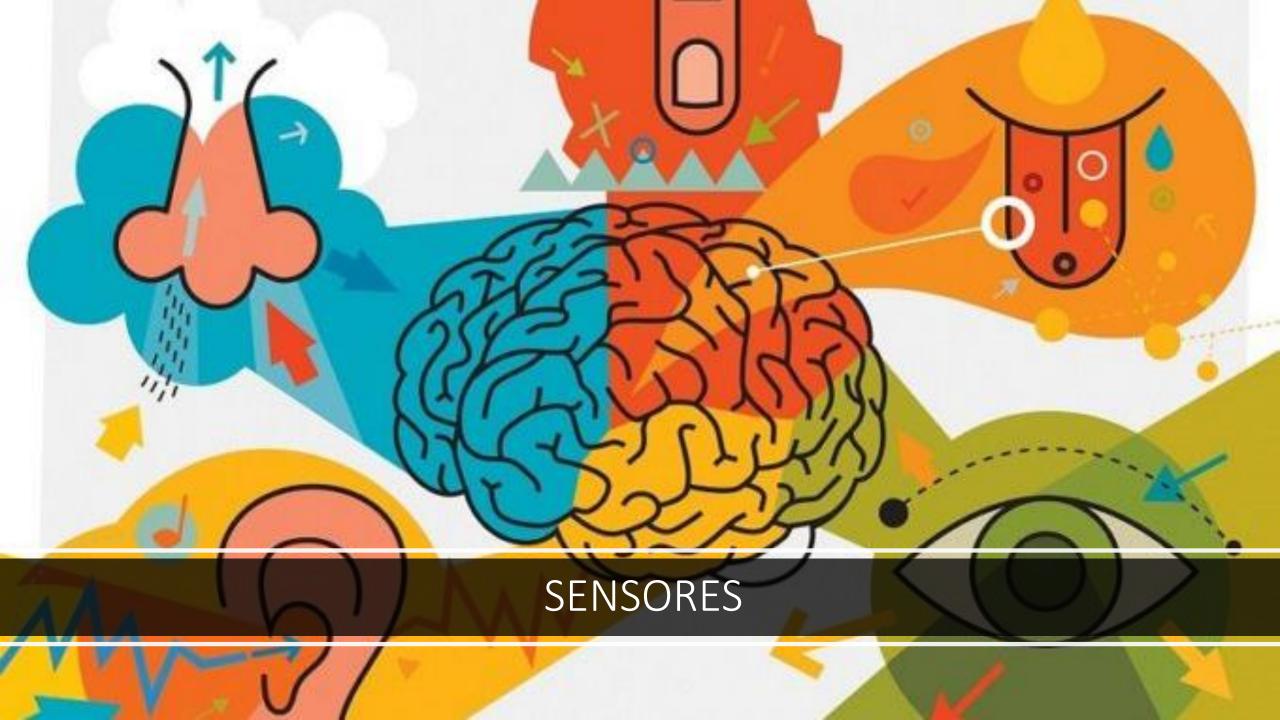


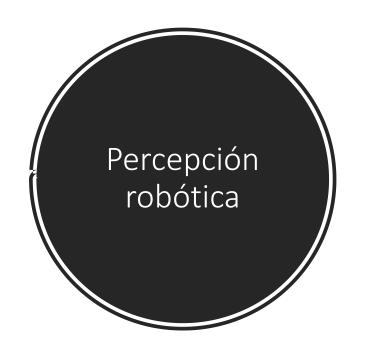


HARDWARE ROBÓTICO



EFECTORES





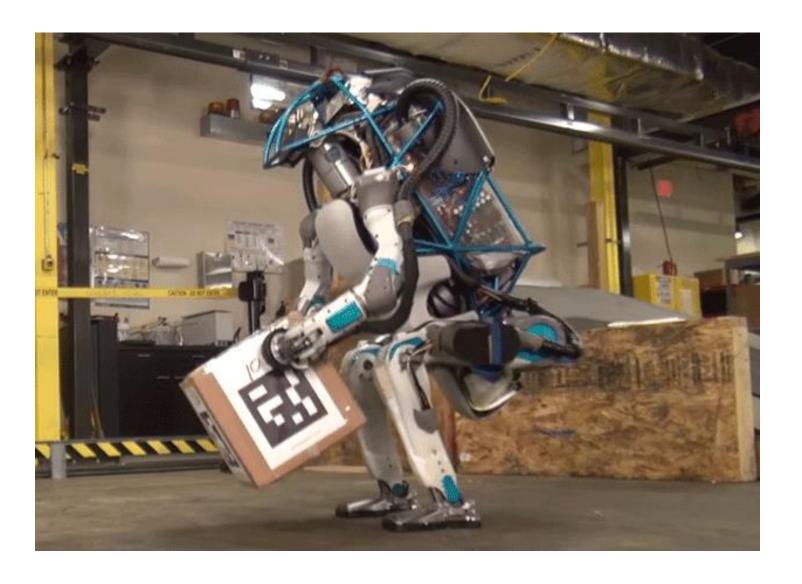


Localización ens Park avenue rth street street ue DA





