

Magnetohydrodynamics Homework 3

1. (1) $\begin{bmatrix} B_r \\ B_\theta \\ B_z \end{bmatrix} = B_0 \begin{bmatrix} \frac{1}{k} J_1(kr) e^{-l z} \\ \sqrt{1 - \frac{l^2}{k^2}} J_1(kr) e^{-l z} \\ J_0(kr) e^{-l z} \end{bmatrix}$ 为柱坐标系下一轴对称磁场(与 θ 无关) $= B_0 e^{-l z} \begin{bmatrix} \frac{1}{k} J_1(kr) \\ \sqrt{1 - \frac{l^2}{k^2}} J_1(kr) \\ J_0(kr) \end{bmatrix}$

$$\nabla \times \vec{B} = \left(\frac{1}{r} \frac{\partial B_z}{\partial \theta} - \frac{\partial B_\theta}{\partial z} \right) \hat{r} + \left(\frac{\partial B_r}{\partial z} - \frac{\partial B_z}{\partial r} \right) \hat{\theta} + \frac{1}{r} \left[\frac{\partial}{\partial r} (r B_\theta) - \frac{\partial B_r}{\partial \theta} \right] \hat{z}$$

$$= -\frac{\partial B_\theta}{\partial z} \hat{r} + \left(\frac{\partial B_r}{\partial z} - \frac{\partial B_z}{\partial r} \right) \hat{\theta} + \frac{1}{r} \frac{\partial}{\partial r} (r B_\theta) \hat{z}$$

$$= B_0 \begin{bmatrix} -\sqrt{1 - \frac{l^2}{k^2}} J_1(kr) (-l) e^{-l z} \\ \frac{1}{k} J_1(kr) (-l) e^{-l z} - e^{-l z} \frac{d}{dr} J_0(kr) \\ \frac{1}{r} \sqrt{1 - \frac{l^2}{k^2}} e^{-l z} \frac{d}{dr} [r J_1(kr)] \end{bmatrix}$$

注意到: $\frac{d}{dx} J_0(x) = -J_1(x)$ 和 $\frac{d}{dx} [x J_1(x)] = x J_0(x)$, 于是:

$$\nabla \times \vec{B} = B_0 e^{-l z} \begin{bmatrix} l \sqrt{1 - \frac{l^2}{k^2}} J_1(kr) \\ -\frac{l^2}{k} J_1(kr) + k J_1(kr) \\ k \sqrt{1 - \frac{l^2}{k^2}} J_0(kr) \end{bmatrix} = \sqrt{k^2 - l^2} B_0 e^{-l z} \begin{bmatrix} \frac{1}{k} J_1(kr) \\ \sqrt{1 - \frac{l^2}{k^2}} J_1(kr) \\ J_0(kr) \end{bmatrix} = \sqrt{k^2 - l^2} \vec{B}$$

因 k, l 为常数, 故此磁场为线性无场

(2) $\vec{B} = \begin{bmatrix} B_r \\ B_\theta \\ B_z \end{bmatrix} = B_0 \begin{bmatrix} 0 \\ \frac{br}{1+b^2 r^2} \\ \frac{1}{1+b^2 r^2} \end{bmatrix}$ 也为一直坐标系下的轴对称磁场(与 θ 无关) $= \frac{B_0}{1+b^2 r^2} \begin{bmatrix} 0 \\ br \\ 1 \end{bmatrix}$
且 $B_r = 0$
且与 z 也无关

$$\nabla \times \vec{B} = -\frac{\partial B_z}{\partial r} \hat{\theta} + \frac{1}{r} \frac{\partial}{\partial r} (r B_\theta) \hat{z}$$

$$= B_0 \left[\frac{2b^2 r}{(1+b^2 r^2)^2} \hat{\theta} + \frac{1}{r} \frac{d}{dr} \left(\frac{br^2}{1+b^2 r^2} \right) \hat{z} \right] = B_0 \left[\frac{2b^2 r}{(1+b^2 r^2)^2} \hat{\theta} + \frac{2b}{(1+b^2 r^2)^2} \hat{z} \right]$$

$$= B_0 \frac{2b}{(1+b^2 r^2)^2} \begin{bmatrix} 0 \\ br \\ 1 \end{bmatrix} = \frac{2b}{1+b^2 r^2} \vec{B} \text{ 为非线性无场}$$

2. (1) 无作用力场基本方程 $\begin{cases} \nabla \times \vec{B} = \alpha \vec{B} & \text{①} \\ \nabla \cdot \vec{B} = 0 & \text{②} \end{cases}$ 对①式两边取旋度得:

对②式两边取旋度得: $\nabla \times (\nabla \times \vec{B}) = \nabla \times (\alpha \vec{B})$

两边均用矢量恒等式展开得:

$$\nabla \cdot (\nabla \times \vec{B}) - \nabla^2 \vec{B} = \alpha \nabla \times \vec{B} + \nabla \alpha \times \vec{B}$$

