

Oujda  
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## **MAS Course 04**

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## **CONTENTS**

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**APPLICATION : CALENDARS & CITIZEN AGENTS**

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## DECENTRALIZED CALENDARS

## DECENTRALIZED CALENDARS [Demazeau 06]

An internal project, to support every day's life of every citizen.

### VOWELS approach

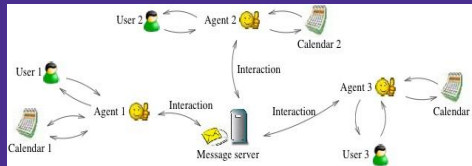
- One personal assistant per life domain, being the **A**
- Environment **E** : Temporal environment mainly
- Interactions **I** : Sharing, Trusting, Negotiating
- Groups **O** : Family, Team, Consortium
- User **U**: Importance and urgency are subjective

Y. Demazeau, D. Melaye, M.-H. Verrons, "A Decentralized Calendar System Featuring Sharing, Trusting and Negotiating", 19th IEA/AIE'06, Antalya, 2006.

## DECENTRALIZED CALENDARS

### Decentralized Calendars

- Negotiating meetings and sharing events
- Importance and urgency as subjective features
- Local storage of the calendars and partial mutual knowledge



### Approach

- Individual interactions : Sharing, Trusting, Negotiating
  - Full sharing: CSP-like solution
  - Partial sharing: introduction of trust
  - No sharing: negotiation is necessary!
- Broadcasting to groups : Family, Team, Consortium

## Sharing Timetables

When timetables are shared, the meetings can be scheduled by well-known CSP techniques...

### Groups

- Social organization of the agents
- Groups are structured in a hierarchy with subsumption relation

### Sharing and groups

- An event can be public or private or...
- ...shared by several agents, but not all of them
- Sharing information or not according to the groups the agent belongs to
- If an agent belongs to several groups, its sharing capability is the logical combination of the sharing capability of its groups

## Importance and Urgency

### Addition of an event

- **Importance** and **urgency**: two common dimensions of time handling, used by all agents,
- Each agent has a subjective vision of the combined priorities. Usually:

	High <b>urgency</b>	Low <b>urgency</b>
High <b>importance</b>	I	II
Low <b>importance</b>	III	IV

### Checking consistency

- A higher priority task cannot be scheduled after a less priority one
- This is the responsibility of the user! The system only checks the constraint

## Trust in Agents

### Why trust?

- Trust is a central mechanism of coordination in situation of ignorance
- Trust can compensate the absence of information due to absence of sharing
- Individual trust supports dynamics

### Sharing with trust

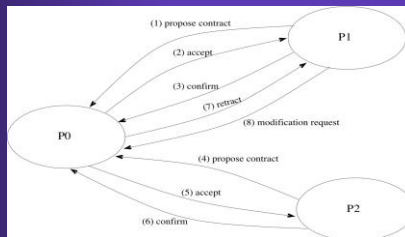
- A trust model calculates a trust capability in an agent permitting the sharing with this agent
- The trust model is based on several sources of trust (reputation, experiences, categorization, etc.)
- Which sources of trust to choose? It depends to the context, all sources are not necessarily at disposal

## Negotiating a meeting (1)

In absence of sharing, negotiation is necessary

### Negotiation level

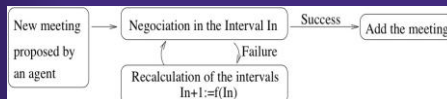
- Several rounds of negotiation
- Proposition, counter-proposition, confirmation and retraction of meetings



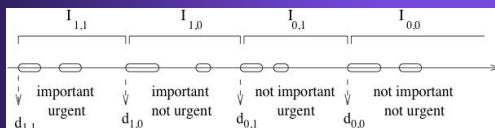
## Negotiating a meeting (2)

### Strategic level

- Negotiation a meeting inside a time interval of possible solutions



- These intervals are built from the tasks and according to the different importance/urgency priorities



## DECENTRALIZED CALENDARS

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## CITIZEN AGENTS

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## CITIZEN AGENTS

To support every day's life of every citizen

### VOWELS approach

- One personal assistant per life domain, being the **A**
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- Groups **O** : Family, Team, Consortium
- User **U**: Importance and urgency are subjective

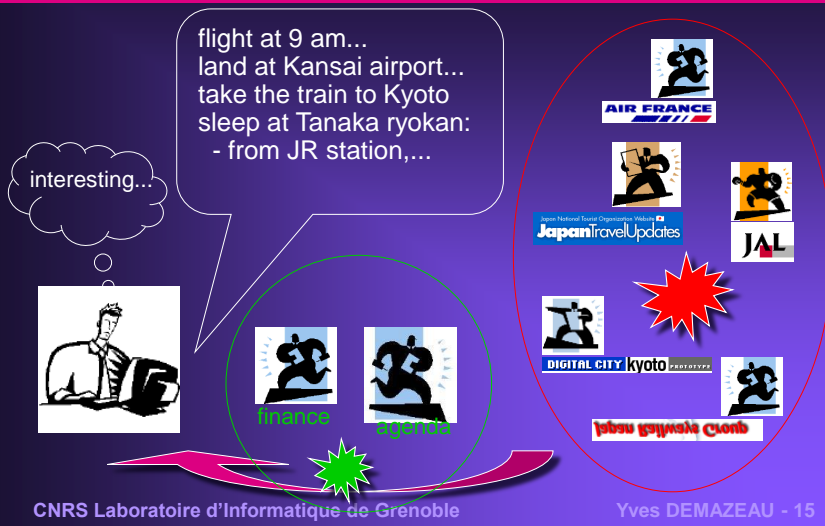
### Applications

- Leisure : citizen as a **consumer**
- Finance : citizen as a **partner**
- Administration : citizen as a **provider**

## CITIZEN AGENTS Towards Complex Requests



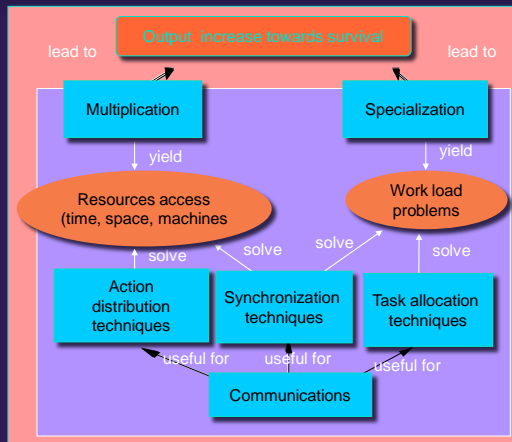
## CITIZEN AGENTS Towards Global Answers



## COGNITIVE COORDINATION

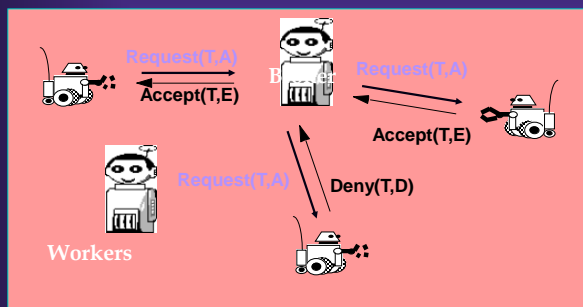


## Systems of coordination



## TA Centralized allocation

### Use of a broker to centralize requests and offers



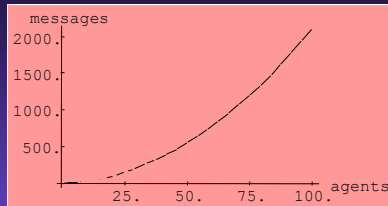
## TA Centralized allocation

### Advantages

- Simple to realize
- System coherence (the broker knows every agent)
- More or less easy to add or suppress agents (check in, check out protocol)

