Analysis 1

Jiaqi Wang

November 29, 2023

Contents

1	Sets	, Spaces and Function 6
	1.1	Metric Space
	1.2	Normed Vector Spaces
	1.3	The reverse triangle inequality
2	Rea	l Numbers 8
	2.1	What are the real numbers?
	2.2	The completeness axiom
	2.3	Alternative characterizations of suprema and infima
	2.4	Maxima and minima
	2.5	The Archimedean property
	2.6	Computation rules for suprema
	2.7	Bernoulli's inequality
3	Sequ	iences 11
	3.1	Sequence
	3.2	Terminology around sequences
	3.3	Convergence of sequences
	3.4	Examples and limits of simple sequences
	3.5	Uniqueness of limits
	3.6	More properties of convergent sequences
	3.7	Limit theorems for sequences taking values in a normed vector space
	3.8	Index shift
4	Real	l-valued sequences 14
	4.1	Terminology
	4.2	Monotone, bounded sequences and convergent
	4.3	Limit theorems
	4.4	The squeeze theorem
	4.5	Divergence to ∞ and $-\infty$
	4.6	Limit theorems for improper limits
	17	Standard sequences 16

5	Serie	s	18
	5.1	Geometric series	18
	5.2	The harmonic series	18
	5.3	The hyperharmonic series	18
	5.4	Only the tail matters for convergence	18
	5.5	Divergence test	18
	5.6	Limit laws for series	18
6	Serie	A	19
	6.1	1	19
	6.2	1	19
	6.3		19
	6.4	Root test	19
7	Comic	a with conord towns	20
/		8	
	7.1		20
	7.2	1	20
	7.3	The Cauchy product	20
8	Subs	equences, limsup and liminf	21
	8.1	1 / 1	21
	8.2		21
	8.3		21
	8.4		21
	8.5		21
	8.6		21
		•	
9	Poin		22
	9.1	1	22
	9.2		22
	9.3	• 1	22
	9.4	<u>.</u>	22
	9.5	Series characterization of completeness in normed vector spaces	22
10	Com	pactness	23
10			23 23
			23 23
	10.2	Antimative characterization of compactness	رر
11	Limi	ts and continuity	24
	11.1	Accumulation points	24
			24
	11.3	Uniqueness of limits	24
			24
			24
			24
			24
			24
			24
			24

12	Real-valued functions	25
	12.1 More limit laws	
	12.2 Building of standard functions	
	12.3 Continuity of standard functions	
	12.4 Limits from the left and from the right	
	12.5 The extended real line	
	12.6 Limits to ∞ or −∞	25
	12.7 Limits at ∞ and $-\infty$	
	12.8 The Intermediate Value Theorem	
	12.9 The Extreme Value Theorem	
	12.10 Equivalence of norms	25
	12.11 Bounded linear maps and operator norms	23
13	Differentiability	26
	13.1 The derivative as a function	
	13.2 Constant and linear maps are differentiable	
	13.3 Bases and coordinates	
	13.4 The matrix representation	
	13.5 The chain rule	
	13.6 Sum, product and quotient rules	
	13.7 Differentiability of components	
	13.8 Differentiability implies continuity	
	13.9 Derivative vanishes in local maxima and minima	26
	13.10The Mean Value Theorem	
	13.10 The Mean value Theorem	20
14	Differentiability of standard functions	27
14	·	27
14	14.1 Global context	27 27
14	14.1 Global context	27 27 27
	14.1 Global context	27 27 27 27
	14.1 Global context	27 27 27 27 27
	14.1 Global context	27 27 27 27 27 28 28
	14.1 Global context	27 27 27 27 28 28 28
	14.1 Global context	27 27 27 27 28 28 28 28
	14.1 Global context	27 27 27 27 28 28 28 28 28
	14.1 Global context	27 27 27 27 28 28 28 28 28 28 28
	14.1 Global context	27 27 27 27 28 28 28 28 28 28 28
15	14.1 Global context . 14.2 Polynomials and rational functions are differentiable . 14.3 Differentiability of the standard functions . Directional and partial derivatives . 15.1 A recurring and very important construction . 15.2 Directional derivatives . 15.3 Partial derivatives . 15.4 The Jacobian of a map . 15.5 Linearization and tangent planes . 15.6 The gradient of a function .	27 27 27 27 28 28 28 28 28 28 28
15	14.1 Global context	27 27 27 27 28 28 28 28 28 28 28 28
15	14.1 Global context	27 27 27 27 28 28 28 28 28 28 28 29 29
15	14.1 Global context	27 27 27 27 28 28 28 28 28 28 28 29 29
15	14.1 Global context	27 27 27 27 28 28 28 28 28 28 28 29 29
15 16	14.1 Global context	27 27 27 27 28 28 28 28 28 28 28 29 29
15 16	14.1 Global context 14.2 Polynomials and rational functions are differentiable 14.3 Differentiability of the standard functions Directional and partial derivatives 15.1 A recurring and very important construction 15.2 Directional derivatives 15.3 Partial derivatives 15.4 The Jacobian of a map 15.5 Linearization and tangent planes 15.6 The gradient of a function The Mean-Value Inequality 16.1 The mean-value inequality for functions defined on an interval 16.2 The mean-value inequality for functions on general domains 16.3 Continuous partial derivatives imply differentiability Higher order derivatives	27 27 27 27 28 28 28 28 28 28 28 29 29 29
15 16	14.1 Global context 14.2 Polynomials and rational functions are differentiable 14.3 Differentiability of the standard functions Directional and partial derivatives 15.1 A recurring and very important construction 15.2 Directional derivatives 15.3 Partial derivatives 15.4 The Jacobian of a map 15.5 Linearization and tangent planes 15.6 The gradient of a function The Mean-Value Inequality 16.1 The mean-value inequality for functions defined on an interval 16.2 The mean-value inequality for functions on general domains 16.3 Continuous partial derivatives imply differentiability Higher order derivatives 17.1 Multilinear maps	27 27 27 27 28 28 28 28 28 28 28 29 29 29 30 30
15 16	14.1 Global context	27 27 27 27 28 28 28 28 28 28 29 29 29 29 30 30
15 16	14.1 Global context 14.2 Polynomials and rational functions are differentiable 14.3 Differentiability of the standard functions Directional and partial derivatives 15.1 A recurring and very important construction 15.2 Directional derivatives 15.3 Partial derivatives 15.4 The Jacobian of a map 15.5 Linearization and tangent planes 15.6 The gradient of a function The Mean-Value Inequality 16.1 The mean-value inequality for functions defined on an interval 16.2 The mean-value inequality for functions on general domains 16.3 Continuous partial derivatives imply differentiability Higher order derivatives 17.1 Multilinear maps 17.2 Relation to n-fold directional derivatives 17.3 A criterion for higher differentiability	27 27 27 27 28 28 28 28 28 28 29 29 29 29 30 30 30 30
15 16	14.1 Global context	27 27 27 28 28 28 28 28 28 28 29 29 29 30 30 30 30 30 30

