### 2IL50 Data Structures

2023-24 Q3

Lecture 8: Augmenting Data Structures



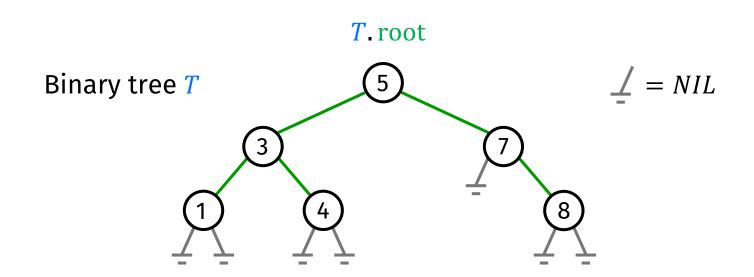
### Announcement

Next Monday March 11 only two lecture rooms: AUD 3 and AUD 6

# **Binary Search Trees**

# Binary search trees

```
root of T denoted by T.root
internal nodes have four fields:
    key (and possible other satellite data)
    left: points to left child
    right: points to right child
    p: points to parent. T.root. p = NIL
```



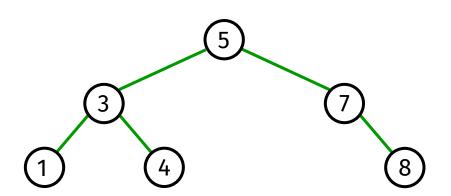
# Binary search trees

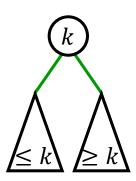
### A binary tree is

- a leaf or
- a root node x with a binary tree as its left and/or right child

#### Binary-search-tree property

- $\blacksquare$  if y is in the left subtree of x, then y. key  $\leq x$ .key
- if y is in the right subtree of x, then y. key  $\geq x$ .key





# Minimizing the running time

All operations can be executed in time proportional to the height h of the tree (instead of proportional to the number n of nodes in the tree)

Worst case:  $\Theta(n)$ 

Solution: guarantee small height (balance the tree)

$$\rightarrow h = \Theta(\log n)$$

#### Balanced binary search trees

Search, Minimum, Maximum, Predecessor, Successor, Insert, and Delete can be executed in time  $\Theta(\log n)$ .

# Red-black Trees

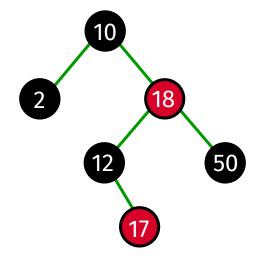
### Red-black trees

#### Red-black tree

binary search tree where each node has a color attribute which is either red or black

#### Red-black properties

- Every node is either red or black.
- 2. The root is black.
- 3. Every leaf (NIL) is black.
- 4. If a node is red, then both its children are black. (Hence no two reds in a row on a simple path from the root to a leaf)
- 5. For each node, all paths from the node to descendant leaves contain the same number of black nodes.



#### Lemma

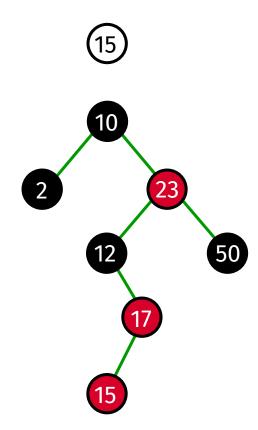
A red-black tree with n nodes has height  $\leq 2 \log(n+1)$ .

### Red-black trees: Insertion

- 1. Do a regular binary search tree insertion
- 2. Fix the red-black properties

#### Step 1

- find the leaf where the node should be inserted
- replace the leaf by a red node that contains the key to be inserted



