

UNIVERSIDAD CENTROAMERICANA “JOSÉ SIMEÓN  
CAÑAS”

Facultad de Ingeniería y Arquitectura Departamento de Electrónica  
e Informática



Técnicas de simulación en computadoras - Ciclo 01/2024

Tarea:  
Segunda tarea práctica grupal

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Sección: 01

Antiguo Cuscatlán, lunes 10 de junio de 2024

# Grupo 10

## Pentagono de lado 20

1) Localización: Mallado, tabla de conectividades  
y tabla de coordenadas de nodos.

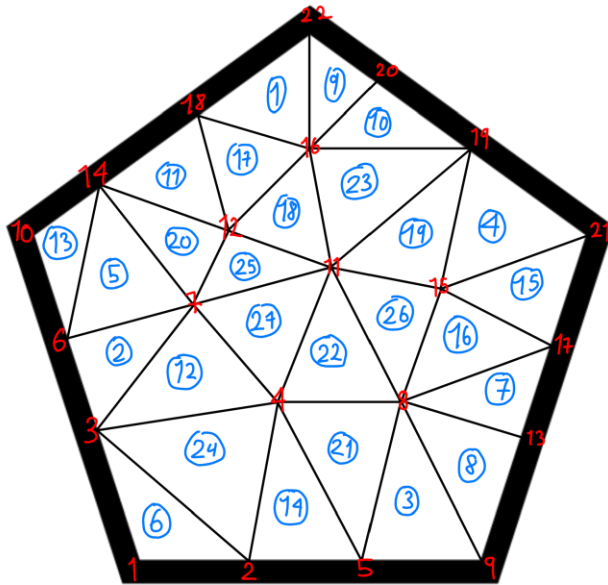


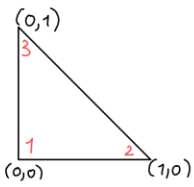
Tabla de coordenadas de nodos

Nodo	x	y
1	-23.28	-13.66
2	-19.36	-13.66
3	-24.49	-9.93
4	-18.34	-9.21
5	-15.44	-13.66
6	-25.71	-6.21
7	-21.41	-5.29
8	-13.09	-8.81
9	-11.52	-13.66
10	-26.92	-2.48
11	-16.2	-3.89

Nodo	x	y
12	-19.97	-2.04
13	-10.31	-9.94
14	-23.75	-0.18
15	-11.66	-4.34
16	-16.80	0.27
17	-9.10	-6.21
18	-20.58	2.13
19	-11.06	-0.18
20	-14.23	2.13
21	-7.89	-2.48
22	-17.40	4.43

Tabla de conectividades.

Elemento	1	2	3
1	22	18	16
2	6	3	7
3	5	9	8
4	21	19	15
5	14	6	7
6	1	2	3
7	13	17	8
8	13	8	9
9	20	22	16
10	20	16	19
11	18	14	12
12	3	4	7
13	10	6	14
14	2	5	4
15	17	21	15
16	17	15	8
17	16	18	12
18	16	12	11
19	15	19	11
20	12	14	7
21	4	5	8
22	4	8	11
23	16	11	19
24	2	4	3
25	11	12	7
26	15	11	8
27	7	4	11



$$N_1 = 1 - \epsilon - \eta$$

$$N_2 = \epsilon$$

$$N_3 = \eta$$

$$\begin{array}{l} A \rightarrow N_1(0,0) = 1 - 0 - 0 = 1 \quad N_2(0,0) = 0 \quad N_3(0,0) = 0 \\ B \rightarrow N_1(1,0) = 1 - 1 - 0 = 0 \quad N_2(1,0) = 1 \quad N_3(1,0) = 0 \\ C \rightarrow N_1(0,1) = 1 - 0 - 1 = 0 \quad N_2(0,1) = 0 \quad N_3(0,1) = 1 \end{array}$$

$$NP = \begin{bmatrix} N_1 & N_2 & N_3 \end{bmatrix} \begin{bmatrix} P_1 \\ P_2 \\ P_3 \end{bmatrix}$$

$$N_{1A}P_1 + N_{2A}P_2 + N_{3A}P_3 = (1)P_1 + (0)P_2 + (0)P_3 = P_1$$

$$N_{1B}P_1 + N_{2B}P_2 + N_{3B}P_3 = (0)P_1 + (1)P_2 + (0)P_3 = P_2$$

$$N_{1C}P_1 + N_{2C}P_2 + N_{3C}P_3 = (0)P_1 + (0)P_2 + (1)P_3 = P_3$$

## 2) Interpolación.

$$P = NT$$

## 3) Aproximación del modelo.

$$-\eta^3 \nabla(\epsilon^2 \nabla P) \approx \eta + \epsilon^3$$

$$Q = \eta + \epsilon^3 + \eta^3 \nabla(\epsilon^2 \nabla NP)$$

## 4) Método de residuos ponderados.

$$\int_A \omega Q \, dA = 0$$

$$\int_A \omega (\eta + \epsilon^3 + \eta^3 \nabla(\epsilon^2 \nabla N)) \, dA = 0$$

