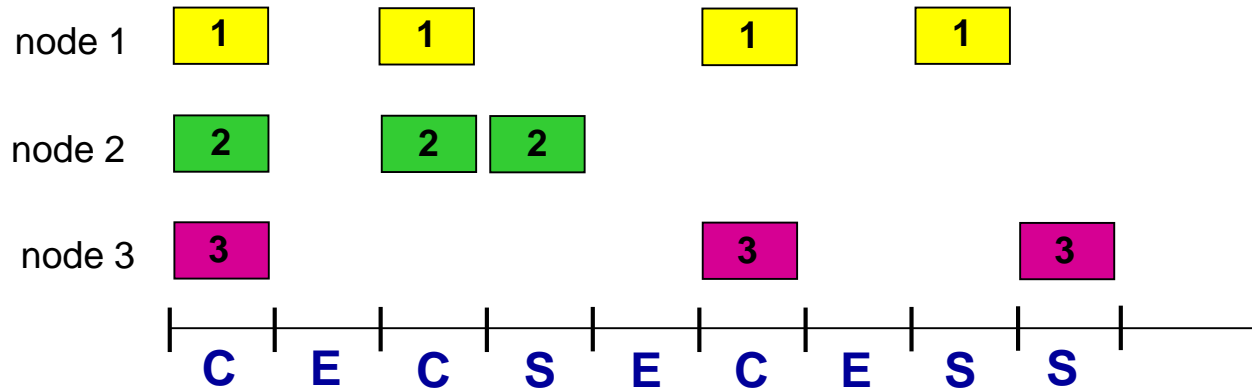
assumptions:

- all frames same size
- time divided into equal size slots (time to transmit 1 frame)
- nodes start to transmit only slot beginning
- nodes are synchronized
- if 2 or more nodes transmit in slot, all nodes detect collision

operation:

- when node obtains fresh frame, transmits in next slot
 - *if no collision:* node can send new frame in next slot
 - *if collision:* node retransmits frame in each subsequent slot with prob. p until success

Slotted ALOHA



Pros:

- single active node can continuously transmit at full rate of channel
- highly decentralized: only slots in nodes need to be in sync
- simple

Cons:

- collisions, wasting slots
- idle slots
- nodes may be able to detect collision in less than time to transmit packet
- clock synchronization

Slotted ALOHA: efficiency

efficiency: long-run fraction of successful slots (many nodes, all with many frames to send)

- suppose: N nodes with many frames to send, each transmits in slot with probability p
- prob that given node has success in a slot $= p(1-p)^{N-1}$
- prob that *any* node has a success $= Np(1-p)^{N-1}$

- max efficiency: find p^* that maximizes $Np(1-p)^{N-1}$
- for many nodes, take limit of $Np^*(1-p^*)^{N-1}$ as N goes to infinity, gives:

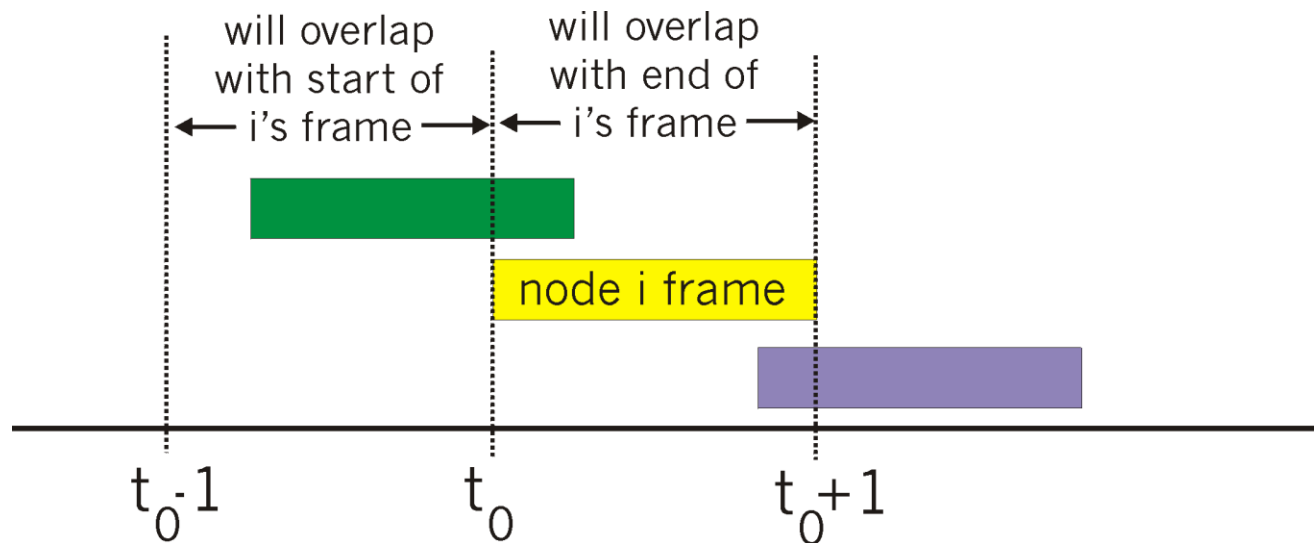
$$\text{max efficiency} = 1/e = .37$$

at best: channel used for useful transmissions 37% of time!



Pure (unslotted) ALOHA

- unslotted Aloha: simpler, no synchronization
- when frame first arrives
 - transmit immediately
- collision probability increases:
 - frame sent at t_0 collides with other frames sent in $[t_0 - 1, t_0 + 1]$



Pure ALOHA efficiency

$P(\text{success by given node}) = P(\text{node transmits}) \cdot$

$P(\text{no other node transmits in } [t_0-1, t_0]) \cdot$

$P(\text{no other node transmits in } [t_0-1, t_0])$

$$= p \cdot (1-p)^{N-1} \cdot (1-p)^{N-1}$$

$$= p \cdot (1-p)^{2(N-1)}$$

... choosing optimum p and then letting $n \rightarrow \infty$

$$= 1/(2e) = .18$$

even worse than slotted Aloha!

