

# Uncertainty in Prediction

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# Recap of last lecture and today's agenda

- Recap of last class
  - Showed how parameter estimation in ML model becomes zero forcing receiver in wireless
- Today's class
  - Understand how generative modeling approach will provide uncertainty in prediction
  - Reference is Chap 2 of FCML

# Uncertainty in prediction

- Our model responsible for generating the data

$$t_n = \mathbf{w}^T \mathbf{x}_n + \epsilon_n$$

- Calculated  $\hat{\mathbf{w}}$  by maximizing the natural logarithm of the likelihood  $\hat{\mathbf{w}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{t}$ 
  - Approach is called maximum likelihood estimation
  - $\hat{\mathbf{w}}$  is a deterministic function of random variable  $\mathbf{t}$ , and is thus also a random variable
- We also estimated noise variance  $\sigma^2$  using maximum likelihood approach
- Suppose we observe a new input  $\mathbf{x}_{new}$ , we would like to predict the output,  $t_{new}$
- To predict  $t_{new}$ , we multiply  $\mathbf{x}_{new}$  by the best set of model parameters,  $\hat{\mathbf{w}}$  i.e.,  $t_{new} = \hat{\mathbf{w}}^T \mathbf{x}_{new}$
- Since  $t_{new}$  is function of random vector  $\hat{\mathbf{w}}$ , it is a random variable
  - We calculate the prediction variability by calculating  $\sigma_{new}^2$ , which is also called the **predictive** variance
- Understand uncertainty in prediction as two-step process
- Step1: Uncertainty in parameter estimate  $\hat{\mathbf{w}}$
- Step2: Uncertainty in  $\hat{\mathbf{w}}$  will help in capturing uncertainty in prediction
  - Uncertainty in  $\hat{\mathbf{w}}$  is mathematically captured using covariance matrix
- Covariance matrix of  $\hat{\mathbf{w}}$  is

$$\text{cov}\{\hat{\mathbf{w}}\} = \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{\hat{\mathbf{w}} \hat{\mathbf{w}}^T\} - \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{\hat{\mathbf{w}}\} \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{\hat{\mathbf{w}}\}^T$$

# Gaussian random vector (recap)

- Density of Gaussian vector

$$p(\mathbf{x}) = \frac{1}{(2\pi)^{N/2} |\boldsymbol{\Sigma}|^{\frac{1}{2}}} \exp \left\{ -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right\}$$

- $\boldsymbol{\mu}$  is the mean vector (same size as  $\mathbf{x}$ ) and  $\boldsymbol{\Sigma}$  is covariance matrix

$$\boldsymbol{\mu} = [2, 1]^T, \boldsymbol{\Sigma} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\boldsymbol{\mu} = [2, 1]^T, \boldsymbol{\Sigma} = \begin{bmatrix} 1 & 0.8 \\ 0.8 & 1 \end{bmatrix}$$

- Gaussian vector with  $\boldsymbol{\Sigma} = \mathbf{I}$

$$\begin{aligned} p(\mathbf{x}) &= \frac{1}{(2\pi)^{N/2} |\mathbf{I}|^{\frac{1}{2}}} \exp \left\{ -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \mathbf{I} (\mathbf{x} - \boldsymbol{\mu}) \right\} = \frac{1}{(2\pi)^{N/2} |\mathbf{I}|^{\frac{1}{2}}} \exp \left\{ -\frac{1}{2} \sum_{n=1}^N (x_n - \mu_n)^2 \right\} \\ &= \frac{1}{(2\pi)^{N/2} |\mathbf{I}|^{\frac{1}{2}}} \prod_{n=1}^N \exp \left\{ -\frac{1}{2} (x_n - \mu_n)^2 \right\} = \prod_{n=1}^N \frac{1}{(2\pi)^{\frac{1}{2}}} \exp \left\{ -\frac{1}{2} (x_n - \mu_n)^2 \right\} \end{aligned}$$

- Elements of  $\mathbf{x}$  are independent with  $p(\mathbf{x}) = \mathcal{N}(\mathbf{0}, \mathbf{I})$

# Uncertainty in parameter estimate $\hat{\mathbf{w}}$

- For our generative model  $t_n = \mathbf{w}^T \mathbf{x}_n + \epsilon_n$

$$p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2) = \prod_{n=1}^N p(t_n|\mathbf{x}_n, \mathbf{w}, \sigma^2) = \prod_{n=1}^N \mathcal{N}(\mathbf{w}^T \mathbf{x}_n, \sigma^2) = \mathcal{N}(\mathbf{X}\mathbf{w}, \sigma^2 \mathbf{I})$$

