Computational Graphics: Lecture 12

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LAR-CC library

download from github

\$ git clone git@github.com:cvdlab/lar-cc.git

download from github

```
In your python files:
import sys
""" import modules from lar-cc/lib
                                      11 11 11
sys.path.insert(0, 'lib/py/')
from simplexn import *
from larcc import *
from lar2psm import *
from largrid import *
```

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LAR representation

Input of a simplicial complex (brc2csr)

From BRC (Binary Row Compressed) to CSR (Compressed Sparse Row)

LAR model: (V,FV,EV)

```
V = [[0, 0], [1, 0], [2, 0], [0, 1], [1, 1], [2, 1]]
FV = [[0, 1, 3], [1, 2, 4], [1, 3, 4], [2, 4, 5]]
EV = [[0,1],[0,3],[1,2],[1,3],[1,4],[2,4],[2,5],[3,4],[4,5]]

VIEW(STRUCT(MKPOLS((V,FV)))); VIEW(EXPLODE(1.2,1.2,1)(MKPOLS((V,FV))))
VIEW(STRUCT(MKPOLS((V,EV)))); VIEW(EXPLODE(1.2,1.2,1)(MKPOLS((V,EV))))
```

```
csrFV = csrCreate(FV)
csrEV = csrCreate(EV)

print "\ncsrCreate(FV) =\n", csrFV
print "\n>>> csr2DenseMatrix"
print "\nFV =\n", csr2DenseMatrix(csrFV)
print "\nEV =\n", csr2DenseMatrix(csrEV)
```

Input of a simplicial complex (brc2csr)

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```
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FV = [[0, 1, 3], [1, 2, 4], [1, 3, 4], [2, 4, 5]]
EV = [[0,1],[0,3],[1,2],[1,3],[1,4],[2,4],[2,5],[3,4],[4,5]]

VIEW(STRUCT(MKPOLS((V,FV)))); VIEW(EXPLODE(1.2,1.2,1)(MKPOLS((V,FV))))
VIEW(STRUCT(MKPOLS((V,EV)))); VIEW(EXPLODE(1.2,1.2,1)(MKPOLS((V,EV))))
```

Lar representation: (CSR matrix)

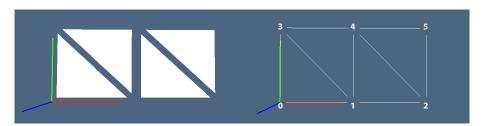
```
csrFV = csrCreate(FV)
csrEV = csrCreate(EV)

print "\ncsrCreate(FV) =\n", csrFV
print "\n>>> csr2DenseMatrix"
print "\nFV =\n", csr2DenseMatrix(csrFV)
print "\nEV =\n", csr2DenseMatrix(csrEV)
```

Input of a simplicial complex (brc2csr)

csrCreate(FV) =
(0, 0)	1
(0, 1)	1
(0, 3)	1
(1, 1)	1
(1, 2)	1
(1, 4)	1
(2, 1)	1
(2, 3)	1
(2, 4)	1
(3, 2)	1
(3, 4)	1
(3, 5)	1





Facet extraction



combinatorial approach

• A k-face of a d-simplex is defined as the convex hull of any subset of k vertices.

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- A (d-1)-face of a d-simplex

$$\sigma^d = \langle v_0, v_1, \dots, v_d \rangle$$

is also called a facet.



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• Each of the d+1 facets of σ^d , obtained by removing a vertex from σ^d , is a (d-1)-simplex.



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- A simplex may be oriented in two different ways according to the permutation class of its vertices.

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- Each of the d+1 facets of σ^d , obtained by removing a vertex from σ^d , is a (d-1)-simplex.
- A simplex may be oriented in two different ways according to the permutation class of its vertices.
- The simplex orientation is so changed by either multiplying the simplex by -1, or by executing an odd number of exchanges of its vertices.



combinatorial approach

The chain of oriented boundary facets of σ^d , usually denoted as $\partial \sigma^d$, is generated combinatorially as follows:

$$\partial \sigma^d = \sum_{k=0}^d (-1)^d \langle v_0, \dots, v_{k-1}, v_{k+1}, \dots, v_d \rangle$$

Implementation

Test of implementation

```
>>>larSimplexFacets([[0]])
[[]]
>>>larSimplexFacets([[0,1]])
[[0],[1]]
>>>larSimplexFacets([[0,1,2,]])
[[0,1],[0,2],[1,2]]
>>>larSimplexFacets([[0,1,2,3]])
[[0,1,2],[0,1,3],[0,2,3],[1,2,3]]
>>>larSimplexFacets([[0,1,2,3,4]])
[[0,1,2,3],[0,1,2,4],[0,1,3,4],[0,2,3,4],[1,2,3,4]]
```

Test of implementation

