## 4 Friday, February 11, 2011

Last time, we gave a proof that almost every plane curve of degree d is smooth parameter space  $\mathbb{A}^N: N=\binom{d+2}{2}$ .

Another proof, continuing from the middle of the last one:

*Proof.* The dimension of S (as defined last time) is N+2-3=N-1 (the three from  $F_x=F_y=F_z=0$ ). So  $\pi(S)$  is at most N-1 dimensional, and so it's  $\overline{\pi(S)}$ . But dim Z=N, so  $\overline{\pi(S)}\neq Z$ .  $\square$ 

Some words about topology  $\mathbb{A}^N=\mathbb{C}^N$  is a complex variety of dimension N. As a real manifold, it's dimension is 2N. In the complex topology, you can have closed disks, e.g.  $|z|\leq 1$  (has positive measure). In the Zariski topology, closed subsets have no measure. e.g., in  $\mathbb{C}$ , the only closed subsets are finite point sets. In  $\mathbb{C}^2$ , V(ax+by+c) has no measure (it's a complex plane (dimension 1)).

**Proposition.** A smooth curve C of degree 3 in  $\mathbb{P}^2$  contains exactly 9 flex points.

*Proof.* Let f be a cubic defining C. The second partial derivatives of f are linear, so the determinant of the Hessian is a cubic polynomial which defines the Hessian curve H.

**Theorem** (Bézout's theorem). A curve of degree m in  $\mathbb{P}^2$  intersects a curve of degree n in exactly mn points.

By this theorem (not yet proved), the two cubics C and H intersect in 9 points. One can show that the multiplicities are one, and that C and H don't have a factor in common. Thus, we get exactly 9 flexes.

**Example.** 
$$y^2 = x^3 - x$$
 homogenization gives  $y^2z = x^3 - xz^2$  Then  $f = x^3 - xz^2 - y^2z$ . The Hessian matrix is

$$\begin{bmatrix} 6x & 0 & -2z \\ 0 & -2z & -2y \\ -2z & -2y & -2x \end{bmatrix}$$

Then  $H(f) = 8(3zx^2 - 3y^2x + z^3)$ .

The flexes: You can eliminate z from f = H(f) = 0. Then you get a homogeneous polynomial in x and y. You can solve for x/y, let y be 1, and then plug back in and solve for z. In this example, we get that one of the flex points is at (x:y:z) = (0:1:0).

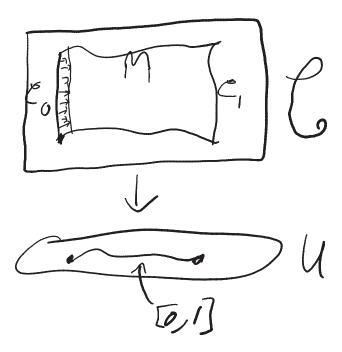
## Genus and Euler characteristic

Goal: Want to understand the topological structure of smooth plane curves.

It's useful to put them in a family. Notation as above. Let  $U = Z - \Sigma = Z - \pi(S)$ . This is the parameter space for smooth plane curves of degree d. The smooth plane curves are the fibers of the projection  $\mathcal{C} \subset \mathbb{P}^2 \times U$  to U.

**Proposition.** All the smooth curves of degree d are homeomorphic to each other (as real manifolds of dimension 2).

*Proof.* The problem set shows that U is path-connected (in the complex topology). Connect the two points in U (which correspond to curves in  $\mathbb{P}^2 \times U$ ) by a path.



We have a function  $f: M \to [0,1]$ . Define a diffeomorphism by taking the gradient of f, and look at the gradient flow. This tells us how to identify the fibers.

Corollary. Smooth plane curves are orientable, connected surfaces.

*Proof.* Orientability is simple. To orient a smooth surface, we must give a continuously varying orientation to the tangent planes. But tangent plane is a C-vector space (of dimension one,  $\sum f_i(p)v_i=U$ ). So multiplying any tangent vector by i defines a counterclockwise rotation by 90°, which orients the tangent plane.

We'll do connected next time.