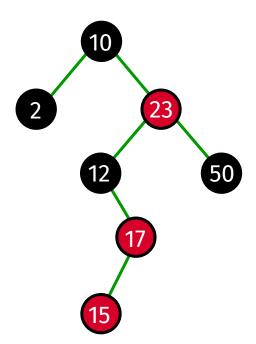
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- 1. Do a regular binary search tree insertion
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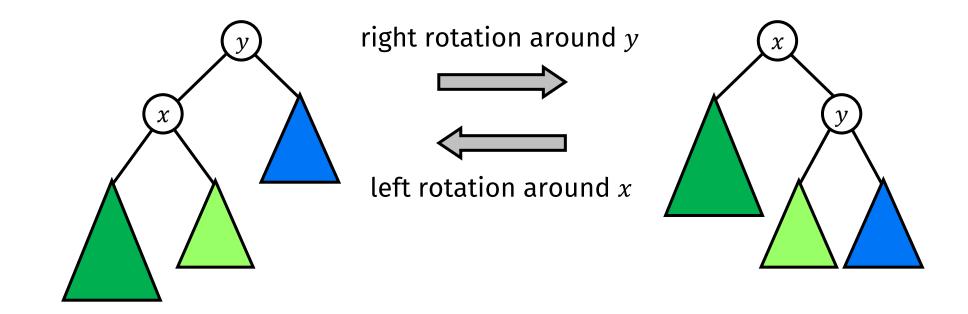
#### Red-black properties

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- 3. Every leaf (NIL) is black.
- 4. If a node is red, then both its children are black.
- 5. For each node, all paths from the node to descendant leaves contain the same number of black nodes.

The new node is red → Property 2 or 4 can be violated. Remove the violation by rotations and recoloring.



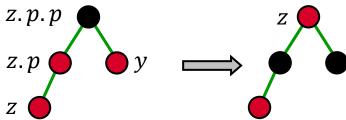
# Rotation



# Step 2: Fixing the red-black properties

Invariant: z and z. p are both red and this is the only red-black violation (or z is a red root  $\Rightarrow$  just recolor and terminate)

```
while z \neq T. root and z.p is red if z.p == z.p.p. left y = z.p.p. right case i: y is red
```



color z.p and y black, color z.p.p red

$$z = z.p.p$$

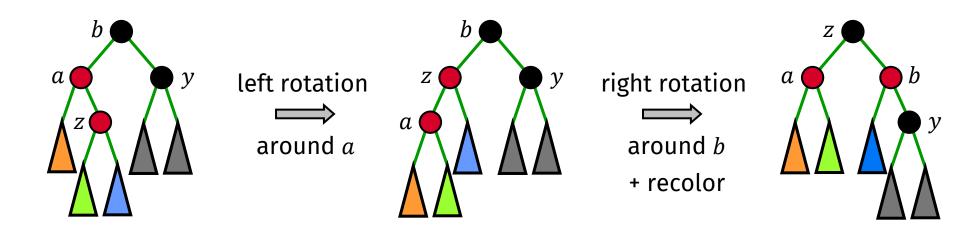
continue up the tree

else ... // symmetric case

# Step 2: Fixing the red-black properties

Invariant: z and z. p are both red and this is the only red-black violation (or z is a red root  $\Rightarrow$  just recolor and terminate)