### Drawbacks

- Sensitive to broker failure
- Bottleneck for messages (in  $O(N^2)$ )
- Useless for very large networks (use many brokers)



## TA Acquaintance networks

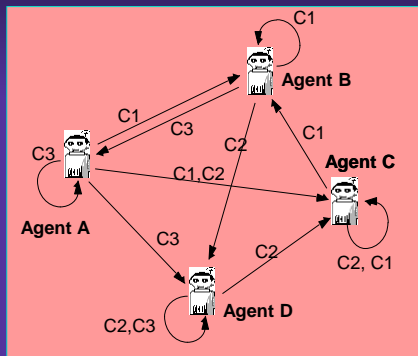
Each agent "knows" the skills of a set of agents

### Direct allocation

- An agent request a service to agents it directly knows

### Indirect allocation

- Speech acts are propagated through the network
- Uses algorithms adapted from distributed operating systems classics



## TA Acquaintance networks

### Advantages

- Not sensitive to failures or shut down of agents
- Good performances due to parallelism
- Can introduce learning methods to increase performances

### Drawbacks

- Problem of reorganization of acquaintance network when an agent is suppressed (see the problem of management of URL links in the WWW)
- More difficult to implement (due to parallelism)
- Subject to incoherencies

## TA Contract Net [Smith 80]

### The most widely known algorithm in DAI

#### Uses the protocol of state markets and two types of agents (two roles)

- Managers and Bidders

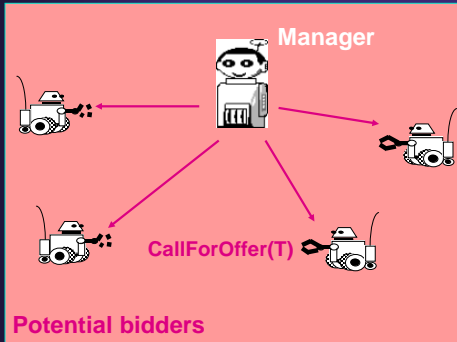
**It is realized in 4 steps :** Call for offer, Offers (bids), Awarding contract, Contracting and work

#### Problems with the Contract Net

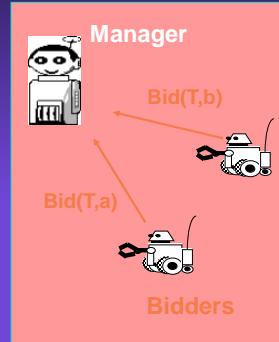
- Subcontractors and commitment
- Deadlines
- Multiple managers and optimality

## TA Contract Net : Call for Offer & Offers

### Call for offer

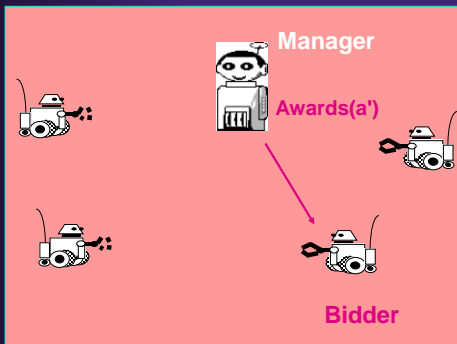


### Offers (bids)

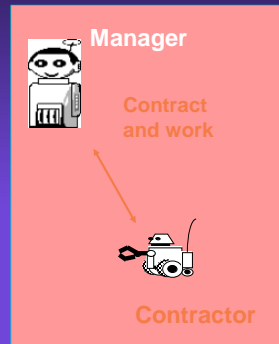


## TA Contract Net : Awarding contract & Contract

### Awarding contract

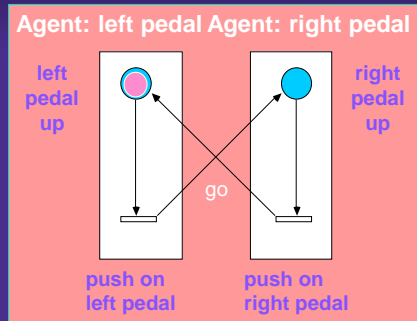


### Contracting and work



## SYNCHRONIZATION The Cyclist example

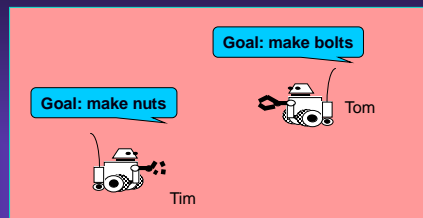
### The cyclist example



## SYNCHRONIZATION The resource access example

**behavior Tim**  
go to the machine  
places metal in  
machine  
makes a nut  
carry nut to stock

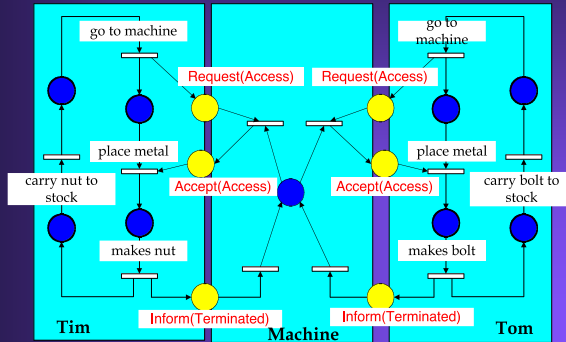
**behavior Tom**  
go to the machine  
places metal in  
machine  
makes a bolt  
carry bolt to stock



**Pb: conflict between Tim and Tom to access the machine**

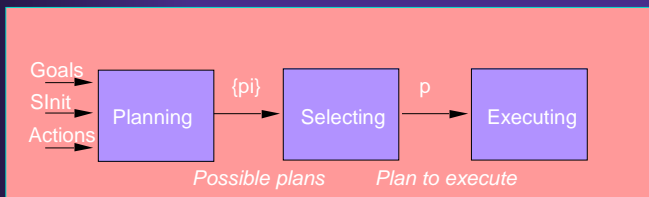
## SYNCHRONIZATION The resource access example

Consider the machine as an agent (at least as a process) which gives access to one agent at one time



## AD Multi-Agent Planning [Grosz 96]

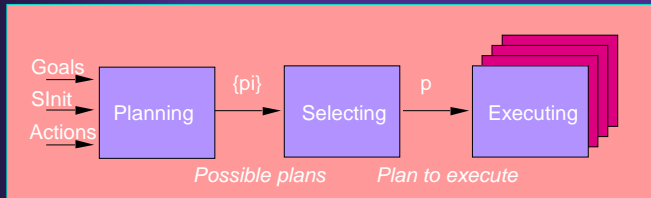
Find a sequence of operators  $O_i$  such that  $S_{fin} = On(... O_2(O_1(S_{init})) ...)$ . Each operator is seen as a transition in a state space. The solution is obtained by finding a path from initial state to final state.



Centralized planning for multiple agents  
Centralized coordination for partial plans  
Distributed coordination for partial plans

## AD Centralized planning

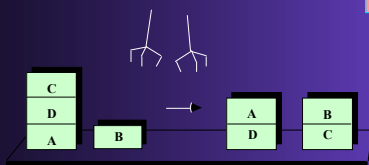
A central system which both plans and distribute plans among agents. Agents are just executors.



