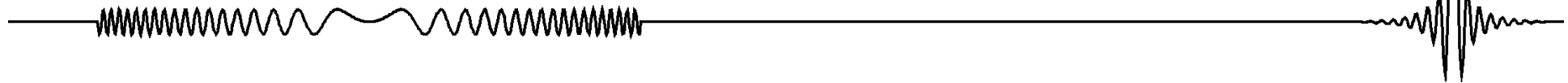


Applied Signal Processing & Computer Science



Chapter 3: Signals

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Chapter 3: Signals

3.1 Signal Classes

3.2 Some Useful Signal Operations

3.3 Delta Function

3.4 Why Digital Signal Processing?

3.5 Some Discrete-Time Signals

3.1 Signal Classes

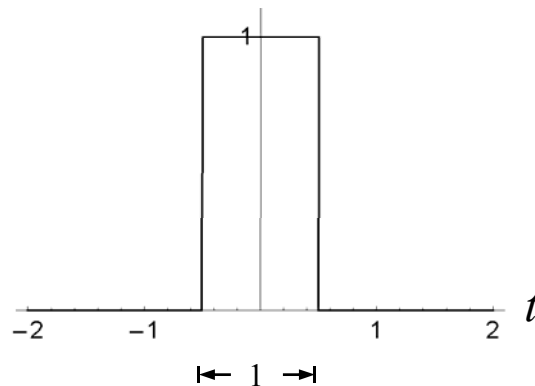
- energy(-limited) vs. power(-limited)

Energy(-limited) Signals:

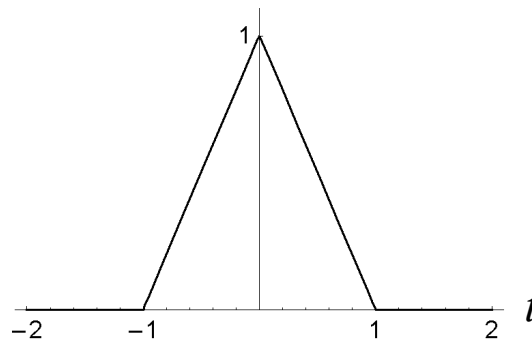
$$E = \int_{-\infty}^{+\infty} |u(t)|^2 dt < \infty$$

Examples of important energy-limited signals:

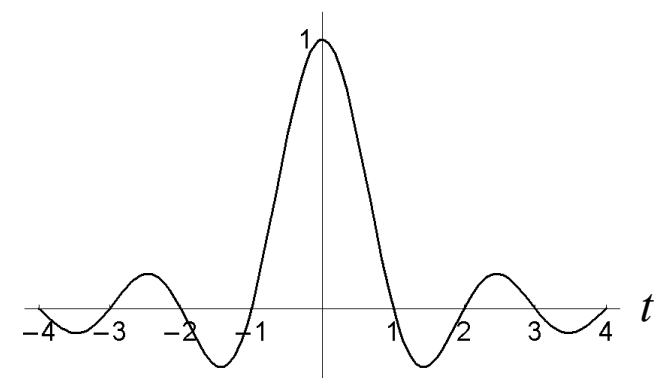
$$\text{rect}(t) = \begin{cases} 1 & |t| < 1/2 \\ 1/2 & |t| = 1/2 \\ 0 & |t| > 1/2 \end{cases}$$



$$\text{tri}(t) = \begin{cases} 1 - |t| & |t| < 1 \\ 0 & |t| \geq 1 \end{cases}$$



$$\text{sinc}(t) = \text{si}(\pi t) = \frac{\sin(\pi t)}{\pi t}$$



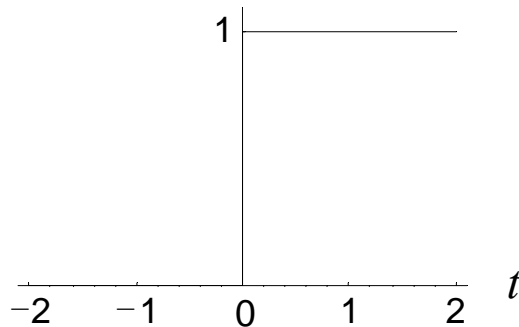
Power(-limited) Signals:

$$\overline{P} = \langle |u(t)|^2 \rangle = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^{+T} |u(t)|^2 dt < \infty$$

Examples:

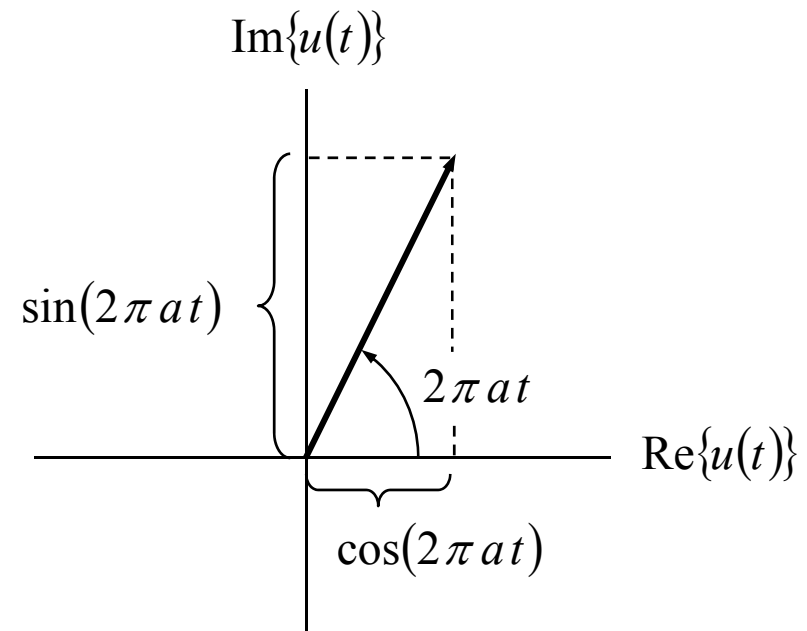
$$\gamma(t) = \begin{cases} 0 & t < 0 \\ 1/2 & t = 0 \\ 1 & t > 0 \end{cases}$$

step function



$$u(t) = \exp(j 2 \pi a t)$$

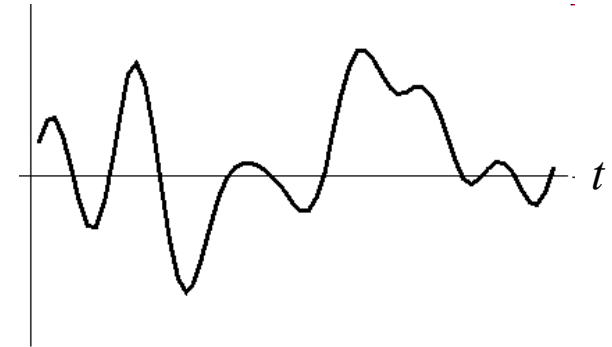
harmonic oscillation ($a \in \Re$)



Signal Classes

- energy(-limited) vs. power(-limited)
- continuous-time vs. discrete-time

Continuous-time Signals: $u(t)$ mit $t \in \mathbb{R}$



Discrete-time Signals: $u[n]$ mit $n \in \mathbb{Z}$



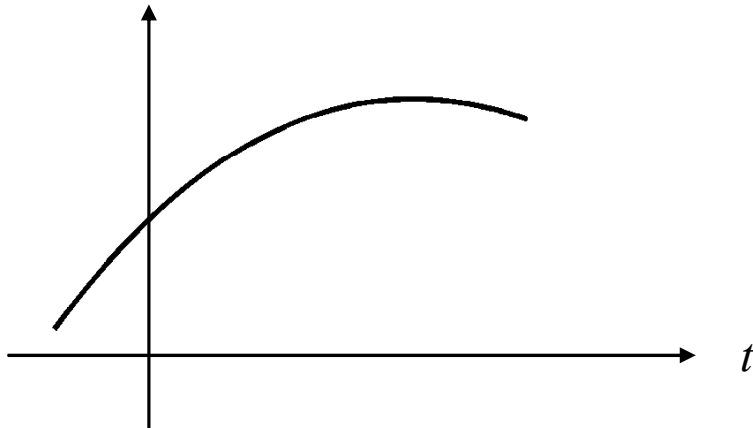
sequence representation: $u[n] \triangleq \{\dots, u[-1], u[0], u[1], u[2], \dots\}$

vector representation: $u[n] \triangleq (\dots, u[-1], u[0], u[1], u[2], \dots)^T = \begin{pmatrix} \dots \\ u[-1] \\ u[0] \\ u[1] \\ u[2] \\ \dots \end{pmatrix}$

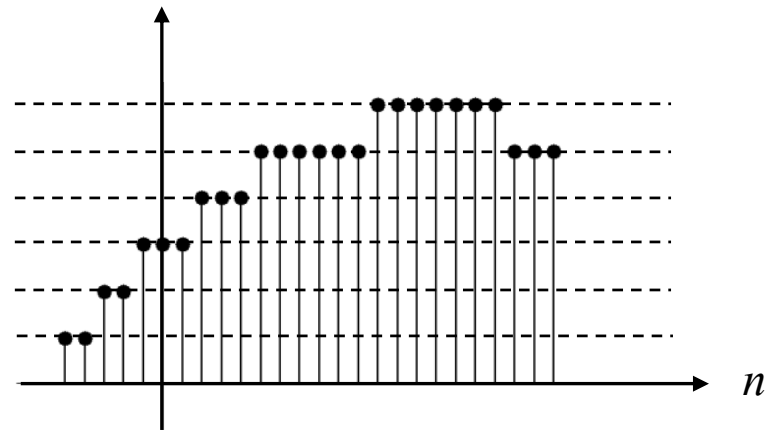
Signal Classes

- energy(-limited) vs. power(-limited)
- continuous-time vs. discrete-time
- analog and digital (discretizing amplitude of the signal)

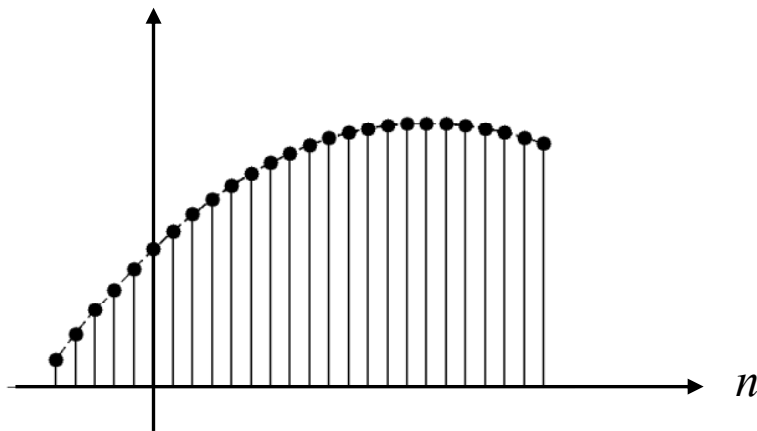
CT/DT vs. A/D



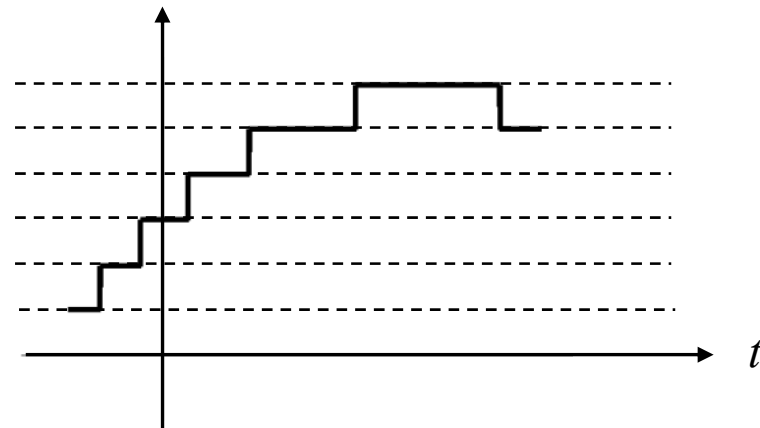
Analog & continuous-time
(analog signal)



Digital & discrete-time
(digital signal)



