

# TP 9 : Introduction to the Lattice Boltzmann Method

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# Lattice Boltzmann Method

A method for fluid simulation based on the Lattice gas automata. This method can be used to numerically solve Navier-Stokes equations.

$$\begin{aligned}\partial_t u - (u \cdot \nabla) u &= -\frac{1}{\rho_0} \nabla p + \nu \nabla u \\ \nabla \cdot u &= 0\end{aligned}$$

with  $u$  the velocity,  $p$  the pressure and  $\nu$  the viscosity

# Lattice Boltzmann Method

We simulate the **populations** of particles on a lattice and therefore we work with continuous values but time and space are still discrete.

Advantages over Lattice gas automata :

- Macroscopic scale
- More particles can be simulated

# D2Q9 model

Two dimensions and 9 directions (8 plus non-moving population)

The value for each direction represents the **density** of particles going in that direction at that point.

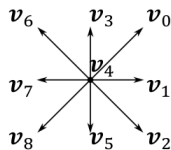
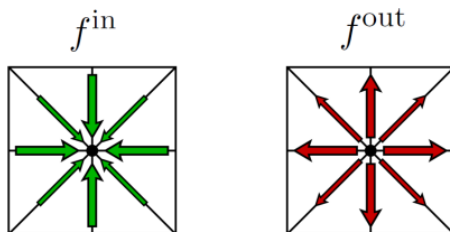


Figure: vectors of the 9 possible directions

# BGK Collision model



$$f_i^{out} = f_i^{in} - \omega \cdot (f_i^{in} - E(i, \rho, u))$$

With  $E$  the local equilibrium

$$E(i, \rho, u) = \rho t_i \left( 1 + \frac{\delta x}{\delta t} \frac{v_i \cdot u}{c_s^2} + \frac{1}{2c_s^4} \left( \frac{\delta x}{\delta t} v_i \cdot u \right)^2 - \frac{1}{2c_s^2} |u|^2 \right)$$

# Propagation

Once  $f_i^{out}$  computed we simply propagate every density to the point it is directed to in order to create  $f_i^{in}$  for time  $t + \delta t$

$$f_i^{in} = f_i^{out}(x - v_i \delta t, t - \delta t)$$

## Border outflows

Since we work on a limited domain we have to take into account the populations going outside of the domain.

therefore we apply outflows conditions :

