1 Friday, February 4, 2011

Geometry of solutions to sets of polynomial equations.

e.g., $x^2 + y^2 + 1 = 0$ \longrightarrow Set of solutions (over \mathbb{C}) is really a sphere (with two points removed) e.g., $y^2 = x^3 - x = x(x-1)(x+1)$ Over \mathbb{C} , the set of solutions is a torus (with one point removed)

Lots of applications to number theory, representation theory, etc.

We'll work over the field \mathbb{C} .

Recall (background reading, §10-7, 10-8 in Artin's Algebra):

Theorem (Hilbert's Nullstellensatz (weak)). The maximal ideals of $\mathbb{C}[x_1,\ldots,x_n]$ are exactly those of the form (x_1-a_1,\ldots,x_n-a_n) corresponding to points $(a_1,\ldots,a_n)\in\mathbb{C}^n$.

This means we can consider \mathbb{C}^n as a purely algebraic object. It's called affine *n*-space, $\mathbb{A}^n_{\mathbb{C}}$ or \mathbb{A}^n for short.

We want to define a nice topology on this space. One choice is to take the Euclidean (complex) topology: define open balls by

$$B_r(x) = \{ y \in \mathbb{C}^n \mid |y - x| < r \}$$

and take these to be a basis.

But this is too many open sets (closed sets), e.g. $\{(x,y) \in \mathbb{C}^n \mid y=e^x\}$ is closed in the Euclidean topology. But we only care about polynomials, so we'll use a coarser topology (fewer open/closed sets).

We'll use the smallest topology such that polynomial functions are continuous. This is called the Zariski topology. Defined by: for a polynomial function $f \in \mathbb{C}[x_1, \ldots, x_n]$, define $D(f) = \{(a_1, \ldots, a_n) \in \mathbb{C}^n \mid f(a_1, \ldots, a_n) \neq 0\}$ and declare all D(f) to be open. (Note: D stands for distinguished.) As f varies over all polynomials, these D(f) are taken to be a basis.

We have, e.g,
$$D(0) = \emptyset$$
, $D(1) = \mathbb{C}^n$, $D(fg) = D(f) \cap D(g)$.

Alternatively, let's see what the closed sets are. For every ideal $I \subseteq \mathbb{C}[x_1, \ldots, x_n]$, the vanishing locus of I is $V(I) = \{(a_1, \ldots, a_n) \in \mathbb{A}^n \mid f(a_1, \ldots, a_n) = 0 \ \forall f \in I\}$. As I varies, these describe all the closed sets in the Zariski topology.

Note that $\mathbb{C}^n \setminus D(f) = V(f)$.

Note:

- 1. Because $\mathbb{C}[x_1,\ldots,x_n]$ is noetherian¹, any I can be written as (f_1,\ldots,f_k) for some f_1,\ldots,f_k . So $V(I)=V(\{f_1,\ldots,f_k\})$.
- 2. The maximal ideals (the smallest non-empty closed sets) exactly correspond to the points of \mathbb{C}^n . (weak Nullstellensatz)

e.g.

- 1) \mathbb{A}^1 : the closed sets are $\emptyset = V(1)$, $\mathbb{A}^1 = V(0)$, and sets of zeros of polynomials, that is, all finite sets of points. (also called the cofinite topology)
- 2) \mathbb{A}^2 : the closed sets are $\emptyset = V(1)$, $\mathbb{A}^1 = V(0)$, finite sets of points, but also union of V(f) with a finite point set for some polynomial $f \in \mathbb{C}[x,y]$.

¹Every ascending chain of ideals stabilizes: given $I_1 \subseteq I_2 \subseteq \cdots \subseteq R$, $\exists k$ such that $I_k = I_{k+1} = \cdots$. Equivalent to that every ideal is finitely generated

Why don't we include V(f,g) for $f,g \in \mathbb{C}[x,y]$? It's because the locus of points where both f and g vanish (assuming they have no common factor) is a finite set of points. Note also that $V(f_1) \cup V(f_2) = V(f_1f_2)$.

 $\mathbb{C}[x_1,\ldots,x_n]$ is called the affine coordinate ring of \mathbb{A}^n . (think of it as set of functions on the space \mathbb{A}^n)

1.1 Projective Space

Claim: \mathbb{A}^2 is somewhat defective.

Not all lines intersect. In particular, rotations of one line can cause it to not intersect another line.

To fix this, we add points at infinity to get \mathbb{P}^2 .

Nice way of doing this: Let

$$\mathbb{P}^2 = \left\{ (x, y, z) \in \mathbb{A}^3 \setminus \{0, 0, 0\} \right\} / (x, y, z) \sim (\lambda x, \lambda y, \lambda z) \qquad (\lambda \neq 0)$$

 \mathbb{A}^2 is contained in the set of points for which $z \neq 0$: If $z \neq 0$, then

$$(x,y,z) \stackrel{\mathbb{P}^2}{=} \left(\frac{x}{z}, \frac{y}{z}, 1\right)$$

We have $(x, y) \in \mathbb{A}^2 \longrightarrow (x, y, 1)$.

$$\mathbb{P}^2 = \mathbb{A}^2 \prod \mathbb{P}^1 = \mathbb{A}^2 \prod \mathbb{A}^1 \prod \operatorname{point}(=\mathbb{A}^0)$$

Elements of \mathbb{P}^2 are written as (x:y:z).

Define a topology on \mathbb{P}^2 . Most natural way is to take a quotient topology from the Zariski topology on $\mathbb{A}^3 \setminus \{0,0,0\} \subseteq \mathbb{A}^3$.

Take a polynomial function $f \in \mathbb{C}[x, y, z]$. We want to say $V(f) = \{(x : y : z) \in \mathbb{P}^2 \mid f(x, y, z) = 0\}$ is closed. But f gives different values on equivalent points.

We can write $f = f_0 + f_1 + \cdots + f_d$, f_i homogeneous of degree i. Then $f(\lambda x, \lambda y, \lambda z) = f_0(x, y, z) + \lambda f_1(x, y, z) + \cdots + \lambda^d f_d(x, y, z)$. We need to take homogeneous polynomials $(f = f_i$ for some i). Now f = 0 and $f \neq 0$ makes sense. Then $V(f_1, \ldots, f_k)$ describe the closed sets.

2 Monday, February 7, 2011

2.1 Affine varieties

Definition. An affine variety is the set of solutions to a system of polynomial equations

$$f_1(x) = f_2(x) = \dots = f_r(x) = 0$$

for $f_1, \ldots, f_r \in \mathbb{C}[x_1, \ldots, x_n]$. (x is shorthand for (x_1, x_2, \ldots, x_n) .)

Alternatively, it's V(I) for some $I = (f_1, \ldots, f_r) \subset \mathbb{C}[x_1, \ldots, x_n]$.

e.g., point: $(x_0, y_0) = (x - x_0, y - y_0)$

line: all (x, y) for which ax + by + c = 0

conic: locus of complex zeros of a quadratic equation in two variables q(x,y)=0

cubic: locus of complex zeros of a cubic polynomial

Classification of these depends on what coordinate changes one allows. If we allow arbitrary invertible linear operators and translations, any line can be converted to x = 0. Any conic can be converted to either $x^2 - y^2 - 1 = 0$ or $x^2 - y = 0$, by completing the square.

Zariski topology on an affine variety $(V(I_0)) = X \subset \mathbb{A}^n$ is just subspace topology induced from Zariski topology on \mathbb{A}^n (i.e., closed sets of X are just all the y = V(I) which are contained in X). Note: $V(0) = \mathbb{A}^n$ so $V(0) \cap X = X$. Check:

$$V(1) = \emptyset$$

$$\bigcap_{\alpha \in S} V(I_{\alpha}) = V\left(\bigcup_{\alpha \in S} I_{\alpha}\right)$$

$$= V\left(\sum_{\alpha \in S} I_{\alpha}\right)$$

(arbitrary intersection of closed sets is closed)

$$V(I) \cup V(J) = V(I \cap J)$$

(To see, consider a point $p \in V(I \cap J)$, $p \notin V(I)$, show that $p \in V(J)$)

2.2 Projective Plane \mathbb{P}^2

Recall

$$\mathbb{P}^2 = \{(x:y:z) \in \mathbb{A}^3 \setminus \{0,0,0\}\} / (x:y:z) \sim (\lambda x:\lambda y:\lambda:z) \qquad (\lambda \neq 0)$$

(lines through origin in \mathbb{A}^3 or \mathbb{C}^3)

A line in \mathbb{P}^2 is given by an equation ax + by + cz = 0 as long as $(a, b, c) \neq (0, 0, 0)$. Note that (a, b, c) and $(\lambda a, \lambda b, \lambda c)$ give the same line for $\lambda \neq 0$. So the set of lines forms another projective plane (dual projective plane $\tilde{\mathbb{P}}$). This equation ax + by + cz = 0 exhibits the duality between points and lines.

Lemma. A pair of distinct lines contains exactly one point in common, and a pair of distinct points lie on exactly one line.

Recall that we had $\mathbb{A}^2 \to \mathbb{P}^2$, $(x,y) \mapsto (x:y:1)$. Bijection between \mathbb{A}^2 and $U_z := \mathbb{P}^2 \setminus \{z=0\}$ (since $(x:y:z) \mapsto \left(\frac{x}{z}, \frac{y}{z}\right)$ if $z \neq 0$). Similarly we have U_x and U_x also in bijection with \mathbb{A}^2 . Then $U_x \cup U_y \cup U_z = \mathbb{P}^2$. This is a cover, and is called the standard affine open covering of \mathbb{P}^2 .