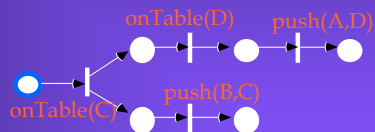
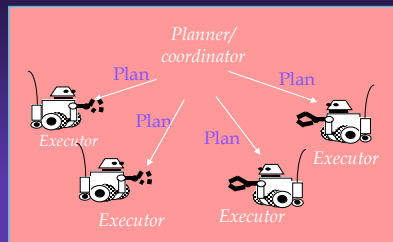
Coordination

## AD Centralized planning

Planning for multiple agents  
= planning  
+ coordination



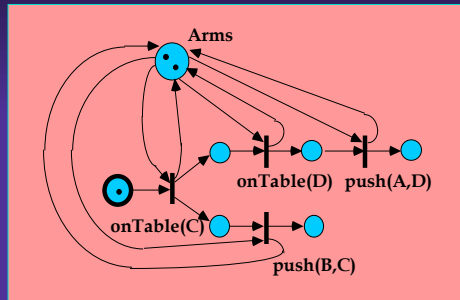
The problem



The plan

## AD Centralized planning

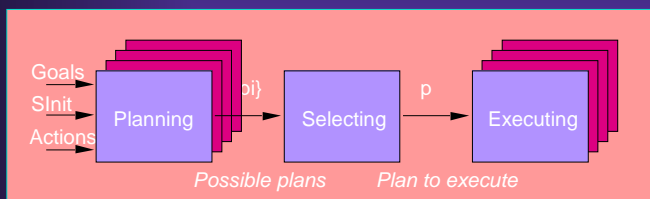
Coordination  
=  
resource  
allocation  
+  
synchronization



Each arm is considered as a resource and is represented as a token in the Petri net

## AD Centralized coordination

The planning process is distributed but coordination of partial plan is centralized. The preferred approach.

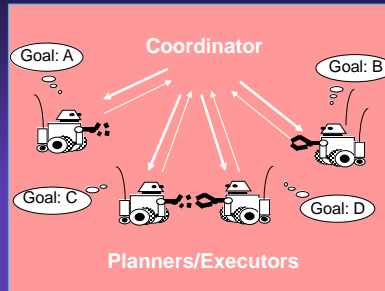




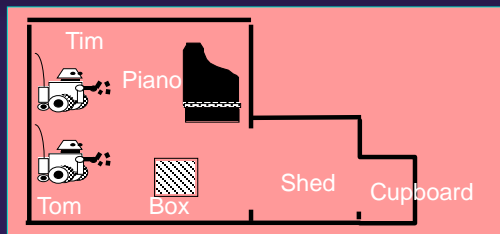
## AD Centralized coordination

### Fusion of partial plans

- Partial plan
- Coordinated plan



## AD Centralized Coordination



**Operator:** movePiano

nbAgents: 2

pre: Loc(Piano, la), Empty(Shed)

del: Loc(Piano, la), Empty(Shed)

add: Loc(Piano, Shed), Full(Shed)

**Operator:** moveBox

nbAgents: 1

pre: Loc(Box, lb), Empty(Shed),

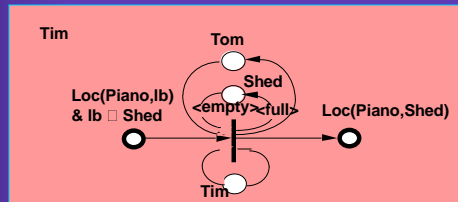
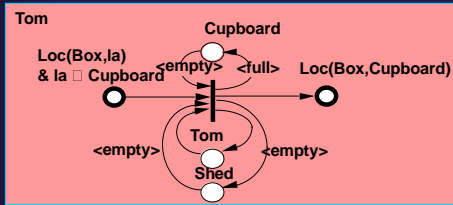
Empty(Cupboard)

del: Loc(Box, lb), Empty(Cupboard)

add: Loc(Box, Cupboard),

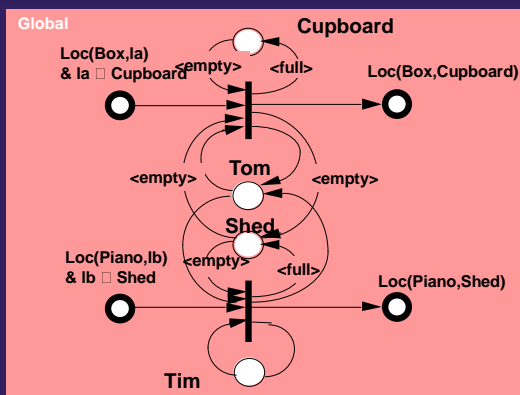
Full(Cupboard)

## AD Centralized Coordination



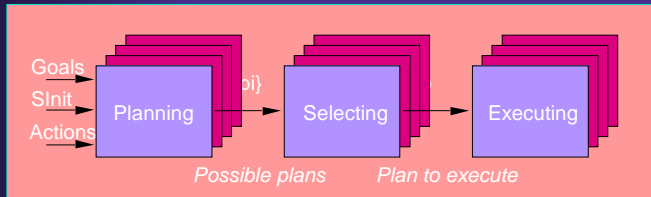
**Principle: stick plans together by unifying places**

## AD Centralized Coordination



## AD Distributed Coordination

The planning process is distributed but coordination of partial plan is centralized. The most difficult.



Partial Global Planning as the main result so far.  
Assumption-based planning algorithms since then.

## AD Distributed coordination [Durfee 91]

Each agent produces a **partial plan**. Existence of **possible conflicts between the different plans** (more difficult situation, non exhaustively solved by now)

### Possible solutions

- **One agent receives all the partial plans** (centralizing, merging, synchronizing partial plans)
- **Every agent sends its partial plans to everybody** (each agent analyses the potential conflicts and identifies the conflicts with its own plans)
- **The partial plans are executed. As soon as some conflict occurs during the execution, it is identified and handled** (which means that dynamic re-planning and execution is possible) (example PGP : Partial Global Planning)

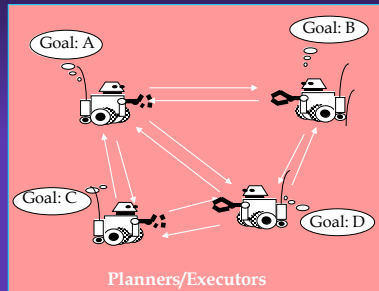
## AD Distributed coordination

### Two questions:

- Find the other agents with whom one should coordinate its plan
- When does it have to be coordinated

### Problems

- Detect conflict and synergies
- Convergence of plans  
*See for instance: PGP (Lesser, Durfee, Decker,..)*



→ Request information and partial plans

## AD Assumption-Based Planning

Agents interact collaboratively in the dialog in order to co-construct a plan without assumption

Agents have a dialogue based on speech acts

Agents can **refine**, **refute**, **repair** a conjecture. The plan is produced and revised through **conjecture / refutation** cycles

As in argumentation, the current plan is acceptable when the conjecture / refutation cycles end and no more objection remains

## AD Assumption-Based Planning [Pellier 05]

### Ideas

- Planning expressed as a problem where agents exchange proposals and counter-proposals
- Agents are able to formulate plan steps on hypothetical states of the world (conjectures)

### Advantages

- The approach merges the three steps : collaborative plan generation, composition, coordination
- The uncertainty as taken into account in the agents reasoning allows the agents to make conjectures and to compose their heterogeneous competences

### An agent can

- Elaborate plans under partial knowledge
- Produce plans that partially contradicts its knowledge

## NEGOTIATION [Davis 83]

## Conflict Resolution

**Agents pursuing similar or different goals will have to face conflicts :** • resource accessibility • alternative solutions • conflicting interests or goals

**Example of conflict resolution techniques :**

- **A priori solution** using strength, authority, ...

## Conflict Resolution

**Agents pursuing similar or different goals will have to face conflicts :** • resource accessibility • alternative solutions • conflicting interests or goals

**Example of conflict resolution techniques :**

- **A priori solution** using strength, authority, ...
- **Mediation** by a third agent which knows about the different points of view, and tries to solve the conflict

**Example of mediation on the net [Koning 95]**

J.-L. Koning, M. Occeello, N. Ferrand, Y. Demazeau, F. Van Aeken & Ch. Baeijs, "A Multi-Agent Approach for Mediation Support on the Net", 1<sup>st</sup> Int. Workshop on Decentralized Intelligent and MAS, DIMAS'95, pp. 251-258, Krakow, 1995.

