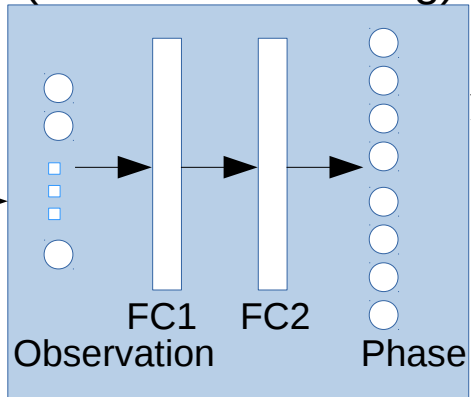


# Environment

## Deep Q-Network (Parameter Sharing)



Action 1

Intersection  
1

Observation 1

Reward 1

Action 2

Intersection  
2

Observation 2

Reward 2

Action n

Intersection  
n

Observation n

Reward n

⋮