Note that $U_x \cap U_y \subseteq U_x$ (this is $\{(x:y:z) | x \neq 0, y \neq 0\} \subset \{(x:y:z) | x \neq 0\}$) is the set $\{y \neq 0\} = D(y)$. So its open in the Zariski topology. $U_x \cap U_y \subseteq U_y$ is also open: $V \subset \mathbb{P}^2$ is open iff all its intersections with the standard affines (standard affine open covers) are open (in the standard affines).

This is the same topology as the other version of the Zariski topology on \mathbb{P}^2 by taking V(f), f homogeneous polynomial in $\mathbb{C}[x,y,z]$. to be a closed set in \mathbb{P}^2 , and then take arbitrary intersections and finite unions. (same as quotient topology on $\mathbb{A}^3 \setminus \{0\}$)

Note: Since Zariski topology \subseteq classical/complex/Euclidean topology (all open sets in Zariski are open in classical)

This means we can define a classical topology as well on \mathbb{P}^2 . It makes \mathbb{P}^2 into a compact Hausdorff space.

Proof. Compact: Let $C_z \subseteq U_z$ be the set of (u, v, 1) such that $|u| \le 1$, $|v| \le 1$ and similarly C_x and C_y . It's clear that C_x , C_y , C_z are compact (also closed subspaces of \mathbb{P}^2 in the complex topology). Since $\mathbb{P}^2 = C_x \cup C_y \cup C_z$, \mathbb{P}^2 is compact.

2.3 Change of coordinates in \mathbb{P}^2

Four special points determine coordinates in \mathbb{P}^2 :

$$e_1 = (1:0:0)$$
 $e_2 = (0:1:0)$ $e_3 = (0:0:1)$ $\epsilon = (1:1:1)$

Think of these as column vectors.

Change of coordinates is described by a 3×3 invertible matrix P.

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = P \begin{bmatrix} x' \\ y' \\ z' \end{bmatrix}$$

(x is old, x' is new)

if the matrix is a scalar (diagonal) matrix, then it doesn't affect any coordinate change. Similarly, the coordinate changes corresponding to P and sP are the same.

If A = (a, b, c) and ℓ is the line ax + by + cz = 0, AX = 0, then A(PX') = 0 or AP(X') = 0, so the equation for ℓ in the new coordinates is AP.

Proposition. Let p_1 , p_2 , q_3 , q be four points in \mathbb{P}^2 , now three collinear. Then $\exists !$ change of coordinates PX' = X such that $X = p_1, p_2, p_3, q$ because $X' = e_1, e_2, e_3, \epsilon$.

Proof. p_1, p_2, p_3 are linearly independent vectors in \mathbb{C}^3 . So \exists transformation P such that $Pp_i = e_i$. Now q is non-collinear with p_1, p_2, p_3 ; all of its coordinates are non-zero. Then scale each coordinate to take q to ϵ (modifies P). This doesn't affect e_1, e_2, e_3 .

Conics we had $x^2 - y^2 - 1 = 0$ and $x^2 - y = 0$ in \mathbb{A}^2 . In \mathbb{P}^2 , these become $x^2 - y^2 - z^2 = 0$ and $x^2 - yz = 0$. We can transform the first into the second by doing $x^2 - y^2 = z^2$, $(x - y)(x + y) = z^2$, coordinate change to $x'y' = z'^2$.

3 Wednesday, February 9, 2011

3.1 Curves in \mathbb{P}^2

Curves in \mathbb{P}^2 are defined by homogeneous irreducible polynomials $f \colon C = V(f)$.

e.g., the line containing a pair of points $(p,q) \in \mathbb{P}^2$ is the set of points up + vq for $(u,v) \neq (0,0)$. It's equation Ax = 0 is obtained by solving Ap = Aq = 0. (Think of A = (a,b,c), $P = (x_1,y_1,z_1)$,

$$q = (x_2, y_2, z_2)$$
. Then $ax_1 + by_1 + cz_1 = 0$, $ax_2 + by_2 + cz_2 = 0$. Then $\begin{bmatrix} x_1 & y_1 & z_1 \\ x_2 & y_2 & z_2 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$. i.e.,

[a, b, c] is the kernel of the 2×3 matrix, which has rank 2.)

The restriction of a homogeneous polynomial f(x, y, z) to a line $\ell = \{up + vq\}$ is obtained by substitution f(up + vq). This is a homogeneous polynomial in u, v of degree $= \deg(f)$. Over \mathbb{C} , any such polynomial can be factored into linear factors $(up_i + vq_i)$. These are the points of ℓ (not necessarily distinct) that lie on V(f). Thus, a plane polynomial curve of degree d meets a line in d points, counted with multiplicity.

Let f be a homogeneous polynomial of degree d in x_1, x_2, x_2 , and let C = V(f). Let f_i denote $\frac{\partial f}{\partial x_i}$ and let $f_{ij} = \frac{\partial^2 f}{\partial x_i \partial x_j}$. Then the Hessian Matrix is the 3×3 symmetric matrix

$$H(f) = \left(\frac{\partial^2 f}{\partial x_i \partial x_j}\right)_{ij}.$$

Proposition (Euler's Formula). Let f, $d = \deg(f)$, f_i be as above. Then $\sum_{i=1}^3 f_i x_i = f \deg(f)$.

Proof. Check it for monomials, since it's additive. (CHECK NOT INCLUDED) □

This works for polynomials in n variables.

Now consider the Taylor expansion of the restriction of f to $\ell = \{up + vq\}$. Setting u = 1 (v = 0 is p, so looking near the point p):

$$f(p+vq) = f(p) + \left(\sum f_i(p)q_i\right)v + \frac{1}{2}\left(\sum f_{ij}q_iq_j\right)v^2 + \mathcal{O}(v^3)$$

with $q = (q_1, q_2, ...)$.

Proposition. 1. If p is a point of C, then f(p) = 0.

- 2. Suppose $p \in C$, and $f_i(p)$ are not all 0. Then the equation of the tangent line T to C a t p is $\sum f_i(p)q_i = 0$.
- 3. Let h be the Hessian of f at p. Then $\det h = 0$ iff p is a flex point C (i.e., a restriction of f to the tangent line at p has a zero of order ≥ 3 at p

Proof. 1. By definition.

- 2. Tangent line: if the restriction of f to T has at least a second order 0 (by definition). So looking at the coefficient of v, this is clear.
- 3. Exercise: Check that the restriction of the quadratic term to the tangent line is 0 iff det h = 0.

Definition. If all the f_i vanish at p, then p is called a *singular* point of C = V(f). Otherwise, say that C is *non-singular* at p. Say that C is a *non-singular curve* if it has no singular points.

3.1.1 Nonsingular curves

e.g. 1, an irreducible conic is always non-singular

Proof. Convert to $x^2 - yz = 0$. $f_x = 2x$, $f_y = -z$, $f_z = -y$. Since $(x, y, z) \in \mathbb{P}^2$, not all these can be zero, so it's nonsinular

- e.g. 2, An irreducible plane cubic can have at most one singular point (exercise)
- e.g. 3, The curve $x^d + y^d + z^d = 0$ is non-singular (smooth) for $d \ge 1$. (Fermat polynomial of degree d).

The partial derivatives are dx^{d-1} , dy^{d-1} , dz^{d-1} , not all zero (in \mathbb{P}^2)

e.g. 4, The curve $x^3 + y^2 - xyz = 0$ is singular at the point (0:0:1).

Proposition. For most values of the coefficients of a polynomial of degree d, the curve $C = V(f) \subseteq \mathbb{P}^2$ is smooth.

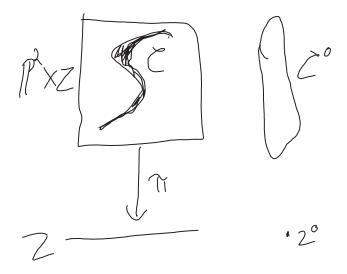
Proof. See two proofs, each of which depends on some theorem which will be proved later.

Setup: Order the monomials of degree d in x, y, z arbitrarily m_1 , m_2 , ..., m_N . (Note: $N = \binom{d+k-1}{k-1}$ for k variables.)

An arbitrary polynomial of degree d is a linear combination of the monomials m_{ν} with some coefficients z_{ν} . Think of z_{ν} as variables and let

$$F = \sum_{\nu=1}^{N} z_{\nu} m_{\nu} \in \mathbb{C}[x, y, z, \{z_{\nu}\}].$$

Then F=0 defines a subvariety \mathcal{C} of the product $\mathbb{P}^2 \times Z$, where Z is \mathbb{A}^N with coordinates z_{ν} .



The fiber $C^0 = \pi^{-1}(z^0)$ of C over a point $z^0 \in Z$ is the curve whose equation is the polynomial obtained

by substituting z_{ν}^{0} for z_{ν} . The 3 partial derivatives F_{x} , F_{y} , F_{z} are polynomials in x, y, z, $\{z_{\nu}\}$ linear in z_{ν} and homogeneous of degree d-1 in x, y, z. They define some subvariety of $\mathbb{P}^{2} \times Z$. Let S be the variety $\{F_{1} = F_{2} = F_{3} = 0\}$. Note that $S \subset \mathcal{C}$ (by Euler).

