

Design Parameters

- F_{bp} = the force output of the brake pedal assembly
- F_d = the force applied to the pedal pad by the driver
- P_{mc} = the hydraulic pressure generated by the master cylinder
- A_{mc} = the effective area of the master cylinder hydraulic piston
- P_{cal} = the hydraulic pressure transmitted to the calliper
- F_{cal} = the one-sided linear mechanical force generated by the caliper
- A_{cal} = the effective area of the calliper hydraulic piston(s) found on one half of the calliper body
- F_{cl} = the clamp force generated by the caliper
- $F_{friction}$ = the frictional force generated by the brake pads opposing the rotation of the rotor
- μ_{bp} = the coefficient of friction between the brake pad and the rotor
- T_r = the torque generated by the rotor
- R_{eff} = the effective radius (effective moment arm) of the rotor (measured from the rotor centre of rotation to the centre of pressure of the caliper pistons)
- F_{tire} = the force reacted between the tire and the ground (assuming friction exists to support the force)
- F_{total} = the total braking force reacted between the vehicle and the ground (assuming adequate traction exists)
- a_v = the deceleration of the vehicle
- m_v = the mass of the vehicle = 500 Kg
- D_s = the stopping distance of the vehicle
- V_v = velocity of moving vehicle
- V_f = the front axle vertical force (weight)
- V_r = the rear axle vertical force (weight)
- WT = the absolute weight transferred from the rear axle to the front axle
- g = the acceleration due to gravity (effectively expressing a_v in units of g's)
- h_{CG} = the vertical distance from the CG to ground.
- $V_{f,d}$ = the front axle dynamic vertical force for a given deceleration
- $V_{r,d}$ = the rear axle dynamic vertical force for a given deceleration
- $F_{tires,f}$ = the combined front tire braking forces
- $F_{tires,r}$ = the combined rear tire braking forces
- $\mu_{peak,f}$ = the maximum effective coefficient of friction between the front tires and the road
- $\mu_{peak,r}$ = the maximum effective coefficient of friction between the rear tires and the road

Braking Calculation

ASC Requirement

As per ASC2022 10.5.C :

Solar cars must be able to repeatedly stop from speeds of 50 km/h (31 mph) or greater, with an average deceleration, on level wetted pavement, exceeding 4.72 m/s^2 . Performance shall be demonstrated with mechanical braking only.

For buffer, we have selected the velocity to be 60km/h and the deceleration to 6 m/s^2 .

Brake Pedal Force (F_{bp})

$$F_{bp} = F_d * \frac{l_2}{l_1}$$

F_d = the force applied to the pedal pad by the driver = 130 N

l_1 = The distance from the brake pedal arm pivot to the output rod clevis attachment

l_2 = The distance from the brake pedal arm pivot to the brake pedal pad

$\frac{l_2}{l_1}$ = Pedal ratio = 5.1

$$F_{bp} = 130 * 5.1 = 663N$$

Master Cylinder Pressure (P_{mc})

$$P_{mc} = \frac{F_{bp}}{A_{mc}}$$

MC Bore = 0.625 in = 0.01587 m

A_{mc} = Effective area of the master cylinder = $\frac{\pi * (0.0158)^2}{4} = 1.98 * 10^{-4}$

$$P_{mc} = \frac{663}{1.98 * 10^{-4}} = 3348484.84 \text{ Pa}$$

Force generated by caliper piston (F_{cal})

$A_{cal} = 3 \text{ in}^2 = 0.001935 \text{ m}^2$

$P_{cal} = P_{mc} = 3348484.84$

$$F_{cal} = P_{cal} * A_{cal}$$

$$F_{cal} = 3348484.84 * 0.001935 = 6479.3N$$

Caliper Clamp Load (F_{cl})

$$F_{cl} = F_{cal} * 2$$

$$F_{cl} = 6479.3 * 2 = 12958.6 \text{ N}$$

Force on disc by brake pads ($F_{friction}$)