## Conflict Resolution

**Agents pursuing similar or different goals will have to face conflicts :** • resource accessibility • alternative solutions • conflicting interests or goals

### Example of conflict resolution techniques :

- **A priori solution** using strength, authority, ...
- **Mediation** by a third agent which knows about the different points of view, and tries to solve the conflict
- **Negotiation** agents in conflict enter a transactional phase (exchanges, compromises, persuasive arguments, disagreement with the compromise or argument, requests for additional information, reasons for disagreement, utilities / preferences for the disagreed-upon issues) in order to reach an agreement, i.e. an equilibrium state

## Negotiation Structure

### Negotiation structure

- **step 1** : A propose a solution
- **step 2** : B evaluates the solution, determines its satisfaction
- **step 3** : If B is satisfied, ok, otherwise B propose another solution with regards to its own goals and constraints
- **step 4** : goto step 1 exchanging A and B roles

## Negotiation control

### Negotiation structure

- **step 1** : A propose a solution
- **step 2** : B evaluates the solution, determines its satisfaction
- **step 3** : If B is satisfied, ok, otherwise B propose another solution with regards to its own goals and constraints
- **step 4** : goto step 1 exchanging A and B roles

### Negotiation control

- **Consensus** (zero cost as summary) : the solution is found without additional cost for either of one or the other agent
- **Compromise** : (negative utility as summary) each party relaxes its weakest constraints. The solution is found as soon as every constraint is satisfied
- **Integration** : (positive utility as summary) each part tries to induce the deep goals of the others and then tries to find a solution which will satisfy these deep goals, even not the fully surface solutions

## Conflict resolution

**Agents pursuing similar or different goals will have to face conflicts** : • resource accessibility • alternative solutions • conflicting interests or goals

### Example of conflict resolution techniques :

- **A priori solution** using strength, authority, ...
- **Mediation** by a third agent which knows about the different points of view, and tries to solve the conflict
- **Negotiation** agents enter a transactional phase in order to reach an agreement, i.e. an equilibrium state
- **Flip a coin**



## Conflict resolution

**Agents pursuing similar or different goals will have to face conflicts :** • resource accessibility • alternative solutions • conflicting interests or goals

### **Example of conflict resolution techniques :**

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## TRUST

## Trust in MAS

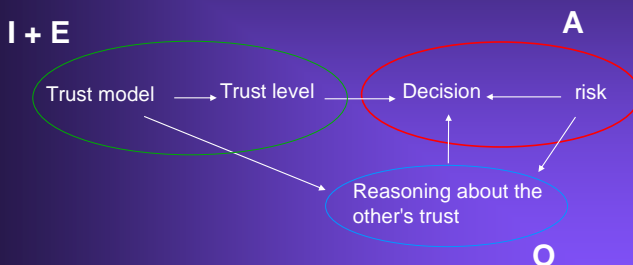
**Expansion of the distributed systems such as electronic trade, services for citizens, or BtoB applications**

- Act in an open, unpredictable, dynamic environment
- Need for guaranteeing security
- Need for providing the best services for other services and users

**Trust: mechanism of social integration and mechanism of coordination**

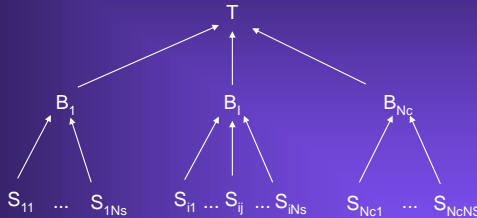
## Trust model based [Melaye 05]

**Trust is regarded as a mental state and consists of beliefs in the behaviour of the other, in connection with something in a precise field or context.**



## Bayesian trust network : first approach

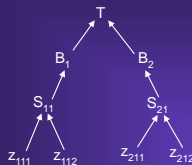
- Beliefs: ability, willingness, danger, opportunity...
- Each component is associated with a probability of satisfaction. The subjective certainty of the beliefs is derived from the credibility of their sources



- Computation by Bayesian inference: influences between the components are supported by conditional probabilities
- Dynamics using Kalman filtering

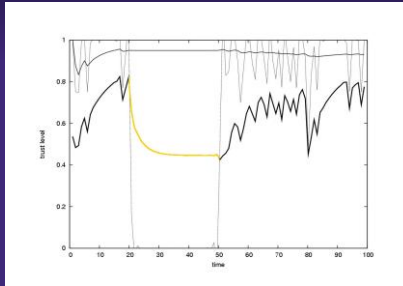
## Dynamic trust model : first experiments

### Simple instantiation of our model



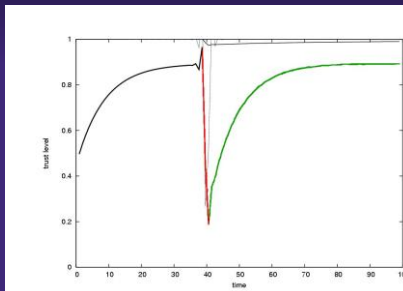
- Two beliefs and only one source
- Bernoulli distribution
- A priori distribution: uniform
- Common sense inertia: the decrease is faster than the increase
- No belief is privileged

## Experiment : erosion of trust



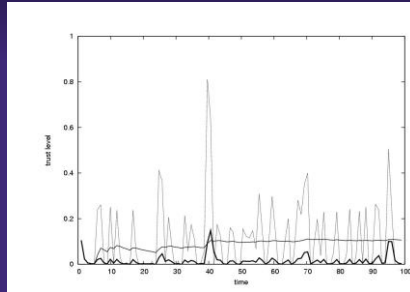
**Erosion:** in the absence of information, trust drifts towards a default value corresponding to an increase of the uncertainty

## Experiment : impact of a negative observation



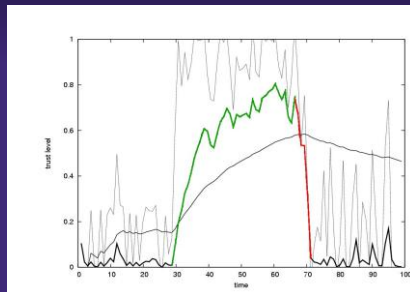
**Only one negative observation corresponds to a contradiction perceived in regard to the previous positive observations**

## Experiment : impact of a positive observation



**Only one positive observation has a weak impact on trust**

## Experiment : versatile behaviour



**Inertia of trust and distrust: speed to swing to one to the other**

# ORGANISATIONS

## History (1)

### -> 1992 : Introducing the concept

- 77 : Distributed Interpretation - Hearsay-II [Lesser 80]
- 80 : Contract Net [Smith 80]
- 83 : Organizational Self-Design - DVMT [Corkill 83]
- 87 : Organizational Structures [Pattison 87]
- 89 : Organization Knowledge - MACE [Gasser 89]
- 90 : Roles and Social Structure [Werner 89]

### 1990 -> 2000 : Settling the concept

- 92 : Organizations and Coordination [Bouron 92]
- 92 : Social Laws [Shoham 92]
- 93 : ASIC [Boissier 93][Ricordel 99]
- 93 : Conventions [Jennings 93]
- 94 : Dependence Networks [Sichman 94]
- 95 : AEIO [Demazeau 95]

## History (2)

### 1990 -> 2000 : Setting the concept

- 96 : PopOrgs [Demazeau 96][Costa 96]
- 96 : Norms [Dignum 96] [Conte 99]
- 96 : Learning [Prasad 96] [Camps 98]
- 98 : Agents, Groups, Roles [Gutknecht 98]
- 98 : Roles [Kendall 98] [Stone 98]
- 99 : Dynamics [Baeijs 98] [Van Aeken 99] [Kozlak 00]

### 1998 -> : Exploiting the concept

- 98 : Organization Oriented Programming [Lemaitre 98]
- 98 : MADKIT platform (AGR) [Gutknecht 98]
- 99 : Institutions [Sergot 99] [Esteva 01]
- 01 : VOLCANO platform (AEIO) [Ricordel 01]
- 01 : MESSAGE methodology [Garijo 01]
- 01 : VOWELS [Demazeau 01]