The fiber \mathcal{C}^0 over a point z^0 of Z is smooth if and only if \mathcal{C}^0 doesn't meet S.

We can construct $\Sigma = \pi(S)$ the image of S via a polynomial $\mathbb{P}^2 \times Z \to Z$. Later we'll prove that the image of the projection of any Zariski closed subvariety of $\mathbb{P}^2 \times Z$ to Z is also Zariski closed.

So the set Σ is closed in the affine space Z. But Σ is not all of Z (because the Fermat curve is smooth). So $\Sigma \subset Z$ is a proper closed subvariety. So the set of z^0 for which \mathcal{C}^0 is smooth is a Zariski open subset of \mathbb{A}^N .

4 Friday, February 11, 2011

Last time, we gave a proof that almost every plane curve of degree d is smooth parameter space $\mathbb{A}^N: N=\binom{d+2}{2}$.

Another proof, continuing from the middle of the last one:

Proof. The dimension of S (as defined last time) is N+2-3=N-1 (the three from $F_x=F_y=F_z=0$). So $\pi(S)$ is at most N-1 dimensional, and so it's $\overline{\pi(S)}$. But dim Z=N, so $\overline{\pi(S)}\neq Z$. \square

Some words about topology $\mathbb{A}^N = \mathbb{C}^N$ is a complex variety of dimension N. As a real manifold, it's dimension is 2N. In the complex topology, you can have closed disks, e.g. $|z| \leq 1$ (has positive measure). In the Zariski topology, closed subsets have no measure. e.g., in \mathbb{C} , the only closed subsets are finite point sets. In \mathbb{C}^2 , V(ax+by+c) has no measure (it's a complex plane (dimension 1)).

Proposition. A smooth curve C of degree 3 in \mathbb{P}^2 contains exactly 9 flex points.

Proof. Let f be a cubic defining C. The second partial derivatives of f are linear, so the determinant of the Hessian is a cubic polynomial which defines the Hessian curve H.

Theorem (Bézout's theorem). A curve of degree m in \mathbb{P}^2 intersects a curve of degree n in exactly mn points.

By this theorem (not yet proved), the two cubics C and H intersect in 9 points. One can show that the multiplicities are one, and that C and H don't have a factor in common. Thus, we get exactly 9 flexes.

Example.
$$y^2 = x^3 - x$$
 homogenization gives $y^2z = x^3 - xz^2$ Then $f = x^3 - xz^2 - y^2z$. The Hessian matrix is

$$\begin{bmatrix} 6x & 0 & -2z \\ 0 & -2z & -2y \\ -2z & -2y & -2x \end{bmatrix}$$

Then $H(f) = 8(3zx^2 - 3y^2x + z^3)$.

The flexes: You can eliminate z from f = H(f) = 0. Then you get a homogeneous polynomial in x and y. You can solve for x/y, let y be 1, and then plug back in and solve for z. In this example, we get that one of the flex points is at (x:y:z) = (0:1:0).

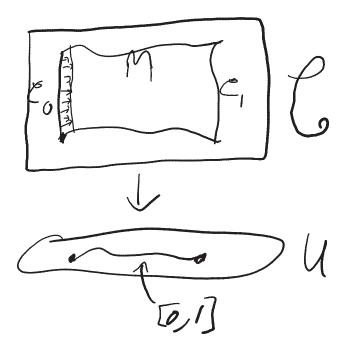
Genus and Euler characteristic

Goal: Want to understand the topological structure of smooth plane curves.

It's useful to put them in a family. Notation as above. Let $U = Z - \Sigma = Z - \pi(S)$. This is the parameter space for smooth plane curves of degree d. The smooth plane curves are the fibers of the projection $\mathcal{C} \subset \mathbb{P}^2 \times U$ to U.

Proposition. All the smooth curves of degree d are homeomorphic to each other (as real manifolds of dimension 2).

Proof. The problem set shows that U is path-connected (in the complex topology). Connect the two points in U (which correspond to curves in $\mathbb{P}^2 \times U$) by a path.



We have a function $f: M \to [0,1]$. Define a diffeomorphism by taking the gradient of f, and look at the gradient flow. This tells us how to identify the fibers.

Corollary. Smooth plane curves are orientable, connected surfaces.

Proof. Orientability is simple. To orient a smooth surface, we must give a continuously varying orientation to the tangent planes. But tangent plane is a \mathbb{C} -vector space (of dimension one, $\sum f_i(p)v_i=U$). So multiplying any tangent vector by i defines a counterclockwise rotation by 90°, which orients the tangent plane.

We'll do connected next time.

5 Monday, February 14, 2011

5.1 Plane curves

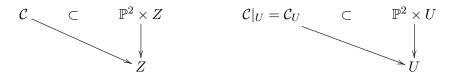
monomials m_1, \ldots, m_N , coefficients z_1, \ldots, z_N

Z= the space of all homogeneous polynomials of degree d in $x,\,y,$ and z= affine space with coordinates z_{ν}

(We have $f(x, y, z) = z_1 x^d + z_2 x^{d-1} + \cdots$)

U = open subset in Z corresponding to smooth plane curves

 $\mathcal{C} \subset \mathbb{P}^2 \times Z$



Proposition. Smooth plane curves are orientable and connected surfaces, and compact.

Proof. Oreintability was done last time.

To check connectedness, we just need to check one smooth curve of degree d is connected. $C: \{x^d + y^d - z^d = 0\}.$

Look at the line y = z. On U_2 , taking z = 1 we have $x^d + y^d = 1$. Since y = z, y = 1, and then $x^d = 0$. Since this is a root of order d, C meets this line in only one point. This means that it's connected. (WHY?)

Given a connected, orientable, compact surface, it's topologically characterized by g = the genus = the # of holes.

Definition. The Euler characteristic of C is 2-2q.

The Euler characteristic can be computed used an arbitrary triangulation, and then E=# vertices -# edges +# faces.

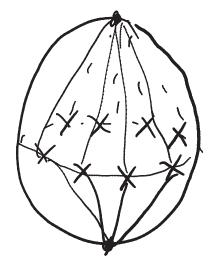
A sphere is, topologically, a tetrahedron, we have that the Euler characteristic is 4-6+4=2. We can do a similar thing for a torus.

What is the Euler characteristic and genus of a smooth plane curve of degree d? Let's represent a smooth plane curve as a branched cover of \mathbb{P}^1 .

Method I Start with the Fermat curve, and do an explicit calculation. $C: \{x^d + y^d - z^d = 0\}$ Taking z = 1, $U_2 \simeq \mathbb{A}^2 \simeq \mathbb{C}^2$. Then we have $x^d + y^d = 1$. Drop y by projection. Fix a value x_0 for x. Then the line $y = x_0$ intersects the curve in $\leq d$ points. Typically, we get d values for y.

Case I $x_0^d \neq 1$. Solve $y^d = 1 - x_0^d$. There are d solution s (if y is a solution, then so is $yr^{2\pi ij/d}$ for $0 \leq j \leq d$)

Case II $x_0^d = 1$. Solve $y^d = 0$. The only solution is y = 0. Now we look at x_0 . Triangulate \mathbb{P}^1 , which is a sphere, as follows. There are d values for x_0 , $x_i^d = 1$, $x_i = e^{2\pi i j/d}$.



These points distribute themselves along the equator of \mathbb{P}^1 . Adding points at the poles, there are 2+d vertices, d+d+d=3d edges, and 2d faces, which gives us 2. This is what happens "downstairs" (in the projected curve onto $X=\mathbb{P}^1$).

Upstairs, there is an induced triangulation:

• vertices: d + d + d = 3d

• edges: $3d^2$

• faces: $2d^2$

Then the Euler characteristic is $E = 3d - 3d^2 + 2d^2 = 3d - d^2 = d(3 - d)$. Then $g = \frac{1}{2}(d-1)(d-2)$.

Method II Let C be a smooth curve of degree d. Assume the coefficient of z^d is not zero. Divide by that coefficient, giving $f(x,y,z) = z^d - a_1(x,y)z^{d-1} + \cdots \pm a_d(x,y)$. Homogenous polynomial $\implies a_i(x,y)$ is degree i in x and y. Then drop z by projection onto $\mathbb{P}^1(x,y)$.

Fix (x_0, y_0) . View $z^d - a_1(x_0, y_0)z^{d-1} + \cdots \pm a_d(x_0, y_0) = 0$ as a polynomial of degree d in z. Typically this has d roots, but for some values of (x, y), there are d - 1 roots.

There is a polynomial Δ , discriminant, degree d(d-1) in x and y. $\Delta=0$ iff there are less than d roots. (The discriminant for a quadratic is b^2-4ac . It tells you whether or not the polynomial has double roots.) (Note, if the discriminant has only simple roots, then the claim above (that there are only d or d-1 roots at any point) is intuitively/geometrically true.)