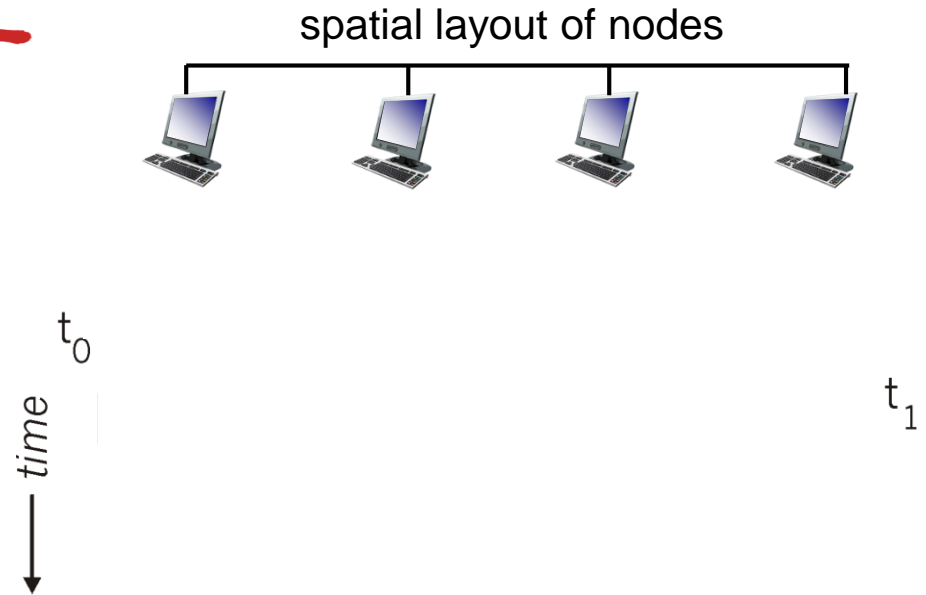
CSMA (carrier sense multiple access)

CSMA: listen before transmit:

- if channel sensed idle: transmit entire frame
- if channel sensed busy, defer transmission
- human analogy: don't interrupt others!

CSMA collisions

- collisions *can* still occur:
propagation delay means
two nodes may not hear
each other's
transmission
- collision: entire packet
transmission time
wasted
 - distance &
propagation delay
play role in
determining collision
probability

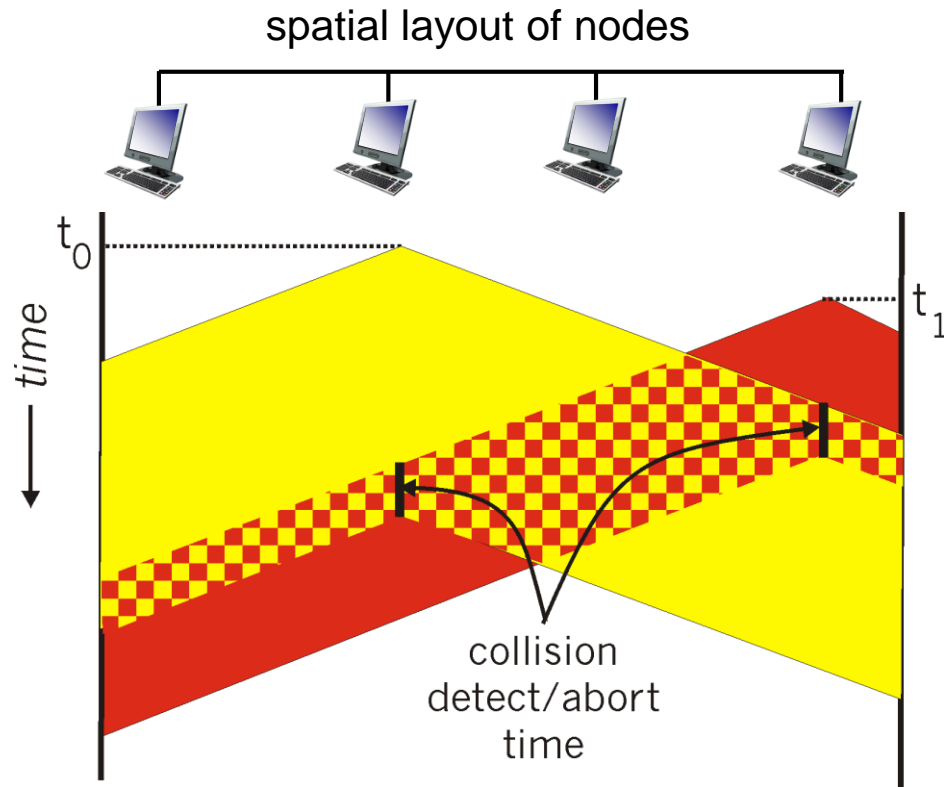


CSMA/CD (collision detection)

CSMA/CD: CSMA+CD (collision detection)

- collision detection:
 - collisions *detected* within short time
 - colliding transmissions are aborted, reducing channel wastage
- Suitable scenarios:
 - easy in wired LANs: measure signal strengths, compare transmitted, received signals
 - difficult in wireless LANs: received signal strength overwhelmed by local transmission strength
- human analogy: the polite conversationalist

CSMA/CD (collision detection)



Ethernet CSMA/CD algorithm

1. NIC receives datagram from network layer, creates frame
2. If NIC senses channel idle, starts frame transmission. If NIC senses channel busy, waits until channel idle, then transmits.
3. If NIC transmits entire frame without detecting another transmission, NIC is done with frame !
4. If NIC detects another transmission while transmitting, aborts and sends jam signal
5. After aborting, NIC enters *binary (exponential) backoff*:
 - after m th collision, NIC chooses K at random from $\{0, 1, 2, \dots, 2^m - 1\}$. NIC waits $K \cdot 512$ bit times, returns to Step 2
 - longer backoff interval with more collisions

“Taking turns” MAC protocols

channel partitioning MAC protocols:

- share channel *efficiently* and *fairly* at high load
- inefficient at low load: delay in channel access, $1/N$ bandwidth allocated even if only 1 active node!

random access MAC protocols

- efficient at low load: single node can fully utilize channel
- high load: collision overhead