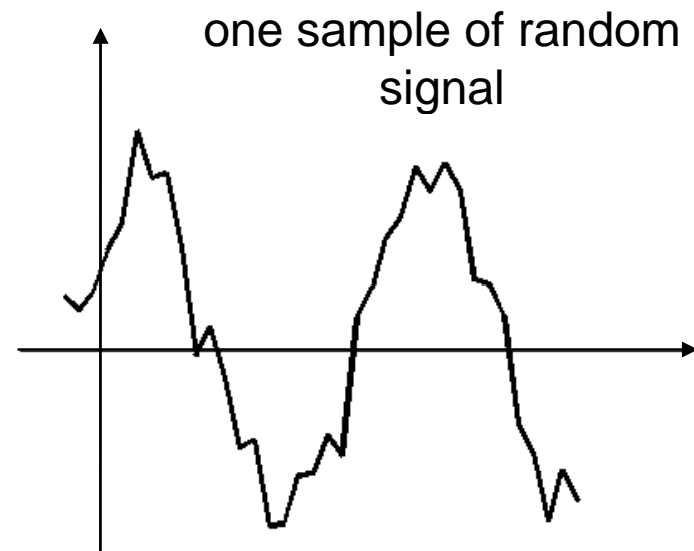
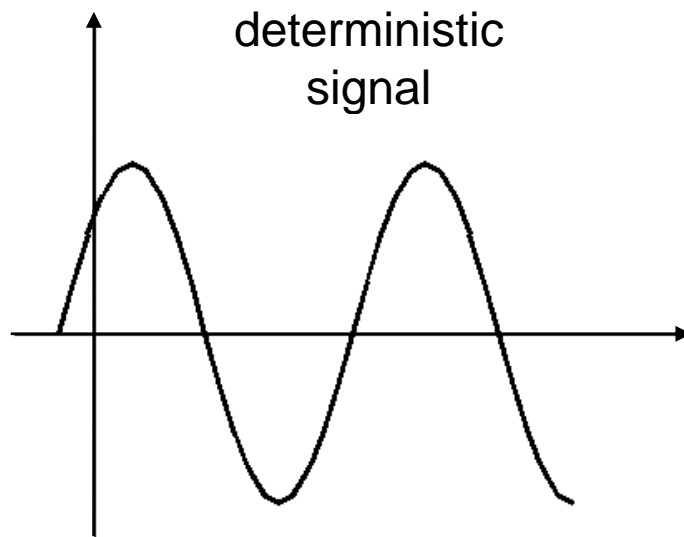
Analog & discrete-time
(sampled-data signal)



Digital & continuous-time
(quantized boxcar signal)

Signal Classes

- energy(-limited) vs. power(-limited)
- continuous-time vs. discrete-time
- analog and digital
- deterministic vs. non-deterministic: random signals vs. irregular signals



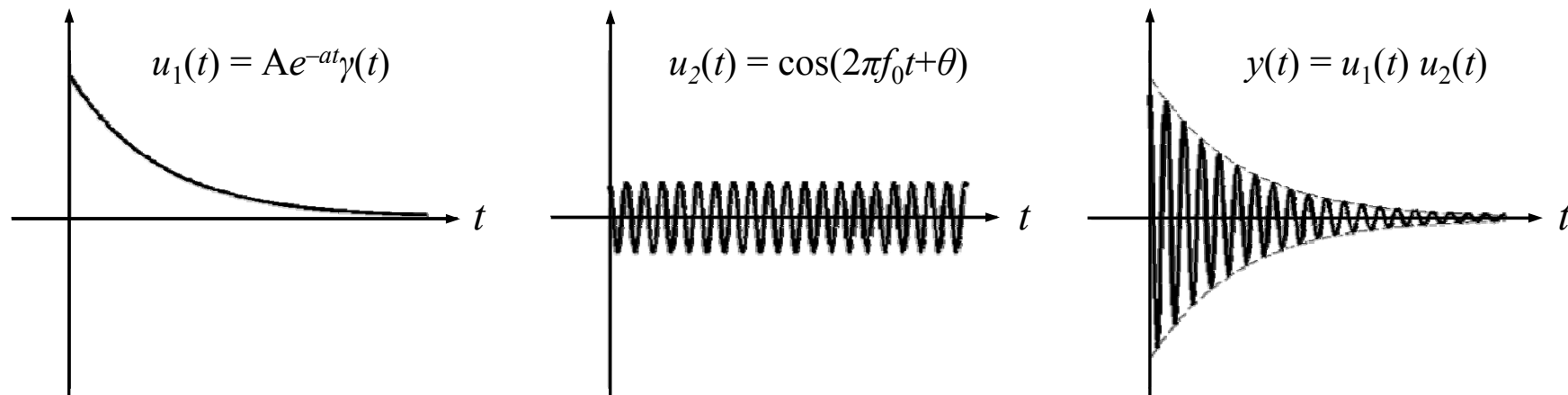
Signal Classes

- energy(-limited) vs. power(-limited)
- continuous-time vs. discrete-time
- analog and digital
- deterministic vs. non-deterministic
- periodic vs. non-periodic: $u(t) = u(t + mT), m \in \mathbb{Z}, T > 0$
- odd vs. even: $u(t) = -u(-t)$

3.2 Some Useful Signal Operations

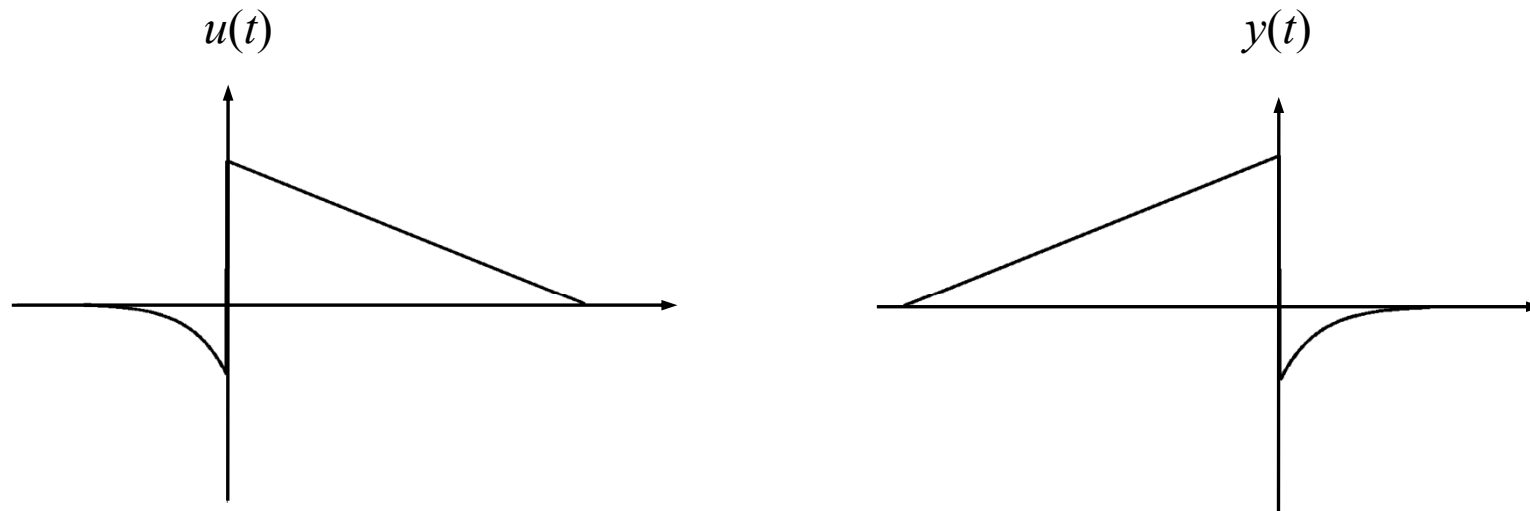
- Scalar multiplication: $y(t) = c u(t)$; $y[n] = c u[n]$; $c = \text{const}$
- Summation: $y(t) = u_1(t) + u_2(t)$; $y[n] = u_1[n] + u_2[n]$
- Multiplication: $y(t) = u_1(t) u_2(t)$; $y[n] = u_1[n] u_2[n]$

Example: amplitude-modulated sinusoid



Some Useful Signal Operations

- **Reflection:** $u(t) \xrightarrow{\text{reflection}} y(t) = u(-t)$



I.e. $y(t)$ is the mirror image of $u(t)$ about the vertical axis

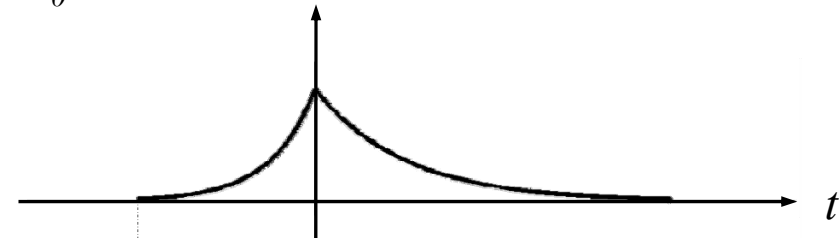
Some Useful Signal Operations

■ **Shifting:** $u(t) \xrightarrow{\text{shifting}} y(t) = u(t + t_0)$

I.e. to shift a signal by t_0 = replace t by $t + t_0$

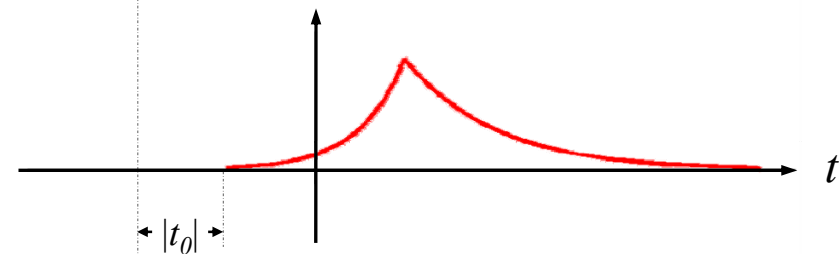
1. If $t_0 = 0$, $y(t) = u(t)$

=>



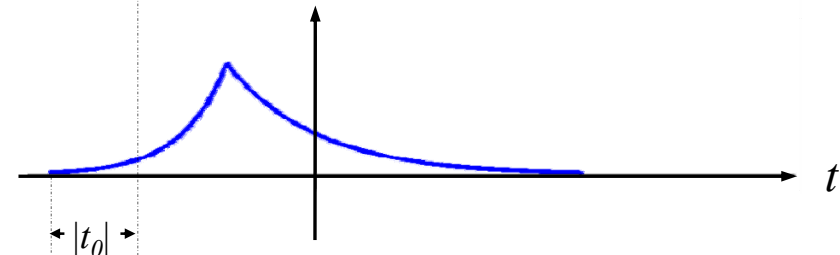
2. If $t_0 < 0$, shifted to the right by $|t_0|$

=>



3. If $t_0 > 0$, shifted to the left by $|t_0|$

=>



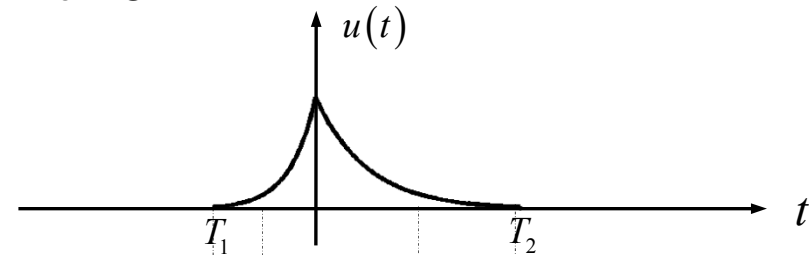
Some Useful Signal Operations

- **Scaling:** $u(t) \xrightarrow{\text{scaling}} y(t) = u(k t)$

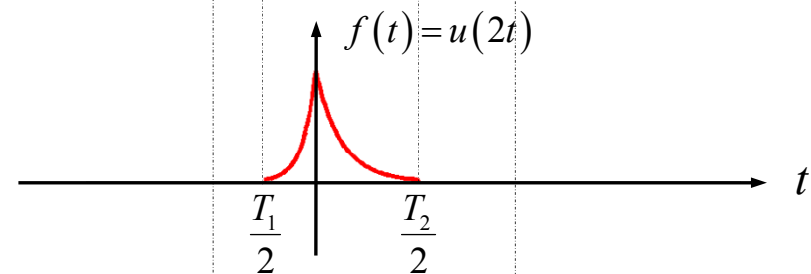
I.e. compression and expansion of a signal in time

1. If $k = 1$, $y(t) = u(t)$

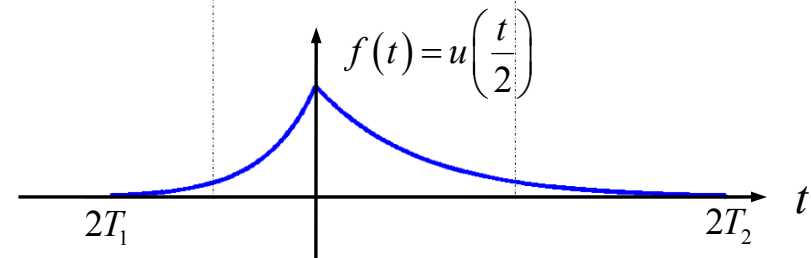
=>



2. If $k > 1$, compressed in t by a factor of k =>

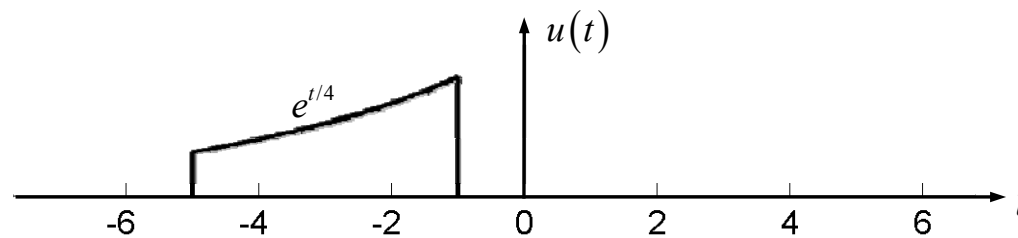


3. If $k < 1$, expanded in t by a factor of k =>



Some Useful Signal Operations

- Exercise: Given $u(t)$, please sketch $u(-2t - 3)$!