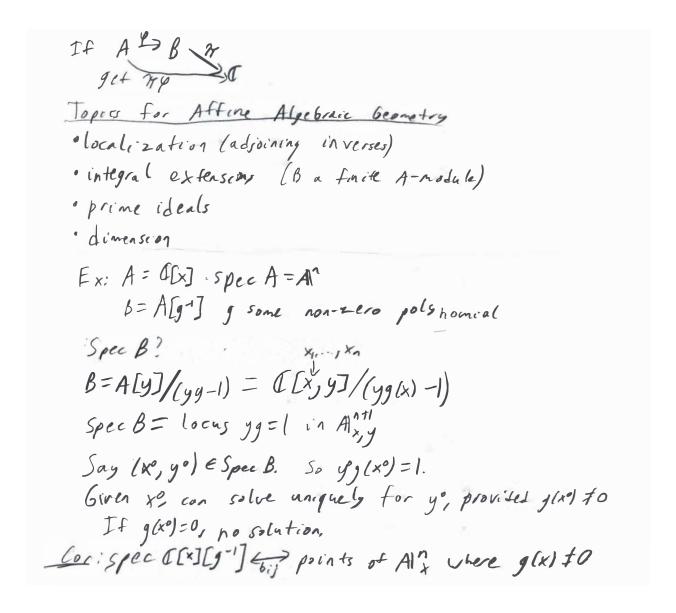
Triangulate $X = \mathbb{P}^1$ by putting vertices at these d(d-1) points. For \mathbb{P}^1 , the Euler characteristic is 2. Pulling the triangulation up, the Euler characteristic is approximately 2d (everything gets multiplied by d). However, we placed the vertices at the d(d-2) points where there are d-1 roots. Then the Euler characteristic is $2d-d(d-1)=3d-d^2$.

6 Wednesday, February 16, 2011

7 Friday, February 18, 2011

8 Tuesday, February 22, 2011

I playing with carres in IP2 II. Affine algebraic geometry (structure of spec A) II. Projective geometry IV cohomology thm: Null stellersatz: Maximal ideals of I[x1, ..., xn] = points in A" (=0") (a,, ..., an) EAM nex iden Ma = Kernel of ham. ([x] -) (Ma = (x, -a, (1/Kn-an) A= ([x]/I quotient of ([x], say I=(f,,..,fn), fie ([x] Cori Then Spec A = {mandenls} (VI) = locas of zeros Why? B/C tum Correspondence Thm: idents of A deads of (x) that contain I maxiteals => maxideals containing I If A isonfinitely generated C-algebra Crity that contains D, then A & C[x]/I Spec A W(I) variety 4 An



9 Wednesday, February 23, 2011

Hilbert Basis Theorem

A ring A is Noetherian if the ideals are finitely generated.

Theorem (Hilbert Basis Theorem). If R is Noetherian, then R[x] is Noetherian

Corollary. $\mathbb{C}[x_1,\ldots,x_n]$ is Noetherian

Any finite-type (finitely generated as an algebra (everything is a polynomial in finitely many things)) \mathbb{C} -algebra is Noetherian. $(A \cong \mathbb{C}[x]/I)$

Equivalent conditions on A:

- 1. A is noetherian (ideals are finitely generated)
- 2. Every infinite increasing family $I_1 \subset I_2 \subset \cdots$ of ideals becomes constant eventually

 $(I_1 < I_2 < \cdots \text{ chain is finite})$

3. Every non-empty set S of ideals contains maximal elements $(\exists I \in S \text{ such that } I \not\subset J \text{ for any } J \in S, J \neq I)$

Corollary. If A is noetherian, I is an ideal of A, and I < A, then I is contained in a maximal ideal. (The maximal ideal is a maximum element in the set of ideals < A.)

Corollary. If A contains no maximal ideal, then A is the zero ring.

Spec
$$A \neq \emptyset \iff A = \{0\}$$

Adjoining inverses to $A = \mathbb{C}[x]$ $(x = x_1, \dots, x_n)$, $B = A[g^{-1}] = \mathbb{C}[x, y]/(yg - 1)$. Then Spec $A = \mathbb{A}^n$, and Spec $B \approx \mathbb{A}^n - V(g)$.

Theorem (Strong Nullstellensatz). Let I be an ideal of $\mathbb{C}[x]$, $g \in \mathbb{C}[x]$. Suppose g vanishes identically on V(I). Then $g^N \in I$ for some $N \gg 0$.

Proof. Idea: Find a ring with no maximal ideal. It is therefore the zero ring. Play with this fact. Say $I = (f_1, \ldots, f_r)$, $f_i \in \mathbb{C}[x]$ $(x = x_1, \ldots, x_n)$. Let's inspect the locus of zeros in $\mathbb{A}^{n+1}_{x,y}$, $V = V(f_1, \ldots, f_r; yg - 1)$.

If $(x^0, y^0) \in V$, then $x^0 \in V(I) = V(f_1, \dots, f_r) \subset \mathbb{A}_x^n$. Therefore $g(x^0) = 0$ (by hypothesis). Then there is no y^0 such that $y^0g(x_0) = 1$.

Therefore, $V = \emptyset$.

We also have that $V = \operatorname{Spec} \mathbb{C}[x,y]/(f_1,\ldots,f_r,yg-1)$. Then $\mathbb{C}[x,y]/(f,yg-1) = \{0\}$. Therefore, (g,yg-1) is the unit ideal in $\mathbb{C}[x,y]$. This means that we can write 1 as a polynomial combination of f and yg-1. Say

$$1 = p_1(x, y)f_1(x) + \dots + f_r(x, y)f_r(x) + q(x, y)(yg - 1).$$

Now work in the ring $B=\mathbb{C}[x][g^{-1}]=\mathbb{C}[x,y]/(yg-1)$. In B yg-1=0 and $y=g^{-1}$. Then

$$1 = p_1(x, g^{-1})f_1(x) + \dots + p_r(x, g^{-1})f_r(x) + 0.$$

Multiply by g^N to clear denominators. Then, since g = g(x),

$$g^N = \tilde{p}_1(x)f_1(x) + \dots + \tilde{p}_r(x)f_r(x).$$

Therefore, $g^N \in I$.

NOTE: If $I \subset J$ are ideals in $\mathbb{C}[x]$, then $V(I) \supseteq V(J)$. But $V(x_1) = V(x_1^2)$. Let I be an ideal. Then rad I = radical of $I = \{g \mid g^n \in I, \text{ some } n > 0\}$.

Theorem.

$$V(I) \supset V(J) \iff I \subset \operatorname{rad} J$$

$$V(I) = V(J) \iff \operatorname{rad} I = \operatorname{rad} J$$

Proof. Say $V(I) \supset V(J)$. Take $g \in I$. Then g = 0 on V(J). Then $g^N \in J$ for some N by the strong Nullstellensatz, and so $g \in \operatorname{rad} J$.

The other direction is left as an exercise.

Definition. Let X be a topological space. Then a closed subset C is *irreducible* if you can't write $C = C_1 \cup C_2$ where C_i closed, $C_i < C$.

A a finite type algebra is noetherian, satisfies the ascending chain condition on ideals. Then Spec A has the descending chain condition on ideals.

Prime ideals: Given a polynomial ring R: (equivalent conditions)

- R/P is a domain
- $P < R, ab \in P \implies a \in P \text{ or } b \in P$
- A, B ideals of R, $AB \subset P \implies A \subset P$ or $B \subset P$. (Recall that the product ideal $AB = \{\text{finite sums } \sum a_i b_i \mid a_i \in A, b_i \in B\}$.)

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Proof. (2) \Longrightarrow (3)
Say AB \subset P, but A \subset P.
\exists a \in A, a \notin P.
AB \subset P \Longrightarrow B \subset P
\forall b \in B, ab \in P, \therefore b \in P, so B \subset P.
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10 Friday, February 25, 2011

Recall:

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If I is an ideal of A, then \operatorname{rad} I = \{x \in A \mid x^n \in I, \text{ some } n > 0\}

V(I) = V(\operatorname{rad} I)

V(I) \supset V(J) \iff I \subset \operatorname{rad} J

irreducible closed set C: C \neq C_1 \cup C_2, C_i < C.
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Proposition. I an ideal, V(I) irreducible if f rad I is prime ideal

Theorem. Let A be a finite-type noetherian ring, I an ideal. Then rad I is the intersection of a finite number of prime ideals rad $I = P_1 \cap \cdots \cap P_k$. Then we can organize $P_i \not\subset P_j$ for $i \neq j$. Then we have that $V(I) = V(P_1) \cup \cdots \cup V(P_k)$; V(I) is a finite union of irreducible closed sets.

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Spec A = \{maximal ideals\}
V(I) = \{\mathfrak{M} \text{ that contains } I\}
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I an ideal. Then $\bar{A} = A/I$.

$$A \to \overline{A}$$

$$I \leadsto (\overline{0})$$

$$rad I \quad rad(\overline{0})$$

$$= nitradical$$

$$= \{x \mid x^n = 0\}$$

The following are equivalent:

• rad
$$I = P_1 \cap \cdots \cap P_k$$

•
$$\operatorname{rad}(\bar{0}) = \bar{P}_1 \cap \cdots \cap \bar{P}_k$$

(in \bar{A}) also prime ideals

Proof. Suppose the theorem is false for some A and some I. Let $S = \{\text{ideals } J \text{ of } A \text{ such that rad } J \text{ is not a finite intersection of prime ideals} \}$. By hypothesis, $S \neq \emptyset$. Then there exists a maximal element I in S. Then rad I not a finite intersection of prime ideals, but every larger ideal is a finite intersection of prime ideals.

