

Computer Vision Praktikum

Landmark Recognition

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Research Prediction Competition

Google Landmark Recognition 2019

Label famous (and not-so-famous) landmarks in images



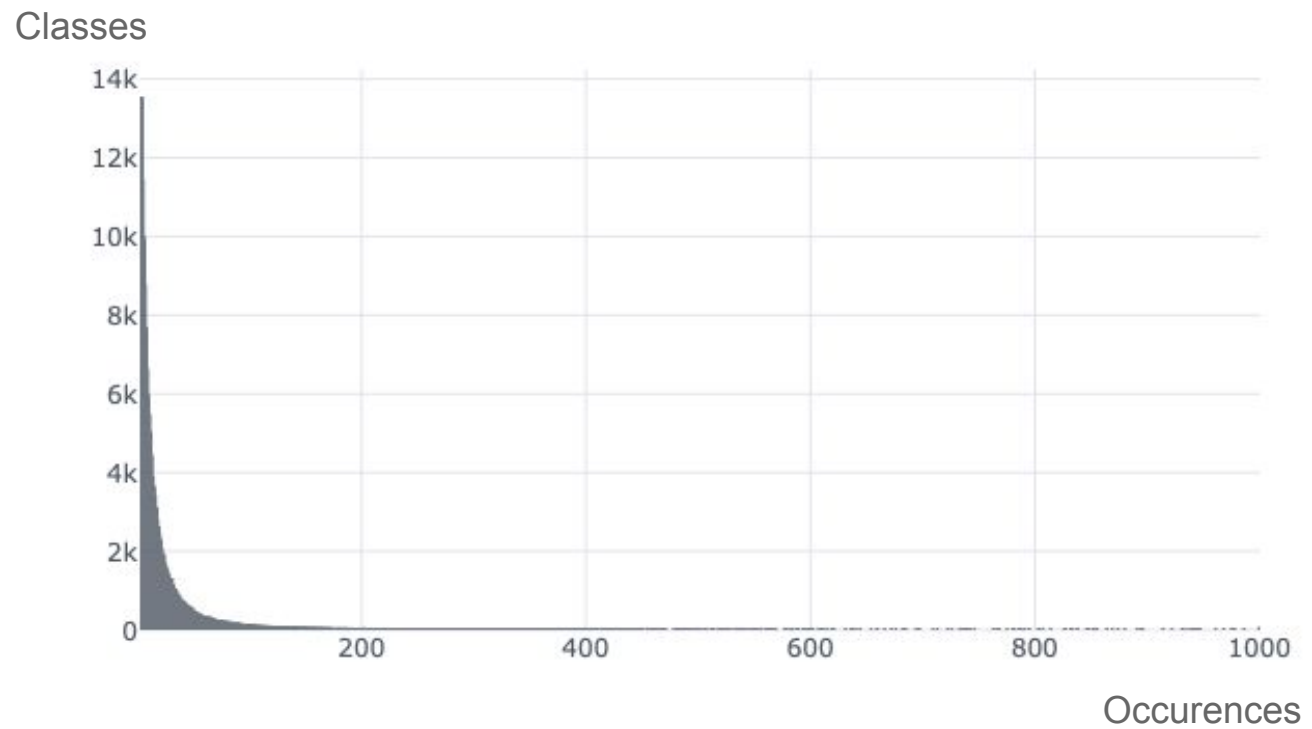
Google · 176 teams · 2 months ago

Motivation

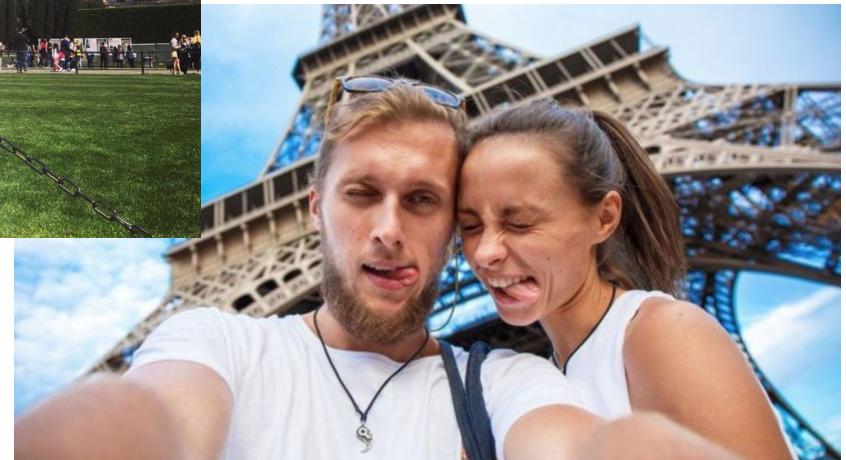