## Definitions (1)

An arrangement of relationships between components, which results into an entity, a system, that has unknown skills at the level of the individuals [Morin 77] : **emergence**

An organization is characterized by : a division of tasks, a distribution of roles, authority systems, communication systems, contribution-retribution systems [Bernoux 85] : **norms**

A decision and communication schema which is applied to a set of actors that together fulfil a set of tasks in order to satisfy goals while guarantying a global coherent state [Malone 87] : **design**

## Definitions (2)

Tools to solve complex problems in order to overcome the individual limitations (cognitive, physical, temporal, institutional, ...) [Gasser 01] : **problem solving**

Models and tools to define a social order and to guarantee a social control [Castefranchi 01] : **socio psychology**

Organizations (O) as a ground brick of MAS just like the Agents (A), the Environment (E), and the Interactions (I), Organizations (O) as elements for structuring sets of entities within the MAS [Demazeau 95 97 02] : **computer engineering**

## Types and Classes [Baeijs 96]

### Types

- **Teams** : shared environment in which agents interact
- **Communities of practice** : formation of groups independently of predefined schemas
- **SIGs** : gathering of agents sharing some interest
- **Markets** : common value sharing
- **Groups** : goal sharing, heterarchical decision
- **Hierarchies** : system sharing, hierarchical decision



## Types and Classes [Baeijs 96]

### Types

- **Teams** : shared environment in which agents interact
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### Classes

- **Centralized** : simple hierarchies, multi-level hierarchies, recursive structures, ...
- **Decentralized** : multiple hierarchies, Markets, Markets, ...
- **Unstructured** : groups, teams, SIGs, communities of practice, ...

## Types and Classes [Baeijs 96]

### Types

- **Teams** : shared environment in which agents interact
- **Communities of practice** : formation of groups independently of predefined schemas
- **SIGs** : gathering of agents sharing some interest
- **Markets** : common value sharing
- **Groups** : goal sharing, heterarchical decision
- **Hierarchies** : system sharing, hierarchical decision

### Classes

- **Centralized** : simple hierarchies, multi-level hierarchies, recursive structures, ...
- **Decentralized** : multiple hierarchies, Markets, Markets, ...
- **Unstructured** : groups, teams, SIGs, communities of practice, ...

## Inspiration sources (1) [Demazeau 02]

### Mathematics

- [Corkill 83], [Bouron 92], [Boissier 93], [Ricordel 99]
- Orders, to improve convergence issues.
- O as predefined authorities or shared social laws, that translate the controller-controlled relationships between possible pairs of agents.
- O are implemented as explicit rules, usually external.

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### Economics

- [Carley 99], [Kozlak 00]
- Markets, to educate users and to preserve resources.
- O as types and roles of agents sharing a common value, limiting their interactions with the environment and other agents.
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### Mechanics

- [Baeijs 98]
- Forces, to extract solutions of unsolved problems.
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### Social Psychology

- [Sichman 94], [Hannoun 99]
- Graphs, to compute the Human and Social Sciences models
- O express social dependences wrt actions and resources, enable to build dependence networks forming coalitions.
- O is represented as a network of acquaintances and links.

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J. Sichman, R. Conte, Y. Demazeau & C. Castelfranchi, "A Social Reasoning Mechanism based on Dependence Networks", 12<sup>th</sup> Eur. Conference on AI, ECAI'94, pp. 188-192, 1994.

## Inspiration sources (3) [Demazeau 02]

### Sociology

- [Costa 96], [Demazeau 96]
- Relationships, to maintain functional integrity of systems.
- O as states of organizations, to be matched with the set of interacting agents (population).
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### Thermodynamics

- [Van Aeken 99]
- MAS in WWW, to dynamically structure it, to optimize its social organization.
- O as recursive pairs of agents looking like the same, to be permanently restructured to optimize balance and entropy.
- O are represented by non-ordered binary trees.

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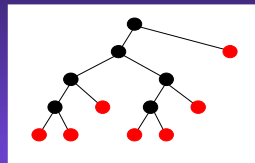
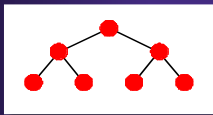
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## Minimal Multi-Agent Systems (1) [Van Aeken 98]

### Atomic agents and more complex agents

$$\Lambda = \{ S \mid S = \Delta \text{ or } S = (G D) = (D G) \text{ with } G, D \in \Lambda \}$$



### Agents behavior

- « qui se ressemble, s'assemble »

### MAS behavior

- Size of a closed SMAM is constant over time
- Equilibrium of a closed SMAM is maximizing over time
- Entropy of a closed SMAM is maximizing over time

## Minimal Multi-Agent Systems (2) [Van Aeken 98]

### Measuring SMAMs : Size, EQUilibrium, Entropy

$$EQ(S) = \frac{E(S)}{\log_2(TR(S))}$$

$$EQ(D) = 1$$

$$E(S) = \sum \frac{N(A)}{2^{N(A)}}$$

Francis Van Aeken & Yves Demazeau, "Minimal Multi-Agent Systems" (poster), 3rd International Conference on Multi-Agent Systems, ICMAS 98, IEEE, pp. 471-472, Paris, July 1998.

## FRIENDS (industrial project)

### A joint project between INPG and France Telecom

#### Vowels Approach

- Agents and Organizations as basic design bricks
- Dynamics principle : « qui se ressemble, s'assemble »
- Size of a closed SMAM is constant over time
- Equilibrium of a closed SMAM is maximizing over time
- Entropy of a closed SMAM is maximizing over time

#### Applications

- Augmented SMAMs vs. pure SMAMs
  - introduction of symbols
  - Adding attributes
- Friends
  - Off-Line (users and keywords)
  - On-Line (communityware, testing at ICMAS 98)
  - Numbercruncher (clustering, France Telecom QuiQuoiOù)

## FRIENDS (industrial project) / Numbercruncher

### QuiQuoiOù Data (France Telecom)

- 4997 services
- 146674 keywords, 16384 being different
- 70337 seconds (19.5 hours)
- 128 identified groups at level 7, and 18 at level 6

### Identified Groups at level 6

- |                |                |               |             |
|----------------|----------------|---------------|-------------|
| ■ RELIGION     | ■ LINGUISTIQUE | ■ SPORT       | ■ POLITIQUE |
| ■ ALIMENTATION | ■ ZOOLOGIE     | ■ LITTÉRATURE | ■ MUSIQUE   |
| ■ COMMERCE     | ■ MEDIA        | ■ DROIT       | ■ MEDECINE  |
| ■ ART          | ■ TRANSPORTS   | ■ EDUCATION   | ■ TELECOM   |
| ■ INFORMATIQUE | ■ GEOGRAPHIE   |               |             |

### Example of the GEOGRAPHIE subgroups

- |              |          |            |               |
|--------------|----------|------------|---------------|
| ■ CANADA     | ■ FRANCE | ■ BELGIQUE | ■ AGRICULTURE |
| ■ TRANSPORTS | ...      |            |               |

## Self-organisation

Firstly mentioned in the domain of physics

**Definition :** Changes to the internal order or organisation of a system without guidance or management from an outside source

**Examples :** Natural selection (characteristics that support survival become more common in the species), evolutionary computation, brain plasticity, neural networks, flocking behaviour

**Often confused with emergence, but...**

- there are instances of self-organisation without emergence
- there are instances of emergence without self-organisation



## PopOrgs (1) : Populations [Demazeau 96]

The **Population** structure is the set of agents, the set of possible behaviors of the agents, and the set of all interaction processes between agents

**Pop** = (Ag, Bh, Ip; bc, ic)

- Ag set of **Agents**
- Bh set of **Behaviors** agents are able to perform
- Ip set of interaction processes
- bcAg  $\rightarrow P(Bh)$ , **behavioral capability**  
bc(a), set of behaviors a is able to perform
- ic Ag x Ag  $\rightarrow P(Ip)$ , **interaction capability**  
ic(a1,a2), set of interaction processes  
agents a1 and a2 may perform together

## PopOrgs (2) : Organisations

The **Organization** structure is composed of organizational roles and organizational links

**Org** = (Ro; Li)

**Ro** is defined in a relational way

- e.g.  $Ro \subseteq Lp \times Gp$  : global processes (Gp) and local processes (Lp), the role is the part of agent's behavior that is integrated in the global process.
- e.g.  $Ro \subseteq Fo \times Lv$  : foci of interest (Fo), representation levels (Lv), the role is the agent's behavior for a given focus at a given level.