Note:

- $I = \operatorname{rad} I$
- I is not a prime ideal

Then there exist ideals $K, L, K \not\subset I, L \not\subset I$, but $KL \subset I$. Replace K by K+I, L by L+I. Then we have

$$(K+I)(L+I) \subset KL + KI + IL + II \subset I.$$

(so it's ok to do these replacements).

Now K, L > I. Replace K and L with their radicals.

$$(\operatorname{rad} K)(\operatorname{rad} L) \subset \operatorname{rad}(KL) \subset \operatorname{rad} I = I$$

(so it's ok to these replacements.)

We have

$$\operatorname{rad} K = P_1 \cap \cdots \cap P_r$$
$$\operatorname{rad} L = Q_1 \cap \cdots \cap Q_s$$

. . .

We made a mistake somewhere. (Supposed to replace I by a zero ideal?) The version on the web is probably correct. Let's skip this for now.

Finite Group Action

Let B be a finite type domain, G the finite group of automorphisms of B. Let $A = B^G$.

Theorem. • A is a finite type domain

- G operates on Spec B = Y
- Y maps to Spec A = X. $Y \to X$ is surjective, and the fibers are the G-orbits in Y

Example. $B = \mathbb{C}[x,y], \ \sigma(x) = -x, \ \sigma(y) = -y.$ Then $\langle \sigma \rangle$ is a group of order 2.

The invariant functions are $u = x^2$, $v = y^2$, and w = xy. It's not hard to see that every invariant function can be written as some combination of these.

$$A = B^G = \mathbb{C}[u, v, w]/(w^2 - uv)$$

Then Spec $A = X = \text{locus of } w^2 = uv \text{ in } \mathbb{A}^3_{u,v,w}$. This is a double cone in 3-space.

Proof. A finite type domain:

Take $\beta \in B$, orbit $\{b_1 = \beta, \dots, b_r\}$. Let $p(x) = (x - b_1) \cdots (x - b_r) = x^r - s_1(b)x^{r-1} + \cdots \pm s_r(b)$. We have that β is a root of p(x). Since the $s_i(b)$ are symmetric functions, $s_i(b) \in B^G = A$.

Since B is a finite type domain, say B is generated as an algebra by β_1, \ldots, β_m . Then each β_i is a root of the polynomial, coefficients in A.

Let $A_0 = \mathbb{C}$ -algebra generated by these roots. Then A_0 is a finite-type domain contained in B. Every element in B is a polynomial in β_1, \ldots, β_m .

If a polynomial with β_i as a root has degree d_i , then we only need monomials in β_i with degree $\leq d_i$. There are only a finite number of monomials in β_i of degree $\leq d_i$. Then B is spanned as an A_0 -module by these monomials. Thus, B is a finite A_0 -module.

 $A_0 \subset A \subset B$. Since A_0 is a finite-type domain, A_0 is noetherian. B is a finite-type A_0 -module. A is a submodule. Therefore, A is a finite-type A_0 module. Thus, A is a finite-type algebra. \square

11 Monday, February 28, 2011

B finite type, G operator(?)

$$A = B^G$$

Showed A finite type

$$Y = \operatorname{Spec} B$$

$$X = \operatorname{Spec} A$$

 $X \leftrightarrow \{G \text{ orbits in } Y\}$

$$G \times B \to B$$

$$\sigma, b \leadsto \sigma(b)$$

(left)
$$\sigma \tau(b)$$
: first τ , then σ

Then G operates on the right on Y.

$$q \in Y$$
, σ sends $q \to q^{\sigma}$

$$q^{\sigma\tau}$$
: first σ , then τ

View

$$y \leftrightarrow \{\text{homomorphisms } B \to \mathbb{C}\}$$

 $q \leftrightarrow \pi_q : B \to \mathbb{C}$
 $\leftrightarrow \{\text{max ideals of } B\}$
 $q \leftrightarrow m_q$

Operation on Y:

$$B \xrightarrow{\sigma} B$$

$$\downarrow^{\pi}$$

$$\mathbb{C}$$

$$\pi_q \circ \sigma(b) = \pi_q(\sigma b)$$

Define q^{σ} = that point such that $\pi_{q^{\sigma}} = \pi_q \circ \sigma$.

Operation on max ideals:

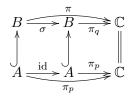
$$\mathfrak{M}_{q^{\sigma}} = \sigma^{-1}\mathfrak{M}_q$$

 $Y \to X$?

For any $p \in X$,



 $Y \to X$ sends $q \leadsto r$



Therefore, G-orbits in Y map to points of X.

We want to show that different orbits $\{q_1, \ldots, q_r\} \neq \{q'_1, \ldots, q'_s\}$ in Y map to different points p, p' in X.

Proof. Plan: Find an element $a \in A$ such that a = 0 on orbit $\{q_i\}$, $\pi_q(a) = 0$, $a \neq 0$ on orbit $\{q'_j\}$. Then $\pi_{q'_j}(a) \neq 0$. This would give us that $a \in \mathfrak{M}_{q_i}$ (same as $\in \mathfrak{M}_p$) and $a \notin \mathfrak{M}_{q'_j}$ (same as $\notin \mathfrak{M}_{p'}$).

In B, choose $b \in \mathfrak{M}_{q_1}$ (then) such that $b \notin \mathfrak{M}_{q'_j}$ for all $j = 1, \ldots, s$. (Note: $b(q) := \pi_q(b)$.)

Diversion: Suppose
$$B = \mathbb{C}[x_1, \dots, x_n]/(f_1, \dots, f_k)$$
. b represented by the polynomial $p(x_1, \dots, x_n)$. Spec $B \approx V(f_1, \dots, f_k)$ in \mathbb{C}^n . Spec $B = (\max \text{ ideals}) = (\text{homomorphisms } B \to \mathbb{C}) = (V(I) \text{ if } B = \mathbb{C}[x]/I)$

We can do this. (Think about choosing (hyper-?)planes that do not pass through finite sets of points.)

Let $a = \prod_{\sigma \in G} \sigma(b)$. a is invariant. a = 0 on q_1 because b divides a in B (since some $\sigma \in G$ is the

identity). Therefore a = 0 on the orbit (q_1) . $a \neq 0$ on q'_1 .

 $\sigma(b)$ evaluated at q_1' is $\pi_{q_1'}(\sigma b) = \pi_{q_1'}(b) = b$ evaluated at q_1'' .

Therefore, $a \neq 0$ on the orbit.

11.1 Localization

Note: we always assume that the rings are domains and assume (whenever possible) that they're finite type algebras.

Definition. A multiplicative system S in a domain A is a subset of A satisfying

- $1 \in S$
- $0 \notin S$
- if $s, t \in S$, then $st \in S$

Definition. The elements of S serve as denominators in the ring of fractions

$$A_S := \left\{ \frac{a}{s} \,\middle|\, s \in S, a \in A \right\} \middle/ \sim$$

where $\frac{a}{s} \sim \frac{b}{t}$ if at = bs

$$A \hookrightarrow A_S$$

 $a \leadsto a/1$

Example. $S = \{1, s, s^2, \ldots\}, s \neq 0.$ $A_S = A[s^{-1}] = A[y]/(sy - 1)$

Example. $S = A - \{0\}, A_S = \text{fraction field}$

Example. P a prime ideal of A, $S = A - P = \{s \mid s \notin P\}$. Then $s \notin P$, $t \notin P \implies st \notin P$. Then A_S is the *localization of* A at P. This is (perversely) denoted A_P .

If $A \subset B$ a subring, then we can relate ideals of A and B: Extended ideal: I^e

I ideal of A

IB = ideal of B generated by $\{I\}$

The elements are

$$\sum_{\text{finite}} x_i b_i \qquad , \ x_i \in I, \ b_i \in B$$

Contracted ideal: J^c : For J an ideal of B, $(J \cap A) = ideal$ of A

$$(I^e)^c \supset I$$

$$(J^c)^e \subset J$$

For $A \subset B = A_S$:

$$I^e = IA_s = \{x/s \mid x \in I, s \in S\} / \sim$$

 $J^c = J \cap A$. If $y/s \in J$, then $y \in J \cap A = J^c$. Therefore, $y/s \in (J^c)^e$. Thus, $J \subset (J^c)^e$, so $J = (J^c)^e$.

Corollary. If A noetherian, then A_S noetherian

Proof. Take an increasing sequence $J_1 \subset J_2 \subset \cdots$ of ideals in A_S . Let $I_{\nu} = J_{\nu} \cap A$. Then $I_1 \subset I_2 \subset \cdots$. Since A is noetherian, this is eventually constant. Therefore $I_{\nu}^e = (J_{\nu}^c)^e$ eventually constant. Thus A_S is noetherian.

12 Wednesday, March 2, 2011

S a multiplicative system

 $1 \in S$

 $0 \in S$

 $S_1, S_2 \in S \implies S_1 S_2 \in S$.

Ring of fractions A_S localized ring

 $A \hookrightarrow A_S$

$$(J^c)^e = J$$

$$(A \cap J)A_S$$

Localizing prime ideal (s...?)

I ideal of $A, I \cap S \neq \emptyset \implies I^e = \text{unit ideal of } A_S$

Proposition. P prime ideal of A. $P \cap S \neq \emptyset$. Then

- $(P^e)^c = P$
- P^e (= P_S) is a prime ideal of A_S

$$P^e = PA_S = \{s^{-1}x \mid x \in P\}$$

Proof. For any ideal P, $(P^e)^c \supset P$.