case ii and iii: y is black

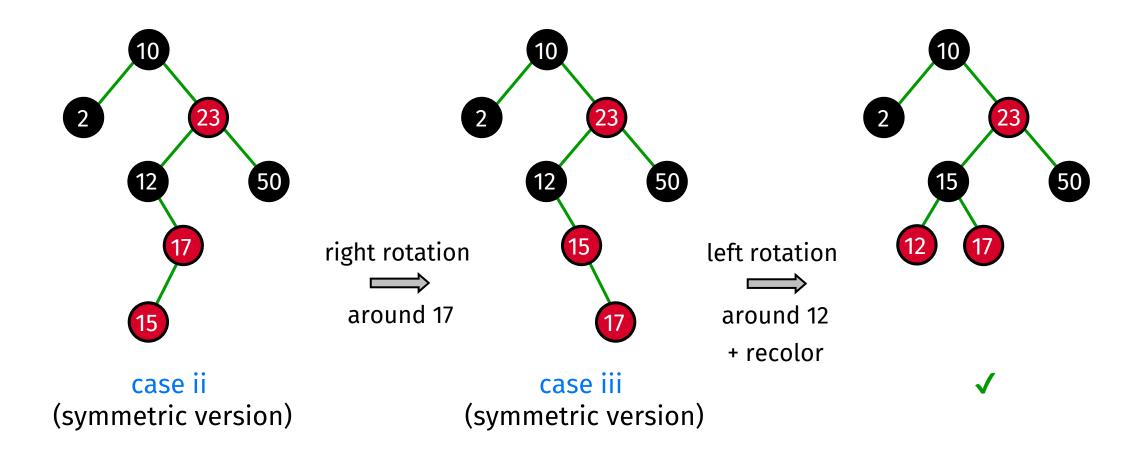


case ii: z == z.p. right

case iii: a == a.p. left

### Red-black trees: Insertion

- 1. Do a regular binary search tree insertion
- 2. Fix the red-black properties



### Red-black trees: Insertion

- 1. Do a regular binary search tree insertion
- 2. Fix the red-black properties
  - move up the tree as long as case i occurs and recolor accordingly
  - as soon as case ii or iii occurs at most two rotations and two recolorings ✓
  - $\blacksquare$  if you reach the root or the parent of z is black  $\checkmark$

Running time?  $O(\text{height of the tree}) = O(\log n)$ 

### Red-black trees: Deletion

- 1. Do a regular binary search tree deletion
- 2. Fix the red-black properties
  - Slightly more complicated case distinction than insertion see book for details
  - can be done by recoloring as before and at most three rotations

Search, insert, and delete can be executed with a red-black tree in  $O(\log n)$  time.

# **Augmenting Data Structures**

### Data structures

Data structures are used in many applications

directly: the user repeatedly queries the data structure

indirectly: to make algorithms run faster

In most cases a standard data structure is sufficient (possibly provided by a software library)

But sometimes one needs additional operations that are not supported by any standard data structure

need to design new data structure?

Not always: often augmenting an existing structure is sufficient

# Example

S set of elements, each with a unique key.

#### **Operations**

Search(S, k): return a pointer to an element x in S with x. key = k, or NIL if such an element does not exist.

OS-Select(S, i): return a pointer to an element x in S with the i<sup>th</sup> smallest key (the key with rank i)

**Solution:** sorted array

 A
 2
 5
 6
 9
 10
 11
 24
 27
 31
 35
 41
 43
 54
 55
 73

the key with rank i is stored in A[i]

## Example

S set of elements, each with a unique key.

#### **Operations**

```
Search(S, k): return a pointer to an element x in S with x. key = k, or NIL if such an element does not exist.
OS-Select(S, i): return a pointer to an element x in S with the i<sup>th</sup> smallest key (the key with rank i)
Insert(S, x): inserts element x into S, that is, S ← S ∪ {x}
Delete(S, x): remove element x from S
```

