

SDGB/DGGB 7844 HW 3: Capture-Recapture Method

Instructor: Prof. Nagaraja

Due: 11/5 in class

Submit your homework as follows: (a) hardcopy of assignment only in class; (b) e-mail assignment and code to fordhamRcomputing@gmail.com by the start of class. In your e-mail, use the subject heading: “HW 3: [Your name]” and include HW 3 and your name the file names you attach. Comment your code for full credit. Complete your work individually.

In the beginning of the 17th century, John Graunt wanted to determine the effect of the plague on the population of England; two hundred years later, Peirre Simon Laplace wanted to estimate the population of France. Both Graunt and Laplace implemented what is now called the *capture-recapture method*. This technique is used to not only count human populations (such as the homeless) but also animals in the wild.

In its simplest form, n_1 individuals are “captured,” “tagged”, and released. A while later, n_2 individuals are “captured” and the number of “tagged” individuals, m_2 , is counted. If N is the true total population size, we can estimate it with \hat{N}_{LP} as follows:

$$\hat{N}_{LP} = \frac{n_1 n_2}{m_2} \quad (1)$$

using the relation $\frac{n_1}{N} = \frac{m_2}{n_2}$. This is called the Lincoln-Peterson estimator¹.

We make several strong assumptions when we use this method: (a) each capture is independent of the others, (b) each individual is equally likely to be captured, (c) there are no births, deaths, immigration, or emigration of individuals (i.e., a closed population), and (d) the tags do not wear off (if it is a physical mark) and no tag goes unnoticed by a researcher.

Goal: In this assignment, you will develop a Monte-Carlo simulation of the capture-recapture method and investigate the statistical properties of the Lincoln-Peterson and Chapman estimators.

¹Interestingly, this estimator is also the maximum likelihood estimate which you will learn about in DGGB 781A (MSSD students) and which we will talk about briefly later in the semester. As you probably guessed, more complex versions of this idea have been developed since the 1600s.

1. Simulate the capture-recapture method for a population of size $N = 5,000$ when $n_1 = 100$ and $n_2 = 100$ using the `sample()` function (we assume that each individual is equally likely to be “captured”). Determine m_2 and calculate \hat{N}_{LP} using Eq.1.
2. Write a function to simulate the capture-recapture procedure using the inputs: N , n_1 , n_2 , and the number of simulation runs. The function should output in list form (a) a data frame with two columns: the values of m_2 and \hat{N}_{LP} for each iteration and (b) N . Run your simulation for 1,000 iterations for a population of size $N = 5,000$ and make a histogram of the resulting \hat{N}_{LP} vector². Indicate N on your plot.
3. What percent of the estimated population values in question 2 were infinite? Why can this occur?
4. An alternative to the Lincoln-Peterson estimator is the Chapman estimator:

$$\hat{N}_C = \frac{(n_1 + 1)(n_2 + 1)}{m_2 + 1} - 1 \quad (2)$$

Use the saved m_2 values from question 2 to compute the Chapman estimate for each case. Construct a histogram of the resulting \hat{N}_C estimates, indicating N on your plot.

5. An estimator is considered *unbiased* if, on average, the estimator equals the true population value. For example, the sample mean $\bar{x} = \sum_{i=1}^n x_i/n$ is unbiased because on average the sample mean \bar{x} equals the population mean μ (i.e., the sampling distribution is centered around μ). This is a desirable property for an estimator to have because it means our estimator is not systematically wrong. To show that some estimator $\hat{\theta}$ is an unbiased estimate of the true value θ , we need to mathematically prove that $E[\hat{\theta}] - \theta = 0$ where $E[\cdot]$ is the expectation (i.e., theoretical average)³. We will check for this property empirically by replacing the theoretical average $E[\hat{\theta}]$ with the sample averages of $\hat{\theta}$ from our simulation (i.e., $\sum_{i=1}^{n_{sim}} \hat{\theta}/n_{sim}$ where n_{sim} is the number of simulation runs).

Estimate the bias of the Lincoln-Peterson and Chapman estimators, based on the results of your simulation. Is either estimator unbiased when $n_1, n_2 = 100$?

6. Based on your findings thus far, is the Lincoln-Peterson or Chapman estimator better? Justify your answer.
7. Can we get better estimates using larger sample sizes? Let's restrict $n = n_1 = n_2$. Write a function which computes the bias and variance of the Chapman estimator for varying sample sizes n . The inputs for this function should be: N , number of simulation runs per

²Basically, you are empirically constructing the sampling distribution for \hat{N}_{LP} here. Remember the Central Limit Theorem which tells us the sampling distribution of the sampling mean? Each statistic has a sampling distribution and we are simulating it here (but using frequency instead of probability on the y -axis).

³Everyone: note that the sample size n does not appear in this equation. For an estimator to be unbiased, this property cannot depend on sample size. MSSD students: $E[X] = \int_{-\infty}^{\infty} xf(x) dx$.

sample size, and n . The function should return in list form (a) a data frame with three columns: n , bias of estimator, and standard deviation of estimator for each sample size and (b) the true population size. Run this function using the following arguments: (a) $N = 100,000$ for each sample size, (b) 1,000 simulation runs, and (c) n ranging from 100 to 5,000 (use `seq(from=100, to=5000, by=50)`). Include in your function an indicator of your progress every time you complete runs for 10 sample sizes.

Based on your results, construct two plots: (a) bias versus n and (b) variance versus n (e.g., y -axis variable vs. x -axis variable). Indicate zero on both plots and connect the points with a line. Describe what you see.

8. An estimator $\hat{\theta}$ is called *consistent* if, as the sample size goes to infinity, the bias of the estimator goes to zero⁴. That is, $E[\hat{\theta}]$ gets closer to θ as the sample size increases. This is another desirable property for an estimator.

For the simpler case where $n_1 = n_2$, could \hat{N}_C be a consistent estimator? Justify your answer.

9. Explain why the assumptions (a), (b), and (c) listed on the first page are unrealistic.

⁴MSSD students: $\hat{\theta}_n$ is a consistent estimator of θ if $\lim_{n \rightarrow \infty} P(|\hat{\theta}_n - \theta| > \varepsilon) = 0$, $\varepsilon > 0$ (i.e., convergence in probability).