```
>>>larSimplexFacets([[0]])
[[]]
>>>larSimplexFacets([[0,1]])
[[0],[1]]
>>>larSimplexFacets([[0,1,2,]])
[[0,1],[0,2],[1,2]]
>>>larSimplexFacets([[0,1,2,3]])
[[0,1,2],[0,1,3],[0,2,3],[1,2,3]]
>>>larSimplexFacets([[0,1,2,3,4]])
[[0,1,2,3],[0,1,2,4],[0,1,3,4],[0,2,3,4],[1,2,3,4]]
```

are such facets oriented?



Examples of facet extraction from 3D simplicial cube

```
V,CV = larSimplexGrid1([1,1,1])
VIEW(EXPLODE(1.5,1.5,1.5)(MKPOLS((V,CV))))
SK2 = (V,larSimplexFacets(CV))
VIEW(EXPLODE(1.5,1.5,1.5)(MKPOLS(SK2)))
SK1 = (V,larSimplexFacets(SK2[1]))
VIEW(EXPLODE(1.5,1.5,1.5)(MKPOLS(SK1)))
look also at
V,CV = larSimplexGrid1([5,5,2])
```



Assignment

Change the larSimplexFacets so that the extracted facets are coherently oriented



Boundary computation

From cells and facets to boundary operator

```
def boundary(cells,facets):
    csrCV = csrCreate(cells)
    csrFV = csrCreate(facets)
    csrFC = matrixProduct(csrFV, csrTranspose(csrCV))
    facetLengths = [csrCell.getnnz() for csrCell in csrCV]
    return csrBoundaryFilter(csrFC,facetLengths)

def coboundary(cells,facets):
    Boundary = boundary(cells,facets)
    return csrTranspose(Boundary)
```

Oriented boundary example

```
V,CV = larSimplexGrid1([4,4,4])
VIEW(EXPLODE(1.5,1.5,1.5)(MKPOLS((V,CV))))
FV = larSimplexFacets(CV)
EV = larSimplexFacets(FV)
VIEW(EXPLODE(1.5,1.5,1.5)(MKPOLS((V,FV))))
csrSignedBoundaryMat = signedBoundary (V,CV,FV)
boundaryCells_2 = signedBoundaryCells(V,CV,FV)
def swap(1): return [1[1],1[0],1[2]]
boundaryFV = [FV[-k] if k<0 else swap(FV[k]) for k in boundaryCells_2]
boundary = (V,boundaryFV)
VIEW(EXPLODE(1.5,1.5,1.5)(MKPOLS(boundary)))
```

Oriented boundary example

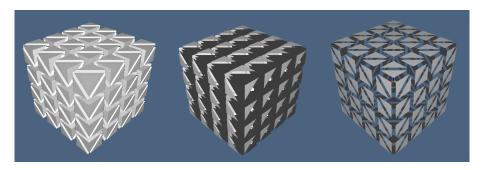


Figure: Simplicial complexes: (a) 3-complex S_3 ; (b) 2-complex $S_2 = K_2(S_3)$; (c) 2-complex $T_2 = \partial S_3 \subset S_2$)

Extrusion



Simplicial extrusion

Computation

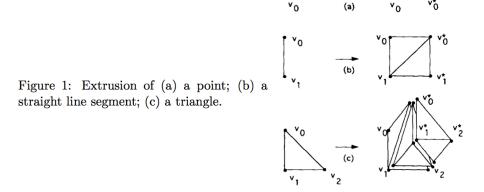


Figure: example caption

Simplicial extrusion

Computation

Let us concentrate on the generation of the simplex chain γ^{d+1} of dimension d+1 produced by combinatorial extrusion of a single simplex

$$\sigma^d = \langle v_0, v_1, \dots, v_d, \rangle.$$

Then we have, with $|\gamma^{d+1}| = \sigma^d \times I$, and I = [0,1]:

$$\gamma^{d+1} = \sum_{k=0}^{d} (-1)^{kd} \langle v_k, \dots v_d, v_0^*, \dots v_k^* \rangle$$

with $v_k \in \sigma^d \times \{0\}$ and $v_k^* \in \sigma^d \times \{1\}$, and where the term $(-1)^{kd}$ is used to generate a chain of coherently-oriented extruded simplices.



Example of simplicial complex extrusion

```
V = [[0,0],[1,0],[2,0],[0,1],[1,1],[2,1],[0,2],[1,2],[2,2]]
FV = [[0,1,3],[1,2,4],[2,4,5],[3,4,6],[4,6,7],[5,7,8]]
model = larExtrude1((V,FV),4*[1,2,-3])
VIEW(EXPLODE(1,1,1.2)(MKPOLS(model)))
```

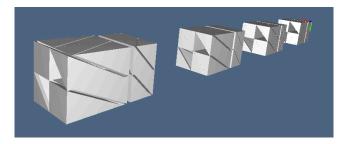


Figure: A simplicial complex providing a quite complex 3D assembly of tetrahedra.

Multidimensional simplicial grids

The generation of simplicial grids of any dimension and shape is amazingly simple

The input parameter shape is either a tuple or a list of integers used to specify the shape of the created array