We want to show \subset . Let $z \in (P^e)^c$. Then $z = s^{-1}x$ for some $x \in P$, and $z \in A$. Then $sz = ss^{-1}x = x \in P$. Since P is prime, and $s \notin P$, $z \in P$, and so $(P^e)^c \subset P$.

Now we show that P^e is prime:

We have that $z_1z_2 \in P^e$ for $z_i \in A_S$. Then $z_1 = s_1^{-1}a_1$, $z_2 = s_2^{-1}a_2$. Then $z_1z_2 = (s_1s_2)^{-1}(a_1a_2) \in P^e$. Therefore $(s_1s_2)(z_1z_2) = a_1a_2 \in P^e$. Since $a_1a_2 \in A$, this is also in $(P^e)^c = P$. Since $a_1a_2 \in P$ and P prime, either $a_1 \in P$ or $a_2 \in P$, $s_1^{-1}a_1 \in P^e$ or $s_2^{-1}a_2 \in P^e$.

$$P\operatorname{Spec} A_S \longleftrightarrow \operatorname{subset} \text{ of } P\operatorname{Spec} A = \{P \mid P \cap S \neq \emptyset\}$$

Back to the case where P is a prime ideal of A and $S = A - P = \{s \in A \mid s \notin P\}$. Write A_P for A_S . If I is an ideal of A, $I_P = I_S$ extended ideal.

Proposition. P_P is a maximal ideal of A_P and it is the only maximal ideal of A_P .

Lemma. For a ring R, the following are equivalent:

- (1) R has a unique maximal ideal \mathfrak{M}
- (2) The elements of R that are not invertible form an ideal
- (2) roof \Rightarrow (1) Suppose that the non-units form an ideal I. Then R/I is a field because every element is the residue of a unit, and therefore invertible. Thus I is a maximal ideal. Since any other element is a unit, we cannot include any other element without turning the ideal into the entire ring. Thus, this is maximal.
- (1) \Longrightarrow (2) Suppose there exists a unique maximal ideal \mathfrak{M} . Let $u \in R$. Then (u) = R if and only if u is a unit. If u is not a unit, then (u) < R, and so $(u) \subset$ some maximal ideal. Then $(u) \subset \mathfrak{M}$. Then \mathfrak{M} contains all the non-invertible elements, and so the non-invertible elements of R form an ideal (in particular \mathfrak{M}).

Proposition above. $s^{-1}a \in A_P$, $s \notin P$.

If $a \in P$, then $s^{-1}a \in P_P$. If $a \notin P$, then $s^{-1}a$ is invertible, and so $a^{-1}s \in A_S$.

²Sorry if this proof is unclear. I was trailing behind Prof. Artin, and so wasn't understanding the proof well.

³If R is not noetherian, this requires Zorn's Lemma/The Axiom of Choice.

Definition. A (noetherian) ring R is *local* if it has a unique maximal ideal \mathfrak{M} . (Note that R/\mathfrak{M} is a field.)

Example. $A = \mathbb{C}[x, y]$. The prime ideals are

- (0)
- (f(x,y)) for f irreducible
- maximal ideal $\mathfrak{M}_{(a,b)} = (x-a,y-b) \longleftrightarrow (a,b) \in \mathbb{C}^2$

 $A_{(0)}$: fraction field $\mathbb{C}(x,y)$ of $\mathbb{C}[x,y]$

 $A_{\mathfrak{M}_{(a,b)}}$: a local ring. The prime ideals $\operatorname{PSpec} A_{\mathfrak{M}} = \{P \mid P \cap S \neq \emptyset\} = \{P \mid P \subset \mathfrak{M}\} = \{0\}$ $P = (f) \mid f(a,b) = 0$ $\mathfrak{M}_{(a,b)}$

Lemma. Suppose I is an ideal of the ring A and M is a finite A-module such that M = IM. Then there exists a $z \in I$ such that (1-z)M = 0.

Proof. Say (x_1, \ldots, x_r) generate M. We can write x_i as a combination of $\{x_1, \ldots, x_r\}$ with coefficients in I:

$$x_i = \sum_j p_{ij} x_j \qquad p_{ij} \in I$$

$$X = PX \qquad P \text{ matrix } (p_{ij})$$

$$(\mathbb{I} - P)X = 0$$

$$Q(\mathbb{I} - P) = \delta \mathbb{I}$$

where Q is the cofactor matrix for $\mathbb{I} - P$ with entries in A, and $\delta = \det(\mathbb{I} - P)$.

$$Q(\mathbb{I} - P)X = 0$$

$$\therefore \delta X = 0$$

$$\mathbb{I} - P = \begin{pmatrix} 1 - p_{11} & \cdots & & \\ & \ddots & & \\ & & 1 - p_{nn} \end{pmatrix}$$

$$\delta = 1 - z$$

Since the $p_{ij} \in I$, we have $z \in I$. Then (1-z)X = 0, so (1-z) kills M.

Lemma (Nakayama Lemma). Let A be a local ring with a maximal ideal \mathfrak{M} , and let M be a finite A-module. If $M = \mathfrak{M}M$, then M = 0.

Proof. Take $z \in \mathfrak{M}$. We have a z with (1-z)M=0. Since $1-z \notin \mathfrak{M}$, 1-z is invertible, and so M=0 (since we can multiply by $(1-z)^{-1}$).

13 Friday, March 4, 2011

Integral Extensions

 $A \subset B$ domains

Definition. $b \in B$ is integral over A if it's a root of a monic polynomial. $f(x) = x^n - a_1 x^{n-1} + \cdots \pm a_r$ coefficients in A

Proposition. The following are equivalent:

- (1) b is integral over A
- (2) A[b] is a finite A-module
- (3) There exists an A[b]-module M which:
 - (i) is faithful⁴ as an A[b]-module
 - (ii) is a finite A-module

Proof.

- $(1) \implies (2)$ Clear
- $(2) \implies (3) \text{ Clear}$
- (3) \Longrightarrow (1) Take the generators for M as an A-module, (v_1, \ldots, v_n) . Then $bv_i = \sum a_{ij}v_j$ for $a_{ij} \in A$. We can write this as

$$(b\mathbb{I} - A)V = 0$$
 $V = \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$

Let C be the coefficient matrix of $(b\mathbb{I}-A)$. Then $C(b\mathbb{I}-A) = \det(b\mathbb{I}-A)\mathbb{I}$. Let $\delta := \det(b\mathbb{I}-A)$. Then $\delta V = 0$. Since M is faithful, $\delta = 0$.) Expanding δ gives $\delta = b^n - (\operatorname{tr} A)b^{n-1} + \cdots \pm \det A$ is a monic polynomial for b. The coefficients are in A, so A[b] is integral.

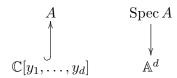
Proposition. Let A be noetherian.

- If B is generated as an A-algebra by elements integral over A, then every element of B is integral over A.
- If B is generated over A by a finite number of integral elements, then B is a finite A-module. (e.g., B integral over A and a finite type \mathbb{C} -algebra.)

Proof. Take $z \in B$. Then $z \in A[b_1, \ldots, b_k]$ for b_i integral. $A[b_1, \ldots, b_k]$ is a finite A-module. Therefore A[z] is contained in a finite module, so it itself is finite.

⁴A module is faithful if for any $z \in A[b]$, $z \neq 0$, $zM \neq 0$.

Proposition (Noether Normalization). Let K be a field, and let A be a finite-type K-algebra and a domain. There exist $y_1, \ldots, y_d \in A$ algebraically independent⁵, and A is a finite module over $K[y_1,\ldots,y_d]$. 6



Proof. Given A generated by x_1, \ldots, x_n (some finite set). Independent on n(???) If x_1, \ldots, x_n dependent, there exists a polynomial relation $f(x_1, ..., x_n) = 0$ of degree d. Let h(x) be the degree d part of f. Then h(0, 0, 0, ..., 1) = coefficient of x_n^d in h and in f. If the coefficient of $x_n^d \neq 0$, then f(x) looks like $cx_n^d + g_{n-1}(x_1, \ldots, x_{n-1}^{d-1} + \cdots + g_0(x_1, \ldots, x_{n-1})$. If $c \neq 0$, this is a monic polynomial of which x_n is a root, and its coefficients are in the ring $K[x_1, \ldots, x_{n-1}]$. Therefore, x_n is integral over $K[x_1,\ldots,x_{n-1}]$. By induction, we get a tower of integral extensions.

If c = 0, then make a change of variables $x_i \mapsto x_i + u_i x_n$ (for i < n), $x_n \mapsto u_n x_n$. Now the coefficient of x_n^d will be $h(x_1 + u_1 x_n, \dots, x_{n-1} + u_{n-1} x_{n-1}, u_n x_n)|_{x_1 = \dots = x_{n-1} = 0, x_n = 1} = h(u_1, \dots, u_n).$ This is non-zero for most choices of u_i .⁷

Corollary (A version of Nullstellensatz). Let K be a field, B a finite-type K-algebra that is also a field. Then B is a finite K-module.

It follows, without much trouble, from this that if $K = \mathbb{C}$, $B = \mathbb{C}$, too; if B is a finite field

extension of \mathbb{C} , then $B = \mathbb{C}$.