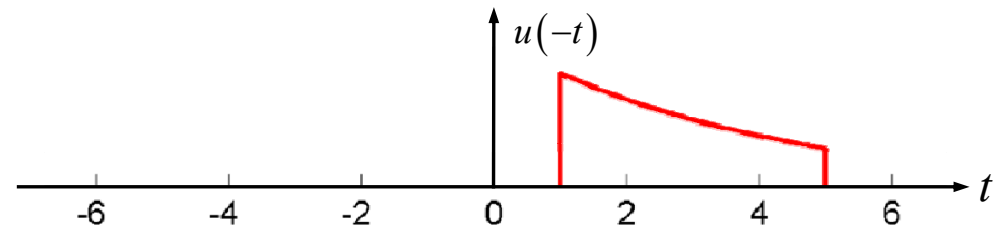
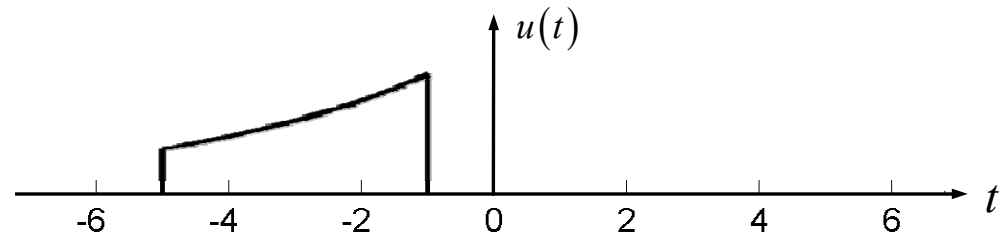
Some Useful Signal Operations

- Exercise: Given $u(t)$, please sketch $u(-2t-3)$!

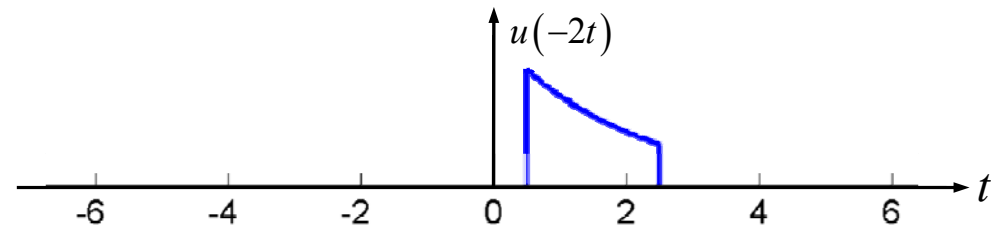
- Solution: $u(-2t-3) = u\left(-2\left(t + \frac{3}{2}\right)\right)$

I.e.

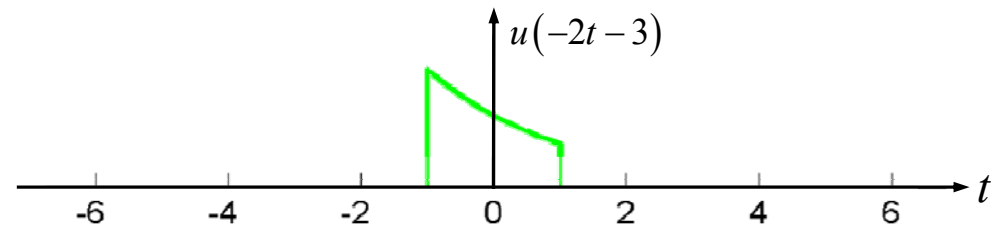
- ▶ Step 1: reflection



- ▶ Step 2: compress by a factor of 2



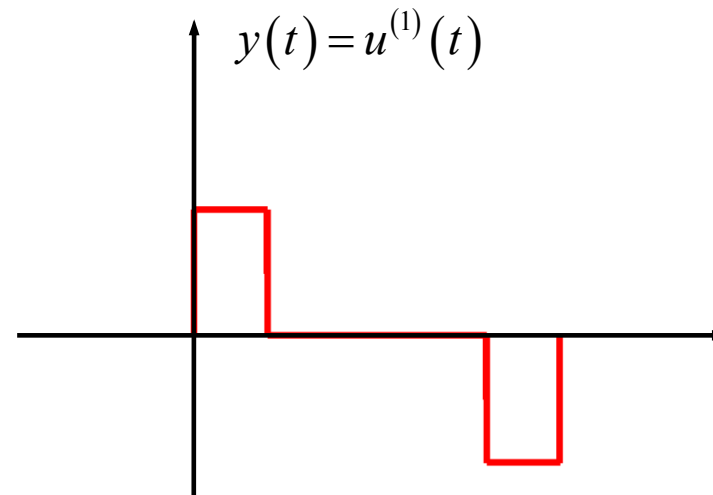
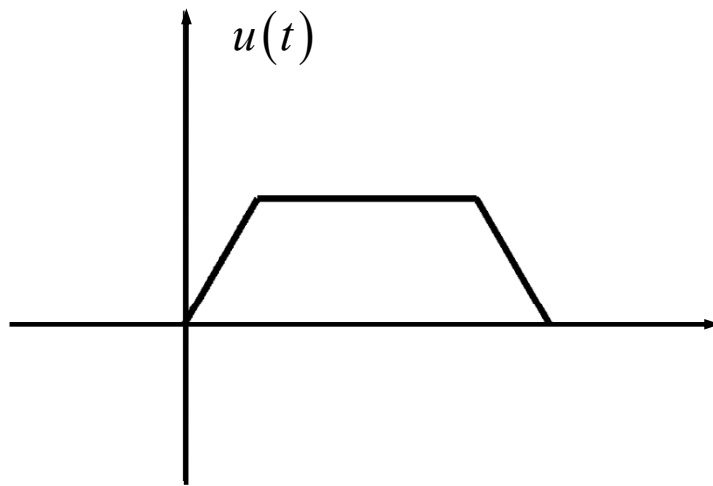
- ▶ Step 3: shift in time by 3/2



Some Useful Signal Operations

- **Differential:** $u(t) \xrightarrow{\text{differential}} y(t) = u^{(1)}(t) = \frac{d}{dt}u(t)$

All about finding **rates of change** of one quantity compared to another.



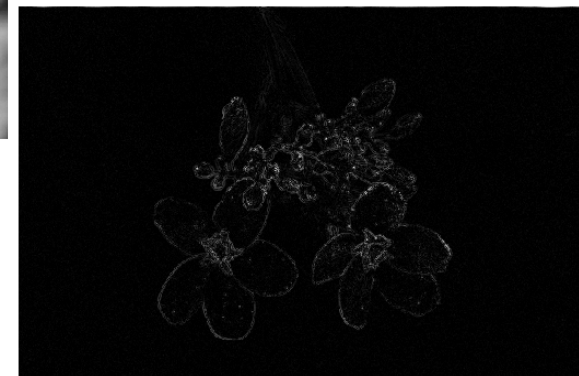
it emphasizes the change of a signal.

Some Useful Signal Operations

Example: Image sharpening by differentiation



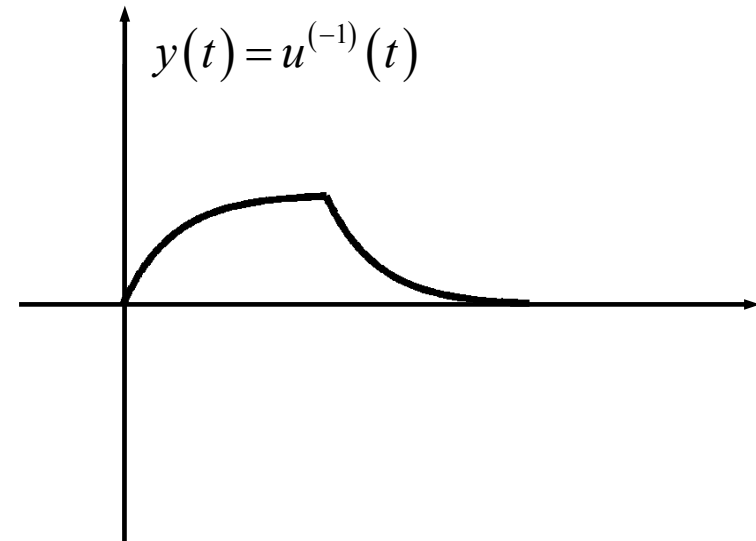
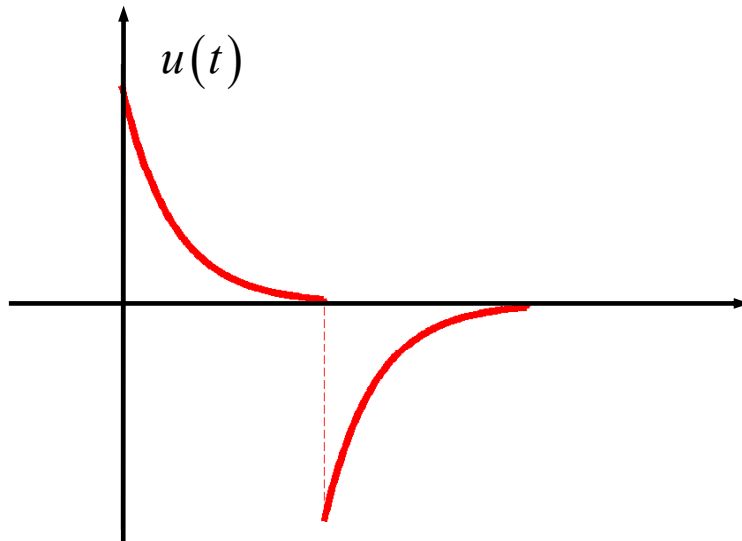
RGB image



Some Useful Signal Operations

- **Integral:** $u(t) \xrightarrow{\text{integral}} y(t) = u^{(-1)}(t) = \int_{-\infty}^t u(\tau) d\tau$

By differentiation we find the derivative of the given function, whereas by integration we **find the function whose derivative is known**.



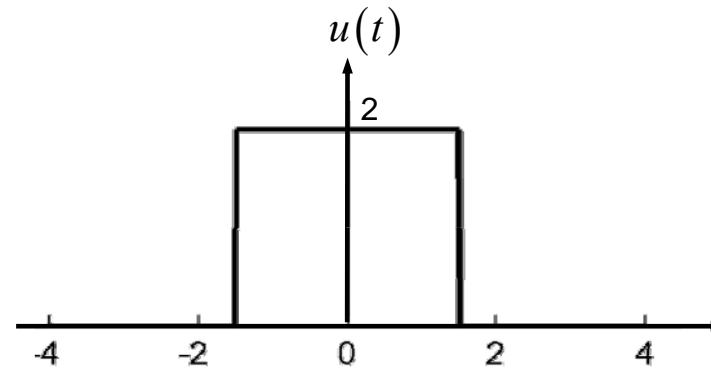
Integral table: <http://www.integral-table.com/>

Some Useful Signal Operations

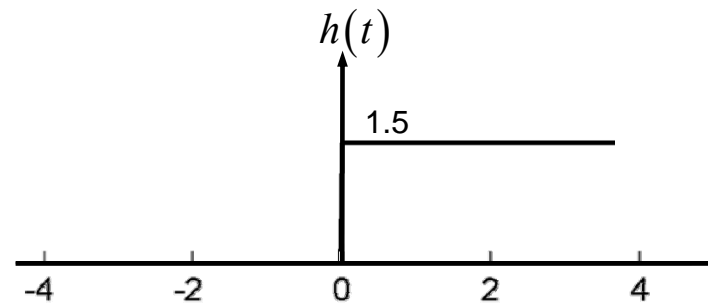
■ Exercise: Combined Operations

Given $u(t)$, $h(t)$ and $\tau = -1$, solve $\int_{-\infty}^{\infty} u(t)h(\tau - t)dt$ graphically.

► $u(t) = 2 \operatorname{rect}\left(\frac{t}{3}\right)$



► $h(t) = 1.5 \gamma(t)$

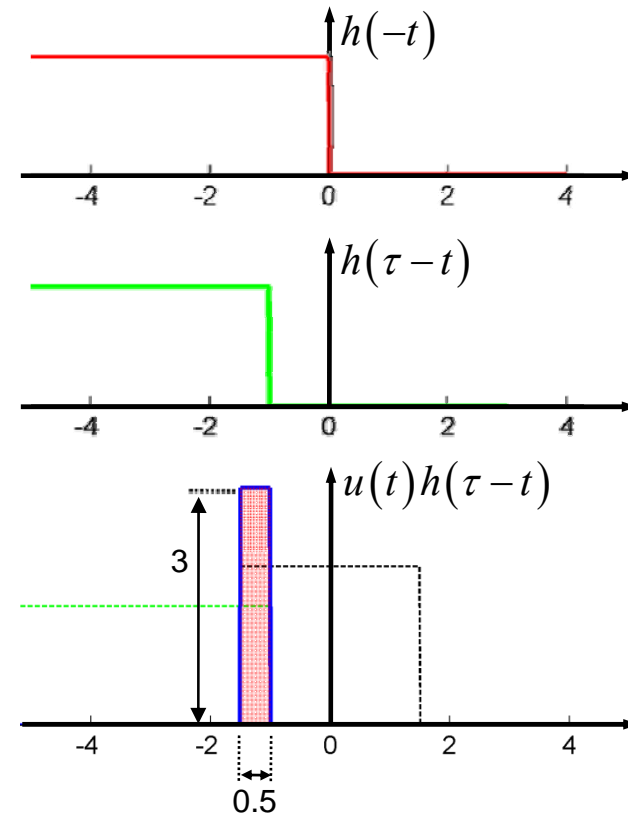


Some Useful Signal Operations

- Given $u(t)$, $h(t)$ and $\tau = -1$, solve $\int_{-\infty}^{\infty} u(t)h(\tau - t)dt$ graphically.