Temple of Hera



Challenges



Challenges



Challenges



Santa Maria Maggiore



Metric: Global Average Precision

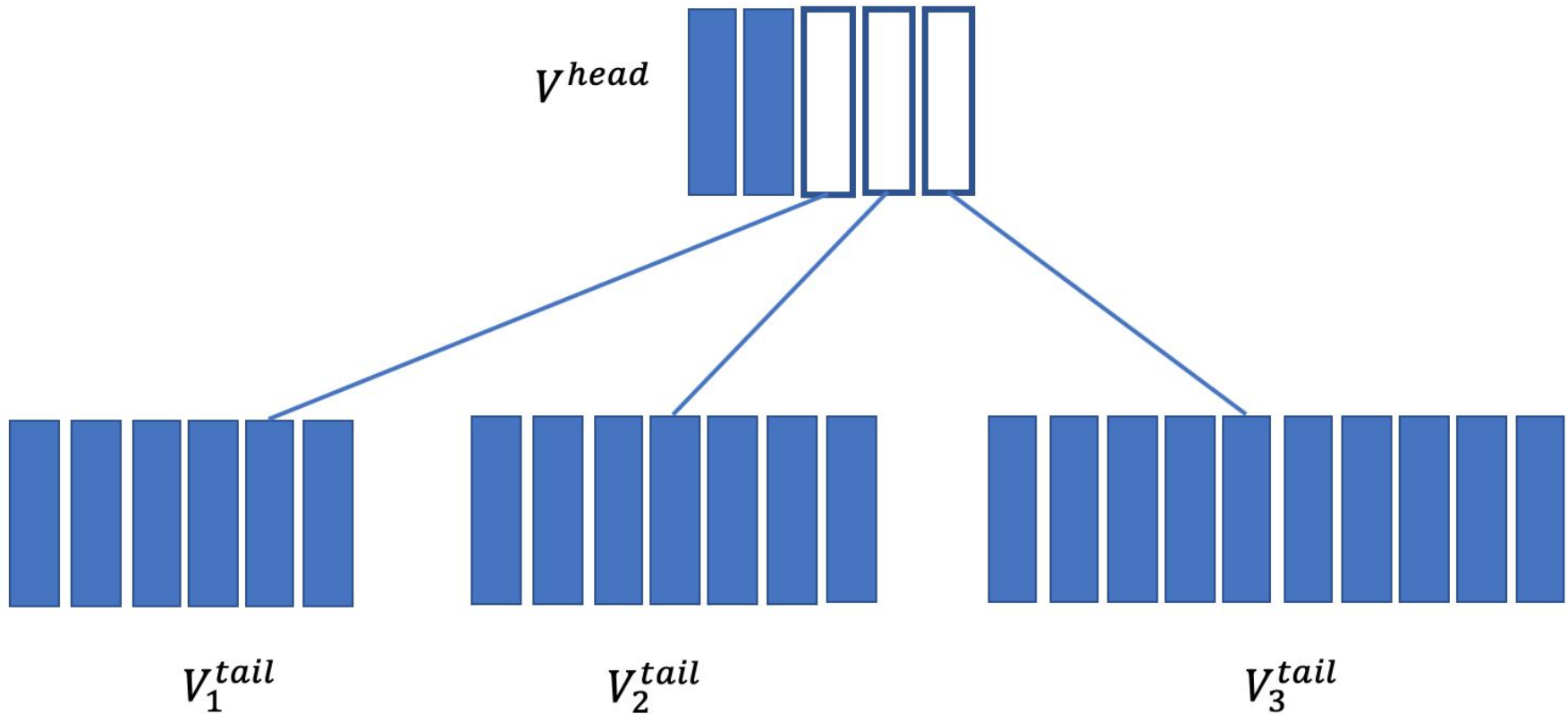
$$GAP = \frac{1}{M} \sum_{i=1}^N P(i)rel(i)$$

N	total number of predictions
M	total number of queries
$P(i)$	precision at rank i
$rel(i)$	relevance of prediction i