- $p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)$  is the generating distribution (or likelihood). We have

$$\begin{aligned}\mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)}\{\hat{\mathbf{w}}\} &= \int \hat{\mathbf{w}} p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2) d\mathbf{t} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \int \mathbf{t} p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2) d\mathbf{t} \\ &= (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)}\{\mathbf{t}\} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{X} \mathbf{w} = \mathbf{w}\end{aligned}$$

- Expectation of  $\hat{\mathbf{w}}$  w.r.t. generating distribution will tell us what  $\hat{\mathbf{w}}$  on an average will be
- Expected value of  $\hat{\mathbf{w}}$  is the true parameter value
  - Estimator, on an average, is neither too big or small – estimator is unbiased
- Covariance matrix of  $\hat{\mathbf{w}}$  now is

$$\begin{aligned}\text{cov}\{\hat{\mathbf{w}}\} &= \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)}\{\hat{\mathbf{w}}\hat{\mathbf{w}}^T\} - \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)}\{\hat{\mathbf{w}}\} \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)}\{\hat{\mathbf{w}}\}^T \\ &= \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)}\{\hat{\mathbf{w}}\hat{\mathbf{w}}^T\} - \mathbf{w}\mathbf{w}^T\end{aligned}$$

## Covariance matrix calculation (2)

- We next simplify the first term

$$\begin{aligned}\mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{ \hat{\mathbf{w}} \hat{\mathbf{w}}^T \} &= \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{ ((\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{t}) ((\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{t})^T \} \\ &= (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{ \mathbf{t} \mathbf{t}^T \} \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1}\end{aligned}\quad (1)$$

- We know that  $p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2) = \mathcal{N}(\mathbf{X}\mathbf{w}, \sigma^2 \mathbf{I})$  such that mean of  $\mathbf{t}$  is  $\mathbf{X}\mathbf{w}$  and covariance  $\sigma^2 \mathbf{I}$

$$\begin{aligned}\text{cov}\{\mathbf{t}\} = \sigma^2 \mathbf{I} &= \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{ \mathbf{t} \mathbf{t}^T \} - \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{ \mathbf{t} \} \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{ \mathbf{t} \}^T \\ \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{ \mathbf{t} \mathbf{t}^T \} &= \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{ \mathbf{t} \} \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{ \mathbf{t} \}^T + \sigma^2 \mathbf{I} \\ &= \mathbf{X}\mathbf{w}(\mathbf{X}\mathbf{w})^T + \sigma^2 \mathbf{I} = \mathbf{X}\mathbf{w}\mathbf{w}^T \mathbf{X}^T + \sigma^2 \mathbf{I}\end{aligned}$$

- Substituting  $\mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{ \mathbf{t} \mathbf{t}^T \}$  into (1), which is

$$\begin{aligned}\mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{ \hat{\mathbf{w}} \hat{\mathbf{w}}^T \} &= (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{ \mathbf{t} \mathbf{t}^T \} \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \\ &= (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{X} \mathbf{w} \mathbf{w}^T \mathbf{X}^T \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} + \sigma^2 (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \\ &= \mathbf{w} \mathbf{w}^T + \sigma^2 (\mathbf{X}^T \mathbf{X})^{-1}\end{aligned}$$

- Finally, we have

$$\text{cov}\{\hat{\mathbf{w}}\} = \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)} \{ \hat{\mathbf{w}} \hat{\mathbf{w}}^T \} - \mathbf{w} \mathbf{w}^T = \mathbf{w} \mathbf{w}^T + \sigma^2 (\mathbf{X}^T \mathbf{X})^{-1} - \mathbf{w} \mathbf{w}^T = \sigma^2 (\mathbf{X}^T \mathbf{X})^{-1}$$

# Variance calculation

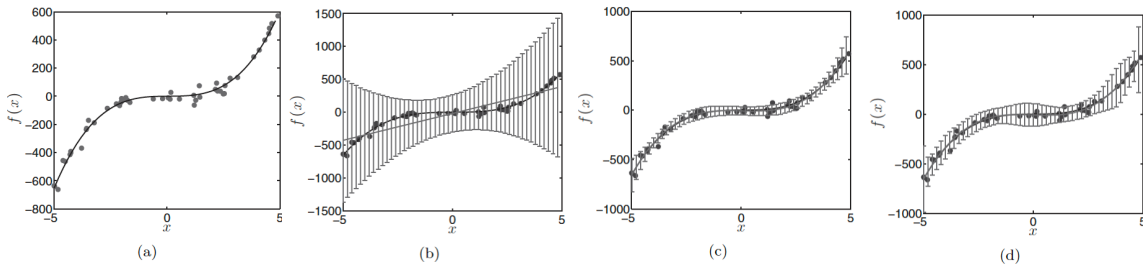
- We now calculate the **predictive** variance  $\sigma_{new}^2 = \text{var}\{t_{new}\}$ , where  $t_{new} = \hat{\mathbf{w}}^T \mathbf{x}_{new}$