**Li**  $\subseteq Ro \times Ro$

### PopOrgs (3) : Pop $\bowtie$ Org

The suitable relation between the Pop and the Org is the **system's organization implementation**

It is any relation  $\text{imp} = \text{Pop} \bowtie \text{Org}$ , on  $(\text{Ro} \times \text{Ag}) \cup (\text{Li} \times \text{Ip})$ ,  $\text{Pop} = (\text{Ag}, \text{Bh}, \text{Ip}; \text{bc}, \text{ic})$ ,  $\text{Org} = (\text{Ro}; \text{Li})$ .

- if  $(r, a) \in \text{imp}$ ,  $r$  is said to implemented by  $a$
- if  $(l, p) \in \text{imp}$ ,  $l$  is said to implemented by  $p$

**imp is said "proper" iff  $\bowtie$  is an homomorphism.**

- $\forall r \in \text{Ro}, \exists a \in \text{Ag} / (r, a) \in \text{imp}$ , and  $r$  is properly implemented by some behavior  $b \in \text{bc}(a)$
- $\forall l = (l1, l2) \in \text{Li}, \exists ip \in \text{Ip} / \{ (l, ip) \in \text{imp} \wedge \exists (a1, a2) \in \text{Ag} \times \text{Ag} / ip \in \text{ic}(a1, a2), (r1, a1) \in \text{imp}, (r2, a2) \in \text{imp}, \text{ and } r1, r2 \text{ are properly implemented by the behaviors of } a1 \text{ and } a2, \text{ respectively} \}$

### PopOrgs (4) : Pop $\bowtie$ Org [Demazeau 96]

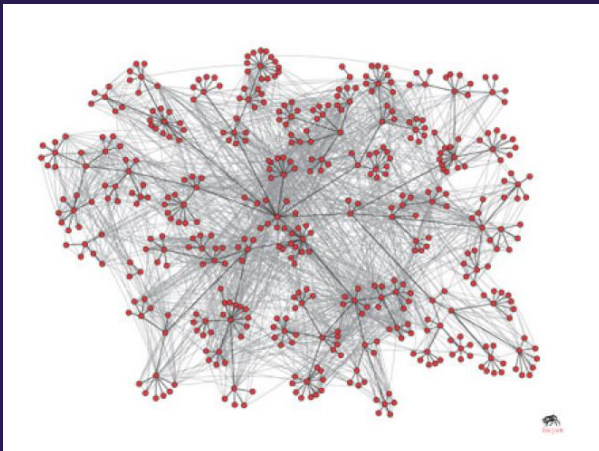
The Interior ( = Population + Organization ) of a time-invariant multi-agent system is captured by a **population-organization structure**  $\text{PopOrg} = (\text{Pop}, \text{Org}; \text{imp})$ , where

- $\text{Pop} = (\text{Ag}, \text{Bh}, \text{Ip}; \text{bc}, \text{ic})$  is a population structure
- $\text{Org} = (\text{Ro}; \text{Li})$  is a organization structure
- $\text{imp} \subseteq (\text{Ro} \times \text{Ag}) \cup (\text{Li} \times \text{Ip})$  is an organization implementation relation as defined previously

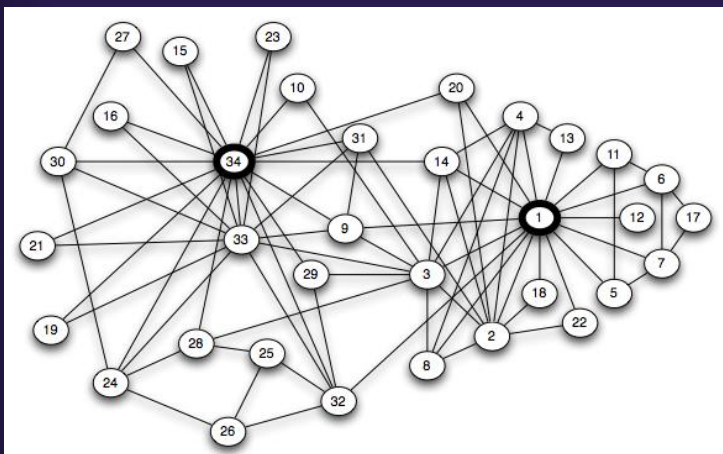
Y. Demazeau & A. Rocha Costa, "Populations and Organizations in Open MAS", 1<sup>st</sup> Nat. Symposium on Parallel and Distributed AI, PDAI'96, Hyderabad, 1996.

## NETWORKS

## Employees Network at HP Labs [Easley 09]



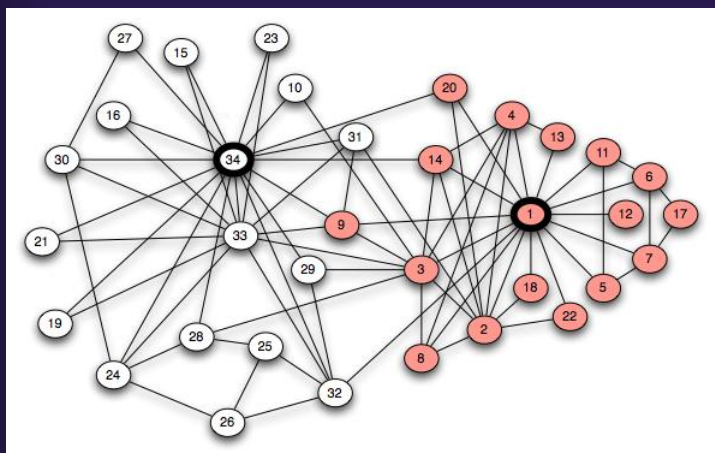
## Friendship Network at the Karate Club [Easley 09]