Proof. Take $b \in B$. $\mathbb{C}[b]$ is a finite \mathbb{C} -module. Therefore, b is a root of an irreducible polynomial with coefficients in \mathbb{C} . Therefore, it is a root of a linear polynomial over \mathbb{C} , so $b \in \mathbb{C}$.

Proof. Noether Normalization says B a finite module over polynomial ring $A = K[y_1, \ldots, y_d]$. If d=0, then we're done. If d>0, then $y_1\in A, B$, so $\frac{1}{y_1}\in B$. Thus B is a field. But $\frac{1}{y_1}$ is not integral over $K[y_1, \ldots, y_d]$.

If A is a domain with fraction field K, then A is integrally closed in K if every element of K which is integral over A is an element of A.

Example. $A = \mathbb{C}[x,y]/(y^2 - x^3)$. This is not integrally closed: Let $z = \frac{y}{x}$. Then $z^2 = \frac{y^2}{x^2} = \frac{x^3}{x^2} = x$. $z^3 = \frac{y^3}{x^3} = \frac{x^3y}{x^3} = y$. z is a root of the monic polynomial $z^2 - x$, and of $z^3 - y$. Then $z^2 = \frac{y^2}{x^2} = \frac{x^3}{x^2} = x$.

Theorem. Let A be a finite-type algebra and a domain, and let K be the fraction field of A. Then the integral closure of A in K, the set of integral elements, is a finite A-module.

Given an A-module M, then $M^* := \hom_A(M, A)$ is also an A-module. If $M \subset N$, then $M^* \supset N^*$ (in good situations).

⁵There are no polynomial relations among them.

⁶I'm still confused by this statement.

⁷For fields with finite characteristic, you'll have to make a non-linear change of variables.

14 Monday, March 7, 2011

15 Wednesday, March 9, 2011

Theorem. Let A be a finite type algebra and a domain, and let K be the field of fractions. Then the integral closure of A is a finite extension L/K, and is a finite A-module.

Proof. Had the trace pairing $L \times L \to K$, $x, y \sim tr(xy)$. It's non-degenerate because:

 $yx \neq 0$, put $y = x^{-1}$

 $\langle x, y \rangle = t(1) = [L:K]$

Reduce to the case of A integrally closed by Noether Normalization.

 $k[y] \subset A$, A a finite k[y]-module

 $k[y] \subset K \subset L$.

Replace A by k[y].

 \therefore , we may assume that A is integrally closed. Then if $\alpha \in L$ is integral over $A, tr(\alpha) \in A$.

Therefore, if B is any subring of L, and a finite A-module, then all elements are integral over A. Therefore, $B \times B \to A$, $x, y \leadsto \langle x, y \rangle = tr(xy)$.

We want to show that there is a maximal such B. Then B is the integral closure in L.

Start with one, B_0 , big enough so that it contains a basis for L/K. (We can do this because for any $\gamma \in L$, γ is algebraic in K; $\gamma^n - a_1 \gamma^{n-1} + \cdots \pm a_n = 0$ with $a_i \in K$. Since K is the field of fractions, we can clear denominators, getting $d\gamma^n - a'_1\gamma^{n-1} + \cdots \pm a'_n = 0$, with $d, a'_i \in A$. Then $d\gamma$ is integral over A; multiply everything by d^{n-1} .) Denote the basis by (v_1, \ldots, v_n) , $v_i \in B_0$, n = [L:K].

Investigate some larger algebra (which is still a finite A-module) B. Then $A \subset B_0 \subset B$.

$$B \times B \to A$$

 $\beta, v_i \leadsto b_i := \langle \beta, v_i \rangle \in A$

map

$$\beta \leadsto (b_1, \dots, b_n) \in A^n$$

$$B \stackrel{\Phi}{\to} A^n$$

This is A-linear (homomorphism of A-modules)

 Φ is injective: $\Phi(\beta) = 0$ means $\langle \beta, v_i \rangle = 0$ for all i. Since $\{v_i\}$ is a basis for L/K, $\langle \beta, y \rangle = 0$ for all $y \in L$. Thus, $\beta = 0$.

Then we can identify B with $\Phi(B)$ as a submodule of A^n . Since A is noetherian, submodules have the ascending chain condition.

(DIGRESSION ABOUT GALOIS GROUPS AND G-ORIBTS NOT INCLUDED)

Let $A \subset B$ be a domain, A finite-type and integrally closed, and B a finite A-module. What about prime ideals in A and B?

extended ideal of $P \subset A$ is $P^e = PB$ ideal of B

contracted ideal of $Q \subset B$ is $Q^c = A \cap Q$ ideal of A

Fact (General Fact). If Q is a prime ideal of B, then Q^c is a prime ideal of A.

$$A \xrightarrow{B} B$$
kernel Q

$$B/Q a \text{ domain } (Q \text{ prime})$$

The image is a domain, so Q^c is a prime ideal.

Back to the case above,

$$A \hookrightarrow B$$
 $P' \qquad Q' \qquad \text{we mean } P' = A \cap Q'$
 $P \qquad Q \qquad P = A \cap Q, \quad Q' \supset Q$

Fact 15.1 (Lying Over). Given P a prime ideal of A, there exists a A prime ideal of B, with $A \cap Q = P$. (The map PSpec $B \to P$ Spec A is injective.)

Fact 15.2 (Going Up). Given

$$A \xrightarrow{} B$$

$$P' \qquad Q' \longleftarrow \text{exists}$$

$$P \qquad Q$$

Fact 15.3 (Going Down). If A is integrally closed, then given

$$A \xrightarrow{} B$$

$$P' \qquad Q'$$

$$P \qquad Q \leftarrow \text{exists}$$

Lemma. Given

$$A \hookrightarrow B$$

$$P' \qquad Q'$$

$$P \qquad Q$$

If P' = P, then Q' = Q.

Proof. Case 1: P=0. We need to show that if P'=0, then Q'=0. Take $\alpha \in Q' \subset B$. Then α is integral over A (because it's in B?). We have $\alpha^r - a_1 \alpha^{r-1} + \cdots \pm a_r = 0$. Since $a_r \in Q'$ and $a_r \in A$, we have $a_r \in P' = \{0\}$. Thus $a_r = 0$. If $\alpha \neq 0$, then cancel α from the relation, and repeat until r=1. Then $\alpha^1 - a_1 = 0$. Since $a_1 \in A$ and $a_1 \in Q'$, $a_1 \in P'$. Then $a_1 = 0$ and $\alpha = 0$, which is a contradiction.

Case 2: (general case). Go to $\bar{A} = A/P \subset \bar{B} = B/Q$.

$$\bar{A} \hookrightarrow \bar{B}$$
 $\bar{P}' \qquad \bar{Q}'$
(0) (0)

Then case 1 says that $\bar{P}'=(0)$ implies that $\bar{Q}'=(0)$. Then $\bar{P}'=(0) \iff P'=P$ and $\bar{Q}'=(0) \iff Q'=Q$.

Lemma. If Q is a maximal ideal of B, then $Q^c = P$ is maximal in A.

Proof. Q is maximal in B if and only if $\bar{B} = B/Q$ is a field. Then $A/P = \bar{A} \subset \bar{B}$ is a field. Then \bar{B} is a finite \bar{A} -module.

Lemma. If $A \subset B$ is a field and B is a finite A-module, then A is a field.

Proof. Take a non-zero element in $\alpha \in A$ (we want to show that it's invertible). Then α is invertible in B. Since B is a finite A-module, so $u = \alpha^{-1}$ is integral over A. Then $u^r - a_1 u^{r-1} + \cdots \pm a_r = 0$ with $a_i \in A$. Multiply by α^{r-1} . Then we get $u - a_1 + a_2 \alpha - \cdots \pm a_r \alpha^r = 0$, with all of these elements of A.

(To be finished next time?)

16 Friday, March 11, 2011

Finite group action on an integrally closed finite-type domain $B, A = B^G$, (has the?) invariants

 $\max A \leftrightarrow G$ -orbit in $\max B$

A is finite type and integrally closed

B is a finite A-module

Definition. A is normal if it's integrally closed in the field of fractions of A (i.e., it's own fraction field).

Theorem. Let G be a finite group that acts on an integrally closed finite-type domain B, $A = B^G$. Then

- PSpec $A \leftrightarrow (PSpec B)/G$
- This preserves inclusions. More formally, If $P \leftrightarrow orbit \{Q_j\}$ and $P' \leftrightarrow orbit \{Q'_i\}$, then $P \subset P'$ if and only if $\forall j \exists i$ such that $Q_i \subset Q'_i$.

We have $Q \rightsquigarrow A \cap Q$, Spec $B \rightarrow \operatorname{Spec} A$

Lemma. Let Q_1, \ldots, Q_m ; Q'_1, \ldots, Q'_n be prime ideals of B. Suppose $Q_j \not\subset any Q'_i$, $j = 1, \ldots, m$, $i = 1, \ldots, n$. Then there exists $\alpha \in B$, $\alpha \in Q_1, \ldots, Q_m$, $\alpha \notin Q'_1, \ldots, Q'_n$.

Proof. Plan: Solve for a single Q_j . Find $\alpha_j \in Q_j$, $\notin Q'_1, \ldots, Q'_n$. Then the product $(\alpha_1 \cdots \alpha_m)$ works; $\alpha_1 \cdots \alpha_m \in Q'_i \Longrightarrow \text{some } \alpha_j \in Q'_i$. This would be a contradiction.