#### Solution?

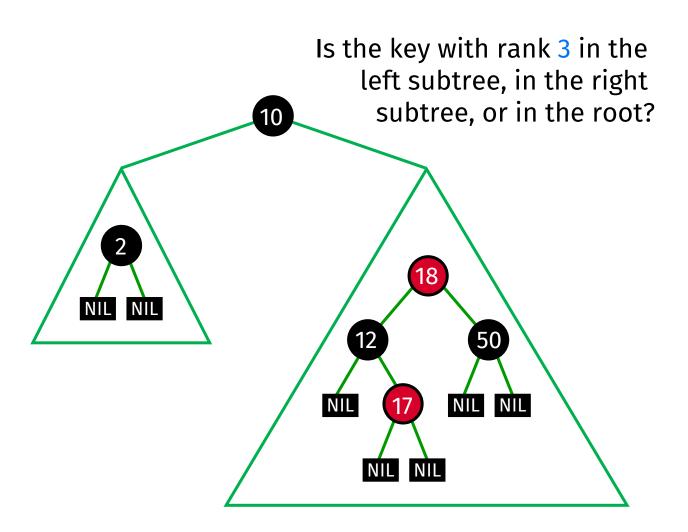
### Use red-black trees

OS-Select(S, 3): report key with rank 3

Idea 1: store the rank of each node in the node

2

2 1



### Use red-black trees

OS-Select(S, 3): report key with rank 3

Idea 1: store the rank of each node in the node



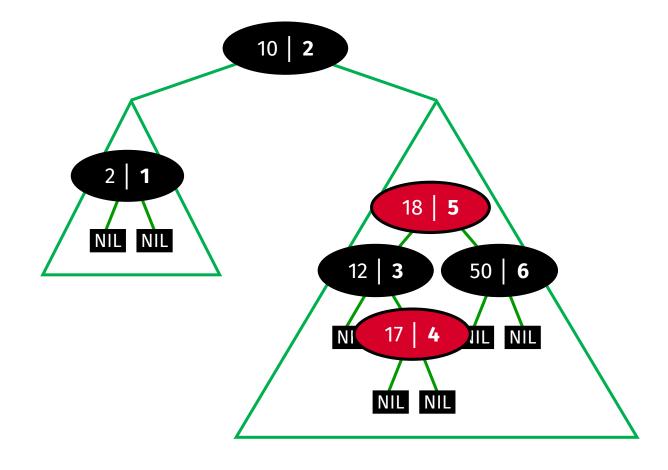


#### Problem:

Insertion can change the rank of every node!

Worst case O(n)

Idea 2: store the size of the subtree in each node

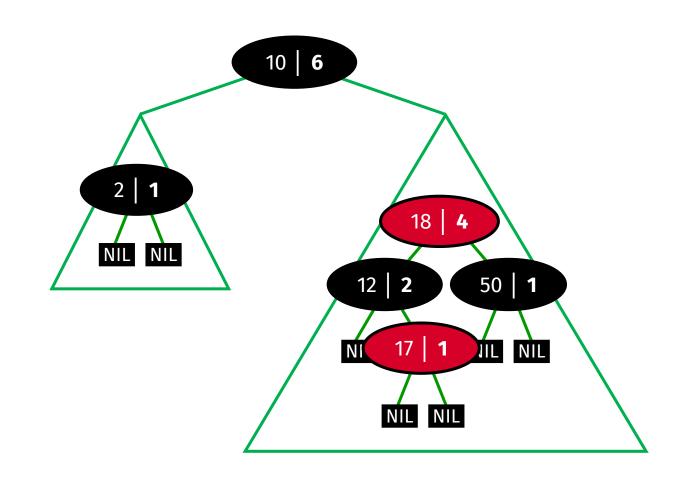


### Idea 2: store the size of the subtree

#### Store in each node *x*:

- $\blacksquare$  x. left, x. right
- $\blacksquare$  x. parent
- $\blacksquare$  x.key
- $\blacksquare$  x. color
- x. size = number of keys insubtree rooted at x(NIL. size = 0)

Order-Statistic tree



### Order-statistic trees: OS-Select

OS-Select(x, i): return pointer to node containing the i<sup>th</sup> smallest key of the subtree rooted at x

```
OS-Select(x, i)

1 r = x. left. size + 1

2 if i == r

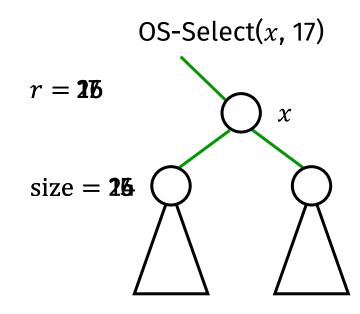
3 return x

4 elseif i < r

5 return OS-Select(x. left, i)

6 else

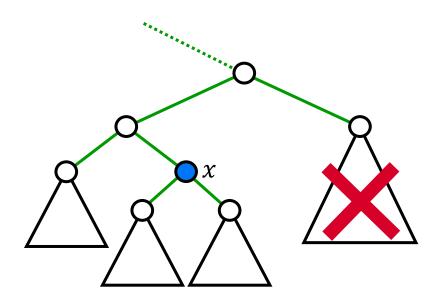
7 return OS-Select(x. right, i - r)
```