18	Polynomials and approximation by polynomials	31
	18.1 Homogeneous polynomials	31
	18.2 Taylor's theorem	31
	18.3 Taylor approximations of standard functions	31
19	Banach fixed point theorem	32
20	Implicit function theorem	33
	20.1 The objective	33
	20.2 Notation	33
	20.3 The implicit function theorem	33
	20.4 The inverse function theorem	33
21	Function sequences	34
	21.1 Point-wise convergence	34
	21.2 Uniform convergence	34
	21.3 Preservation of continuity under uniform convergence	34
	21.4 Differentiability theorem	34
	21.5 The normed vector space of bounded functions	34
22	Function series	35
	22.1 The Weierstrass M-test	35
	22.2 Conditions for differentiation of function series	35
23	Power series	36
	23.1 Convergence of power series	36
	23.2 Standard functions defined as power series	36
	23.3 Operations with power series	36
	23.4 Differentiation of power series	36
	23.5 Taylor series	36
24	Riemann integration in one dimension	37
	24.1 Riemann integrable functions and the Riemann integral	37
	24.2 Sums, products of Riemann integrable functions	37
	24.3 Continuous functions are Riemann integrable	37
	24.4 The fundamental theorem of calculus	37
25	Riemann integration in multiple dimensions	38
	25.1 Partitions in multiple dimensions	38
	25.2 Riemann integral on rectangles in \mathbb{R}^n	38
	25.3 Properties of the multidimensional Riemann integral	38
	25.4 Continuous functions are Riemann integrable	38
	25.5 Fubini's theorem	38
	25.6 The (topological) boundary of a set	38
	25.7 Jordan content	38
	25.8 Integration over general domains	38
	25.9 The volume of bounded sets	38

26	Cha	nge-of-variables Theorem	39
	26.1	Polar coordinates	39
	26.2	Cylindrical coordinates	39
	26.3	Spherical coordinates	39

1 Sets, Spaces and Function

1.1 Metric Space

Definition 1.1.1 – distance Let X be a set. A function $d: X \times X \to X$ is called a *distance* on X if it satisfies the following properties:

- (i) Positivity: For all $a, b \in X$, it holds that $d(a, b) \ge 0$.
- (ii) Non-degeneracy: For all $a, b \in X$, if d(a, b) = 0, then a = b.
- (iii) Symmetry: For all $a, b \in X$, it holds that d(a, b) = d(b, a).
- (iv) Triangle inequality: For all $a,b,c \in X$, it holds that $d(a,c) \le d(a,b) + d(b,c)$.
- (v) Reflexivity: For all $a \in X$, it holds that d(a, a) = 0.

Usually conditions (ii) and (v) are combined into one condition: For all $a, b \in X, d(a, b) = 0$ if and only if a = b.