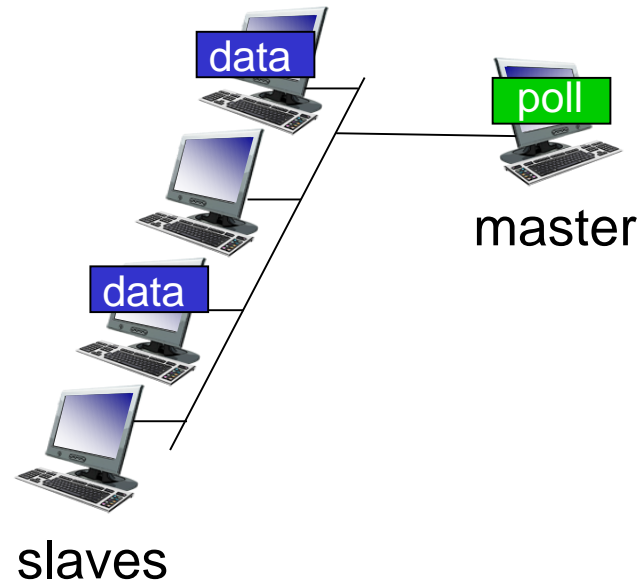
“taking turns” protocols

look for best of both worlds!

“Taking turns” MAC protocols

polling:

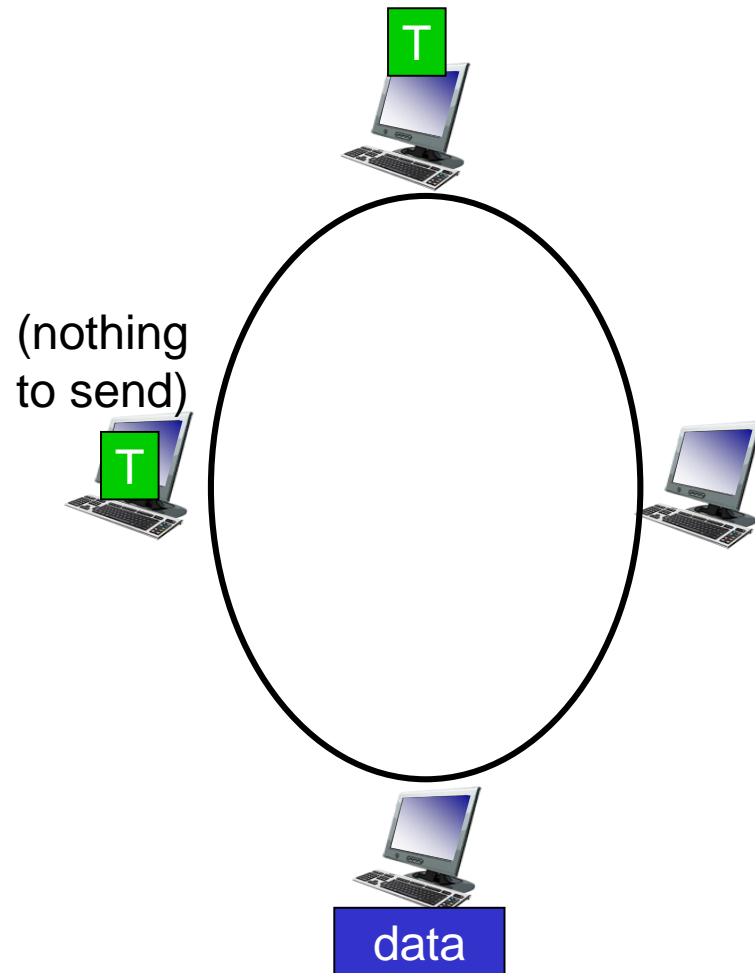
- master node “invites” slave nodes to transmit in turn
- typically used with “dumb” slave devices
- concerns:
 - polling overhead
 - latency
 - single point of failure (master)



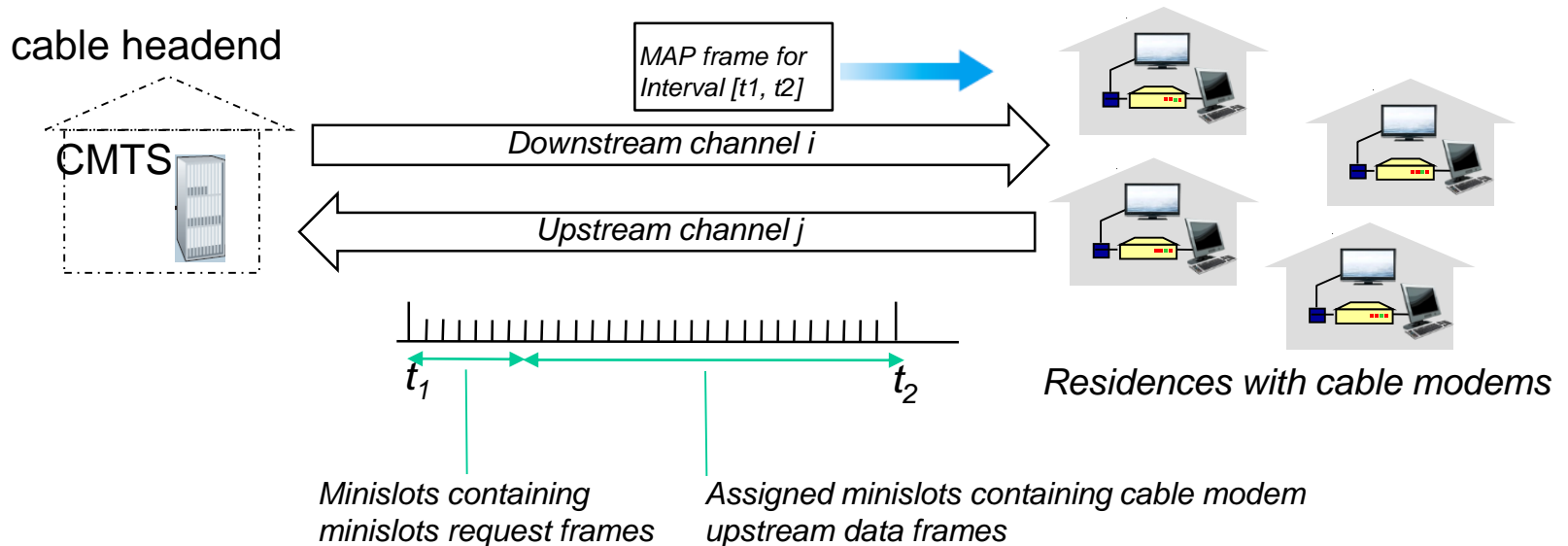
“Taking turns” MAC protocols

token passing:

- control *token* passed from one node to next sequentially.
- token message
- concerns:
 - token overhead
 - latency
 - single point of failure (token)



Case study: Cable access network



DOCSIS: data over cable service interface spec

- FDM over upstream, downstream frequency channels
- TDM upstream: some slots assigned, some have contention
 - downstream MAP frame: assigns upstream slots
 - request for upstream slots (and data) transmitted random access (binary backoff) in selected slots

Summary of MAC protocols

- *channel partitioning*, by time, frequency or code
 - Time Division, Frequency Division
- *random access* (dynamic),
 - ALOHA, S-ALOHA, CSMA, CSMA/CD
 - carrier sensing: easy in some technologies (wire), hard in others (wireless)
 - CSMA/CD used in Ethernet
 - CSMA/CA used in 802.11
- *taking turns*
 - polling from central site, token passing
 - Bluetooth, FDDI, token ring

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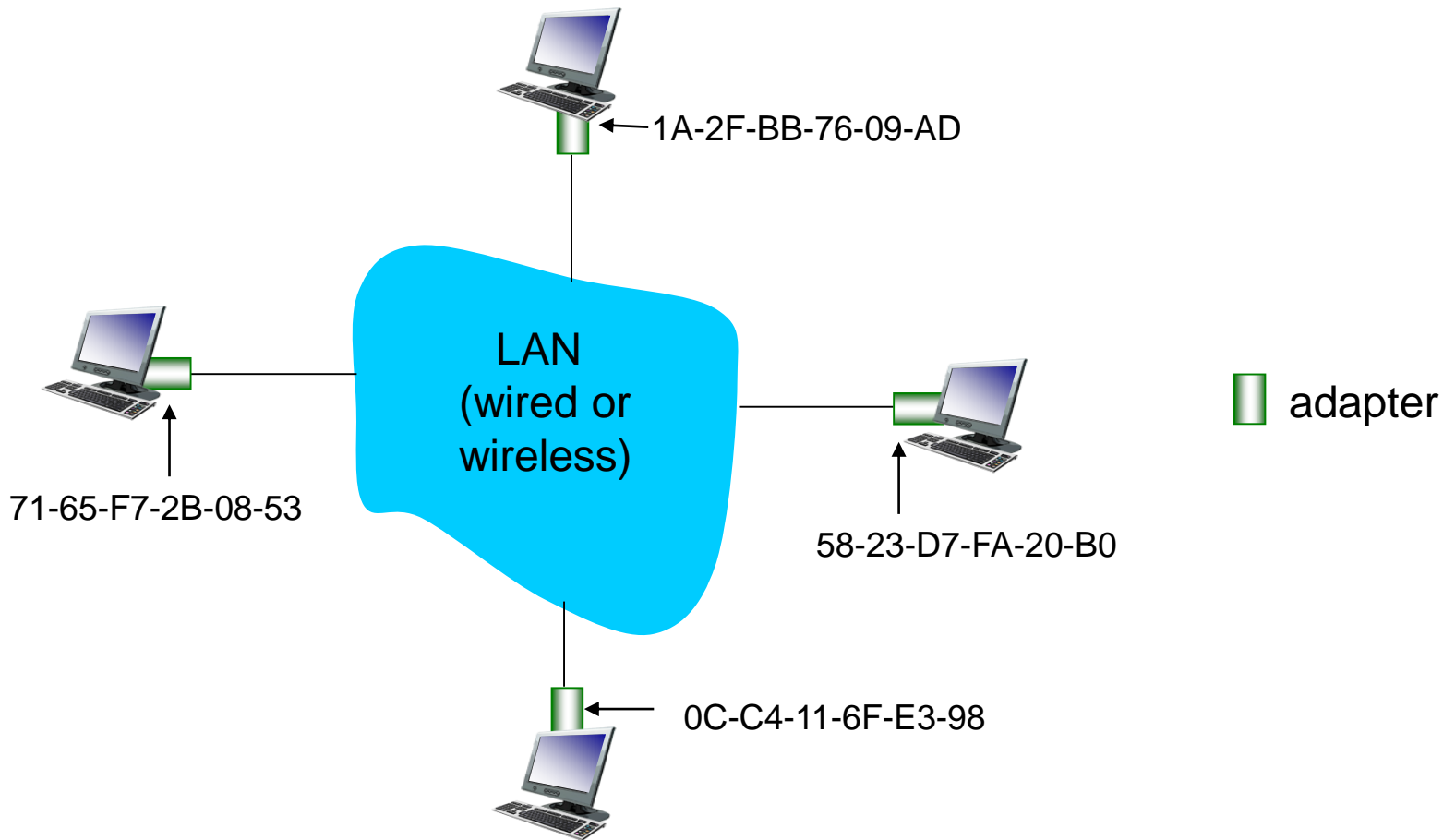
MAC addresses and ARP

- 32-bit IP address:
 - *network-layer* address for interface
 - used for layer 3 (network layer) forwarding
- MAC (or LAN or physical or Ethernet) address:
 - function: *used ‘locally’ to get frame from one interface to another physically-connected interface (same network, in IP-addressing sense)*
 - 48 bit MAC address (for most LANs) burned in NIC ROM, also sometimes software settable
 - e.g.: 1A-2F-BB-76-09-AD

hexadecimal (base 16) notation
(each “numeral” represents 4 bits)