Running time?  $O(\log n)$ 

## Order-statistic trees: OS-Rank

OS-Rank(T, x): return the rank of x in the linear order determined by an inorder walk of T = 1 + number of keys smaller than x



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OS-Rank(T, x)

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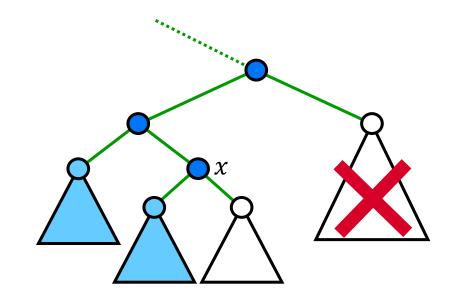
2 y = x

3 while y \neq T. root

4 if y == y. p. right

5 r = r + y. p. left. size + 1

6 y = y. p
```



Running time?  $O(\log n)$ 

### **OS-Rank: Correctness**

```
OS-Rank(T, x)

1 r = x. left. size + 1

2 y = x

3 while y \neq T. root

4 if y == y. p. right

5 r = r + y. p. left. size + 1

6 y = y. p
```

#### **Invariant**

At the start of each iteration of the **while** loop, r = rank of x. key in  $T_v$ 

subtree with root *y* 

#### **Initialization**

 $r = \text{rank of } x. \text{ key in } T_x \quad (y = x)$ 

= number of keys smaller than x. key in  $T_x + 1$ 

= x. left. size + 1 (binary-search-tree property)

### **OS-Rank: Correctness**

```
OS-Rank(T, x)

1 r = x. left. size + 1

2 y = x

3 while y \neq T. root

4 if y == y. p. right

5 r = r + y. p. left. size + 1

6 y = y. p
```

#### **Invariant**

At the start of each iteration of the **while** loop, r = rank of x. key in  $T_y$ 

#### **Termination**

loop terminates when y = T. root

- → subtree rooted at *y* is entire tree
- $\rightarrow r = \text{rank of } x. \text{ key in entire tree}$

### **OS-Rank: Correctness**

```
OS-Rank(T, x)