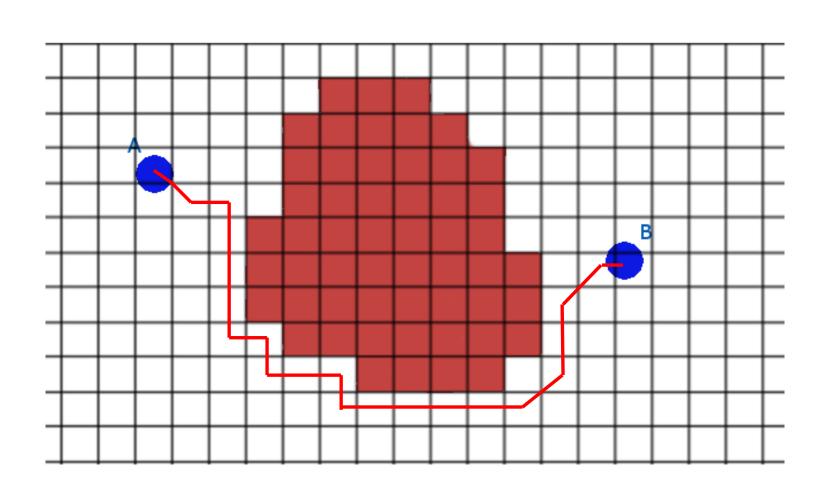




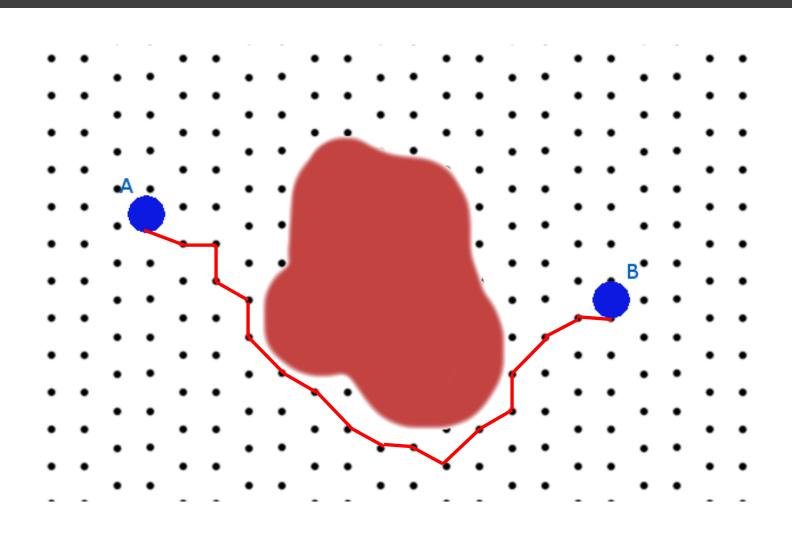
ESPACIO DE CONFIGURACIÓN



DESCOMPOSICIÓN EN CELDAS



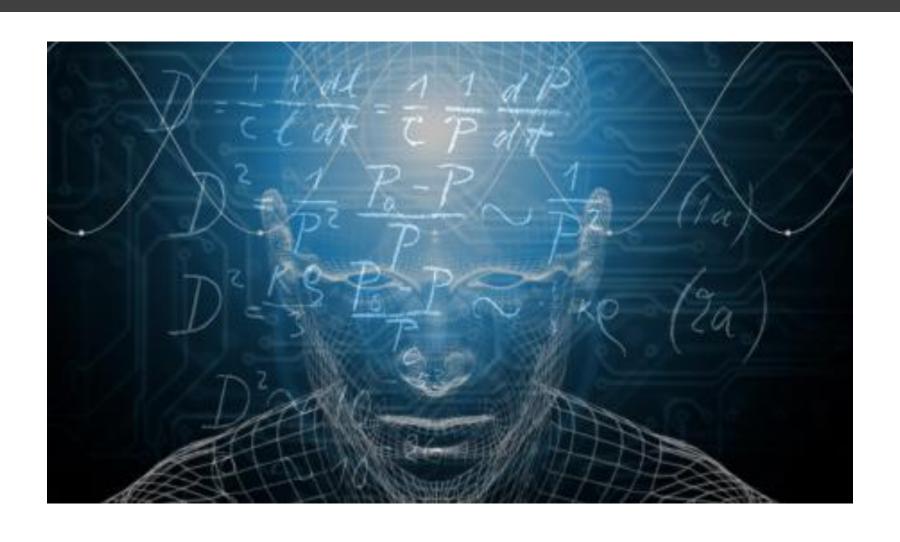
ESQUELETIZACIÓN