- Solution:

- ▶ Reflection of $h(t)$
- ▶ Shifting to the left by 1
- ▶ Multiplication with $u(t)$
- ▶ Integral



$$\int_{-\infty}^{\infty} u(t)h(\tau - t)dt = 0.5 \times 3 = 1.5$$

Convolution

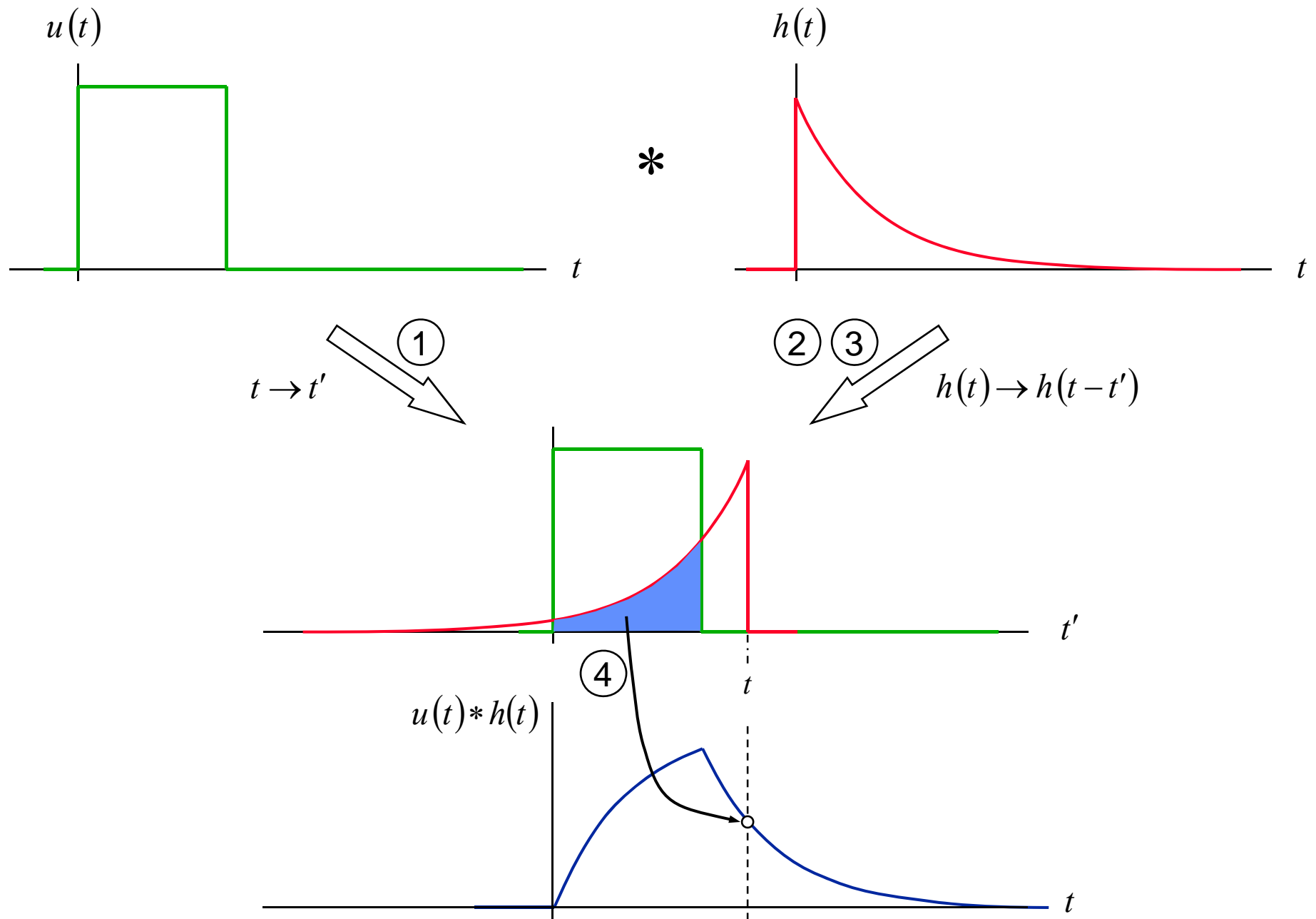
= linear time-invariant operation

Definition:

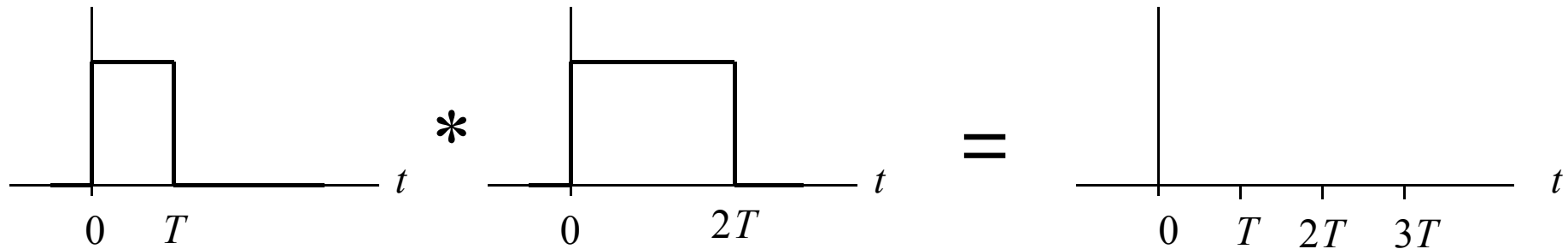
$$\begin{aligned} u(t) * h(t) &= \int_{-\infty}^{+\infty} u(t') h(t - t') dt' \\ &= \int_{-\infty}^{+\infty} u(t - t') h(t') dt' = h(t) * u(t) \end{aligned}$$

Interpretation 1: $h(t)$ as Integration Kernel

- ① $u(t) \rightarrow u(t')$
- ② $h(t) \rightarrow h(-t')$ Reflection at ordinate
- ③ $h(-t') \rightarrow h(t - t')$ Shift to position t
- ④ $\int_{-\infty}^{+\infty} u(t') h(t - t') dt'$ Multiplication and integration of the product



Tutorial: Convolution



graphical Convolution on-line (“Joy of Convolution”) and many other toys:

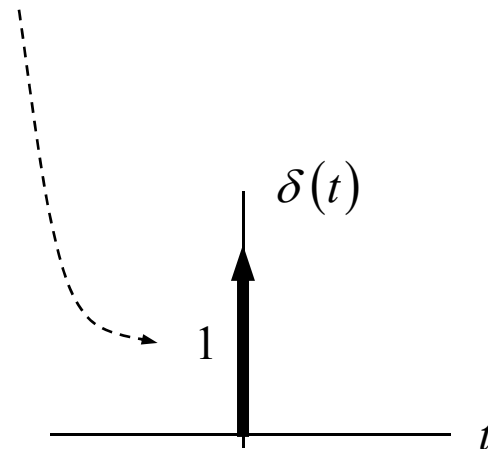
www.jhu.edu/~signals/index.html

3.3 Delta “Functions”: unit impulse function

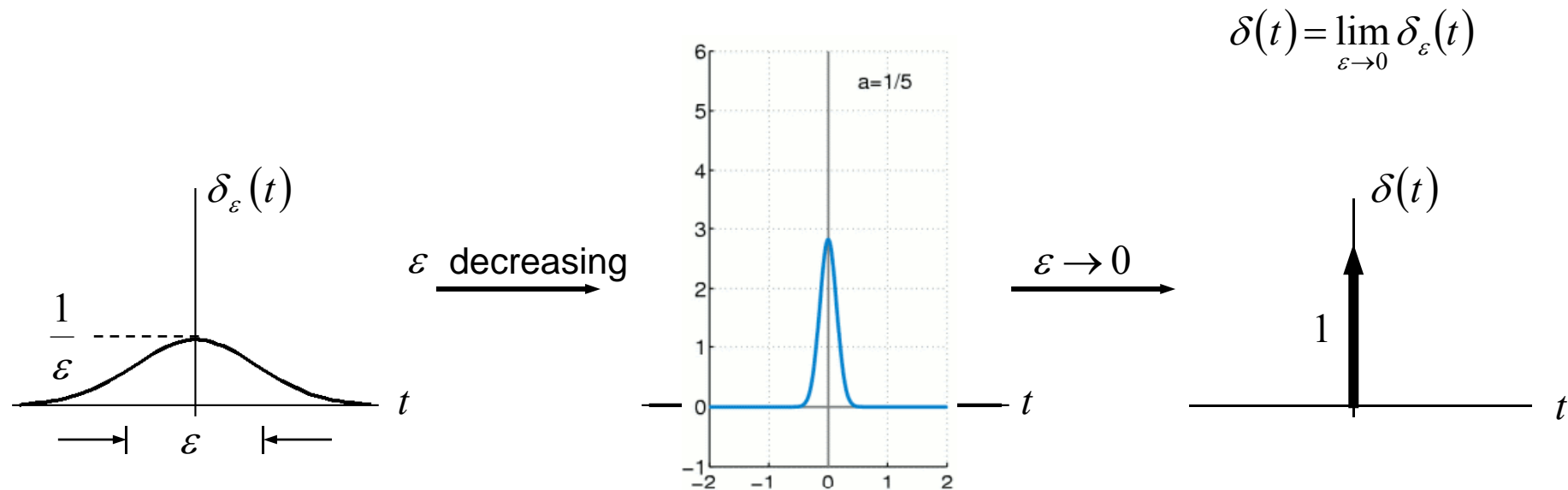
Dirac's Delta Impulse $\delta(t)$:

$$\int_{-\infty}^{+\infty} \delta(t - t_0) u(t) dt = u(t_0) \quad u(t) \text{ continuous at } t = t_0$$

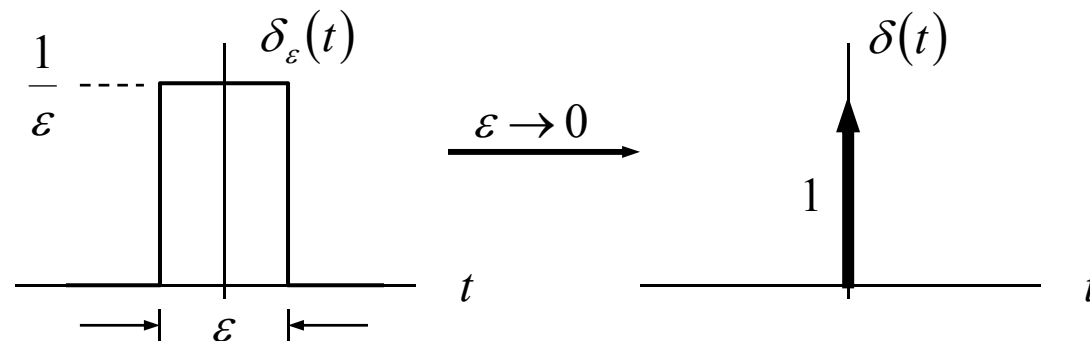
$$\Rightarrow \int_{-\infty}^{+\infty} \delta(t) dt = 1 \quad \text{and} \quad \delta(t) = 0 \quad \forall \quad t \neq 0$$



$\delta(t)$ as a limit of a sequence of functions $\delta_\varepsilon(t)$:



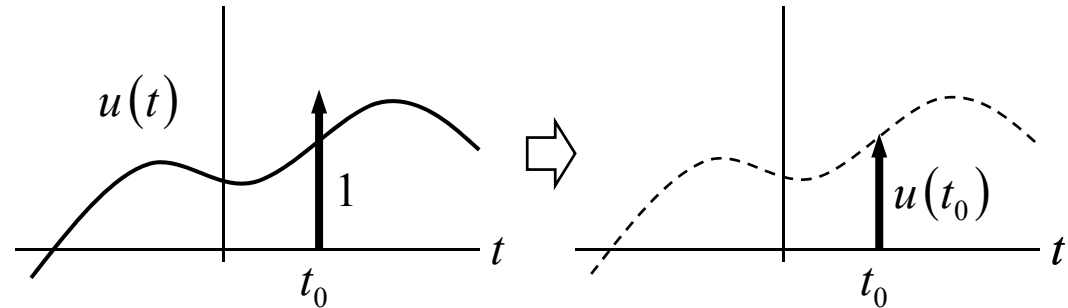
Simplified graphical representation: $\delta_\varepsilon(t) = \frac{1}{\varepsilon} \text{rect}\left(\frac{t}{\varepsilon}\right)$