LAN addresses and ARP

each adapter on LAN has unique **LAN** address

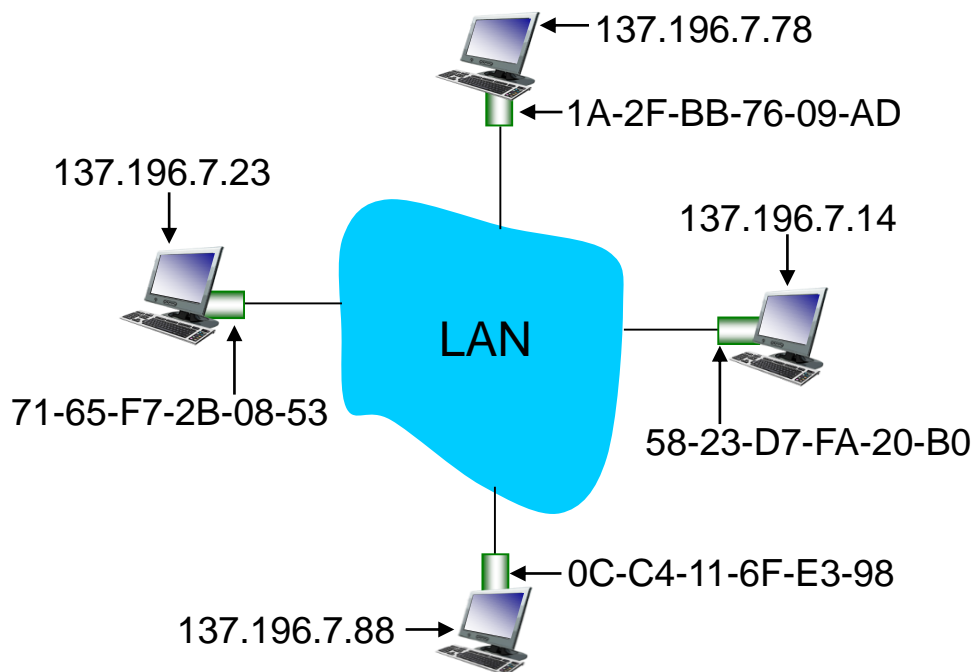


LAN addresses (more)

- MAC address allocation administered by IEEE
- manufacturer buys portion of MAC address space (to assure uniqueness)
- analogy:
 - MAC address: like ID Number
 - IP address: like postal address
- MAC flat address → portability
 - can move LAN card from one LAN to another
- IP hierarchical address *not* portable
 - address depends on IP subnet to which node is attached

ARP: address resolution protocol

Question: how to determine interface's MAC address, knowing its IP address?



ARP table: each IP node (host, router) on LAN has table

- IP/MAC address mappings for some LAN nodes:
< IP address; MAC address; TTL >
- TTL (Time To Live): time after which address mapping will be forgotten (typically 20 min)

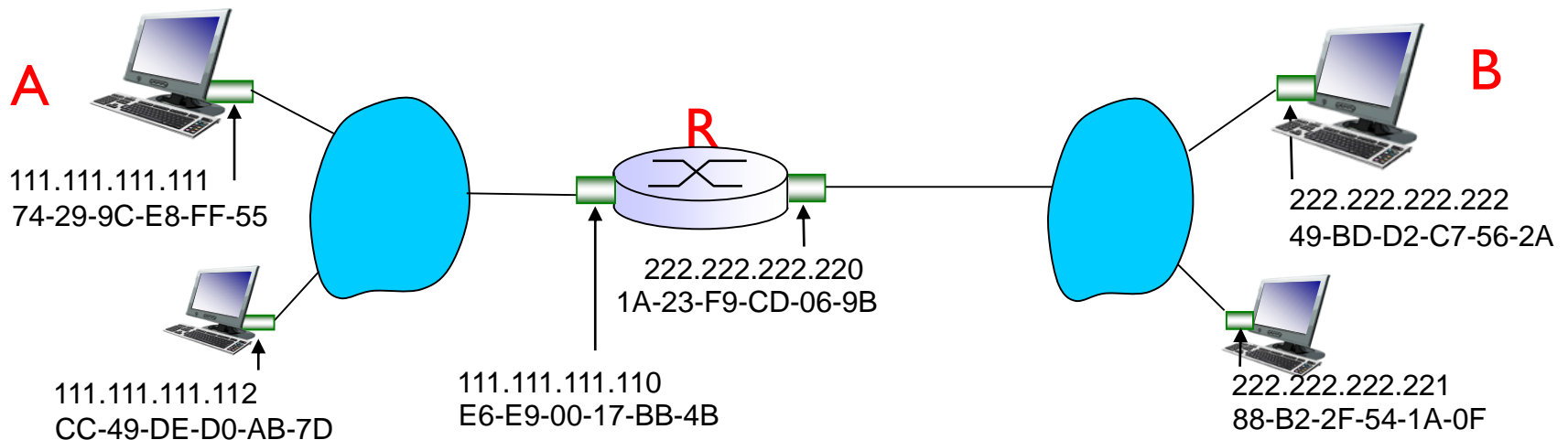
ARP protocol: same LAN

- A wants to send datagram to B
 - B's MAC address not in A's ARP table.
- A **broadcasts** ARP query packet, containing B's IP address
 - destination MAC address = FF-FF-FF-FF-FF-FF
 - all nodes on LAN receive ARP query
- B receives ARP packet, replies to A with its (B's) MAC address
 - frame sent to A's MAC address (unicast)
- A caches (saves) IP-to-MAC address pair in its ARP table until information becomes old (times out)
 - soft state: information that times out (goes away) unless refreshed
- ARP is “plug-and-play”:
 - nodes create their ARP tables *without intervention from net administrator*