1 r = x.left.size + 1

2 y = x

3 while y \neq T.root

4 if y == y.p.right

5 r = r + y.p.left.size + 1

6 y = y.p
```

#### **Invariant**

At the start of each iteration of the **while** loop, r = rank of x. key in  $T_v$ 

### Maintenance case i: $y = y \cdot p$ right

- → all keys in  $T_{y.p.left}$  and y.p.key are smaller than x.key
- → rank x. key in  $T_{y.p}$  = rank x. key in  $T_y + y$ . p. left. size + 1

case ii: 
$$y = y \cdot p \cdot \text{left}$$

- $\rightarrow$  all keys in  $T_{y.p.right}$  and y.p. key are larger than x. key
- $\rightarrow$  rank x. key in  $T_{y.p} = \text{rank } x$ . key in  $T_y$

### Order-statistic trees: Insertion and deletion

Insertion and deletion

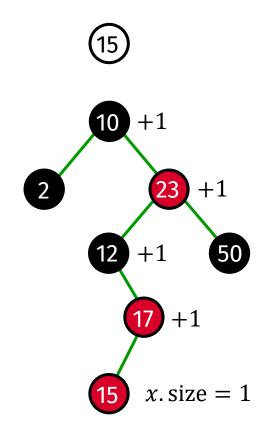
as in a regular red-black tree, but we have to update x. size field

### Red-black trees: Insertion

- 1. Do a regular binary search tree insertion
- 2. Fix the red-black properties

#### Step 1

- find the leaf where the node should be inserted
- replace the leaf by a red node that contains the key to be inserted
- $\blacksquare$  size of the new node = 1
- increment size of each node on the search path



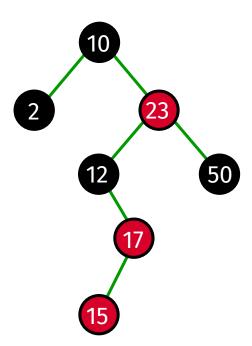
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- 1. Do a regular binary search tree insertion
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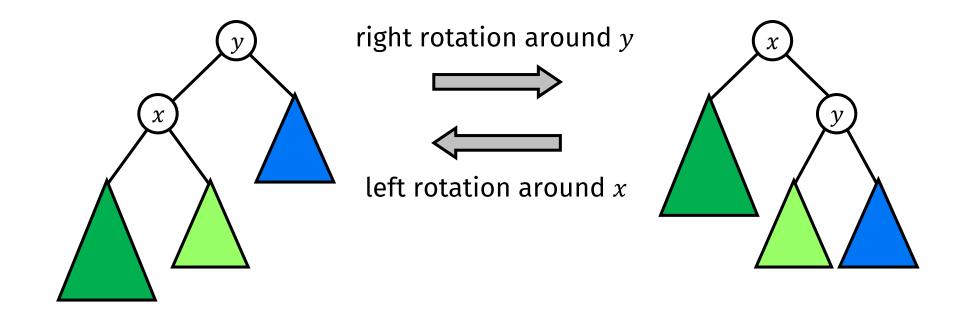
#### Red-black properties

- Every node is either red or black.
- 2. The root is black.
- 3. Every leaf (NIL) is black.
- 4. If a node is red, then both its children are black.
- 5. For each node, all paths from the node to descendant leaves contain the same number of black nodes.

The new node is red → Property 2 or 4 can be violated. Remove the violation by rotations and recoloring.



### Rotation



A rotation affects only x. size and y. size

We can determine the new values based on the size of children:

$$x$$
. size =  $x$ . left. size +  $x$ . right. size + 1

### Order-statistic trees

The operations Insert, Delete, Search, OS-Select, and OS-Rank can be executed with an order-statistic tree in  $O(\log n)$  time.

# Augmenting data structures

#### Methodology for augmenting a data structure

- 1. Choose an underlying data structure.
- 2. Determine additional information to maintain.
- 3. Verify that we can maintain additional information for existing data structure operations.
- 4. Develop new operations.

You don't need to do these steps in strict order!

Red-black trees are very well suited to augmentation ...

#### OS tree

- 1. R-B tree
- 2. *x*. size
- 3. maintain size during insert and delete
- 4. OS-Select and OS-Rank

# Augmenting red-black trees

#### Theorem [RB-tree Augmentation]

Augment an RB-tree with field f, where x. f depends only on information in x, x. left, and x. right (including x. left. f and x. right. f). Then we can maintain values of f in all nodes during insert and delete without affecting  $O(\log n)$  performance.

When we alter information in x, changes propagate only upward on the search path for x ...

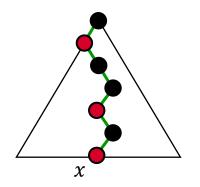
## Augmenting red-black trees

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### Proof (insert)

Step 1 Do a regular binary search tree insertion



go up from inserted node and update f additional time:  $O(\log n)$ 

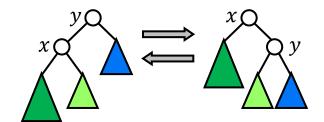
## Augmenting red-black trees

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### Proof (insert)

Step 2 Fix the red-black properties by rotations and recoloring



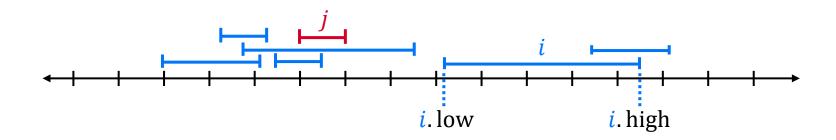
update f for x, y, and their ancestors additional time per rotation:  $O(\log n)$ 

Example: Interval Trees

### Interval trees

S set of closed intervals

closed: endpoints are part of the interval



#### **Operations**

Interval-Insert(T, x): adds an interval x, whose int field is assumed to contain an interval, to the interval tree T.

Interval-Delete(T, x): removes the element x from the interval tree T.

Interval-Search(T, j): returns pointer to a node x in T such that x, int overlaps j, or NIL if no such element exists.

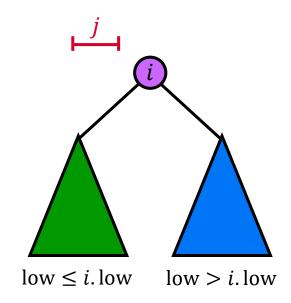
- 1. Choose an underlying data structure.
- 2. Determine additional information to maintain.
- 3. Verify that we can maintain additional information for existing data structure operations.
- 4. Develop new operations.

- 1. Choose an underlying data structure.
  - use red-black trees
    - $\blacksquare$  each node x contains interval x. int
    - $\blacksquare$  key is left endpoint x. int. low

inorder walk would list intervals sorted by low endpoint

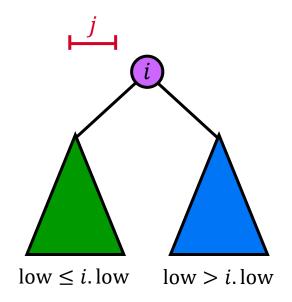
- 2. Determine additional information to maintain.
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- Choose an underlying data structure. ✓
- 2. Determine additional information to maintain.
- 3. Verify that we can maintain additional information for existing data structure operations.
- 4. Develop new operations.



case 1:  $i \cap j \neq \emptyset$  report i

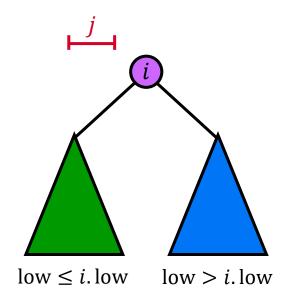