Properties of Delta Impulses (1)

- Sifting Property:

$$\delta(t - t_0)u(t) = \delta(t - t_0)u(t_0)$$

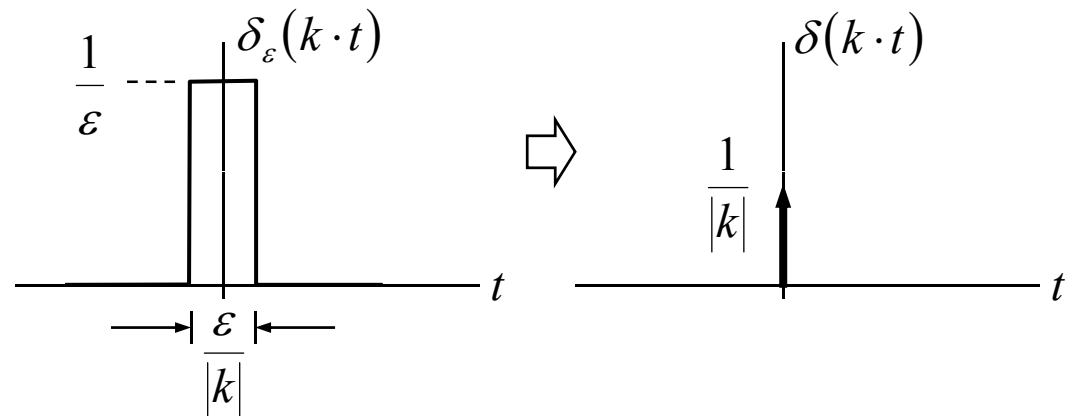


- Symmetry:

$$\delta(-t) = \delta(t)$$

- Coordinate Transformation:

$$\delta(k \cdot t) = \frac{1}{|k|} \delta(t) \quad k \in \mathbb{R}$$



Proof:
$$\int_{-\infty}^{+\infty} \delta(k \cdot t) dt = \frac{1}{|k|} \int_{-\infty}^{+\infty} \delta(k \cdot t) d(k \cdot t) = \frac{1}{|k|}$$

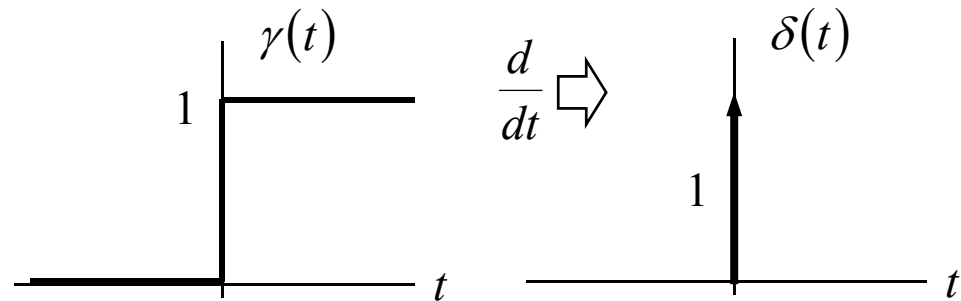
Properties of Delta Impulses (2)

- Orthogonality:

$$\int_{-\infty}^{+\infty} \delta(t - t_1) \delta(t - t_2) dt = \delta(t_1 - t_2)$$

- Relationship to the Step Function:

$$\int_{-\infty}^t \delta(\tau) d\tau = \gamma(t) \quad \Rightarrow \quad \frac{d}{dt} \gamma(t) = \delta(t)$$



Derivatives of Delta Impulses

- 1st Derivative:

$$\int_{-\infty}^{+\infty} \delta'(t - t_0) u(t) dt = -u'(t_0)$$

with $u(t)$ 2 times differentiable at $t = t_0$

- ν^{th} Derivative:

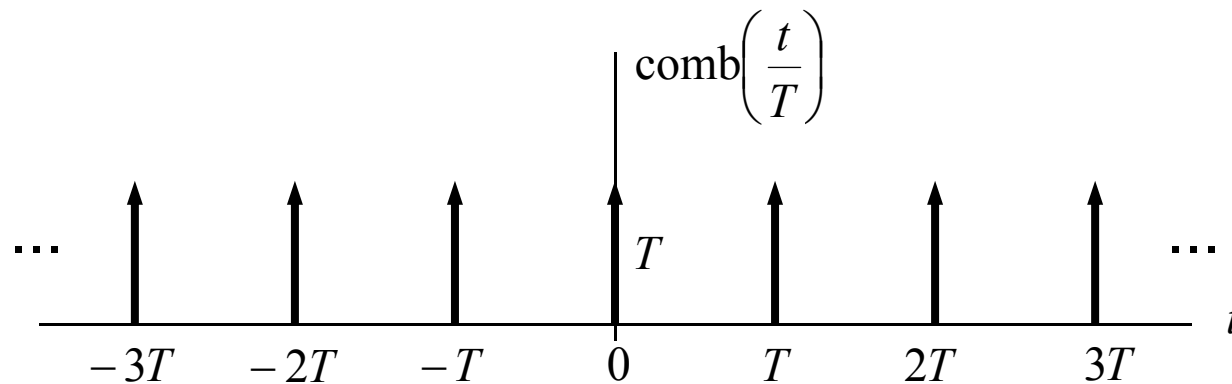
$$\int_{-\infty}^{+\infty} \delta^{(\nu)}(t - t_0) u(t) dt = (-1)^\nu u^{(\nu)}(t_0)$$

with $u(t)$ $(\nu+1)$ times differentiable at $t = t_0$

Periodic Delta Pulse (Comb Function)

$$\text{comb}(t) = \sum_{n=-\infty}^{+\infty} \delta(t - n)$$

$$\text{comb}\left(\frac{t}{T}\right) = T \sum_{n=-\infty}^{+\infty} \delta(t - nT) \quad T \geq 0$$



3.4 Why Digital Signal Processing?

- Flexibility in system reconfiguration
- Better control of accuracy
- Perfectly reproducible
- No performance drift with temperature or age
- Signal processors are becoming more powerful and cheaper
- **Educational purpose: Easy to start!**

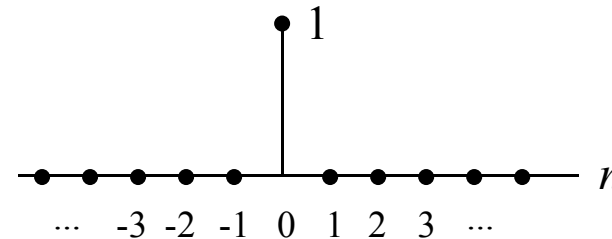
3.5 Some Discrete-time Signals

- Unit Impulse Sequence
- Unit Step Sequence
- Sinusoidal and Exponential Sequences
- Fundamental and Harmonic Component
- Example: Beat Rate

Unit Impulse Sequence

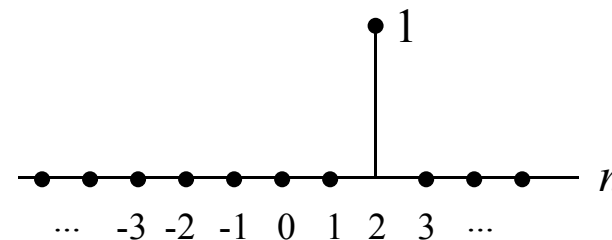
- Unit impulse sequence $\delta[n]$ (also called discrete-time impulse or the unit impulse)

$$\delta[n] = \begin{cases} 1, & n = 0, \\ 0, & n \neq 0. \end{cases}$$



- The unit sample sequence shifted by k samples:

$$\delta[n-k] = \begin{cases} 1, & n = k, \\ 0, & n \neq k. \end{cases}$$

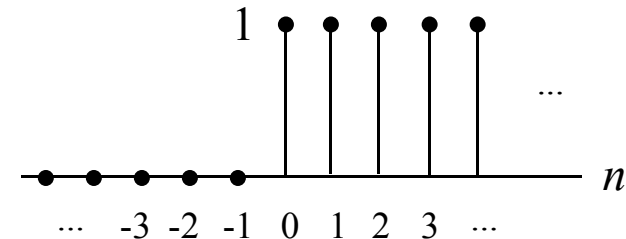


example with $k=2$

Unit Step Sequence

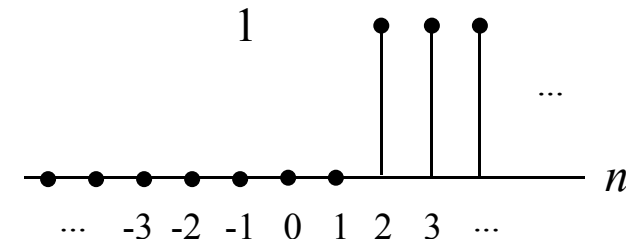
- Unit step sequence $\gamma[n]$:

$$\gamma[n] = \begin{cases} 1, & n \geq 0, \\ 0, & n < 0. \end{cases}$$



- Unit step sequence shifted by k samples:

$$\gamma[n-k] = \begin{cases} 1, & n \geq k, \\ 0, & n < k. \end{cases}$$



- The unit step sequences are related as follows:

$$\gamma[n] = \sum_{m=0}^{\infty} \delta[n-m] = \sum_{k=-\infty}^n \delta[k],$$
$$\delta[n] = \gamma[n] - \gamma[n-1].$$

Sinusoidal and Exponential Sequences

- Real sinusoidal sequence

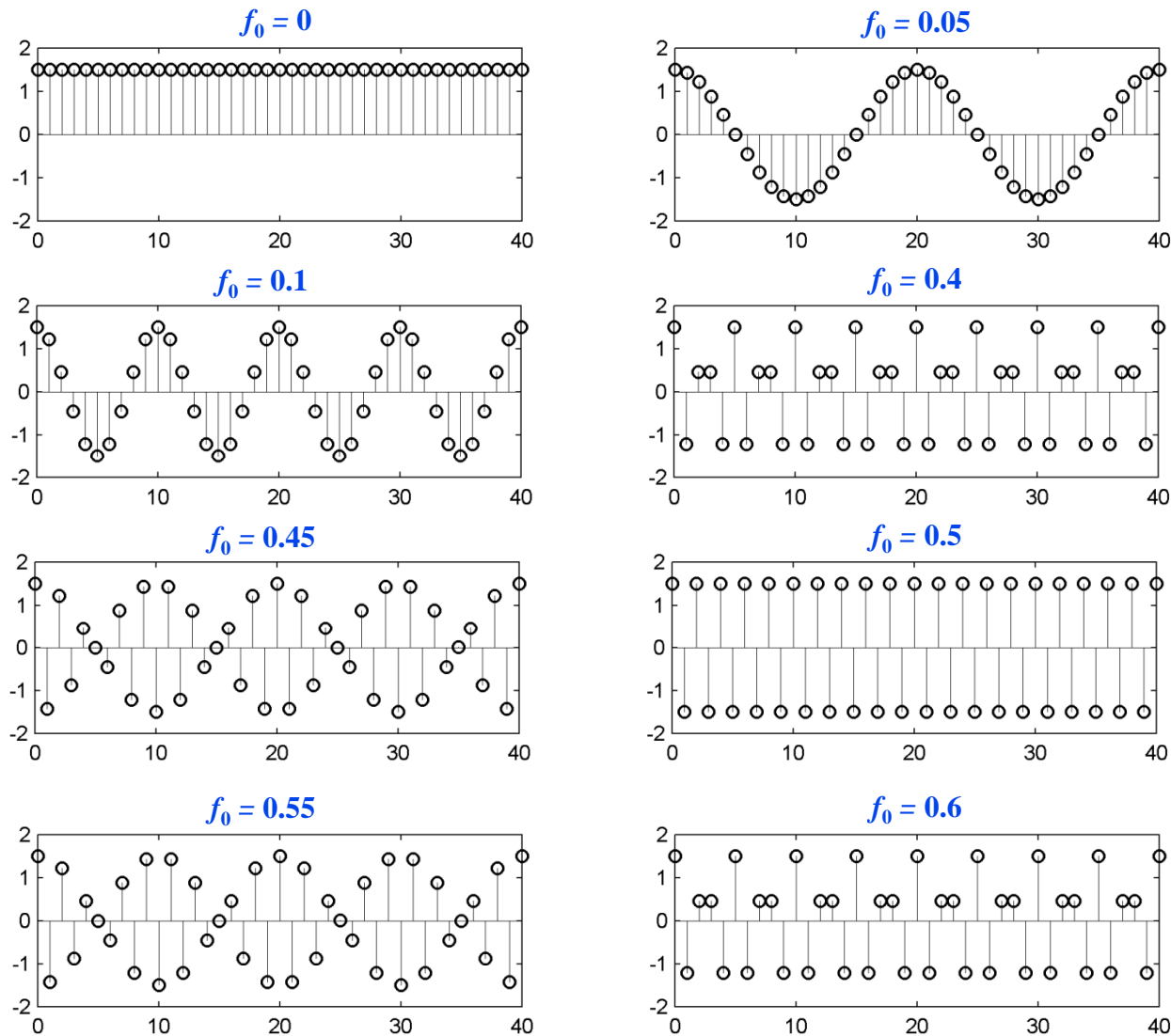
$$u[n] = \underset{\substack{\uparrow \\ \text{amplitude}}}{A} \cos\left(2\pi \underset{\substack{\uparrow \\ \text{frequency}}}{f_0} n + \underset{\substack{\uparrow \\ \text{phase}}}{\phi}\right), \quad -\infty < n < \infty$$