$$\begin{aligned}\sigma_{new}^2 &= \text{var}\{t_{new}\} = \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)}\{t_{new}^2\} - (\mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)}\{t_{new}\})^2 \\&= \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)}\{(\hat{\mathbf{w}}^T \mathbf{x}_{new})^2\} - (\mathbf{w}^T \mathbf{x}_{new})^2 \\&= \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)}\{\mathbf{x}_{new}^T \hat{\mathbf{w}} \hat{\mathbf{w}}^T \mathbf{x}_{new}\} - \mathbf{x}_{new}^T \mathbf{w} \mathbf{w}^T \mathbf{x}_{new} \\&= \mathbf{x}_{new}^T \mathbb{E}_{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \sigma^2)}\{\hat{\mathbf{w}} \hat{\mathbf{w}}^T\} \mathbf{x}_{new} - \mathbf{x}_{new}^T \mathbf{w} \mathbf{w}^T \mathbf{x}_{new} \\&= \mathbf{x}_{new}^T (\sigma^2 (\mathbf{X}^T \mathbf{X})^{-1} + \mathbf{w} \mathbf{w}^T) \mathbf{x}_{new} - \mathbf{x}_{new}^T \mathbf{w} \mathbf{w}^T \mathbf{x}_{new} \\&= \sigma^2 \mathbf{x}_{new}^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_{new} + \mathbf{x}_{new}^T \mathbf{w} \mathbf{w}^T \mathbf{x}_{new} - \mathbf{x}_{new}^T \mathbf{w} \mathbf{w}^T \mathbf{x}_{new} \\&= \mathbf{x}_{new}^T \text{COV}\{\hat{\mathbf{w}}\} \mathbf{x}_{new}\end{aligned}$$

- To summarize, we have

$$\begin{aligned}t_{new} &= \hat{\mathbf{w}}^T \mathbf{x}_{new} = \mathbf{x}_{new}^T \hat{\mathbf{w}} = \mathbf{x}_{new}^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{t} \\ \sigma_{new}^2 &= \mathbf{x}_{new}^T \text{COV}\{\hat{\mathbf{w}}\} \mathbf{x}_{new} = \sigma^2 \mathbf{x}_{new}^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_{new}\end{aligned}$$

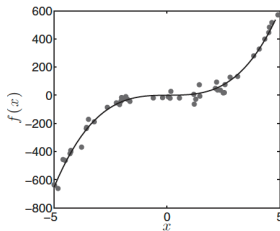
# Predictive variability an example (1)



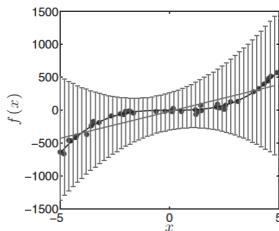
- Figure (a) shows the function  $f(x) = 5x^3 - x^2 + x$  and data points sampled from this function and corrupted by Gaussian noise with mean zero and variance 1000
- Figures (b), (c) and (d) show  $t_{new} \pm \sigma^2$  new for linear, cubic and sixth order models
- Linear model has very high predictive variance
  - Unable to model deterministic trend in data very well, and assumes much of data variation as noise



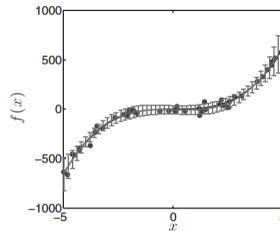
## Predictive variability an example (2)



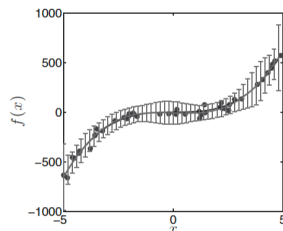
(a)



(b)



(c)



(d)

- Cubic model is better able to model the trend
  - It is the correct order and this is reflected in its much more confident predictions
- Sixth-order model is over-complex
  - It has too much freedom and can therefore fits the data well for quite a large range of parameter values
- For all models, predictive variance increases as we move towards the edge of data
- Model is less confident in areas where it has less data – an appealing property

# Summary and next agenda

- Summary till now
  - Generative modeling approach tells us how confident the model is about the predictions it is making
  - Maximum likelihood approach favors complex models
- Next agenda
  - Bayesian approach, similar to regularization, can avoid complex models<sup>1</sup>
  - Bayesian approach also allows us to incorporate our prior belief about the model
- Let's re-discuss Facebook example<sup>2</sup>
- We will next see another example of how data can give misleading information

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<sup>1</sup>Chap 3 of FCML

<sup>2</sup>The Chaos Machine: The Inside Story of How Social Media Rewired Our Minds and Our World, book by [Max Fischer](#)