Definition 1.1.2 – metric space A metric space is a pair (X, dist), where X is a set and dist is a distance function $dist : X \times X \to \mathbb{R}$ on X.

Example 1.1.3 Let $X = \{ \text{Die Hard, Barbie, Oppenheimer} \}$

d	Die Hard	Barbie	Oppenheimer
Die Hard	0	5	2
Barbie	5	0	3
Oppenheimer	2	3	0

Then d is a distance function on X

Definition 1.1.4 – ball in a metric space Let (X,d) be a metric space. Let $c \in X$ and $r \in \mathbb{R}$. The ball of radius r centered at c is the set

$$B(c,r) = \{x \in X | d(c,x) < r\}$$

Example 1.1.5 If $(X,d) = (\mathbb{R}, d_{\mathbb{R}})$, then $B(1,3) = (-2,4) = \{x \in \mathbb{R} \mid |x-1| < 3\}$

Example 1.1.6 Let $X := \{ \text{Die Hard, Barbie, Oppenheimer} \}$, with distance defined before. Then $B(\text{Barbie, 4}) = \{ \text{Barbie, Oppenheimer} \} = \{ x \in X \mid d(x, Barbie) < 3 \}$.

1.2 Normed Vector Spaces

Definition 1.2.1 – norm Let V be a vector space over \mathbb{R} . A norm on V is a function $\|\cdot\|: V \to \mathbb{R}$ such that

- Positivity: for all $u, v \in V$ we have $||u|| \ge 0$ and ||u|| = 0 if and only if u = 0.
- Non-degeneracy: for all $u \in V$ if ||u|| = 0 then u = 0.
- Absolute Homogeneity: for all $u \in V$ and for all $\lambda \in \mathbb{R}$ we have $||\lambda u|| = |\lambda|||u||$.
- Triangle inequality: for all $u, v \in V$ we have $||u + v|| \le ||u|| + ||v||$.

Example 1.2.2 Let $V = \mathbb{R}^n$. Then $\|\cdot\|_2 : \mathbb{R}^n \to \mathbb{R}$ defined by $\|x\|_2 = \sqrt{x_1^2 + \dots + x_n^2}$ is a norm on \mathbb{R}^n .

Proposition 1.2.3 – Let $(V, \|\cdot\|)$ be a normed vector space. Then the function $d: V \times V \to \mathbb{R}$ defined by $d(u, v) = \|u - v\|$ is a distance on V. And (V, d) is a metric space.

Remark 1.2.4 (Notation for Euclidean distance on \mathbb{R}^d and \mathbb{R}). We will usually write $\mathrm{dist}_{\mathbb{R}^d}$ instead of $\mathrm{dist}_{\|\cdot\|_2}$ for the standard (Euclidean) distance on \mathbb{R}^d . In particular, if $d \geq 2$, we have

$$\operatorname{dist}_{\mathbb{R}^d}(v, w) = \|v - w\|_2 = \sqrt{\sum_{i=1}^d (v_i - w_i)^2}$$

and if d = 1 we just have

$$dist_{\mathbb{R}} = |v - w|$$

And if there is no room for confusion, we will just leave out the subscript altogether and write dist instead of $\operatorname{dist}_{\mathbb{R}^d}$.

1.3 The reverse triangle inequality

Lemma 1.3.1 – Reverse triangle inequality Let $(V, \|\cdot\|)$ be a normed vector space. Then for all $u, v \in V$ we have,

$$|||v|| - ||w||| \le ||v - w||$$

2 Real Numbers

2.1 What are the real numbers?

Definition 2.1.1 – Real numbers The real numbers are a complete totally ordered field.

2.2 The completeness axiom

Definition 2.2.1 – Upper and Lower bound We say a number $M \in \mathbb{R}$ is an *upper bound* for a set $A \subseteq \mathbb{R}$ if

$$\forall a \in A[a \leq M].$$

We say a number $m \in \mathbb{R}$ is a *lower bound* for a set $A \subseteq \mathbb{R}$ if

$$\forall a \in A[a \ge M].$$

Given the definition of upper and lower bounds, we define what it means for a set to be bounded from above, bounded from below and just bounded.

Definition 2.2.2 – bounded from above, bounded from below, bounded A set $A \subseteq \mathbb{R}$ is *bounded from above* if there exists an upper bound for A.

A set $A \subseteq \mathbb{R}$ is *bounded from below* if there exists a lower bound for A.

A set $A \subseteq \mathbb{R}$ is *bounded* if it is bounded from above and bounded from below.

Definition 2.2.3 – Least upper bound (supremum) Precisely, *M* is a *least upper bound* of a subset *A* if both

- 1. *M* is an upper bound of *A*.
- 2. For every upper bound $L \in \mathbb{R}$ of A, it holds that $M \leq L$.

Proposition 2.2.4 – Suppose both M and W are a least upper bound of a subset $A \subseteq \mathbb{R}$. Then M = W.

