

Polyhedral geometry 2

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Affine spaces

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Affine space

The idea of affine space corresponds to that of a set of points where the **displacement** from a point \mathbf{x} to another point \mathbf{y} is obtained by summing a vector \mathbf{v} to the \mathbf{x} point.

Definition

A set \mathcal{A} of points is called an **affine space** modeled on the vector space \mathcal{V} if there is a function

$$\mathcal{A} \times \mathcal{V} \rightarrow \mathcal{A} : (\mathbf{x}, \mathbf{v}) \mapsto \mathbf{x} + \mathbf{v}$$

called **affine action**, with the properties:

1. $(\mathbf{x} + \mathbf{v}) + \mathbf{w} = \mathbf{x} + (\mathbf{v} + \mathbf{w})$ for each $\mathbf{x} \in \mathcal{A}$ and each $\mathbf{v}, \mathbf{w} \in \mathcal{V}$;
2. $\mathbf{x} + \mathbf{0} = \mathbf{x}$ for each $\mathbf{x} \in \mathcal{A}$, where $\mathbf{0} \in \mathcal{V}$ is the null vector;
3. for each pair $\mathbf{x}, \mathbf{y} \in \mathcal{A}$ there is a unique $(\mathbf{y} - \mathbf{x}) \in \mathcal{V}$ such that

$$\mathbf{x} + (\mathbf{y} - \mathbf{x}) = \mathbf{y}.$$

Dimension

The affine space \mathcal{A} is said of **dimension** n if modeled on a vector space \mathcal{V} of dimension n .

Vector sum vs affine action

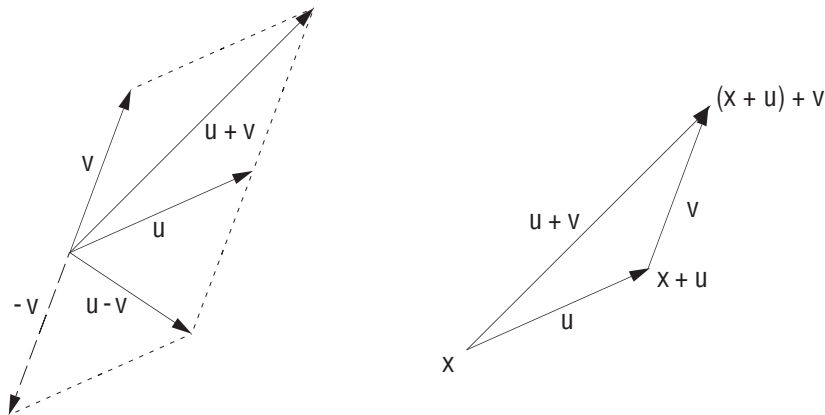


Figure : (a) Vector sum and difference are given by the parallelogram rule
(b) associativity of displacement (point and vector sum) in an affine space

Operations on vectors and points

- ▶ The **addition** of vectors is a primitive operation in a vector space.
- ▶ The **difference** of vectors is defined through the two primitive operations:

$$\mathbf{v}_1 - \mathbf{v}_2 = \mathbf{v}_1 + (-1)\mathbf{v}_2.$$

- ▶ Addition and difference of vectors are geometrically produced by the **parallelogram rule**
- ▶ notice also the **associative property** of the affine action on a point space.

Operations on vectors and points

The sum of a set $\{\mathbf{v}_i\}$ of vectors ($i = 1, \dots, n$) can be geometrically obtained, in an affine space:

- ▶ by setting $\mathbf{p}_0 = \mathbf{0}$
- ▶ $\mathbf{p}_i = \mathbf{p}_{i-1} + \mathbf{v}_i$,
- ▶ so that

$$\sum_i \mathbf{v}_i = \mathbf{p}_n - \mathbf{p}_0$$

Remark

1. the addition of points is **not** defined;
2. the difference of two points is a **vector**;
3. the sum of a point and a vector is a **point**.

Positive, affine and convex combinations

Three types of combinations of vectors or points can be defined. They lead to the concepts of **cones**, **hyperplanes** and **convex sets**, respectively.

Positive combination

Let $\mathbf{v}_0, \dots, \mathbf{v}_d \in \mathbb{R}^n$ and $\alpha_0, \dots, \alpha_d \in \mathbb{R}^+ \cup \{0\}$.

The vector

$$\alpha_0 \mathbf{v}_0 + \dots + \alpha_d \mathbf{v}_d = \sum_{i=0}^d \alpha_i \mathbf{v}_i$$

is called a **positive combination** of such vectors.

The set of all the positive combinations of $\{\mathbf{v}_0, \dots, \mathbf{v}_d\}$ is called the **positive hull** of $\{\mathbf{v}_0, \dots, \mathbf{v}_d\}$ and denoted $\text{pos}\{\mathbf{v}_0, \dots, \mathbf{v}_d\}$.

This set is also called the **cone** generated by the given vectors

Affine combination

Let $\mathbf{p}_0, \dots, \mathbf{p}_d \in \mathbb{E}^n$ and $\alpha_0, \dots, \alpha_d \in \mathbb{R}$, such that $\alpha_0 + \dots + \alpha_d = 1$.

The point

$$\sum_{i=0}^d \alpha_i \mathbf{p}_i := \mathbf{p}_0 + \sum_{i=1}^d \alpha_i (\mathbf{p}_i - \mathbf{p}_0)$$

is called an **affine combination** of the points $\mathbf{p}_0, \dots, \mathbf{p}_d$.

Affine combination

The set of all affine combinations of $\{\mathbf{p}_0, \dots, \mathbf{p}_d\}$ is an **affine subspace**, denoted by $\text{aff}\{\mathbf{p}_0, \dots, \mathbf{p}_d\}$

It is easy to verify that:

$$\text{aff}\{\mathbf{p}_0, \dots, \mathbf{p}_d\} = \mathbf{p}_0 + \text{lin}\{\mathbf{p}_1 - \mathbf{p}_0, \dots, \mathbf{p}_d - \mathbf{p}_0\}.$$

Affine combination

1. The **dimension** of an affine subspace is the dimension of the corresponding linear vector space.
2. Affine subspaces of \mathbb{E}^d with dimensions 0, 1, 2 and $d - 1$ are called **points**, **lines**, **planes** and **hyperplanes**, respectively.
3. Affine subspaces are also called **flats**.

Double description

Every affine subspace can be described either as

- ▶ the **intersection** of affine **hyperplanes**, or as
- ▶ the **affine hull** of a finite set of **points**.

Convex combination

Let $\mathbf{p}_0, \dots, \mathbf{p}_d \in \mathbb{E}^n$ and $\alpha_0, \dots, \alpha_d \geq 0$, with $\alpha_0 + \dots + \alpha_d = 1$.

The point

$$\alpha_0 \mathbf{p}_0 + \dots + \alpha_d \mathbf{p}_d = \sum_{i=0}^d \alpha_i \mathbf{p}_i$$

is called a **convex combination** of points $\mathbf{p}_0, \dots, \mathbf{p}_d$.

A **convex** combinations is both **positive** and **affine**.

Convex hull

The set of **all** convex combinations of $\{\mathbf{p}_0, \dots, \mathbf{p}_d\}$ is a convex set, called **convex hull** of $\{\mathbf{p}_0, \dots, \mathbf{p}_d\}$, and is denoted by $\text{conv}\{\mathbf{p}_0, \dots, \mathbf{p}_d\}$.

Properties

- ▶ the convex hull of a set of points is the **intersection of all convex sets** that contain them
- ▶ the convex hull of a set of points is the **smallest set** that contains them