Addressing: routing to another LAN

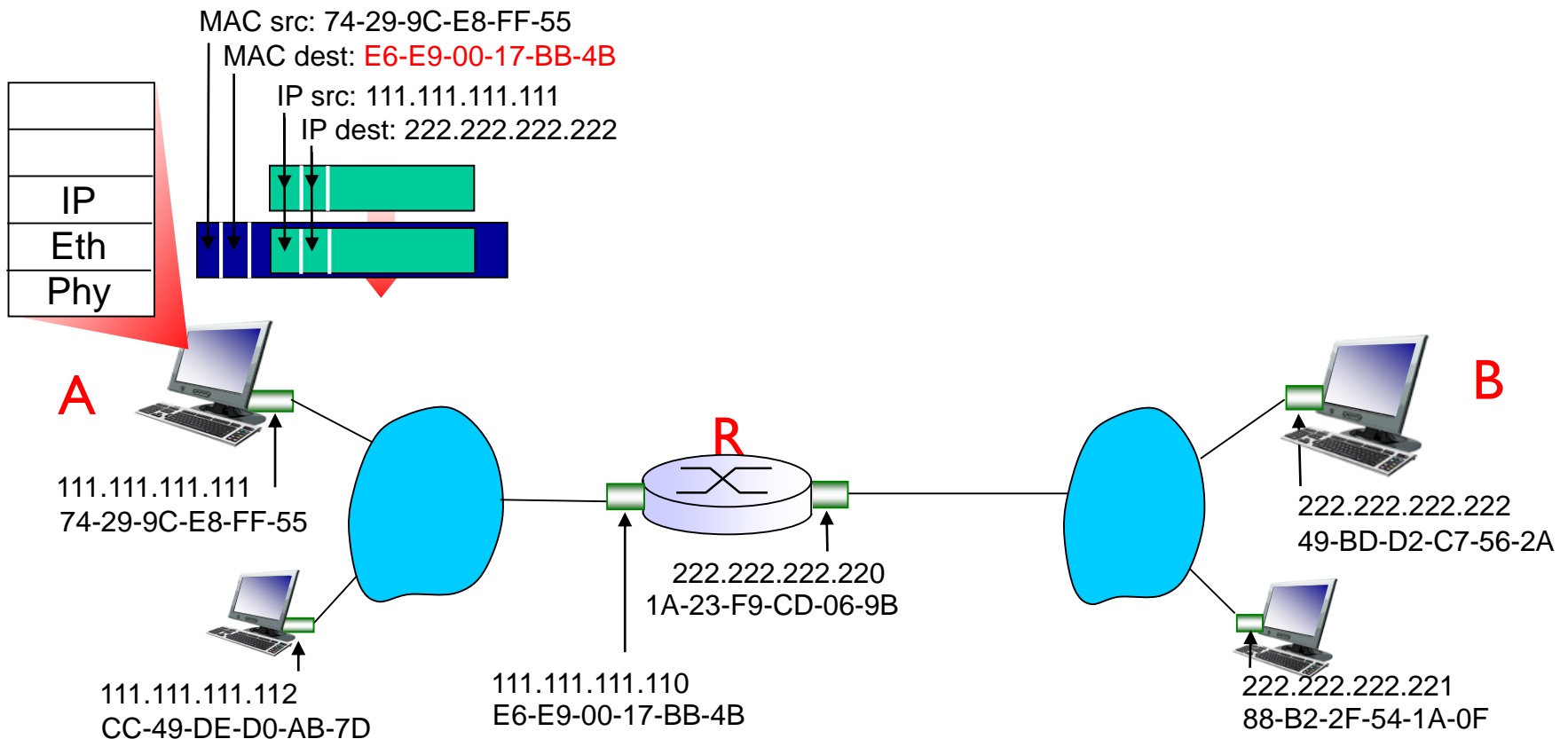
walkthrough: **send datagram from A to B via R**

- focus on addressing – at IP (datagram) and MAC layer (frame)
- assume A knows B's IP address
- assume A knows IP address of first hop router, R (how?)
- assume A knows R's MAC address (how?)



