Convergence of Gradient Descent: Smooth and Convex Settings



Outline



- 1. Gradient Descent and Decent lemma for Smooth functions
 - GD for Non-Convex Smooth Functions
 - GD for Convex and Smooth function
 - GD for Smooth and Strongly Convex functions

2. Projection



Problem:

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Which Complete the proof of Descent Lemma.





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- In general for non-convex functions, this is the best one can establish for GD.
- In the above theorem, we don't have any condition on the final iterate but

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Use Decent lemma with k = T - 1, and so on..

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Since $\bar{f} \leq f(x^T)$, it follows

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- ullet In practice, choose a large T and apply early stopping.







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f is $M\mbox{-smooth}$ and convex. and x^* be a global minimizer of f. Running \mbox{GD}

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- Requires differentiability; non-smooth cases call for subgradient methods.



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• since f is m-strongly convex

$$f(y) \ge f(x) + \langle \nabla f(x), y - x \rangle + \frac{m}{2} \|y - x\|^2.$$

ullet Fix x and optimize over y then

$$\nabla f(x) + \frac{m}{2} (2(y - x)) = 0$$
$$\Rightarrow y = x - \frac{1}{m} \nabla f(x).$$





 \bullet Substitute the value of y in RHS of above equation and LHS in $f(x^{\ast}),$



ullet Substitute the value of y in RHS of above equation and LHS in $f(x^*)$,

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$$\Rightarrow \left\| \nabla f(x) \right\|^2 \ge 2m (f(x) - f(x^*)).$$



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- In this case, we can give a guarantee on $\|x^T x^*\|$. The choice of step-size in that case would be $\alpha_k = \frac{2}{M+m}$
- 2 Left as exercise!



Convergence Rates of Gradient Descent



Assumptions	Rate	Guarantee





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f is M -smooth	$ \min_{0 \le k < T} \ \nabla f(x_k)\ ^2 \le \frac{2M \left(f(x_0) - f^*\right)}{T} $	Best-iterate gradient norm





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	T	
f is M -smooth and	$f(x_T) - f^* \le \frac{M}{2T} \ x_0 - x^*\ ^2$	Final-iterate function
convex	21	gap





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f is M -smooth	$ \min_{0 \le k < T} \ \nabla f(x_k)\ ^2 \le \frac{2M \left(f(x_0) - f^*\right)}{T} $	Best-iterate gradient norm
convex	21	Final-iterate function gap
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$ f(x_T) - f^* \le \left(1 - \frac{m}{M}\right)^T \left(f(x_0) - f^*\right) $	Exponential (linear) convergence



Let Here,
$$\kappa = M/m$$
, $R = \|x_0 - x^*\|$, and $\Delta_0 = f(x_0) - f^*$.

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f is m -strongly convex, M -smooth	$ x_T - x^* \le \varepsilon$	$O(\kappa \ln(R/\varepsilon))$
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$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\min_{0 \le k < T} \ \nabla f(x_k)\ \le \varepsilon$	$O\left(\frac{M\Delta_0}{arepsilon^2} ight)$



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$$\min_{x \in \Omega} f(x) \tag{5}$$



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$$P_{\Omega}(x)$$



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$$P_{\Omega}(x) := \arg\min_{z \in \Omega} \frac{1}{2} \|z - x\|^2 \tag{6}$$





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The projection of a vector $y \in \mathbb{R}^d$ onto Ω is given component-wise by:

$$[P_{\Omega}(y)]_i = \max\{0, y_i\}, \quad \text{for each } i = 1, \dots, d$$
(8)

Example 2:Box



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Exercise: Given a point $y \in \mathbb{R}^d$, determine the projection $P_{\Omega}(y)$ onto Ω .





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The projection $P_{\Omega}(y)$ onto Ω is given by:

• If $||y||_2 \le 1$, then $P_{\Omega}(y) = y$



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- If $||y||_2 > 1$,



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Contraction/Non-expansive Property of Projection:



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The projection $P_{\Omega}(y)$ onto Ω is given by:

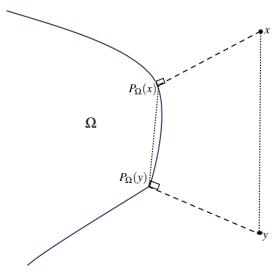
- If $||y||_2 \le 1$, then $P_{\Omega}(y) = y$
- If $\|y\|_2 > 1$, then $P_{\Omega}(y) = \frac{y}{\|y\|_2}$

Contraction/Non-expansive Property of Projection:

$$\left| \|P_{\Omega}(x) - P_{\Omega}(y)\| \le \|x - y\|, \quad \forall x, y \in \mathbb{R}^n \right| \tag{11}$$

Figure: Illustration of Contraction Property





Convergence of GD for Constrained Optimization



Projected Gradient Descent:

$$x^{k+1} = P_{\Omega}[x^k - \alpha_k \nabla f(x_k)]$$

- Thanks to the Contraction property of Projection, the distance gets smaller after projection
- The GD algorithm remains the same with the projection step
- The convergence rates remain the same

References I



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Thank You!