Take
$$Q_1 = Q, Q'_1, \dots, Q'_n, \alpha \in Q, \notin Q'_i$$
.
 $\alpha = \beta_i \in Q, \notin Q'_i, i = 1, \dots, \beta_1 \dots \beta_n \in Q. \dots \text{(Proof not included)}$

Proof. (of theorem) In C:

$$B \xrightarrow{\sigma} B$$

$$A \xrightarrow{\text{id}} A$$

Since Q is a prime ideal of B and $P = A \cap Q$, we have that σQ is a prime ideal of B and $P = A \cap \sigma Q$. Then an orbit of Q corresponds to one point in PSpec A. By the lying over theorem, Spec $B \to \operatorname{Spec} A$ is surjective. Therefore (Spec B)/ $G \to \operatorname{Spec} A$ is also surjective.

Injective: $\{Q_1, \ldots, Q_m\}, \{Q'_1, \ldots, Q'_n\}$ distinct orbits. $A \cap Q_j = P, A \cap Q'_i = P'$, show $P \neq P'$.

Claim. We can't have $Q_i \subset Q'_j$ for some i, j and also $Q'_k \subset Q_\ell$ for some k, ℓ .

Proof. We can renumber, i = j = 1. $Q'_k \subset Q_\ell \implies \sigma Q'_k \subset \sigma Q_\ell$. We may then assume that $\ell = 1$; since σ runs through the whole orbit, we can choose an appropriate σ .

Then $Q_1 \subset Q_1$, $Q_k' \subset Q_1$. Then $Q_k' \subset Q_1 \subset Q_1'$. Then $Q_k' \subset Q_1'$. Thus k = 1, because $Q_k' = \sigma Q_1'$ for some σ (and permutations can't take sets to proper subsets of themselves). Then $Q_1' \subset Q_1 \subset Q_1'$, so $Q_1 = Q_1'$. This is a contradiction, since orbits are disjoint. Thus, we may suppose that $Q_i \not\subset Q_i'$ for any i, j.

There exists an $\alpha \in Q_1 \cap \cdots \cap Q_m$, $\notin Q_i'$. Take $\gamma = \prod_{\sigma} \sigma \alpha$, $\gamma \in Q_j$, $\notin Q_i'$, and $\gamma \in A$. Thus, $\gamma \in P$, $\notin P'$, so $P \neq P'$.

The proof of the second point is skipped (See notes that Prof. Artin posted). \Box

Let B be a finite A-module for a normal A.



$$P' = A \cap Q', P = A \cap Q$$

Theorem (Going Up). In the diagram above, given P, P', Q, there exists a Q'.

Theorem (Going Down). In the diagram above, given P, P', Q', there exists a Q.

Proof. Let K be the fraction field of A and L be the fraction field of B.

Case 1: L/K is Galois, has Galois group G(?). B is normal.

 σ acts on B: The elements of B are integral of A. If β is integral, so is $\sigma\beta$. Then, since B is normal, B is the integral closure of A in B. Thus, B0 is integral closure of B1.

 $A = B^G$. (We know that B is a finite B^G -module.): $A \subset B^G$ and A is normal. Since B is integral over A, B^G is integral over A, so $A = B^G$.

Then the theorem follows from the previous theorem.

Case 2: (general case): L/G not Galois, and/or B not normal: Put $L \subset F$ a Galois extension of K with Galois group G. Let C be the integral closure of A in F. This is a finite A-module. Then G operates on C. Then $A = C^G$ (by the same reasoning as in case 1).

$$A \hookrightarrow B \hookrightarrow C$$

$$P' \qquad Q' \qquad R'$$

$$P \qquad R$$

By lying over, there exists a prime ideal R', $B \cap R' = Q'$. Case 1 says that there exists an R. Then $A \cap R = P$. Put $Q = B \cap R$.

17 Monday, March 14, 2011

Definition. The *Knull dimension* of a ring A is the length of the longest chain of prime ideals $P_0 < P_1 < \cdots < P_d$.

In a dimension zero ring, every prime ideal is maximal and also minimal. Therefore, there are a finite number of prime/minimal ideals.

If A is a domain of dimension 1, then (0) is a prime ideal and all the other prime ideals are maximal.

Definition. The *codimension* of a prime ideal P is the length of the longest chain $P_0 < P_1 < \cdots < P_d = P$.

If A is a domain, then P has codimension 0 if P = (0), and P has codimension 1 if it's not zero and there does not exist P' with (0) < P' < P.

Theorem (Knull's Principal Ideal Theorem). Let A be a domain. Let $x \in A$ with $x \neq 0$, and let P be a prime ideal. If $x \in P$ and P is is the minimal prime ideal containing x, then P has codimension 1.

 $(P/x \in P \longleftrightarrow prime \ ideals \ \bar{B} \ of \ \bar{A} = A/(x).$ Therefore, the Knull dimension of \bar{A} is the Knull dimension of A, - 1.)

Discrete valuations

Generalize order of vanishing of f(x) at x = a. For $f(x_1, \ldots, x_n)$, talking about order of vanishing at (a_1, \ldots, a_n) doesn't make much sense. But we can define the order of vanishing along a subvariety of codimension 1.

Let K be a field. A discrete valuation(?) v is a group homomorphism $K^{\times} \stackrel{v}{\to} \mathbb{Z}^+$ such that $v(\alpha + \beta) \ge \min\{v(\alpha), v(\beta)\}$ and $v(\alpha\beta) = v(\alpha) + v(\beta)$. " $v(\alpha) = k$ means α vanishes to order k (has a zero of order k)". $v(\alpha) = -k$, " α has a pole of order k.

A homomorphism $K^{\times} \stackrel{v}{\to} \Gamma^+$ (an ordered group with +) is also a valuation. This is unimportant!

Definition. The (discrete) valuation ring R associated to a discrete valuation v is $R = \{\alpha \in K^{\times} | v(\alpha) \ge 0\} \cup \{0\}$ ("no pole").

Remorse: You always have to add $\{0\}$, or define $v(0) = \infty$ (but this is artificial)

Definition. A fractional ideal is a non-zero finitely generated submodule of K.

Properties of DVR (discrete valuation ring):

- subring of K and local domain (local ring that's a domain, ring with one maximal ideal)
- $\mathfrak{M} = \{\alpha \in K \mid v(\alpha) > 0\} \cup \{0\}$
- \mathfrak{M} is a principle ideal generated by any $t \in K^{\times}$ with v(t) = 1.
- ideals of R are $\mathfrak{M}^k = (t^k)$ and zero ideal (K > 0) $(\mathfrak{M}^k = \{\alpha \mid v(\alpha) > k\})$
- \bullet R is normal
- The fractional ideals of R are (t^k) , $k \in \mathbb{Z}$.

Write $(t^k) = \mathfrak{M}^k$ also for k < 0. Then $\mathfrak{M}^{k+l} = \mathfrak{M}^k \mathfrak{M}^l$, $k, l \in \mathbb{Z}$.

Lemma. v(1) = 0, v(-1) = 0, $v(a^{-1}) = -v(a)$

Take $\alpha \in K^{\times}$, $v(\alpha) = k$. Also, $v(t^k) = k$. $v(t^{-k}\alpha) = 0$. Then $t^{-k}\alpha = u$ is a unit in R, so $\alpha = ut^k$.

18.721 Notes

Proposition. The following are equivalent conditions on a local noetherian domain A:

- (1) A is a DVR
- (2) A is normal and has dimension 1
- (3) A is normal and there exists an $x \in A$ such that \mathfrak{M} is the minimal prime ideal containing x
- (4) M is principle

(P) nof ⇒ (2) We're not doing it (it follows from the properties of a DVR)

- (2) \Longrightarrow (3) There exist only two prime ideals in A: (0) $\neq \mathfrak{M}$. $x \in \mathfrak{M}$, $x \neq 0$ also works.
- (3) \Longrightarrow (4) Take x as in (3). Then $\bar{A} = A/(x)$ has only one prime ideal $\bar{\mathfrak{M}}$ both maximal and minimal. The intersection of the minimal prime ideals is the nilradical of \bar{A} . Therefore $\bar{\mathfrak{M}}$ is the nilradical. Therefore, $\bar{\mathfrak{M}}^N = (0)$, $N \gg 0$. Thus $\mathfrak{M}^N < (x)$.

Choose r such that $\mathfrak{M}^{r-1} \not\subset (x)$ but $\mathfrak{M}^r \subset (x)$. Take $y \in \mathfrak{M}^{r-1}, y \not\in (x)$. We want to show that w = x/y generates \mathfrak{M} . Let $z = w^{-1} = y/x$. Since $y \notin (x)$, $z \notin A$. Now consider $z\mathfrak{M}$.

Lemma. Let A be a normal noetherian domain, I a non-zero ideal, $\gamma \in K = \operatorname{Fract}(A)$. If $\gamma I \subset I$, then $\gamma \in A$.

Proof. $\gamma I \subset I$ means that I is an $A[\gamma]$ -module. $I(\gamma I)$ is faithful, and a finite A-module. Then γ is integral over A, and thus an element of A.

 $z\mathfrak{M} = \frac{y}{x}\mathfrak{M} \subset \frac{\mathfrak{M}^r}{x} \subset A$. We stop here (continue next time).

18 Wednesday, March 16, 2011