Axiom 2.2.5 – Completeness axiom We say that a totally ordered field \mathbf{R} satisfies the *completeness axiom* if every nonempty subset of \mathbf{R} that is bounded from above has a least upper bound.

Lemma 2.2.6 – Every non-empty subset of the real line that is bounded from below has a *largest lower bound*.

Definition 2.2.7 – infimum We usually call the largest lower bound of a non-empty set $A \subseteq \mathbb{R}$ that is bounded from below the *infimum* of A, and we denote it by $\inf A$.

2.3 Alternative characterizations of suprema and infima

Proposition 2.3.1 – alternative characterizationa of supremum Let $A \subseteq \mathbb{R}$ be non-empty and bounded from above. Let $M \in \mathbb{R}$. Then M is the supremum of A if and only if

- 1. *M* is an upper bound for *A*,
- 2. and

for all
$$\varepsilon > 0$$
,
there exists $a \in A$,
 $a > M - \varepsilon$.

Proposition 2.3.2 – alternative characterizationa of infimum Let $A \subseteq \mathbb{R}$ be non-empty and bounded from below. Let $m \in \mathbb{R}$. Then m is the infimum of A if and only if

- 1. m is a lower bound for A,
- 2. and

for all
$$\varepsilon > 0$$
,
there exists $a \in A$,
 $a < m + \varepsilon$.

These alternative characterizations of the supremum and infimum really provide a standard way to determining the supremum and infimum of subsets of the real line.

2.4 Maxima and minima

Definition 2.4.1 – maximum and minimum Let $A \subseteq \mathbb{R}$ be a subset of the real numbers. We say that $y \in A$ is the *maximum* of A, and write $y = \max A$, if

for all
$$a \in A$$
, $a \le y$.

We say that $x \in A$ is the *minimum* of A, and write $x = \min A$, if

for all
$$a \in A$$
, $a \ge x$.

Remark 2.4.2. Even if a set $A \subseteq \mathbb{R}$ is non-empty and bounded, it may not have a maximum or minimum. For example, the set (0,1) has no maximum or minimum.

Proposition 2.4.3 – Let A be a subset of \mathbb{R} . If A has a maximum, then A is non-empty and bounded from above, and $\sup A = \max A$. If A has a minimum, then A is non-empty and bounded from below, and $\inf A = \min A$.

Proposition 2.4.4 Let A be a subset of \mathbb{R} . Assume that A is non-empty and bounded from above. If $\sup A \in A$ then A has a maximum and $\max A = \sup A$.

Proposition 2.4.5 – Let A be a subset of \mathbb{R} . Assume that A is non-empty and bounded from below. If $\inf A \in A$ then A has a minimum and $\min A = \inf A$.

2.5 The Archimedean property

Proposition 2.5.1 – Archimedeean property For every real number $x \in \mathbb{R}$ there exists a natural number $n \in \mathbb{N}$ such that x < n.

Given this proposition, we can define the ceiling function.

Definition 2.5.2 – ceiling function The *ceiling function* $\lceil \cdot \rceil : \mathbb{R} \to \mathbb{Z}$ is defined as follows. For $x \in \mathbb{R}$, $\lceil x \rceil$ denotes the smallest integer $z \in \mathbb{Z}$ such that $x \leq z$.

Proposition 2.5.3 – For every two real numbers $a, b \in \mathbb{R}$ with a < b there exists a $q \in \mathcal{Q}$ with a < q < b.

2.6 Computation rules for suprema

In the proposition below, we use the defintions

$$A + B = \{a + b \mid a \in A, b \in B\}$$

and

$$\lambda A = \{ \lambda a \mid a \in A \}$$

for subsets $A, B \subseteq \mathbb{R}$ and a scalar $\lambda \in \mathbb{R}$.

Proposition 2.6.1 – Let A, B, C, D be non-empty subsets of \mathbb{R} . Assume that A and B are bounded from above and C and D are bounded from below. Then

- 1. $\sup(A+B) = \sup A + \sup B$.
- 2. $\inf(C+D) = \inf C + \inf D$.
- 3. For all $\lambda \geq 0$, $\sup(\lambda A) = \lambda \sup A$.
- 4. For all $\lambda \leq 0$, $\sup(\lambda A) = \lambda \inf A$.
- 5. $\sup(-C) = -\inf C$.
- 6. $\inf(-C) = -\sup C$.

2.7 Bernoulli's inequality

Proposition 2.7.1 – Bernoulli's inequality Let $x \in \mathbb{R}$ and $n \in \mathbb{N}$. Then

- 1. If $x \ge -1$, then $(1+x)^n \ge 1 + nx$.
- 2. If $x \ge 0$ and $n \ge 2$, then $(1+x)^n \ge 1 + nx$.

3 Sequences

3.1 Sequence

Definition 3.1.1 – Sequence A sequence is a function for which the domain is \mathbb{N} .

$$a: \mathbb{N} \to Y$$

Y can be any set.