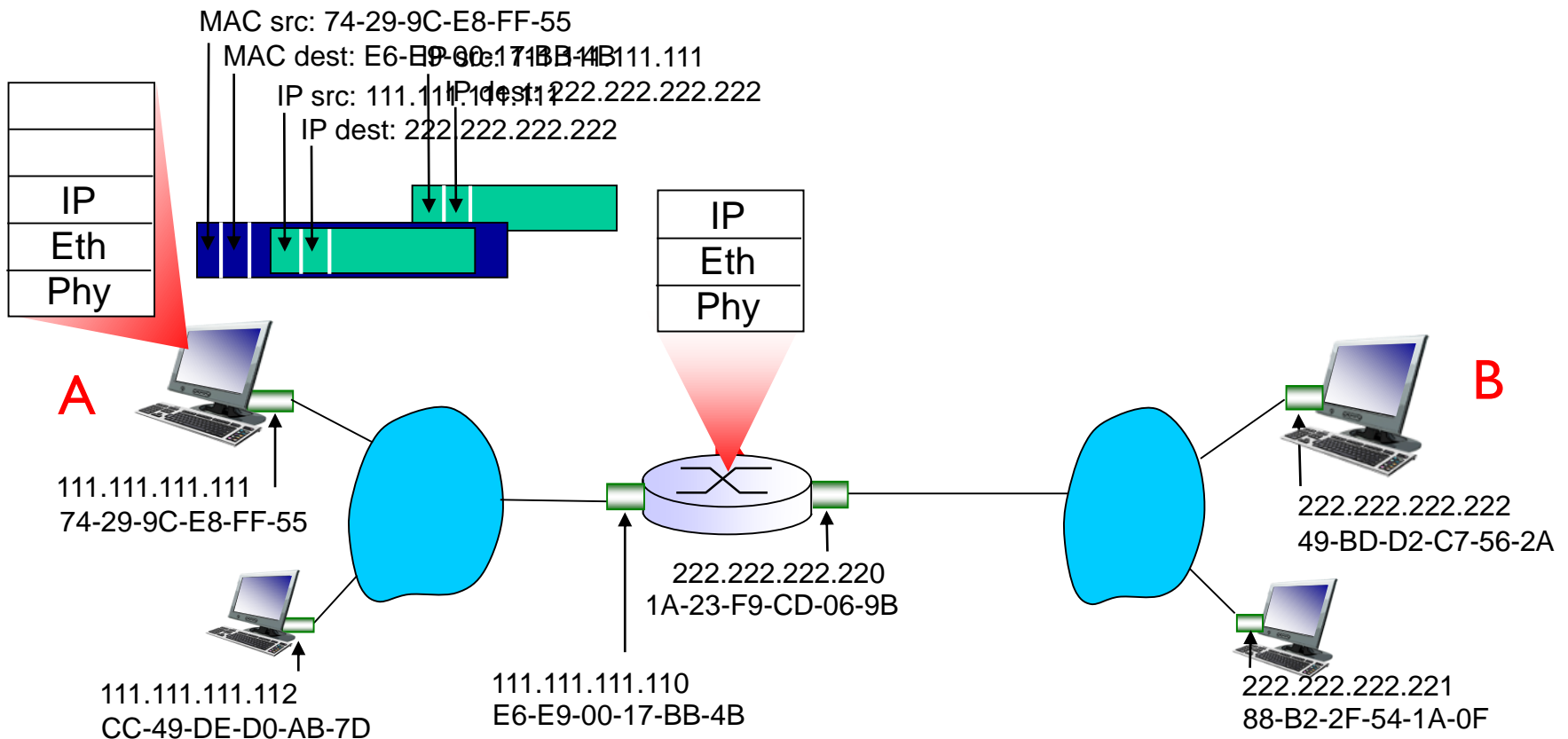
Addressing: routing to another LAN

- A creates IP datagram with IP source A, destination B
- A creates link-layer frame with R's MAC address as destination address, frame contains A-to-B IP datagram



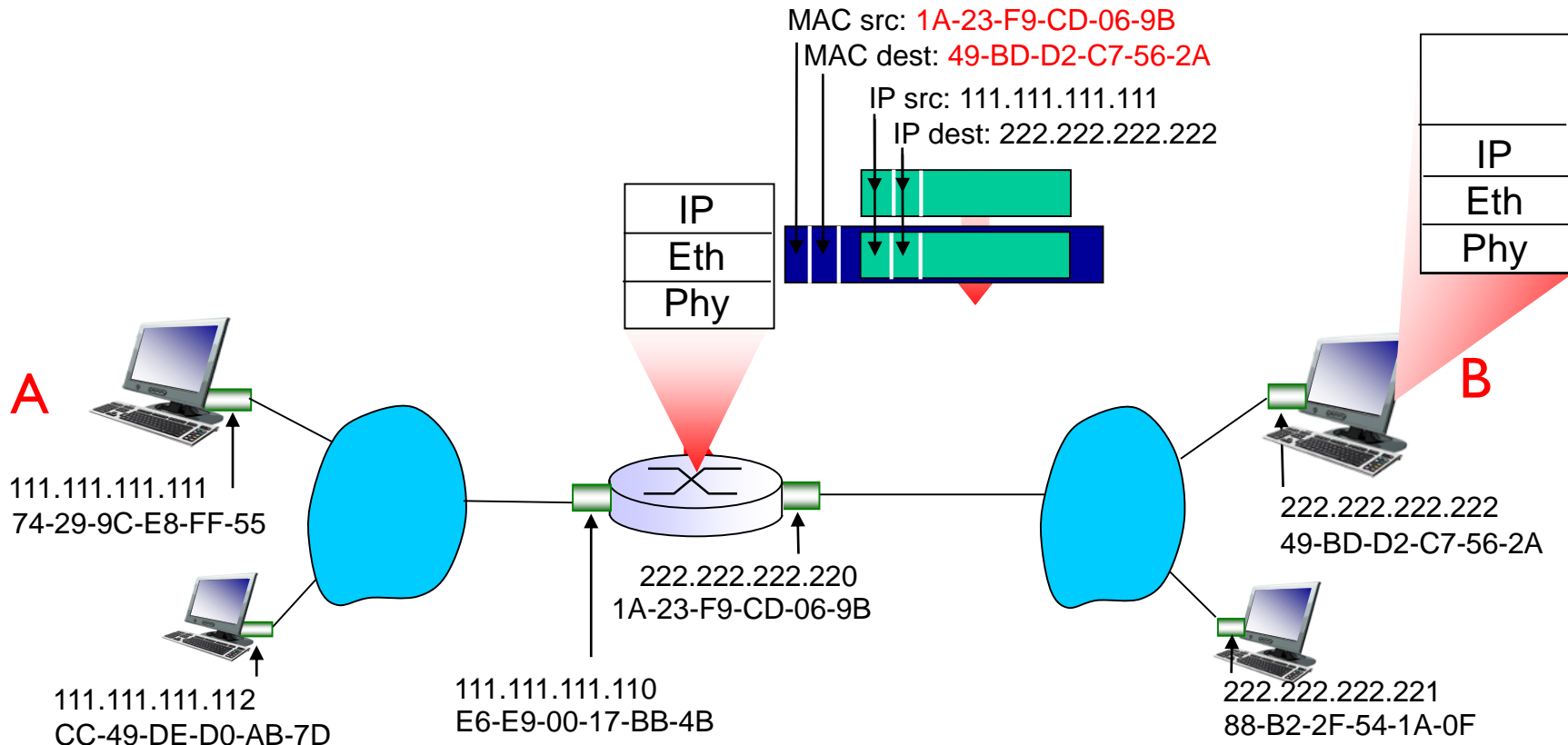
Addressing: routing to another LAN

- frame sent from A to R
- frame received at R, datagram removed, passed up to IP