```
case 1: i \cap j \neq \emptyset report i

case 2: j lies left of i
j cannot overlap any interval in the right subtree
```



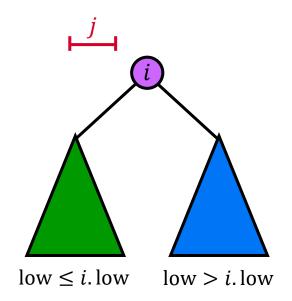


```
case 1: i \cap j \neq \emptyset report i
```

```
case 2: j lies left of i
j cannot overlap any interval in the right subtree
```

```
case 3: j lies right of i need additional information!
```

```
x. \max = \max \text{ endpoint value in subtree rooted at } x
= \max\{i. \text{ high where } i \text{ is stored in the subtree rooted at } x\}
```



i. low  $\leq i$ . left. max

```
x. \max = \max \text{ endpoint value in subtree rooted at } x
= \max\{i. \text{ high where } i \text{ is stored in the subtree rooted at } x\}
```

- Choose an underlying data structure. ✓
- 2. Determine additional information to maintain. ✓
- 3. Verify that we can maintain additional information for existing data structure operations.
- 4. Develop new operations.

### Interval-Search

Running time?  $O(\log n)$ 

```
Interval-Search(T, j)
 1 x = T.root
 2 while x \neq T. nil and j does not overlap x. int
         if x. left \neq NIL and x. left. max \geq j. low
 3
              x = x. left
 4
         else
 5
              x = x. right
 6
 7 return x
Correctness
Invariant
                 If tree T contains an interval that overlaps j,
                 then there is such an interval in the subtree rooted at x.
```

- Choose an underlying data structure. ✓
- 2. Determine additional information to maintain. ✓
- 3. Verify that we can maintain additional information for existing data structure operations.
- 4. Develop new operations. ✓

# Augmenting red-black trees

#### Theorem [RB-tree Augmentation]

Augment an RB-tree with field f, where x. f depends only on information in x, x. left, and x. right (including x. left. f and x. right. f). Then we can maintain values of f in all nodes during insert and delete without affecting  $O(\log n)$  performance.

#### Additional information

 $x. \max = \max$  endpoint value in subtree rooted at x

#### x. max depends only on

- information in x: x. int. high
- information in x. left: x. left. max
- information in x. right: x. right. max
- $\blacksquare$   $x. \max = \max\{x. \text{ int. high, } x. \text{ left. max, } x. \text{ right. max}\}$
- $\rightarrow$  insert and delete still run in  $O(\log n)$  time