## 5) Método de Galerkin

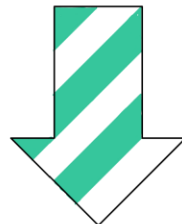
$$\omega = N^+$$

$$\int_A N^+ (\eta + \epsilon^3 + \eta^3 \nabla(\epsilon^2 \nabla N)) \, dA = 0$$

$$\int_A N^+ \eta \, dA + \int_A N^+ \epsilon^3 + \int_A N^+ (\eta^3 \nabla(\epsilon^2 \nabla N)) \, dA = 0$$

$$-\int_A N^+ (\eta^3 \nabla(\epsilon^2 \nabla N)) \, dA = \int_A N^+ \eta \, dA + \int_A N^+ \epsilon^3$$

Continuación en siguiente página.



$$-\int_A N^+ (\eta^3 \nabla (\epsilon^2 \nabla N)) dA P = \underbrace{\int_A N^+ \eta dA}_A + \underbrace{\int_A N^+ \epsilon^3}_B$$

Lado derecho

Resolución de A

$$\int_A N^+ \eta dA \rightarrow \int_0^1 \int_0^{1-\eta} \begin{bmatrix} 1-\epsilon-\eta \\ \epsilon \\ \eta \end{bmatrix} \eta d\epsilon d\eta$$

Integral interna

$$\int_0^{1-\eta} \begin{bmatrix} \eta - \epsilon - \eta^2 \\ \epsilon \eta \\ \eta^2 \end{bmatrix} d\epsilon = \begin{bmatrix} \epsilon (\eta - \eta^2) - \frac{\epsilon^2 - \eta}{2} \\ \frac{\epsilon^2}{2} \\ \epsilon \eta^2 \end{bmatrix} \bigg|_0^{1-\eta} = \begin{bmatrix} \frac{\eta (\eta - 1)^2}{2} \\ \frac{(\eta - 1)^2}{2} \\ -\eta^2 (\eta - 1) \end{bmatrix}$$

Integral externa

$$\int_0^1 \begin{bmatrix} \frac{\eta (\eta - 1)^2}{2} \\ \frac{(\eta - 1)^2}{2} \\ -\eta^2 (\eta - 1) \end{bmatrix} d\eta = \begin{bmatrix} \frac{\eta^2 (3\eta^2 - 8\eta + 6)}{24} \\ \frac{(\eta - 1)^3}{6} \\ -\frac{\eta^3 (3\eta - 4)}{12} \end{bmatrix} \bigg|_0^1 = \begin{bmatrix} \frac{1}{24} \\ \frac{1}{6} \\ \frac{1}{12} \end{bmatrix}$$

Resolución de B

$$\int_A N^+ \epsilon^3 dA = \int_0^1 \int_0^{1-\eta} \begin{bmatrix} 1-\epsilon-\eta \\ \epsilon \\ \eta \end{bmatrix} \epsilon^3 d\epsilon d\eta$$

Integral interna

$$\int_0^{1-\eta} \begin{bmatrix} \epsilon^3 - \epsilon^4 - \epsilon^3 \eta \\ \epsilon^4 \\ \epsilon^3 \eta \end{bmatrix} d\epsilon = \begin{bmatrix} \frac{-\epsilon^5}{5} - \frac{\epsilon^4 (\eta - 1)}{4} \\ \frac{\epsilon^5}{5} \\ \frac{\epsilon^4 \eta}{4} \end{bmatrix} \bigg|_0^{1-\eta} = \begin{bmatrix} \frac{-(\eta - 1)^5}{20} \\ \frac{(\eta - 1)^5}{5} \\ \frac{\eta (\eta - 1)^4}{4} \end{bmatrix}$$

Continuación en siguiente página.