```
VOID = V0,CV0 = [[]],[[0]] # the empty simplicial model

def larSimplexGrid1(shape):
    model = V0ID
    for item in shape:
        model = larExtrude1(model,item*[1])
    return model
```

The returned model has integer vertices, to be scaled and/or translated and/or mapped

Cartesian product of complexes

Cartesian product of two LAR models

Cartesian product of two LAR models

```
def larModelProduct(twoModels):
    (V, cells1), (W, cells2) = twoModels
    @< Cartesian product of vertices @>
    @< Topological product of cells</pre>
    model = [list(v) for v in vertices.keys()], cells
    return model
Cartesian product of vertices
vertices = collections.OrderedDict(): k = 0
for v in V:
    for w in W:
        id = tuple(v+w)
        if not vertices.has_key(id):
            vertices[id] = k
            k += 1 \ 0
```

Cartesian product of two LAR models

(V, cells1), (W, cells2) = twoModels

def larModelProduct(twoModels):

```
@< Cartesian product of vertices @>
    @< Topological product of cells</pre>
    model = [list(v) for v in vertices.keys()], cells
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Cartesian product of vertices
vertices = collections.OrderedDict(): k = 0
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        if not vertices.has_kev(id):
            vertices[id] = k
            k += 1 \ 0
```

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Topological product of cells

```
cells = [ [vertices[tuple(V[v] + W[w])] for v in c1 for w in c2]
        for c1 in cells1 for c2 in cells2] @}
```

Cuboidal grids

VIEW(EXPLODE(1.5,1.5,1.5) (MKPOLS(larCuboids([3,2,1]))))

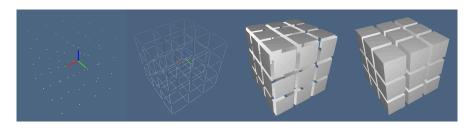


Figure: Exploded views of 0-, 1-, 2-, and 3-dimensional skeletons.

Cuboidal grids

VIEW(EXPLODE(1.5,1.5,1.5)(MKPOLS(larCuboids([3,2,1]))))

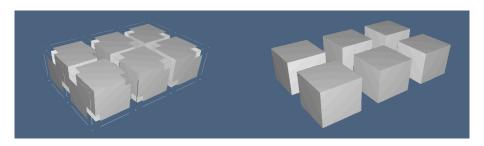


Figure: Exploded views of 0-, 1-, 2-, and 3-dimensional skeletons.

Skeletons



Cuboidal skeletons

A list of BRC characteristic matrices of cellular k-complexes ($0 \le k \le d$) with dimension d, where d = len(shape), is returned by the function <code>gridSkeletons</code> in the macro below, where the input is given by the <code>shape</code> of the grid, i.e. by the list of cell items in each coordinate direction.

```
def gridSkeletons(shape):
    gridMap = larGridSkeleton(shape)
    skeletonIds = range(len(shape)+1)
    skeletons = [ gridMap(id) for id in skeletonIds ]
    return skeletons
```

Cuboidal skeletons

Just notice that the number of returned d-cells is equal to PROD(shape)

```
print "\ngridSkeletons([3]) =\n", gridSkeletons([3])
print "\ngridSkeletons([3,2]) =\n", gridSkeletons([3,2])
print "\ngridSkeletons([3,2,1]) =\n", gridSkeletons([3,2,1])
```

Generation of grid boundary complex

```
def gridBoundaryMatrices(shape):
    skeletons = gridSkeletons(shape)
    boundaryMatrices = [boundary(skeletons[k+1],faces)
                         for k,faces in enumerate(skeletons[:-
    return boundaryMatrices
for k in range(1):
    print "\ngridBoundaryMatrices([3]) =\n", \
            csr2DenseMatrix(gridBoundaryMatrices([3])[k])
for k in range(2):
    print "\ngridBoundaryMatrices([3,2]) =\n", \
            csr2DenseMatrix(gridBoundaryMatrices([3,2])[k])
for k in range(3):
    print "\ngridBoundaryMatrices([3,2,1]) =\n", \
            csr2DenseMatrix(gridBoundaryMatrices([3,2,1])[k])
```

References



References

A. DiCarlo, V. Shapiro, and A. Paoluzzi, Linear Algebraic Representation for Topological Structures, Computer-Aided Design, Volume 46, Issue 1, January 2014, Pages 269-274 (doi:10.1016/j.cad.2013.08.044)