Baseline

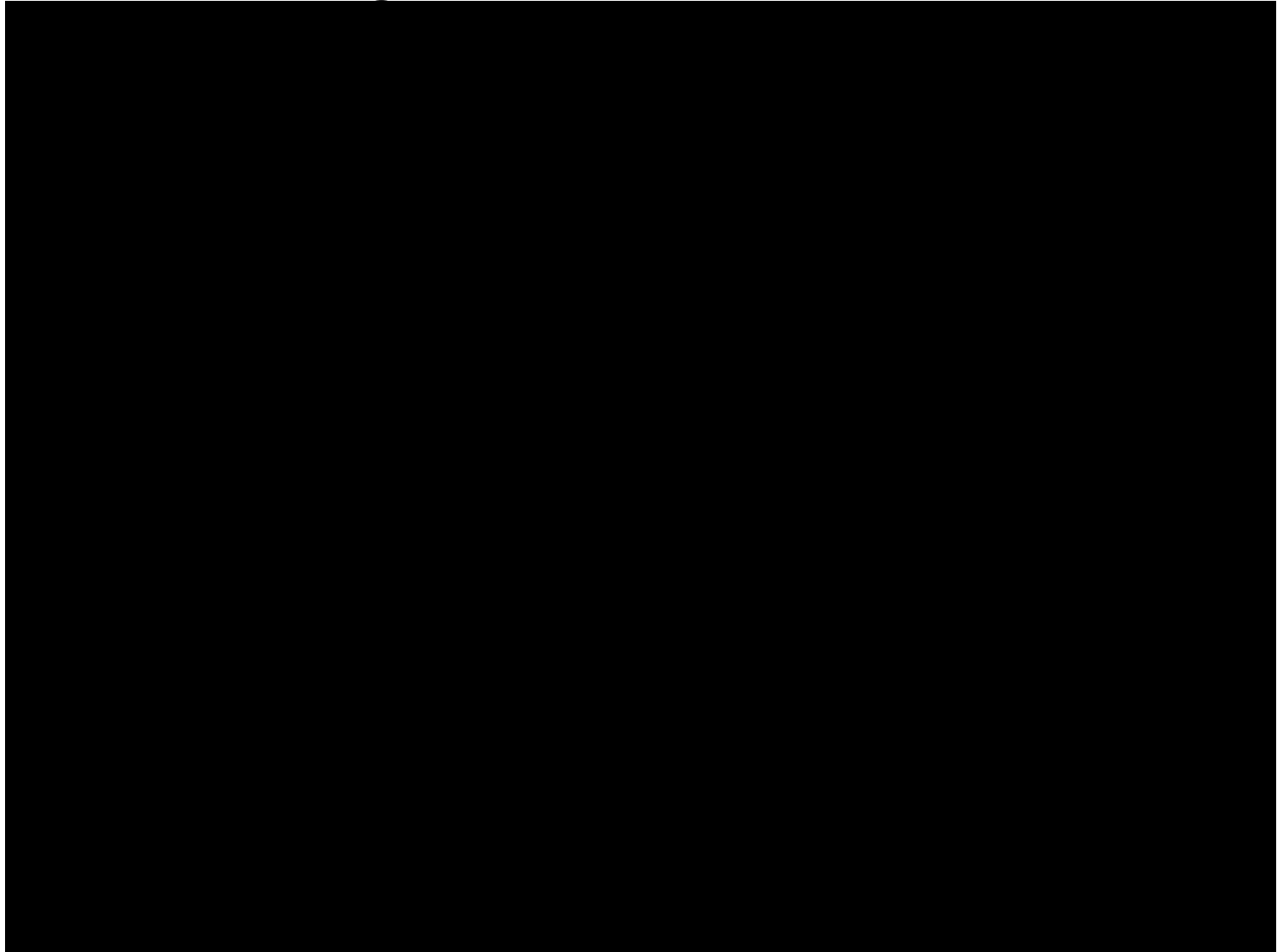
- Random baseline
 - landmark: random label
 - confidence score: uniform distribution
 - GAP = 0%
- Training on 1000 classes
 - ResNet50 (pre-trained on Places365) + Cross entropy
 - GAP= 0%