- In-phase and quadrature components

$$u[n] = u_i[n] + u_q[n]$$

$$\underbrace{u_i[n] = A \cos \phi \cos(2\pi f_0 n)}_{\text{in-phase component}}, \quad \underbrace{u_q[n] = -A \sin \phi \sin(2\pi f_0 n)}_{\text{quadrature component}}$$

- A family of sinusoidal sequences given by $x[n]=1.5\cos(2\pi f_0 n)$



- Exponential sequence

$$u[n] = A \alpha^n, \quad -\infty < n < \infty \quad A, \quad \alpha \text{ are real or complex numbers}$$

$$\alpha = e^{(\sigma_0 + j2\pi f_0)}, \quad A = |A|e^{j\phi}$$

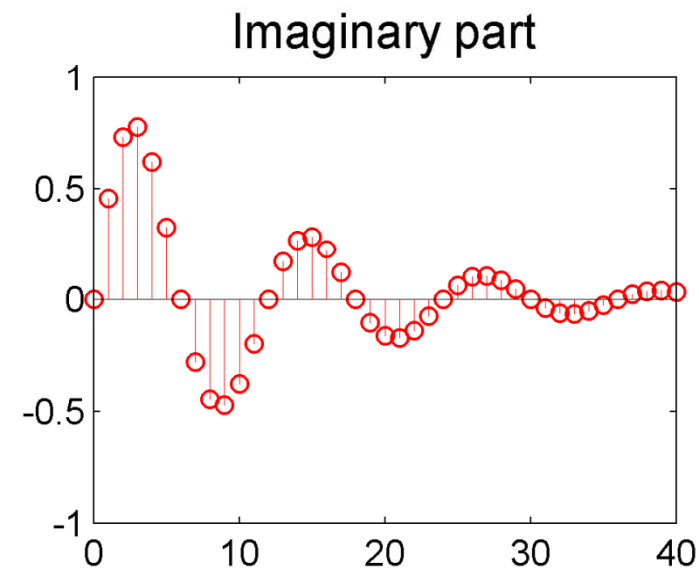
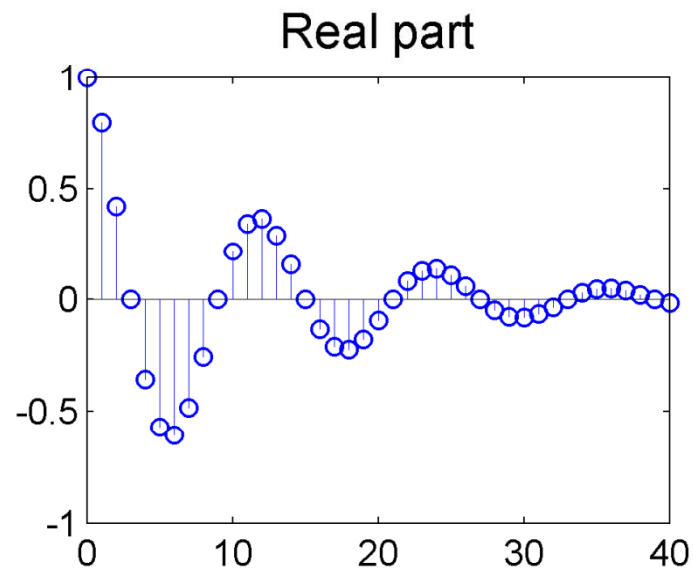
- Real part and imaginary part

$$\text{real part:} \quad u_{\text{re}}[n] = |A|e^{\sigma_0 n} \cos(2\pi f_0 n + \phi)$$

$$\text{imaginary part:} \quad u_{\text{im}}[n] = |A|e^{\sigma_0 n} \sin(2\pi f_0 n + \phi)$$

- Real part and imaginary part are real sinusoidal sequences with constant ($\sigma_0 = 0$), growing ($\sigma_0 > 0$), or decaying ($\sigma_0 < 0$) amplitudes for $n > 0$

- A complex exponential sequence $x[n] = e^{(-1/12 + j\pi/6)n}$



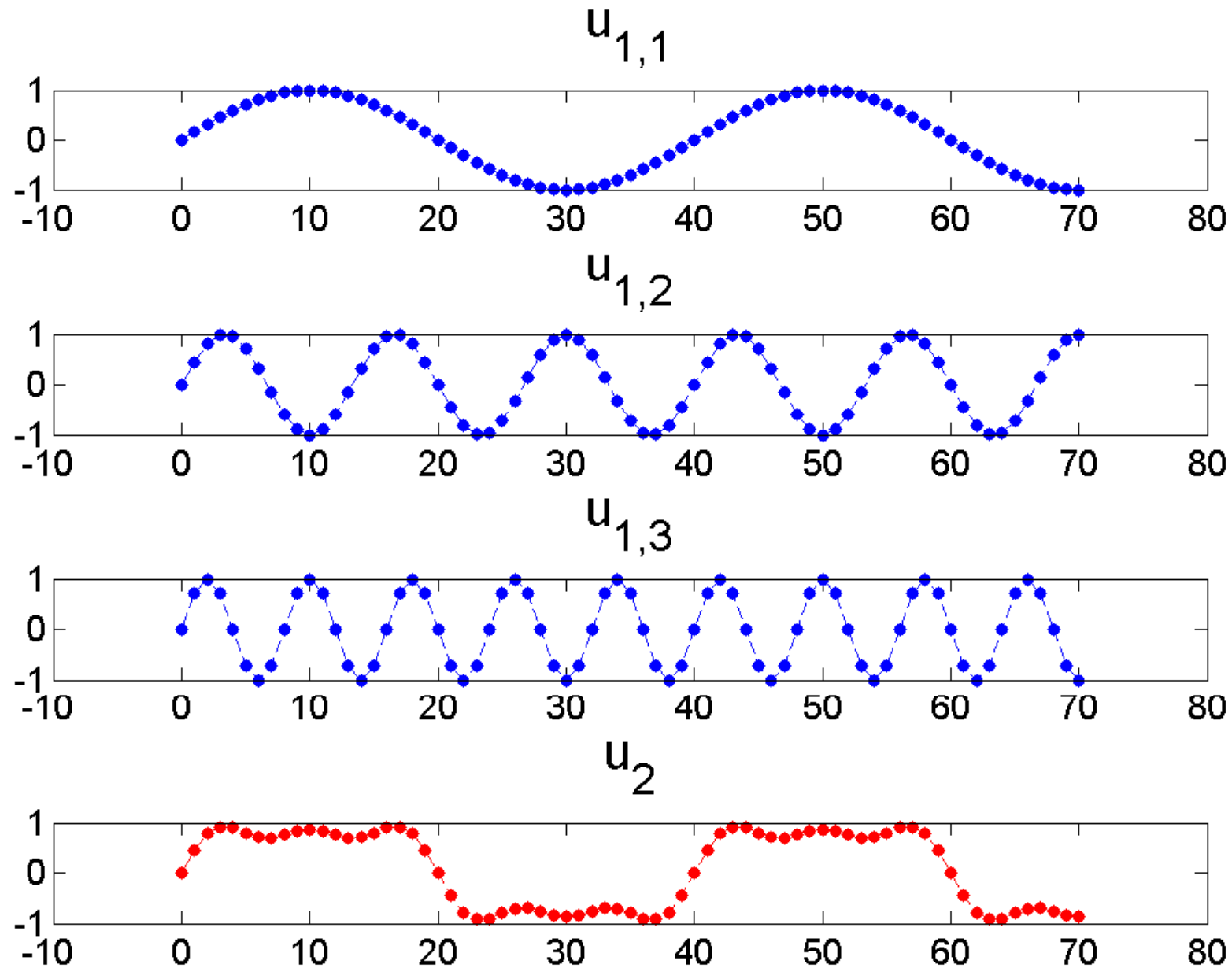
Programming: Generation of a square wave sequence

$$u_{1,1}[n] = \sin(2\pi f_1 n) \gamma[n], \quad f_1 = 0.025$$

$$u_{1,2}[n] = \sin(2\pi f_2 n) \gamma[n], \quad f_2 = 3f_1$$

$$u_{1,3}[n] = \sin(2\pi f_3 n) \gamma[n], \quad f_3 = 5f_1$$

$$u_2[n] = u_{1,1}[n] + \frac{1}{3}u_{1,2}[n] + \frac{1}{5}u_{1,3}[n]$$



Program Download: www.lmf.bv.tum.de => teaching => links

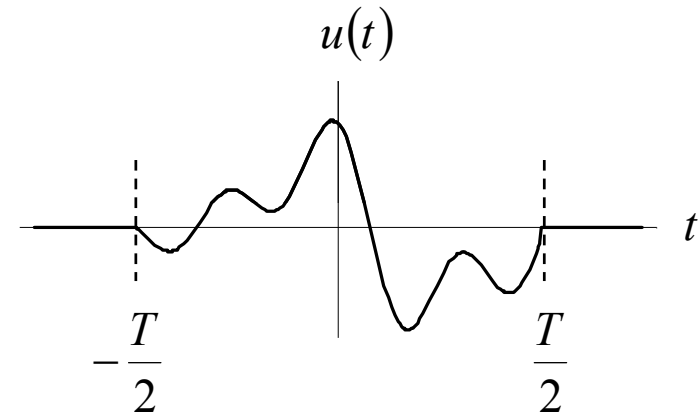
Fundamental and Harmonic Component

- **Fundamental component:** the sinusoidal sequence with the lowest frequency, with its frequency being called **fundamental frequency**
 - e.g. $u_{1,1}[n]$ in the pre-exercise is the fundamental component
 - and f_1 is the fundamental frequency
- **Harmonics:** the sinusoidal sequences whose frequency are interger multiplies of the lowest frequency
 - e.g. $u_{1,2}[n]$ and $u_{1,3}[n]$ are the 3-rd and the 5-th harmonic, respectively.
- **Fourier series expansion:** expression of a periodic signal in the form of linearly weighted combination of a fundamental and a series of harmonic components.
- **Fourier series coefficients:** the weights associated with each component in the expansion.

Fourier Series

- Expansion of energy- and time-limited signals in series of orthogonal harmonic basis functions

- w.l.o.g.: $-\frac{T}{2} < t < +\frac{T}{2}$



- Fourier series: $u(t) = \sum_{n=-\infty}^{+\infty} c_n \cdot \Psi_n(t) \quad \forall \quad |t| < \frac{T}{2}$ with $\Psi_n(t) = \exp\left(j 2 \pi \frac{n}{T} t\right)$
- \uparrow
 Fourier
coefficient of
order n

\uparrow
 basis function
(harmonic oscillation)

\uparrow
 frequency $n \cdot f_0$
with $f_0 = 1/T$

Fourier Series:

$$u(t) = \sum_{n=-\infty}^{+\infty} c_n \exp\left(j 2 \pi \frac{n}{T} t\right) \quad \forall \quad |t| < \frac{T}{2}$$

$$= \underbrace{a_0 + \sum_{n=1}^{+\infty} a_n \cos\left(2 \pi \frac{n}{T} t\right)}_{\text{even part of the signal}} + \underbrace{\sum_{n=1}^{+\infty} b_n \sin\left(2 \pi \frac{n}{T} t\right)}_{\text{odd part of the signal}}$$

- Complete signal description on the interval $\pm T/2$ for signals satisfying **Dirichlet's conditions** (e.g. finite number of discontinuities),
- Converges at points of discontinuity to the average of left-hand and right-hand limits
- Replicates the signal periodically outside of $\pm T/2$, hence poor convergence at discontinuities near the boundaries, i.e. for $u(-T/2) \neq u(T/2)$.