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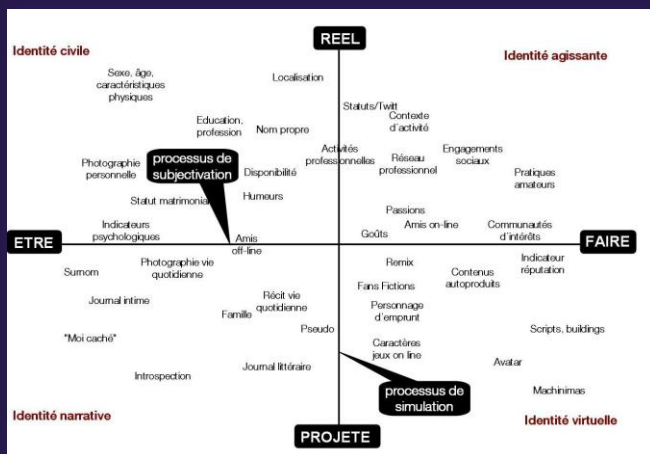
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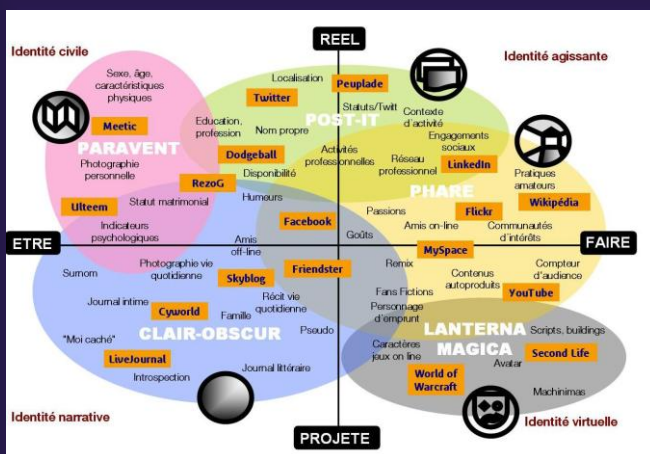
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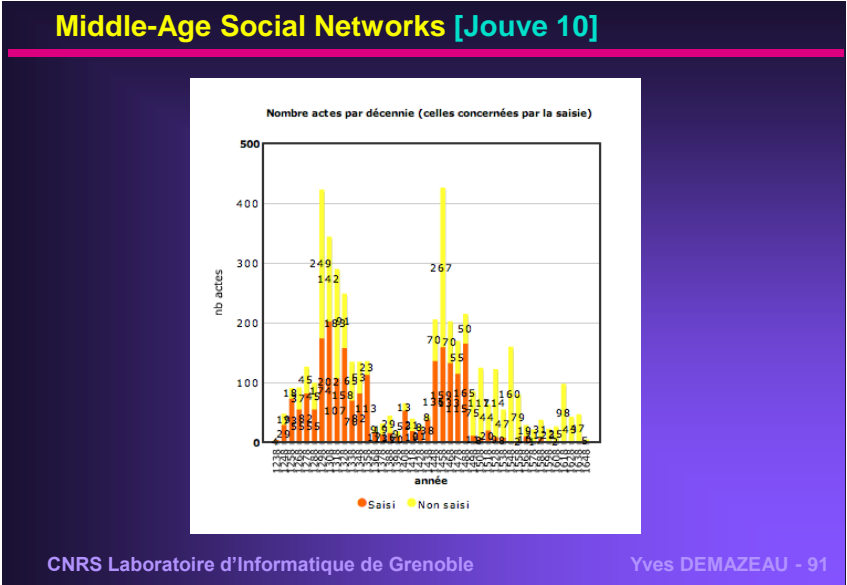
## Social networks (1) [Cardon 09]



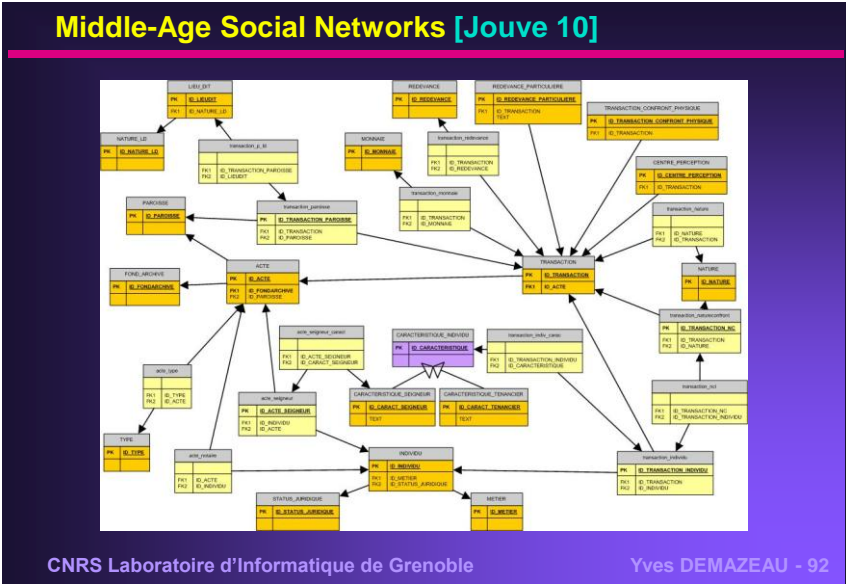
## Social networks (2) [Cardon 09]



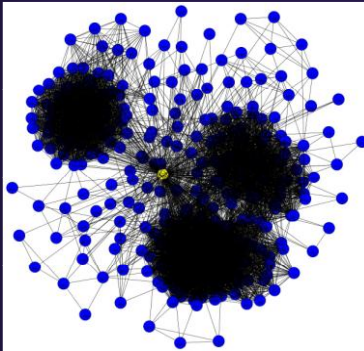
# Middle-Age Social Networks [Jouve 10]



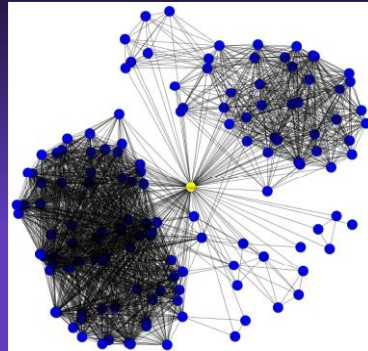
# Middle-Age Social Networks [Jouve 10]



## Middle-Age Social Networks [Lacomme 11]



n° 1714 Pierre de Prestis



n° 2905 Guillaume de Maurs

L. Lacomme, V. Camps, Y. Demazeau, Fl. Hautefeuille & B. Jouva, "Middle Age Social Networks: a dynamic organizational study". PAAMS'11, pp. 211-216, Salamanca, 2011.

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## Middle Age Transport Networks [Easley 09]



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## Dependency Networks [Sichman 94]

Each agent evaluates its social (goals or resource) dependencies from the external description of other agents, in terms of goals, actions, and resources

**social-autonomy (g) = action-autonomy (a,g)  
and resource-autonomy (r,g)**

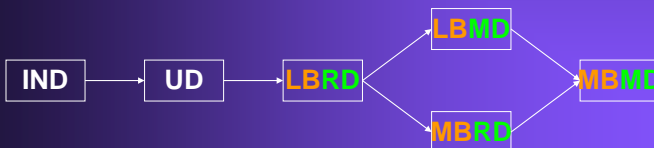
**social-dependency (g) = action-dependency (a,g)  
or resource-dependency (r,g)**

J. Sichman, R. Conte, Y. Demazeau & C. Castellfranchi, "A Social Reasoning Mechanism based on Dependence Networks", 12<sup>th</sup> Eur. Conference on AI, ECAI'94, pp. 188-192, 1994.

## Dependency Networks [Sichman 94]

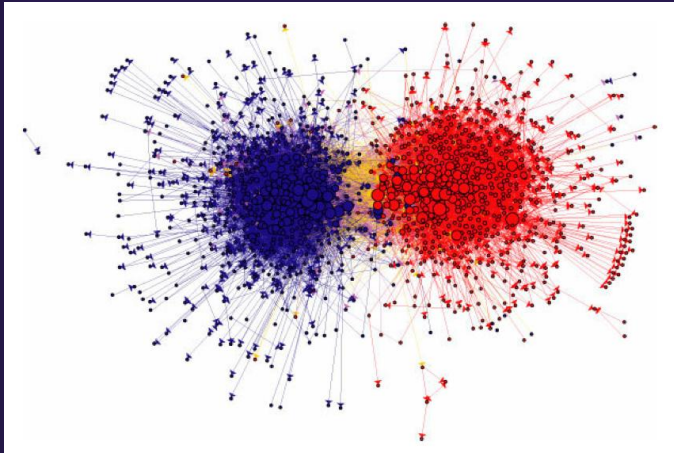
### Dependency Relationships between two agents

- Independency (IND)
- Unilateral dependency (UD)
- Mutual dependency (**MD**)
  - For the same goal
- Reciprocal dependency (**RD**)
  - For different goals
- Locally believed dependency (**LB**)
  - A1 cannot infer the dependency from A2's description
- Mutually believed dependency (**MB**)
  - A1 can infer the dependency from A2's description