PLANIFICAR MOVIMIENTOS INCIERTOS



ALGORITMOS



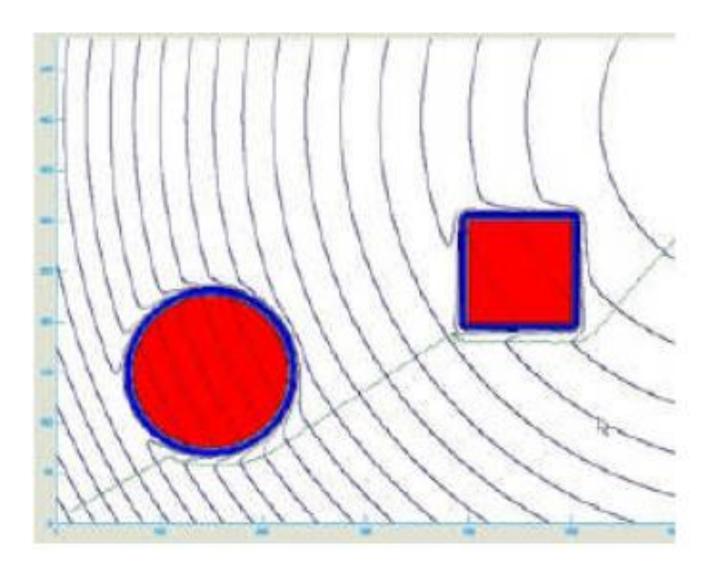




Dinámica y control

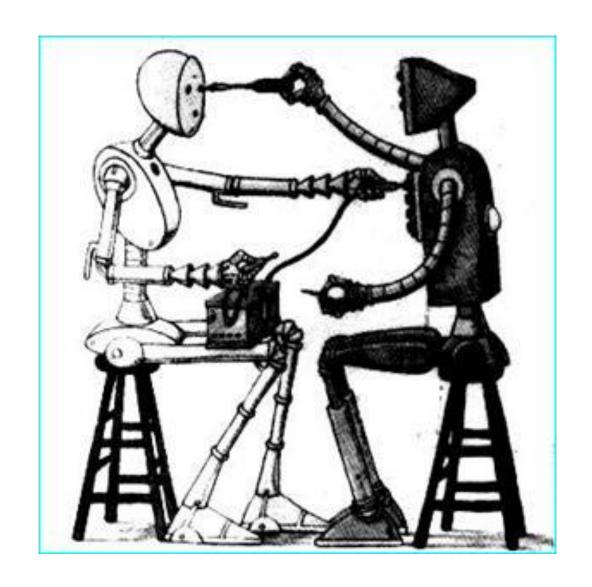








ARQUITECTURA DE HADWARE ROBÓTICO



ARQUITECTURA EN TRES CAPAS