再将①②式代入可得:

$$\vec{B} \times \nabla \alpha = \nabla^2 \vec{B} + \alpha (\alpha \vec{B}) = (\nabla^2 + \alpha^2) \vec{B}$$



$$(2) \text{ 已知 } \begin{cases} (\nabla^2 + \alpha^2) \vec{B} = \vec{B} \times \nabla \alpha & ③ \\ \nabla \cdot \vec{B} = 0 & ② \end{cases}$$

由矢量恒等式得:

$$\nabla^2 \vec{B} = \nabla(\nabla \cdot \vec{B}) - \nabla \times \nabla \times \vec{B} = -\nabla \times (\nabla \times \vec{B})$$

代入③式得:

$$\alpha^2 \vec{B} - \nabla \times (\nabla \times \vec{B}) = \vec{B} \times \nabla \alpha \quad ④$$

对④式两边取散度得: $\nabla \times (\nabla \times \vec{B} - \alpha \vec{B}) + \alpha (\nabla \times \vec{B} - \alpha \vec{B}) = 0$

$$\nabla \cdot (\alpha^2 \vec{B}) - \nabla \cdot \nabla \times (\nabla \times \vec{B}) = \nabla \cdot (\vec{B} \times \nabla \alpha)$$

其中对一矢量场 $\nabla \times \vec{B}$ 总有 $\nabla \cdot \nabla \times (\nabla \times \vec{B}) = 0$, 于是:

$$\nabla \cdot (\alpha^2 \vec{B}) = \nabla \cdot (\vec{B} \times \nabla \alpha)$$

其中:

$$\nabla \cdot (\alpha^2 \vec{B}) = \alpha^2 \nabla \cdot \vec{B} + \vec{B} \cdot \nabla \alpha^2 = 2\alpha \vec{B} \cdot \nabla \alpha$$

$$\nabla \cdot (\vec{B} \times \nabla \alpha) = \nabla \alpha \cdot (\nabla \times \vec{B}) - \vec{B} \cdot \nabla \times \nabla \alpha = \nabla \alpha \cdot (\nabla \times \vec{B})$$

已使用对一标量场 α 总有 $\nabla \times \nabla \alpha = 0$, 于是:

$$2\alpha \vec{B} \cdot \nabla \alpha = (\nabla \times \vec{B}) \cdot \nabla \alpha$$

$$\Rightarrow (\nabla \times \vec{B} - 2\alpha \vec{B}) \cdot \nabla \alpha = 0$$

$$\Rightarrow \nabla \times \vec{B} = 2\alpha \vec{B} \text{ 或 } (\nabla \times \vec{B} - 2\alpha \vec{B}) \perp \nabla \alpha$$

即所对应磁场不一定是无场, 满足 $(\nabla \times \vec{B} - 2\alpha \vec{B}) \perp \nabla \alpha$ 即可

3. 磁流体静力学平衡方程组为:

$$\begin{cases} \nabla p = \vec{j} \times \vec{B} \\ \vec{j} = \frac{1}{\mu_0} \nabla \times \vec{B} \\ \nabla \cdot \vec{B} = 0 \end{cases}$$

○ (1) $\nabla \cdot (\vec{B} \times \nabla p) = \nabla p \cdot (\nabla \times \vec{B}) - \vec{B} \cdot \nabla \times (\nabla p)$

○ 注意到对任意标量场 p 都有 $\nabla \times \nabla p = 0$, 于是

○ $\nabla \cdot (\vec{B} \times \nabla p) = \nabla p \cdot (\nabla \times \vec{B}) = (\vec{j} \times \vec{B}) \cdot \mu_0 \vec{j} = (\mu_0 \vec{j} \times \vec{j}) \cdot \vec{B} = 0$ ✓

○ (2) 注意到:

○ $\nabla \times (\vec{j} \times \vec{B}) = \vec{j}(\nabla \cdot \vec{B}) - \vec{B}(\nabla \cdot \vec{j}) + (\vec{B} \cdot \nabla) \vec{j} - (\vec{j} \cdot \nabla) \vec{B}$

○ $= -\vec{B}(\nabla \cdot \vec{j}) + (\vec{B} \cdot \nabla) \vec{j} - (\vec{j} \cdot \nabla) \vec{B}$

○ 其中:

○ $\nabla \cdot \vec{j} = \nabla \cdot \left(\frac{1}{\mu_0} \nabla \times \vec{B} \right) = \frac{1}{\mu_0} \nabla \cdot (\nabla \times \vec{B}) = 0 \Rightarrow \vec{B}(\nabla \cdot \vec{j}) = 0$

$$\nabla p = -\frac{1}{2\mu_0} \nabla \vec{B}^2 + \frac{1}{\mu_0} \vec{B} \cdot \nabla \vec{B}$$

$$\nabla \times (\vec{j} \times \vec{B}) = \nabla \times \nabla p = 0$$

$$\text{故: } (\vec{B} \cdot \nabla) \vec{j} = (\vec{j} \cdot \nabla) \vec{B}$$