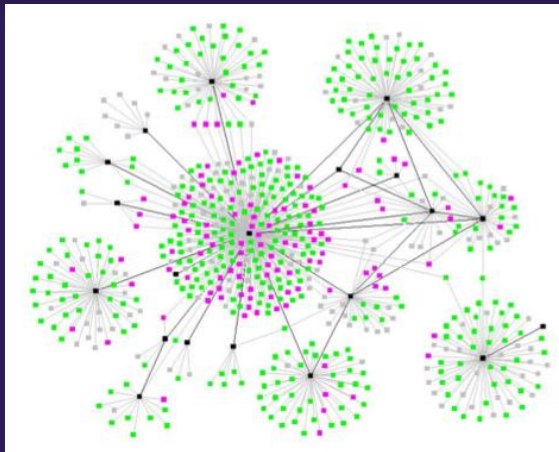
## Web page Network at 2004 US Election [Easley 09]



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## Epidemic Network [Easley 09]

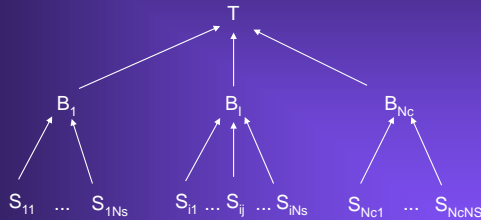


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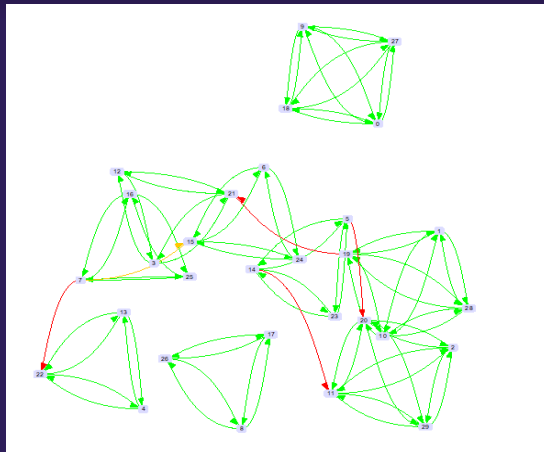
## Trust Networks [Melaye 05]

**Beliefs: ability, willingness, danger, opportunity...**  
Each component is associated with a probability of satisfaction. The subjective certainty of the beliefs is derived from the credibility of their sources

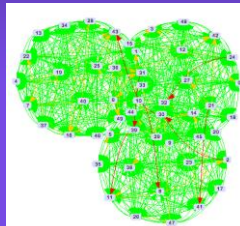
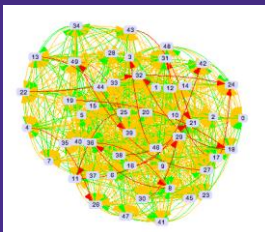
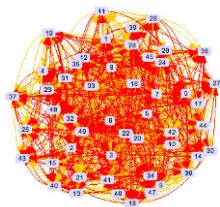


D. Melaye, Y. Demazeau & Th. Bouron, "Which Adequate Trust Model for Trust Networks?", 3<sup>rd</sup> IFIP Conference on Artificial Intelligence Applications and Innovations, AIAI'2006, IFIP, Athens, June 2006.

## Trust Networks / Statics [Melaye 05]



## Trust Networks / Dynamics [Melaye 05]



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## AGENCYITIES

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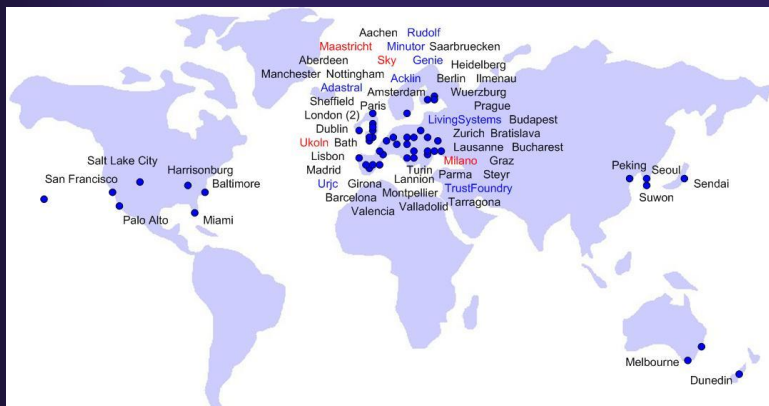
## AGENCYCITIES Europe



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## AGENCYCITIES World



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## **AGENCYCITIES Project [Willmott 03]**

### **100+ organizations involved worldwide**

- Including Industry giants : HP, Fujitsu, Motorola, ...
- Participating in an open test environment
- Long term deployment, evolution and integration of technologies

### **Key technology issues**

- Service interaction / semantics
- Service composition
- Automating service components

### **Concrete terms most groups work on:**

- Particular technology trials
- Particular application focus

## **AGENCYCITIES Network**

### **160 nodes registered**

- 70 or so active
- 30-50 "up" at any moment

### **Each service platform is connected live to the internet**

- FIPA Agent standard implementation
- DAML-OIL/OWL processing
- Local directories and services
- HTTP / XML communication

### **Now moving towards use by some major projects**

- Each working on different applications

## AGENCYCITIES Demo [Jul. 03]

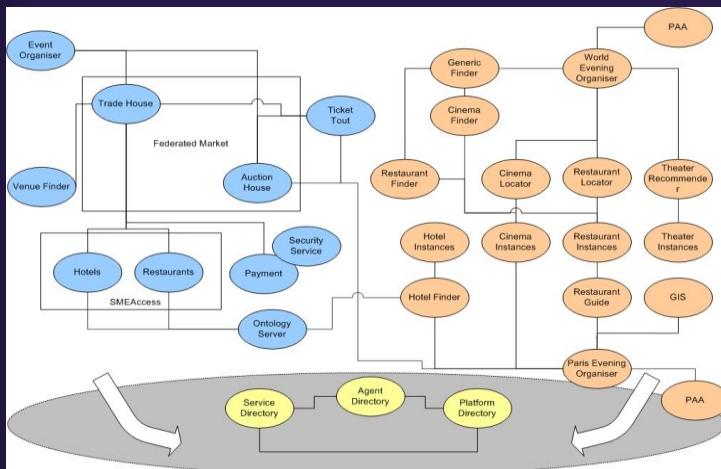
### Agent Based Service Components

- From simple representatives to personal agents to complex federated markets, hosting and infrastructure
- More than 25 service types, nearly 200 agents

### Business as Usual?

- Hosted by 14 companies and Universities
- Deployment on at least 5 different platform (JADE, FIPA-OS, AAP, ATOMIK Agent Shell, ZEUS) Dynamic application creation
- Fully specified communication interfaces
- Coherent frameworks for all aspects of the environment
- Automated process in many areas

## AGENCYCITIES Demo [Jul. 03]



## COMPLEMENTARY REFERENCES

## Complementary references

Traditional description of negotiation mechanisms

R. Davis & R. Smith, "Negotiation as a metaphor for distributed problem solving". *Artificial Intelligence*, 20, 63-109, 1983

The high-performing PGP, nothing better since !

E. Durfee & V. Lesser, "Partial global planning: A coordination framework for distributed hypothesis formation", *IEEE Transactions on Systems, Man, and Cybernetics*, 21, 1167-1183, 1991.

Traditional approaches to collaborative planning

B. Grosz & S. Kraus, S., "Collaborative plans for complex group action", *Artificial Intelligence*, 86, 269-357, 1996.

The strangely so recent Contract Net Protocol...

R. Smith, "The Contract Net Protocol: High-Level Communication and Control in a Distributed Problem Solver", *IEEE Trans. on Computers*, Vol C-29, n° 12, 1980.