Example 3.1.2 Here are some functions that are sequences:

- 1. $a: \mathbb{N} \to \mathbb{Q}$
- 2. $b: \mathbb{N} \to (\mathbb{N} \to Y)$
- 3. $c: \mathbb{N} \to \mathbb{N}$

And some functions that are not sequences:

- 1. $d: (\mathbb{N} \to \mathbb{N}) \to \mathbb{N}$
- 2. $e: \mathbb{Q} \to \mathbb{N}$

3.2 Terminology around sequences

3.2.1 Bounded sequences

Definition 3.2.2 – bouneded sequence Let (X, dist) be a metric space. We say a sequence $a : \mathbb{N} \to X$ is bounded if

```
there exists q \in X,
there exists M > 0,
for all n \in \mathbb{N},
\operatorname{dist}(a_n, q) \leq M.
```

In a normed linear space, we can use a simpler criterion to check whether a sequence is bounded. That is the content of the following proposition.

Proposition 3.2.3 – Let $(V, \|\cdot\|)$ be a normed vector space. Let $a : \mathbb{N} \to V$ be a sequence. The sequence a is bounded if and only if

there exists
$$M > 0$$
,
for all $n \in \mathbb{N}$,
 $||a_n|| \le M$.

3.3 Convergence of sequences

Definition 3.3.1 – Convergence of sequences Let (X, dist) be a metric space. We say that a sequence $a : \mathbb{N} \to X$ converges to a point $p \in X$ if

for all
$$\varepsilon > 0$$
,
there exists $N \in \mathbb{N}$,
for all $n \ge N$,
 $\operatorname{dist}(a_n, p) < \varepsilon$.

We sometimes write

$$\lim_{n\to\infty} a_n = p$$

to express that the sequence (a_n) converges to p.

Definition 3.3.2 – Divergence of sequences Let (X, dist) be a metric space. A sequence $a : \mathbb{N} \to X$ is called *divergent* is it is not convergent.

3.4 Examples and limits of simple sequences

Proposition 3.4.1 – The constant sequence Let (X, dist) be a metric space. Let $p \in X$ and assume that the sequence (a_n) is given by $a_n = p$ for every $n \in \mathbb{N}$. We also say that (a_n) is a constant sequence. Then $\lim_{n\to\infty} = p$.

Example 3.4.2 A standard limit Let $a : \mathbb{N} \to \mathbb{R}$ be a real-valued sequence such that $a_n = 1/n forn \ge 1$. Then $a : \mathbb{N} \to \mathbb{R}$ converges to 0.

Proof. Let $\varepsilon > 0$. Choose $N = \lceil 1/\varepsilon \rceil + 1$. Take $n \ge N$. Then

$$\operatorname{dist}_{\mathbb{R}}(a_n, 0) = |a_n - 0| = |1/n| = 1/n \le 1/N < \varepsilon.$$

3.5 Uniqueness of limits

Proposition 3.5.1 – Uniqueness of limits Let (X, dist) be a metric space and let $a : \mathbb{N} \to \mathbb{R}$ be a sequence in X. Assume that $p, q \in X$ and assume that

$$\lim_{n\to\infty} = p$$
 and $\lim_{n\to\infty} a_n = q$

Then p = q.

3.6 More properties of convergent sequences

Proposition 3.6.1 – Let (X, dist) be a metric space and suppose that $a : \mathbb{N} \to X$ is a sequence. Let $p \in X$. Then the sequence $a : \mathbb{N} \to X$ converges to p if and only if the real-valued sequence

$$n \mapsto \operatorname{dist}(a_n, p)$$

converges to 0 in \mathbb{R} .

Proposition 3.6.2 – Convergent sequences are bounded Let (X, dist) be a metric space. Let $a : \mathbb{N} \to X$ be a sequence in X converging to $p \in X$. Then the sequence $a : \mathbb{N} \to X$ is bounded.

Proposition 3.6.3 – Let (X, dist) be a metric space and let $a : \mathbb{N} \to X$ and $b : \mathbb{N} \to X$ be two sequences. Let $p \in X$ and suppose that $\lim_{n \to \infty} a_n = p$. Then $\lim_{n \to \infty} b_n = p$ if and only if

$$\lim \operatorname{dist}(a_n,b_n)=0$$

Corollary 3.6.4 – Eventually equal sequences have the same limit Let (X, dist) be a metric space and

let $a : \mathbb{N} \to X$ and $b : \mathbb{N} \to X$ be two sequences such that there exists an $N \in \mathbb{N}$ such that for all $n \ge N$,

$$a_n = b_n$$

Then the sequence $a: \mathbb{N} \to X$ converges if and only if the sequence $b: \mathbb{N} \to X$ converges. If the sequences converge, they have the same limit.

