#### Sheet1

# Powerdesign Microlab Robot

25.07.2006

All Values in Ampere

### Gecko3

0.001100								
Part	external sources				internal sources			
	Batte	ery	3,3	3 V	2,5	5 V	1,2	V
	Typ !	Max	Тур	Max	Тур	Max	Typ N	Маx
FPGA (max. Power without heat sink)			0.002	0.020	0.160	0.220	0.550	2.500
2*RAM (Burst Mode)					0.180	0.450		
EZ-USB			0.050	0.085				
EEPROM			0.001	0.003				
SPI Flash			0.010	0.024				
Nordic RF-Modem			0.001	0.200				
Ethernet PHY			0.100	0.150				
LEDs (2*Ethernet, 8*FPGA, 2*EZ-USB)			0.040	0.060				
1,2 V DC/DC Converter (efficiency: 85%)	0.210	0.954						
2,5 V LDO			0.374	0.737				
Total Gaaka?	0.210	0.054	0 570	1 270	0.240	0.670	0.550	2 500
<u>Total Gecko3</u>	<u>0.210</u>	<u>0.954</u>	<u>0.578</u>	<u>1.279</u>	<u>0.340</u>	<u>0.670</u>	<u>0.550</u>	<u>2.500</u>

#### Sheet1

## Colibri

Part	(	external:	sources			internal	sources	
	Battery		3,3 V		Analog 3,3 V		5 V	
	Typ N	/lax	Тур	Max	Тур	Max	Тур	Max
Colibri Module (max. at 312 MHz)			0.200	0.900				
SD Card			0.050	0.100	1			
Video DAC			0.015	0.025	0.070	0.080		
LEDs (2*Ethernet, 8*Colibri))			0.030	0.050	1			
2*USB Devices							0.200	0.300
3,3 V LDO (Analog 3,3 V)	0.077	0.088						
5 V DC/DC Converter (efficiency: 85%)	0.318	0.477						
Total Colibri	<u>0.395</u>	<u>0.565</u>	<u>0.295</u>	<u>1.075</u>	<u>0.070</u>	<u>0.080</u>	<u>0.200</u>	<u>0.300</u>

### Robot Chassis

Part	external sources				internal sources			
	5 V USB		external Supply		Battery		3,3 V	
	Typ N	Лаx	Тур	Max	Тур	Max	Тур 1	Лах
2*Motor					0.100	0.600		
2*Encoder							0.050	0.010
Motor Driver								
IR Sensor							0.090	0.150
3,3 V DC/DC Converter (efficiency: 85%)					1.063	2.638		
Battery Charge Current	0.300	0.500	0.300	0.500	)			
Total Robot Chassis	<u>0.300</u>	<u>0.500</u>	<u>0.300</u>	0.500	<u>1.163</u>	<u>3.238</u>	<u>0.140</u>	<u>0.160</u>

## Total System Power

, , , , , , , , , , , , , , , , , , , ,	В	Battery		3,3 V		l Supply
	Тур	Max	Тур	Max	Тур	Max
	1.76	8 4.75	7 1.0	13 2.51	4 2.068	5.257