Experiment 1: Adaptive Softmax

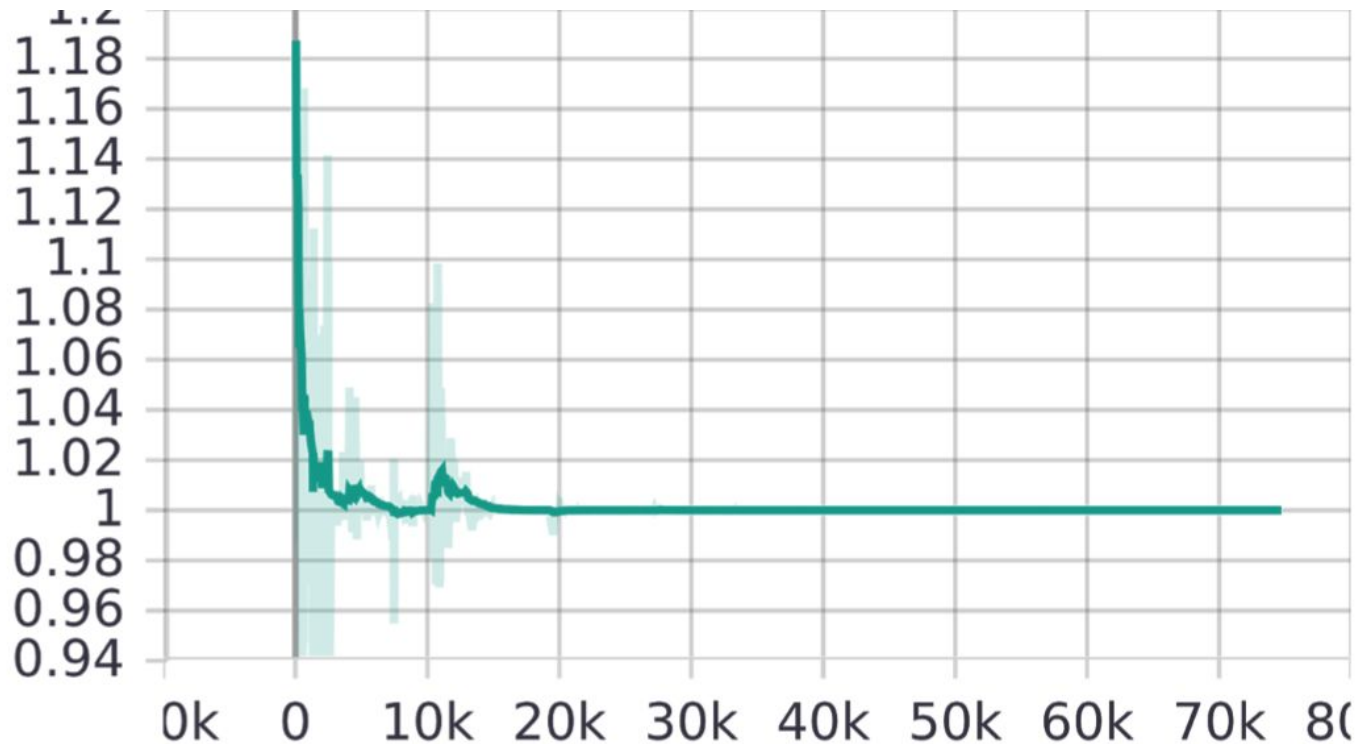


GAP: 1.239%

Feature embedding



Experiment 2: Triplet loss



$$L(A, P, N) = \max(\|f(A) - f(P)\|^2 - \|f(A) - f(N)\|^2 + \alpha, 0)$$

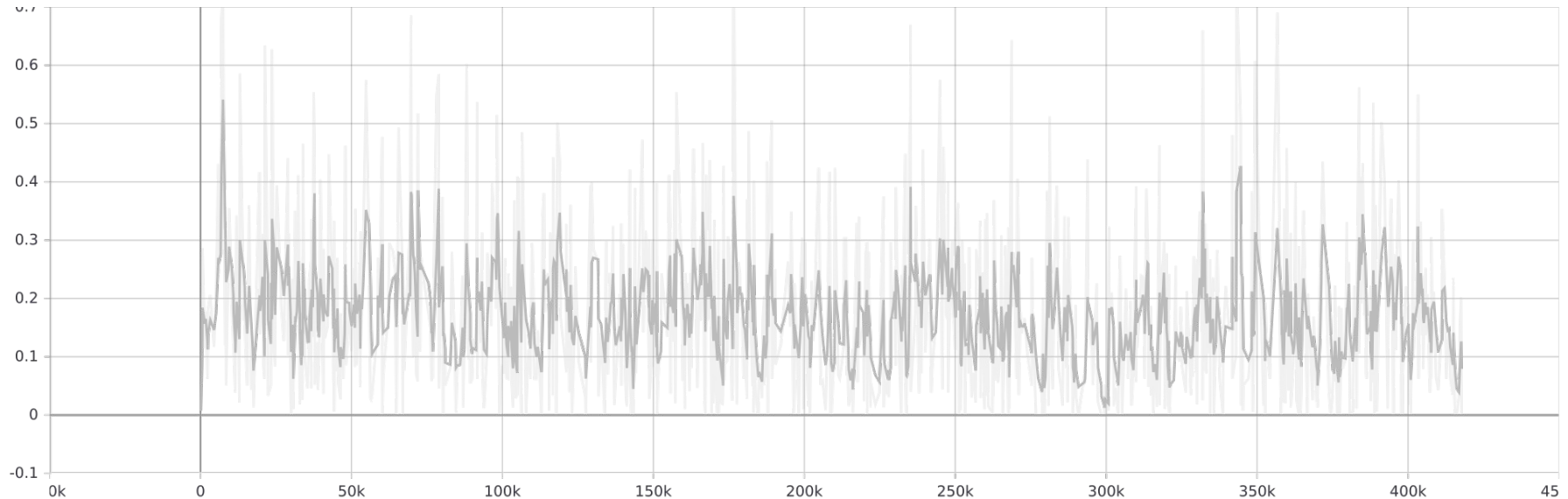
Related works - Solution of first-ranked team

- Data cleaning: matching pairs



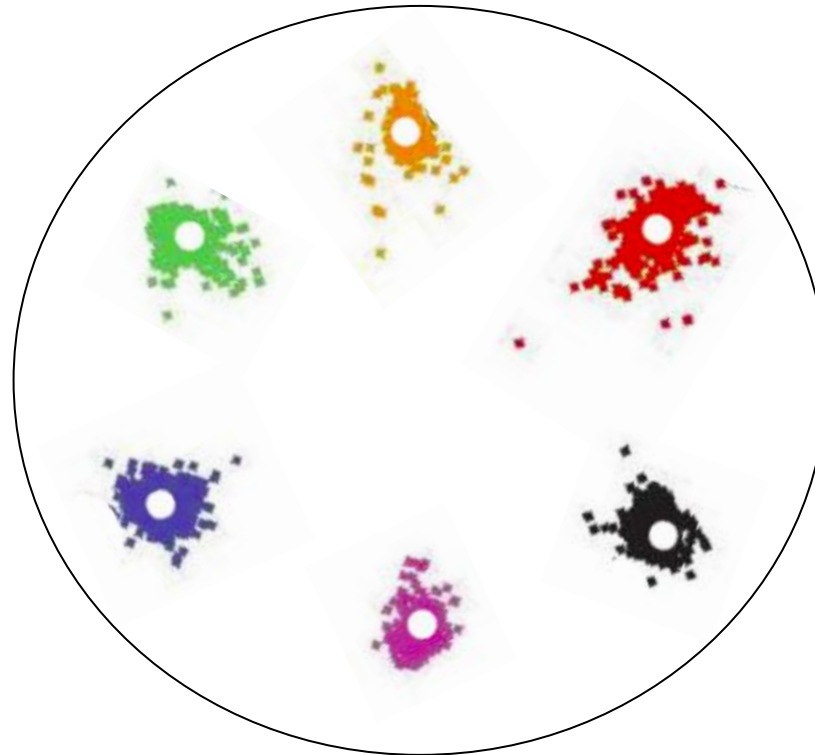
- Training:
 - 6 CNN models
 - contrastive loss and triplet loss

Experiment 3: Triplet Loss on Matching Pairs



GAP = 1.248%

Experiment 4: Triplet Loss on Matching Pairs with Center Loss



Center Loss

GAP = 0.308

Results

Our Experiments	GAP (in Percentage)	Rank
Random	0	130 - 176
1000 Classes	0	130 - 176
Adaptive Softmax	1.239	100 🏆
Triplet Loss	0	130 - 176
Matching Pairs + Triplet Loss	1.248	100 🏆
Matching Pairs + Triplet Loss + Center Loss	0.398	113

Winners' Experiments	GAP (in Percentage)	Rank
JL	37.606	1
GLRunner	35.988	2
smlyaka	35.541	3

Outlook

- Modelling uncertainty (Prediction)
 - Bayesian modelling
 - Dropout during inference
- Re-ranking or Clustering (Post-Processing)
- Mixture of experts (Architecture)
 - Unsupervised learning for gating function
 - E.g. with FINCH clustering