3.7 Limit theorems for sequences taking values in a normed vector space

Theorem 3.7.1 – Let $(V, \|\cdot\|)$ be a normed vector space and let $a: \mathbb{N} \to V$ and $b: \mathbb{N} \to V$ be two sequences. Assume that the $\lim_{n\to\infty} a_n$ exists and is equal to $p\in V$ and that the $\lim_{n\to\infty} b_n$ exists and is equal to $q\in V$. Let $\lambda: \mathbb{N} \to \mathbb{R}$ be a real-valued sequence. Let $\mu\in \mathbb{R}$. Assume that $\lim_{n\to\infty} \lambda_n = \mu$. Then

- 1. The $\lim_{n\to\infty}(a_n+b_n)$ exists and is equal to p+q.
- 2. The $\lim_{n\to\infty}(\lambda_n a_n)$ exists and is equal to μp .

3.8 Index shift

Proposition 3.8.1 – Index shift Let (X, dist) be a metric space and let $a : \mathbb{N} \to X$ be a sequence. Let $k \in \mathbb{N}$ and $p \in X$. Then the sequence $a : \mathbb{N} \to X$ converges to p if and only if the sequence $(a_{n+k})_n$ (i.e. the sequence $n \mapsto a_{n+k}$) converges to p.

4 Real-valued sequences

4.1 Terminology

Definition 4.1.1 – increasing, decreasing and monotone sequences We say a sequence (a_n) is

- 1. *increasing* if for every $n \in \mathbb{N}$, $a_{n+1} \ge a_n$
- 2. *strictly increasing* if for every $n \in \mathbb{N}$, $a_{n+1} > a_n$
- 3. *decreasing* if for every $n \in \mathbb{N}$, $a_{n+1} \leq a_n$
- 4. *strictly decreasing* if for every $n \in \mathbb{N}$, $a_{n+1} < a_n$
- 5. monotone if it is either increasing or decreasing
- 6. strictly monotone if it is either strictly increasing or strictly decreasing

Definition 4.1.2 – upper bound and lower bound for a sequence We say that a number $M \in \mathbb{R}$ is an *upper bound* for a sequence $a : \mathbb{N} \to \mathbb{R}$ if

for all
$$n \in \mathbb{N}$$

$$a_n \leq M$$

We say that a number $m \in \mathbb{R}$ is a *lower bound* for a sequence $a : \mathbb{N} \to \mathbb{R}$ if

for all
$$n \in \mathbb{N}$$

$$a_n \ge m$$

Definition 4.1.3 – bounded sequence We say that a sequence $a : \mathbb{N} \to \mathbb{R}$ is *bounded above* if there exists an $M \in \mathbb{R}$ such that M is an upper bound for a.

We say that a sequence $a : \mathbb{N} \to \mathbb{R}$ is *bounded below* if there exists an $m \in \mathbb{R}$ such that m is a lower bound for a.

Proposition 4.1.4 – Let $a : \mathbb{N} \to \mathbb{R}$ be a sequence. Then $a : \mathbb{N} \to \mathbb{R}$ is bounded if and only if it is both bounded above and bounded below.

4.2 Monotone, bounded sequences and convergent

Theorem 4.2.1 – Let (a_n) be an increasing sequence that is bounded from above. Then (a_n) convergent and

$$\lim_{n\to\infty} a_n = \sup_{n\in\mathbb{N}} a_n \quad (= \sup\{a_n \mid n\in\mathbb{N}\})$$

Theorem 4.2.2 – Let (a_n) be a decreasing sequence that is bounded from below. Then (a_n) is convergent and

$$\lim_{n\to\infty}a_n=\inf_{n\in\mathbb{N}}a_n\quad (=\inf\{a_n\mid n\in\mathbb{N}\})$$

4.3 Limit theorems

Theorem 4.3.1 – Limit theorems for real-valued sequences Let $a : \mathbb{N} \to \mathbb{R}$ and $b : \mathbb{N} \to \mathbb{R}$ be two converging sequences, and let $c, d \in \mathbb{R}$ be real numbers such that

$$\lim_{n\to\infty}a_n=c \text{ and } \lim_{n\to\infty}b_n=d.$$

Then

- 1. The $\lim_{n\to\infty} (a_n+b_n)$ exists and is equal to c+d.
- 2. The $\lim_{n\to\infty}(a_nb_n)$ exists and is equal to $c\cdot d$.
- 3. If $d \neq 0$, then $\lim_{n \to \infty} \left(\frac{a_n}{b_n}\right)$ exists and is equal to $\frac{c}{d}$.
- 4. For every non-negative integer $m \in \mathbb{N}$, the limit $\lim_{n \to \infty} (a_n)^m$ exists and is equal to c^m .
- 5. If for every $n \in \mathbb{N}$, the number a_n is non-negative, then for every positive integer $k \in \mathbb{N} \setminus \{0\}$, the limit $\lim_{n\to\infty} (a_n)^{\frac{1}{k}}$ exists and is equal to $c^{\frac{1}{k}}$.