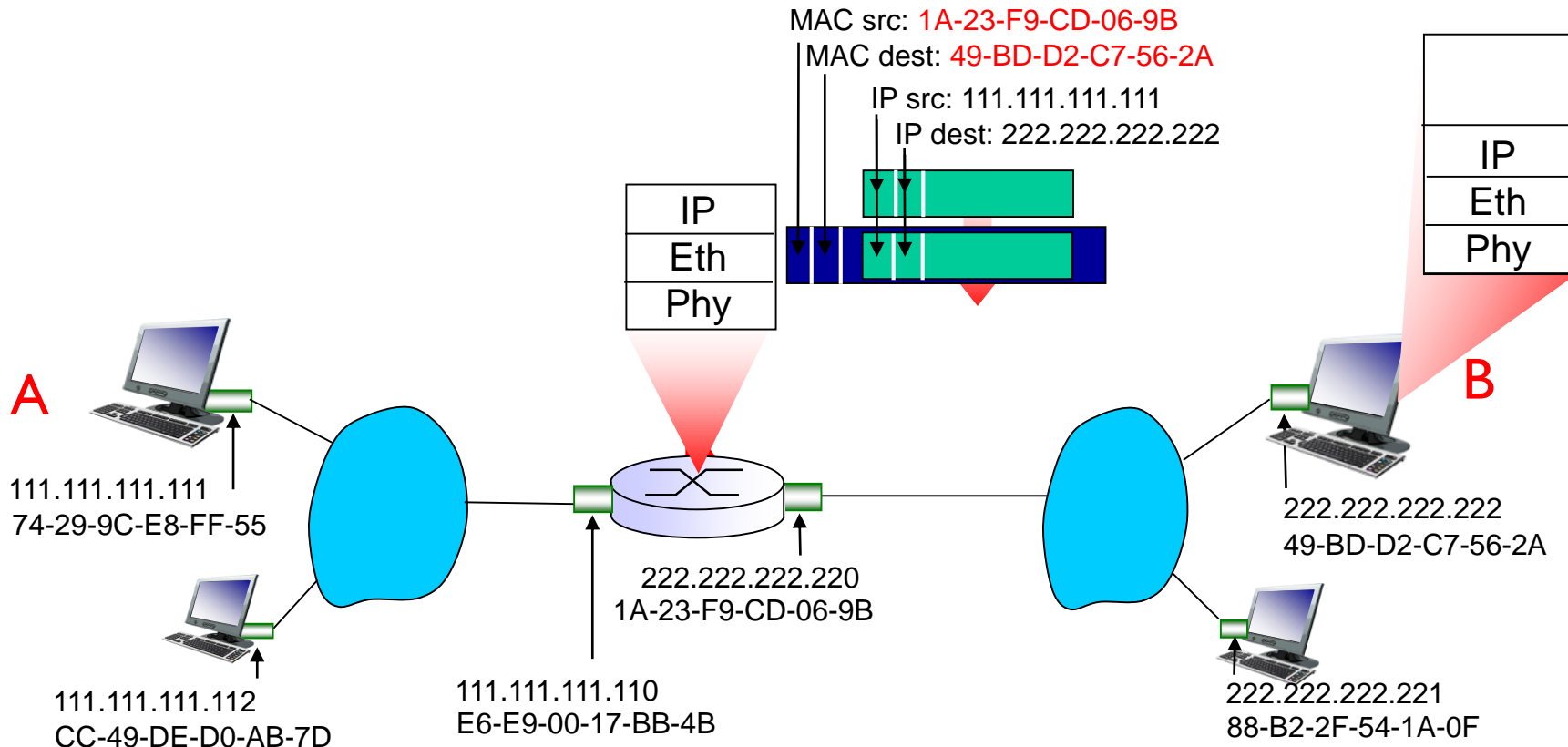
Addressing: routing to another LAN

- R forwards datagram with IP source A, destination B
- R creates link-layer frame with B's MAC address as destination address, frame contains A-to-B IP datagram



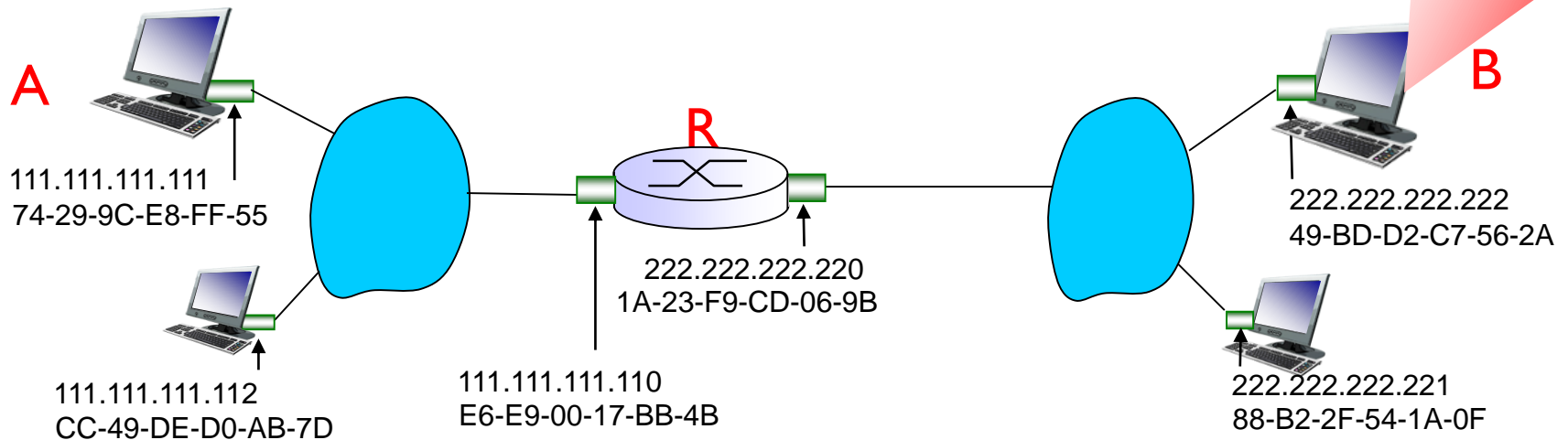
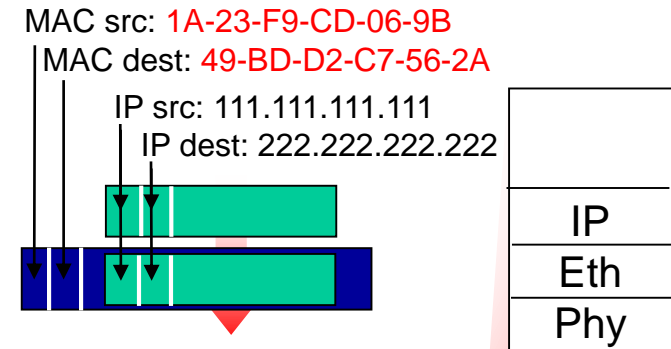
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