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```
fin[col1,0,:] = fin[col1,1,:]
fin[col3,-1,:] = fin[col3,-2,:]
fin[lin1,:,0] = fin[lin1,:,1]
fin[lin3,:,-1] = fin[lin3,:,-2]
```

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# Perturbation function and initial parameters

In order to simulate a Tornado we have to apply a perturbation at the center point at each time.

$$\tilde{u}(t) = u_{LB} \begin{bmatrix} \cos(\omega_p t) \\ \sin(\omega_p t) \end{bmatrix}$$

With  $u_{LB}$  the propagation speed and  $\omega_p$  the pulse frequency

We initialise the system at equilibrium (the velocity is null everywhere) and the density to 1



# macroscopic quantities

The density :

$$\rho(x, t) = \sum_{i=0}^8 f_i^{in}(x, t)$$

The pressure :

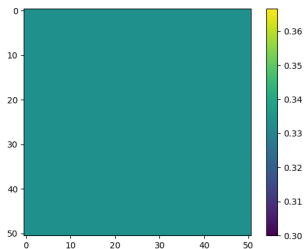
$$p = c_s^2 \rho$$

The velocity :

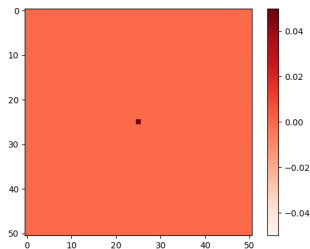
$$u(x, t) = \frac{1}{\rho(x, t)} \frac{\delta x}{\delta t} \sum_{i=0}^8 v_i f_i^{in}(x, t)$$

# Initial result

With the initial values for  $re$ ,  $n_x$ ,  $n_y$ ,  $u_{LB}$  and  $\omega_p = 0.2$

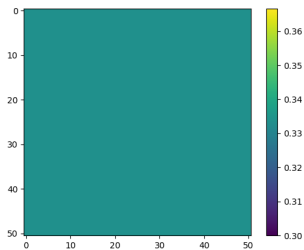


(a) Pressure

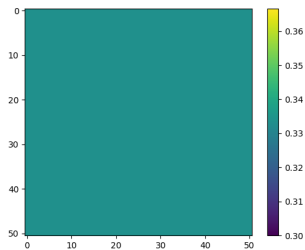


(b) velocity

the pulse frequency  $\omega_p$



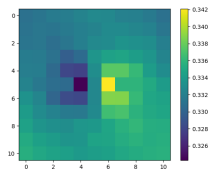
(a)  $\omega_p = 0.8$



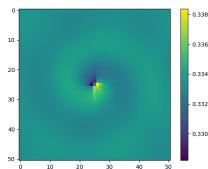
(b)  $\omega_p = 0.15$

$n_x, n_y$ 

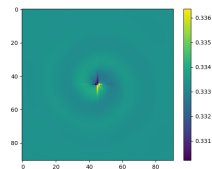
$n_x$  and  $n_y$  define the size of the grid.



(a)  $n_x = n_y = 11$



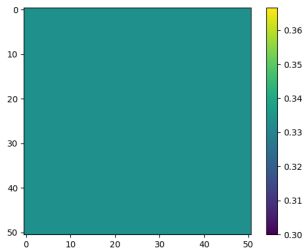
(b)  $n_x = n_y = 51$



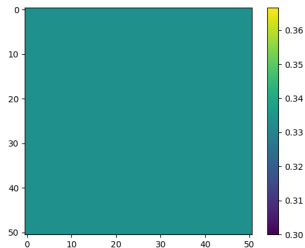
(c)  $n_x = n_y = 91$

# Reynolds number $Re$

$Re = \frac{UL}{\nu}$  is the ratio between the inertial forces and the viscous forces



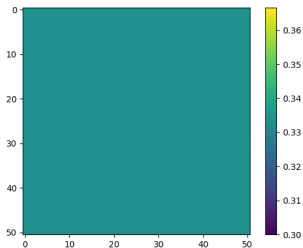
(a)  $Re = 5$



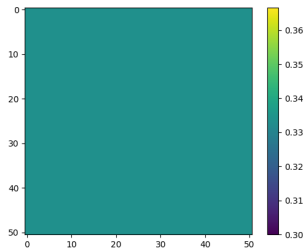
(b)  $Re = 50$

$u_{LB}$ 

$u_{LB}$  is the speed of propagation of the population.  
It is related to the viscosity of the fluid.



(a)  $u_{LB} = 0.1$



(b)  $u_{LB} = 0.005$

## Tornado center

When we introduce a new variable `center` that contains the coordinates of the tornado center on which we apply the perturbation.

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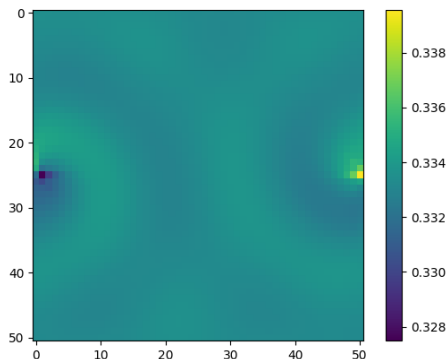
```
center = array([int(nx/2), int(ny/2)])

for t in range(maxIter):
    ...
    u[:,center[0],center[1]] = perturbation(t)
    ...
```

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# Outflow conditions

When moving the center closer to one of the border we have to take into account the the outflow conditions conditions will have an impact.





## Linear trajectory

One possibility is to move the center along a straight line.

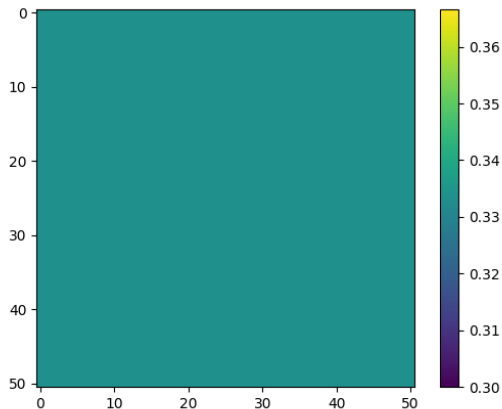
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```
center = array([int(nx/4),int(ny/4)])

for t in range(maxIter):
    ...
    u[:,center[0],center[1]] = perturbation(t)
    if time%80 == 0 :
        center += 1
    ...
```

---

# Linear trajectory



## Pressure determined trajectory

A more realistic option is to move the center towards the lowest pressure at each iteration.

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```
center = array([int(nx/2), int(ny/2)])

for t in range(maxIter):
    ...
    u[:,center[0],center[1]] = perturbation(t)
    c1, c2 = where(P==amin(P))
    center = array([c1[0], c2[0]])
    ...
```

---

# Pressure determined trajectory