4.4 The squeeze theorem

Theorem 4.4.1 – The squeeze theorem Let $a,b,c: \mathbb{N} \to \mathbb{R}$ be three sequences. Suppose that there exists an $N \in \mathbb{N}$ such that for every $n \ge N$, we have

$$a_n \leq b_n \leq c_n$$

and assume $\lim_{n\to\infty} a_n = \lim_{n\to\infty} c_n - L$ for some $L \in \mathbb{R}$. Then $\lim_{n\to\infty} b_n$ exists and is equal to L.

4.5 Divergence to ∞ and $-\infty$

Definition 4.5.1 – We say a sequence $a: \mathbb{N} \to \mathbb{R}$ diverges to ∞ and write

$$\lim_{n\to\infty}=\infty$$

if

for all $M \in \mathbb{R}$, there exists $N \in \mathbb{N}$, for all $n \ge N$, $a_n > M$.

Similarly, we say a sequence (a_n) diverges to $-\infty$ and write

$$\lim_{n\to\infty}a_n=-\infty$$

if

for all $M \in \mathbb{R}$, there exists $N \in \mathbb{N}$, for all $n \ge N$, $a_n < M$. **Proposition 4.5.2** – Let $a : \mathbb{N} \to \mathbb{R}$ be a sequence such that

$$\lim_{n\to\infty}a_n=\infty.$$

Then the sequence (a_n) is bounded from below. Similarly, let $b : \mathbb{N} \to \mathbb{R}$ be a sequence such that

$$\lim_{n\to\infty}b_n=-\infty.$$

Then the sequence (b_n) is bounded from above.

4.6 Limit theorems for improper limits

Theorem 4.6.1 – Limit theorems for improper limits Let $a,b,c,d:\mathbb{N}\to\mathbb{R}$ be four sequences such that

$$\lim_{n\to\infty} a_n = \infty$$
 and $\lim_{n\to\infty} c_n = -\infty$

the sequence (b_n) is bounded from below and the sequence (d_n) is bounded from above. Let $\lambda : \mathbb{N} \to \mathbb{R}$ be a sequence bounded below by some $\mu > 0$. Then

i.
$$\lim_{n\to\infty}(a_n+b_n)=\infty$$

ii.
$$\lim_{n\to\infty}(c_n+d_n)=-\infty$$

iii.
$$\lim_{n\to\infty}(\lambda_n a_n)=\infty$$

iv.
$$\lim_{n\to\infty}(\lambda_n c_n)=-\infty$$

Proposition 4.6.2 – Let $a: \mathbb{N} \to \mathbb{R}$ and $b: \mathbb{N} \to (0, \infty)$ be two sequences. Then

1.
$$\lim_{n\to\infty} a_n = \infty$$
 if and only if $\lim_{n\to\infty} (-a_n) = -\infty$.

2.
$$\lim_{n\to\infty} b_n = \infty$$
 if and only if $\lim_{n\to\infty} \frac{1}{b_n} = 0$.

4.7 Standard sequences

4.7.1 Geometric sequence

Proposition 4.7.2 – Standard limit of of geometric sequence Let $q \in \mathbb{R}$. The sequence (a_n) defined by $a_n := q^n$ for $n \in \mathbb{N}$

- converges to 0 if $q \in (-1,1)$
- converges to 1 if q = 1
- diverges to ∞ if q > 1
- diverges, but not to ∞ or $-\infty$ if $q \le -1$

4.7.3 The n^{th} root of n

Proposition 4.7.4 – Standard limit of the n^{th} **root of** n The sequence (a_n) defined by $a_n := \sqrt[n]{n}$ for $n \in \mathbb{N}$ converges to 1.

Corollary 4.7.5 – Let a > 0. Then the sequence (b_n) defined by $b_n := \sqrt[n]{a}$ converges to 1.

4.7.6 The number e

First let's define the sequence (a_n) by

$$a_n := \left(1 + \frac{1}{n}\right)^n$$
.

We show that (a_n) is increasing and bounded from above by 3. Hence (a_n) converges to some $e \in \mathbb{R}$ by the monotone convergence theorem.

Lemma 4.7.7 – The sequence (a_n) defined by $a_n := \left(1 + \frac{1}{n}\right)^n$ for $n \in \mathbb{N} \setminus \{0\}$ and $a_0 = 1$ is increasing.

Lemma 4.7.8 – The sequence (a_n) defined by $a_n := (1 + \frac{1}{n})^n$ for $n \in \mathbb{N} \setminus \{0\}$ and $a_0 = 1$ is bounded from above by 3.

By these two lemmas, the sequence

$$n \mapsto \left(1 + \frac{1}{n}\right)^n$$

converges.