Integral externa

$$\int_0^1 \begin{bmatrix} \frac{-(\eta-1)^5}{20} \\ \frac{-(\eta-1)^5}{5} \\ \frac{\eta(\eta-1)^4}{4} \end{bmatrix} d\eta = \begin{bmatrix} \frac{-(\eta-1)^6}{120} \\ \frac{-(\eta-1)^6}{30} \\ \frac{\eta^5(5\eta^4 - 24\eta^3 + 45\eta^2 - 40\eta + 15)}{120} \end{bmatrix} = \begin{bmatrix} \frac{1}{120} \\ \frac{1}{30} \\ \frac{1}{120} \end{bmatrix}$$

$$b = \mathcal{J} \begin{pmatrix} \begin{bmatrix} \frac{1}{24} \\ \frac{1}{6} \\ \frac{1}{12} \end{bmatrix} + \begin{bmatrix} \frac{1}{120} \\ \frac{1}{30} \\ \frac{1}{120} \end{bmatrix} \end{pmatrix} = \mathcal{J} \begin{bmatrix} \frac{1}{20} \\ \frac{3}{40} \\ \frac{1}{120} \end{bmatrix}$$

Lado izquierdo

$$\left( - \int N^T \nabla \eta^3 \epsilon^2 (\nabla N) dA \right) P$$

$$U = N^T \quad V = \nabla \eta^3 \epsilon^2 \nabla N$$

$$dU = \nabla N^T \quad dV = \eta^3 \epsilon^2 \nabla N$$

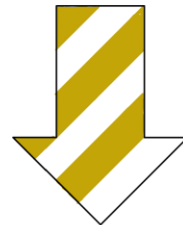
$$-\underbrace{\left( N^T \nabla \eta^3 \epsilon^2 \nabla N \right)}_{T_N} + \int_A \nabla N^T \eta^3 \epsilon^2 \nabla N dA$$

Resolución de integral de k

$$\int_A \nabla N^T \eta^3 \epsilon^2 \nabla N dA$$

$$\nabla N = \begin{bmatrix} \frac{\delta}{\delta \epsilon} \\ \frac{\delta}{\delta \eta} \end{bmatrix} [N_1 \ N_2 \ N_3]$$

Continuación en siguiente página.



$$\nabla N = \mathcal{J}^T \begin{bmatrix} \frac{\delta}{\delta \epsilon} \\ \frac{\delta}{\delta \eta} \end{bmatrix} [1 - \epsilon - \eta \quad \epsilon \quad \eta]$$

$$= J^{-1} \begin{bmatrix} \frac{\partial}{\partial \epsilon} \\ \frac{\partial}{\partial \eta} \end{bmatrix} [1-\epsilon-\eta] \begin{bmatrix} \frac{\partial}{\partial \epsilon} \\ \frac{\partial}{\partial \eta} \end{bmatrix} \epsilon \begin{bmatrix} \frac{\partial}{\partial \epsilon} \\ \frac{\partial}{\partial \eta} \end{bmatrix} \eta = \begin{bmatrix} \frac{\partial}{\partial \epsilon} (1-\epsilon-\eta) & \frac{\partial}{\partial \epsilon} (\epsilon) & \frac{\partial}{\partial \epsilon} (\eta) \\ \frac{\partial}{\partial \eta} (1-\epsilon-\eta) & \frac{\partial}{\partial \eta} (\epsilon) & \frac{\partial}{\partial \eta} (\eta) \end{bmatrix} = \begin{bmatrix} -1 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix} \quad \textcircled{B}$$

$$\nabla N = J^{-1} B$$

$$J^{-1} = \frac{1}{|J|} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} = \frac{1}{|J|} \begin{bmatrix} (y_2 - y_1)(y_1 - y_2) \\ (x_1 - x_2)(x_2 - x_1) \end{bmatrix} = \frac{1}{J} A \quad \textcircled{A}$$

$$\nabla N = \frac{1}{J} A B \quad \nabla N^T = \left( \frac{1}{J} A B \right)^T = \frac{1}{J} B^T A^T$$

$$= \int_A \eta^3 \epsilon^2 dA = \int_0^1 \int_0^{1-\eta} \eta^3 \epsilon^2 d\epsilon d\eta = \frac{1}{420}$$

$$K = \frac{1}{420 J^2} B^T A^T A B P$$

$$R // K T = b$$

$$\downarrow$$

$$\frac{1}{420 J^2} B^T A^T A B P = J \begin{bmatrix} \frac{1}{20} \\ \frac{3}{40} \\ \frac{1}{120} \end{bmatrix}$$