$$F_{friction} = F_{cl} * \mu_{bp}$$

$$\mu_{bp} = 0.4$$

$$F_{friction} = 12958.6 * 0.4 = 5183.44 \text{ N}$$

Torque of rotor (T_r)

$$T_r = F_{friction} * R_{eff}$$

R_{eff} = Effective rolling radius = 12 in = 0.3048 m

$$T_r = 5183.44 * 0.3048 = 1579.91 \text{ N.m}$$

Force on a tire (F_{tire})

$$F_{tire} = \frac{T_r}{R_t}$$

$R_t = 0.254 \text{ m}$

$$\text{Force on front wheels : } F_{tire,f} = \frac{1579.91}{0.254} = 6220.12 \text{ N}$$

$$\text{Force on rear wheels : } F_{tire,r} = \frac{1579.91}{0.254} = 6220.12 \text{ N}$$

$$\sum F = F_{tire,f} + F_{tire,r} = 6220.12 * 4 = 24880.48 \text{ N}$$

Kinetic energy of the vehicle

$$KE = \frac{1}{2} m v^2 = \frac{1}{2} (500) \left(60 * \frac{5}{18} \right)^2 = 69.4 \text{ kJ}$$

Stopping Distance

$$F = \mu * m * g = 0.6 * 500 * 9.8 = 2940 \text{ N}$$

$$d_s = \frac{KE}{F} = \frac{69444}{2940} = 23.6 \text{ m}$$

Deceleration

$$a_v = \frac{v^2 - u^2}{2d_s}$$

$v = 0$; $u = 60 \text{ km/h} = 16.67 \text{ m/s}$

$$a_v = \frac{0^2 - 16.67^2}{2 * 23.6} = -5.89 \text{ m/s}^2$$

CG_f = Distance between front axle to CG = 1.47 m

CG_r = Distance between rear axle to CG = 1.47 m

WB = Distance between front axle to rear axle = 2.94 m

h_{cg} = Height of Centre of gravity = 0.5775 m

$V_t = 500 * 9.8 = 4900 \text{ N}$

Rear axle vertical force (weight)

$$CG_r = \frac{V_r}{V_t} * WB$$

$$V_r = \frac{CG_r * V_t}{WB}$$

$$V_r = \frac{1.47 * 4900}{2.94}$$

$$V_r = 2450 \text{ N}$$

Front axle vertical force (weight)

$$CG_f = \frac{V_f}{V_t} * WB$$

$$V_f = \frac{CG_f * V_t}{WB}$$

$$V_f = \frac{1.47 * 4900}{2.94}$$

$$V_f = 2450 \text{ N}$$

Dynamic absolute weight transferred

$$WT = \frac{a_v}{g} * \frac{h_{cg}}{WB} * V_t$$

$$WT = \frac{5.89}{9.8} * \frac{0.5775}{2.94} * 4900 = 578.48 \text{ N}$$

Dynamic Vertical Force

Front Axle

$$V_{f,d} = V_f + WT$$

$$V_{f,d} = 2450 + 578.48 = 3028.48 \text{ N}$$

Rear Axle

$$V_{r,d} = V_r - WT = 2450 - 578.48 = 1871.52$$

Effect of weight transfer on Tire Output

Front Tire

$$F_{tire,f} = \mu_{peak,f} * V_f = 0.6 * 2450 = 1470 \text{ V}$$

Rear Tire

$$F_{tire,r} = \mu_{peak,r} * V_r = 0.6 * 2450 = 1470 \text{ V}$$

Maximum Braking Force Produced By axle

Front Axle

$$F_{tire,f} = \mu_{peak,f} * V_{f,d} = 0.6 * 3028.48 = 1817.09 \text{ V}$$

Rear Axle

$$F_{tire,r} = \mu_{peak,r} * V_{r,d} = 0.6 * 1871.52 = 1122.91 \text{ V}$$

Braking Efficiency

$$\eta = \frac{\text{Total braking Force}}{\text{Total Weight of vehicle}} * 100$$

$$\eta = \frac{24880.48}{500 * 9.8} * 100$$

$$\eta = 507.76\%$$