Definition 4.7.9 – (**Standard limit of** e) We define the number e by

$$e := \lim_{n \to \infty} \left(1 + \frac{1}{n} \right)^n.$$

4.7.10 Exponentials beat powers

- 5 Series
- 5.1 Geometric series
- **5.2** The harmonic series
- 5.3 The hyperharmonic series
- 5.4 Only the tail matters for convergence
- 5.5 Divergence test
- 5.6 Limit laws for series

- 6 Series with positive terms
- 6.1 Comparison test
- **6.2** Limit comparison test
- 6.3 Ratio test
- 6.4 Root test

- 7 Series with general terms
- 7.1 Series with real terms: the Leibniz test
- 7.2 Series charactersization of completeness in normed vector space
- 7.3 The Cauchy product

- 8 Subsequences, lim sup and liminf
- 8.1 Index sequences and subsequences
- 8.2 (Sequential) accumulation points
- 8.3 Subsequences of a converging sequence
- **8.4** lim sup
- **8.5** liminf
- 8.6 Relations between lim, lim sup and liminf

9 Point-set topology of metric spaces

- 9.1 Open sets
- 9.2 Closed sets
- 9.3 Cauchy sequences
- 9.4 Completeness
- 9.5 Series characterization of completeness in normed vector spaces

- 10 Compactness
- 10.1 Boundedness and total boundedness
- 10.2 Alternative characterization of compactness

11 Limits and continuity

- 11.1 Accumulation points
- 11.2 Limit in an accumulation point
- 11.3 Uniqueness of limits
- 11.4 Sequential characterization of limits
- 11.5 Limit laws
- 11.6 Continuity
- 11.7 Sequential characterization of continuity
- 11.8 Rules for continuous functions
- 11.9 Images of compact sets under continuous functions are compact
- 11.10 Uniform continuity

12 Real-valued functions

- 12.1 More limit laws
- 12.2 Building of standard functions
- 12.3 Continuity of standard functions
- 12.4 Limits from the left and from the right
- 12.5 The extended real line
- 12.6 Limits to ∞ or $-\infty$
- 12.7 Limits at ∞ and $-\infty$
- 12.8 The Intermediate Value Theorem
- 12.9 The Extreme Value Theorem
- 12.10 Equivalence of norms
- 12.11 Bounded linear maps and operator norms

13 Differentiability

- 13.1 The derivative as a function
- 13.2 Constant and linear maps are differentiable
- 13.3 Bases and coordinates
- 13.4 The matrix representation
- 13.5 The chain rule
- 13.6 Sum, product and quotient rules
- 13.7 Differentiability of components
- 13.8 Differentiability implies continuity
- 13.9 Derivative vanishes in local maxima and minima
- 13.10 The Mean Value Theorem

14 Differentiability of standard functions

- 14.1 Global context
- 14.2 Polynomials and rational functions are differentiable
- 14.3 Differentiability of the standard functions

15 Directional and partial derivatives

- 15.1 A recurring and very important construction
- 15.2 Directional derivatives
- 15.3 Partial derivatives
- 15.4 The Jacobian of a map
- 15.5 Linearization and tangent planes
- 15.6 The gradient of a function

- 16 The Mean-Value Inequality
- 16.1 The mean-value inequality for functions defined on an interval
- 16.2 The mean-value inequality for functions on general domains
- 16.3 Continuous partial derivatives imply differentiability

17 Higher order derivatives

- 17.1 Multilinear maps
- 17.2 Relation to *n*-fold directional derivatives
- 17.3 A criterion for higher differentiability
- 17.4 Symmetry of second order derivatives
- 17.5 Symmetry of higher-order derivatives

- 18 Polynomials and approximation by polynomials
- **18.1** Homogeneous polynomials
- 18.2 Taylor's theorem
- 18.3 Taylor approximations of standard functions

19 Banach fixed point theorem

20 Implicit function theorem

- 20.1 The objective
- 20.2 Notation
- 20.3 The implicit function theorem
- **20.4** The inverse function theorem

21 Function sequences

- 21.1 Point-wise convergence
- 21.2 Uniform convergence
- 21.3 Preservation of continuity under uniform convergence
- 21.4 Differentiability theorem
- 21.5 The normed vector space of bounded functions

- 22 Function series
- 22.1 The Weierstrass M-test
- 22.2 Conditions for differentiation of function series

- 23 Power series
- 23.1 Convergence of power series
- 23.2 Standard functions defined as power series
- 23.3 Operations with power series
- 23.4 Differentiation of power series
- 23.5 Taylor series

24 Riemann integration in one dimension

- 24.1 Riemann integrable functions and the Riemann integral
- 24.2 Sums, products of Riemann integrable functions
- 24.3 Continuous functions are Riemann integrable
- 24.4 The fundamental theorem of calculus

25 Riemann integration in multiple dimensions

- 25.1 Partitions in multiple dimensions
- **25.2** Riemann integral on rectangles in \mathbb{R}^n
- 25.3 Properties of the multidimensional Riemann integral
- 25.4 Continuous functions are Riemann integrable
- 25.5 Fubini's theorem
- 25.6 The (topological) boundary of a set
- 25.7 Jordan content
- 25.8 Integration over general domains
- 25.9 The volume of bounded sets

- **26** Change-of-variables Theorem
- **26.1** Polar coordinates
- 26.2 Cylindrical coordinates
- **26.3** Spherical coordinates