Basis functions of Fourier series :

$$\Psi_n(t) = \exp\left(j 2 \pi \frac{n}{T} t\right) = \cos\left(2 \pi \frac{n}{T} t\right) + j \sin\left(2 \pi \frac{n}{T} t\right)$$

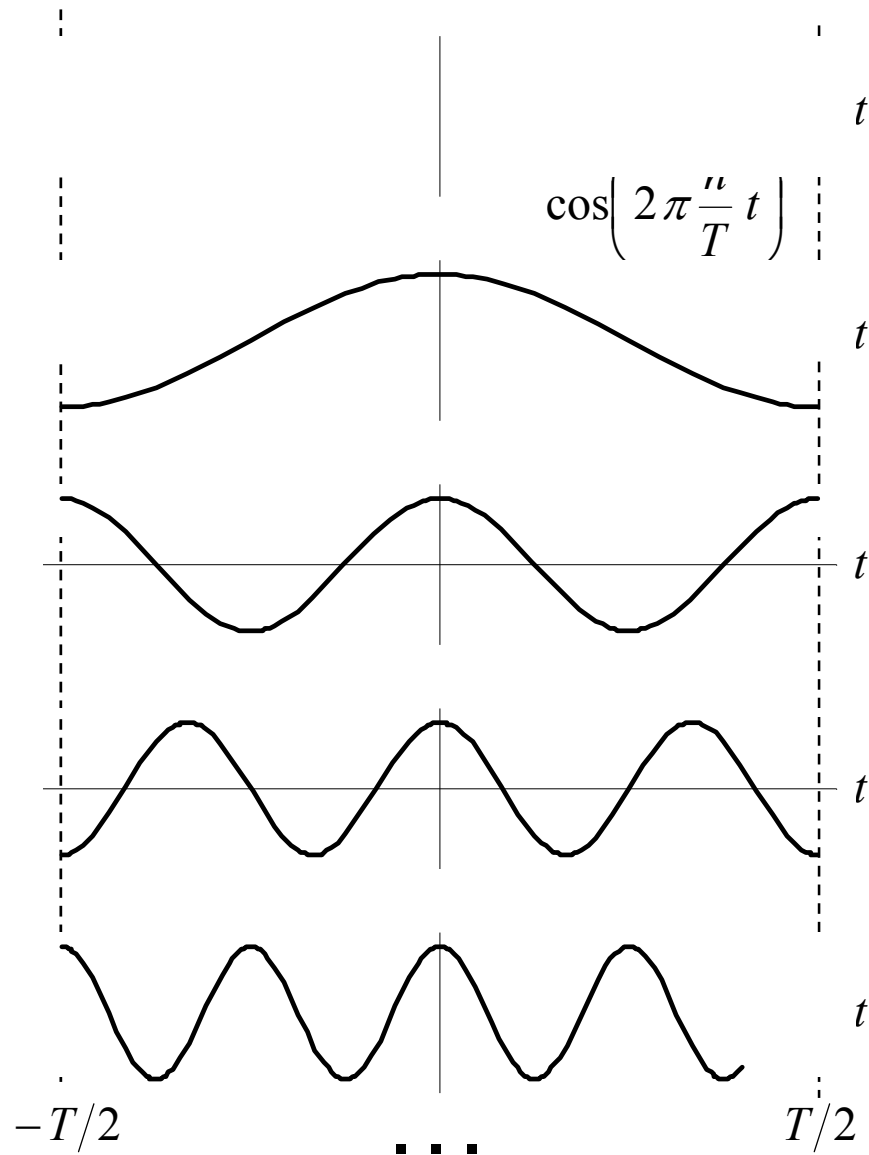
Orthogonality:

$$\int_{-T/2}^{T/2} \Psi_n(t) \Psi_m^*(t) dt = \begin{cases} 0 & n \neq m \\ T & n = m \end{cases}$$

Energy conservation (Parseval's Equation):

$$\int_{-T/2}^{T/2} |u(t)|^2 dt = T \sum_{n=-\infty}^{\infty} |c_n|^2$$

Basis functions of Fourier Series



$n=0$

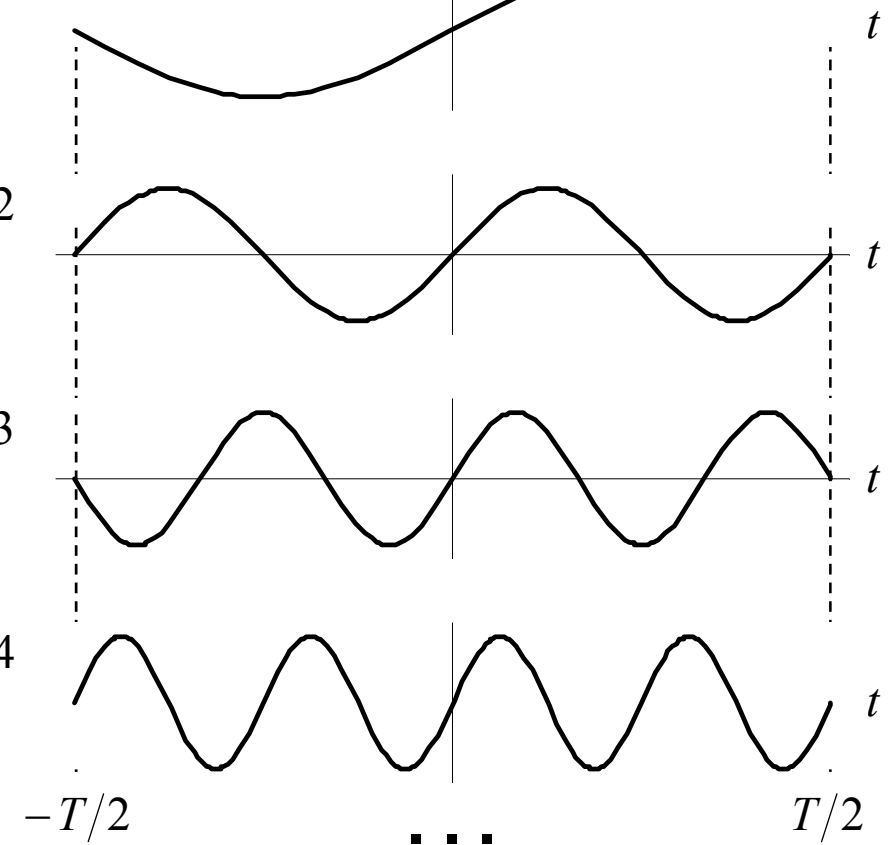
$n=1$

$n=2$

$n=3$

$n=4$

$$\sin\left(2\pi\frac{n}{T}t\right)$$



Computation of Fourier coefficients :

complex:

$$c_n = \frac{1}{T} \int_{-T/2}^{T/2} u(t) \exp\left(-j 2\pi \frac{n}{T} t\right) dt \quad \overbrace{\Psi_n^*(t)}$$
$$c_n = \frac{1}{2} (a_n - j b_n)$$

cos-coefficients:

$$a_0 = c_0 = \frac{1}{T} \int_{-T/2}^{T/2} u(t) dt \quad (\text{constant component, average of signal})$$

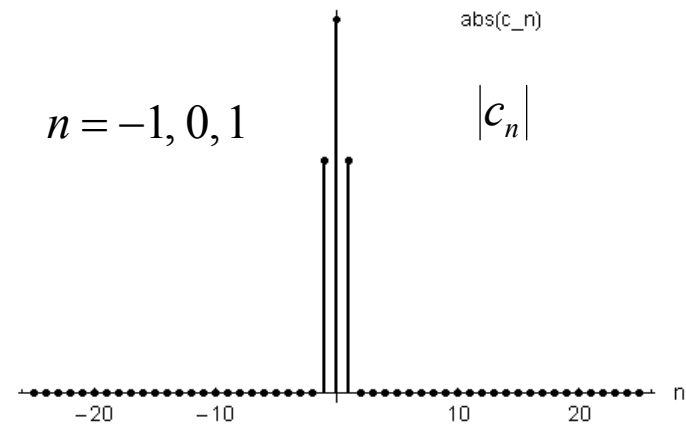
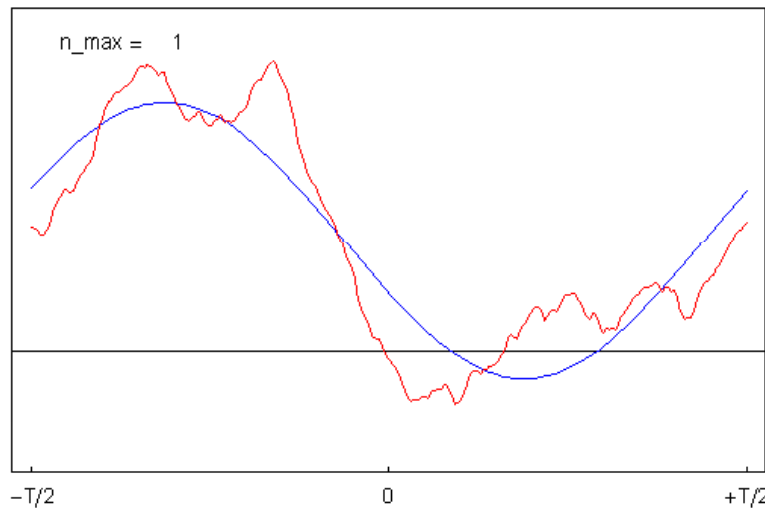
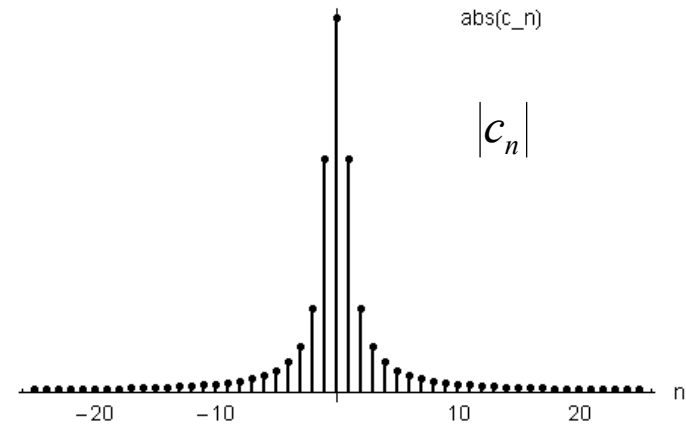
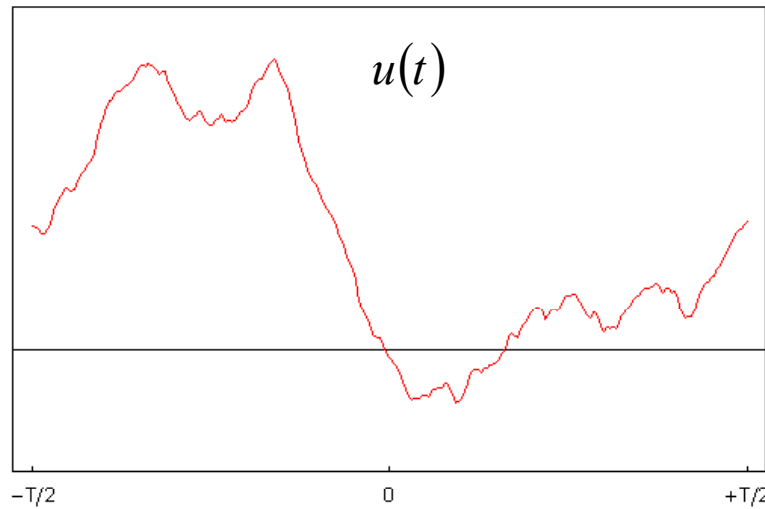
$$a_{n \geq 1} = \frac{2}{T} \int_{-T/2}^{T/2} u(t) \cos\left(2\pi \frac{n}{T} t\right) dt$$

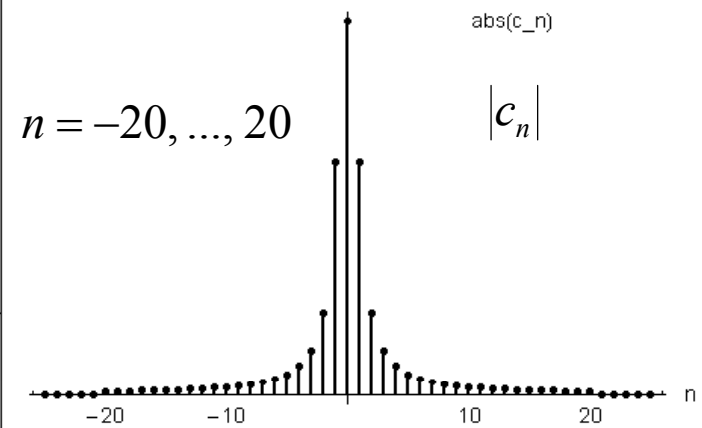
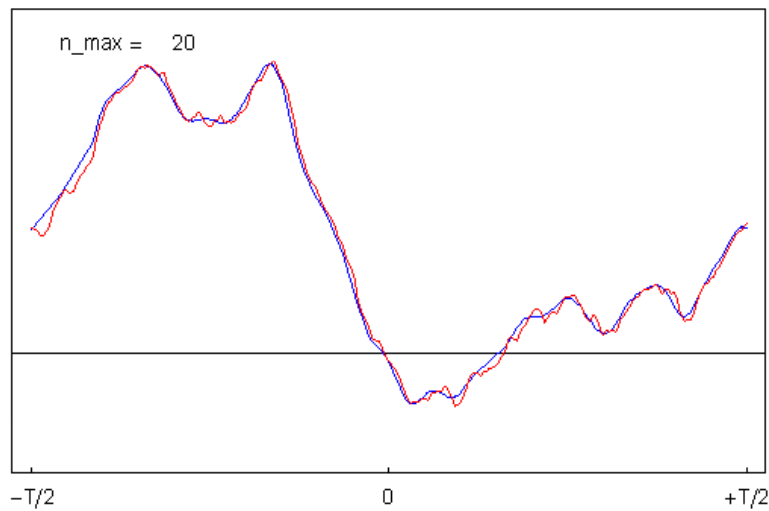
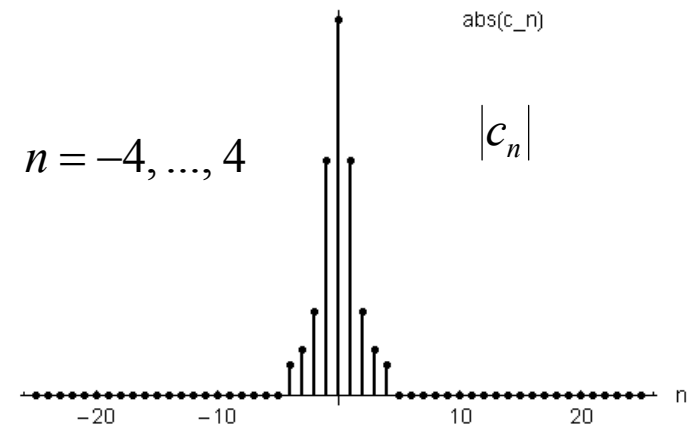
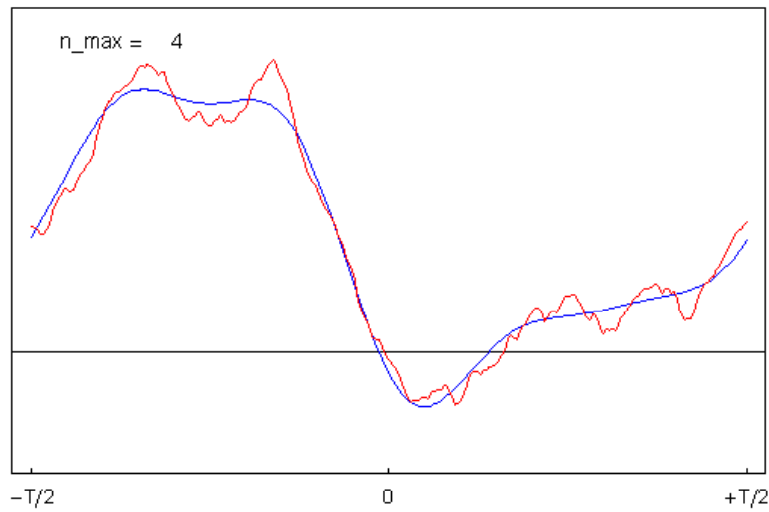
sin-coefficients:

$$b_{n \geq 1} = \frac{2}{T} \int_{-T/2}^{T/2} u(t) \sin\left(2\pi \frac{n}{T} t\right) dt$$

for real-valued signals: $c_{-n} = c_n^*$ and: $a_0, a_n, b_n \in \mathbb{R}$

Approximation of a time-limited (but periodic continuous) Signal by finite Fourier Series





Example: Beat Note

- Exercise: Illustration of the modulation operation

$$u_{1,1}[n] = \cos(2\pi f_1 n),$$

$$u_{1,2}[n] = \cos(2\pi f_2 n), \quad f_1 = 0.05, \quad f_2 = 0.005$$

$$u_2[n] = u_{1,1}[n] \cdot u_{1,2}[n] = \frac{1}{2} \cos(2\pi (f_1 + f_2) n) + \frac{1}{2} \cos(2\pi (f_1 - f_2) n).$$

↑
beat note

- **Beat note**: the high frequency signal generated by the multiplication
- Practice: Play with the Audacity.

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Continuous-time Fourier Transform

$$U(f) = \int_{-\infty}^{+\infty} u(t) \exp(-j 2\pi f t) dt$$

Fourier Transform

$$u(t) = \int_{-\infty}^{+\infty} U(f) \exp(j 2\pi f t) df$$

inverse Fourier Transform

with $u(t)$ absolute integrable: $\int_{-\infty}^{+\infty} |u(t)| dt < \infty$ (sufficient condition)

Some power-limited signals can also be Fourier transformed :

$$U(f) = \lim_{\varepsilon \rightarrow 0} \int_{-\infty}^{+\infty} u(t) \exp(-\varepsilon |t|) \exp(-j 2\pi f t) dt$$

Common symbols :

$$\begin{aligned} u(t) &\circ \longrightarrow \bullet U(f) \\ u(t) &\rightarrow U(f) \\ u(t) &\leftrightarrow U(f) \end{aligned}$$

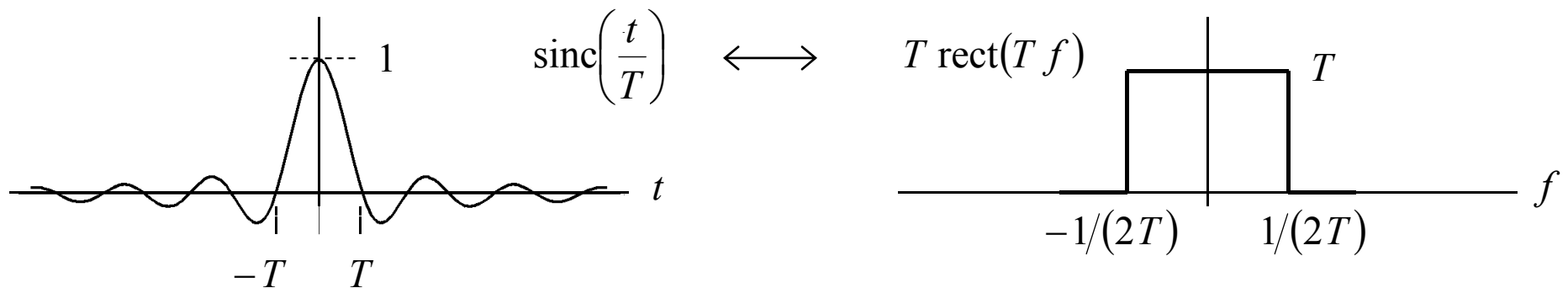
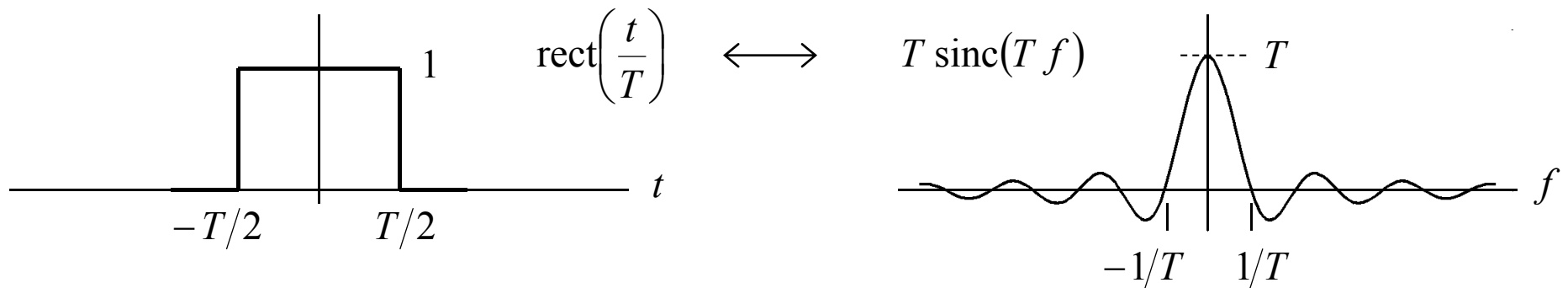
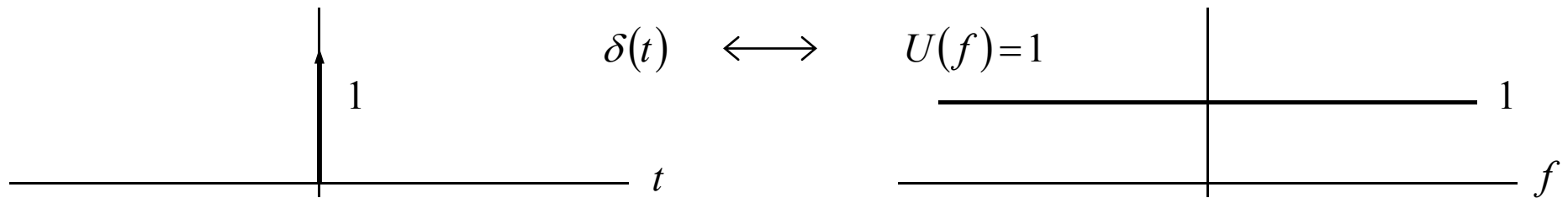
Alternative Expression for Fourier Transform (not used in this lecture):

- ω -notation (very common): $\omega = 2\pi f$

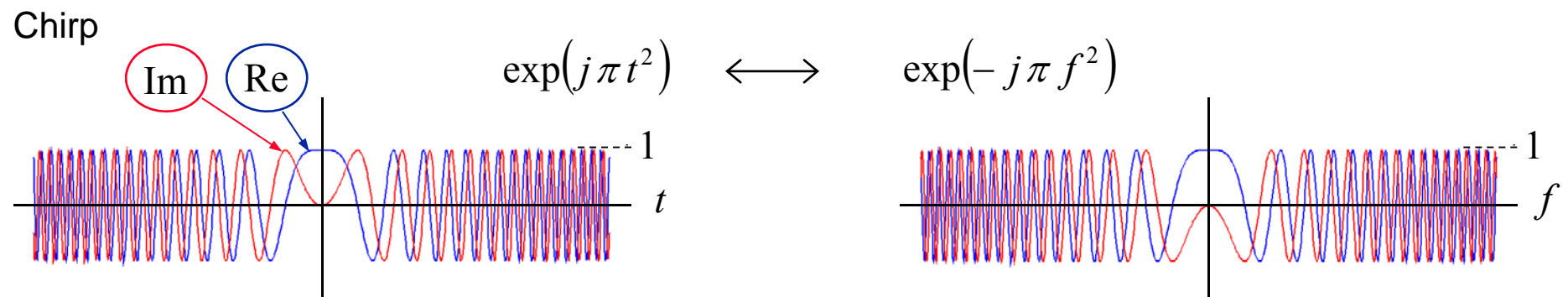
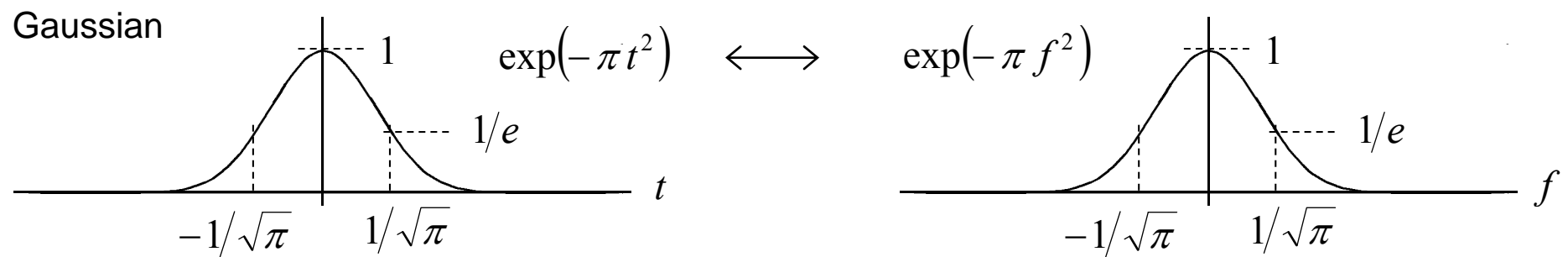
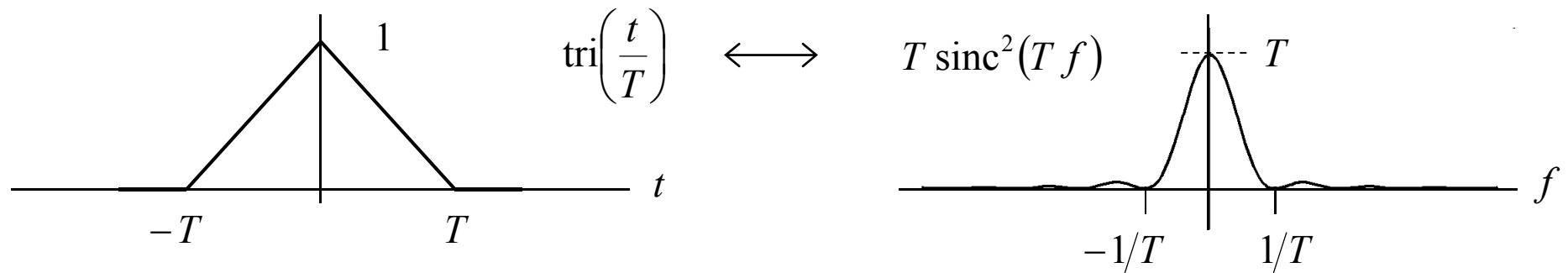
$$U(\omega) = \int_{-\infty}^{+\infty} u(t) \exp(-j\omega t) dt$$

$$u(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} U(\omega) \exp(j\omega t) d\omega$$

Important 1-D Fourier Transform Pairs (1)

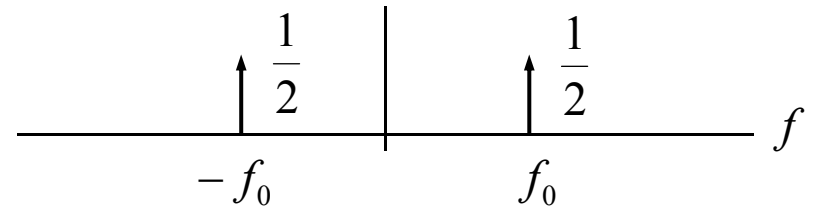
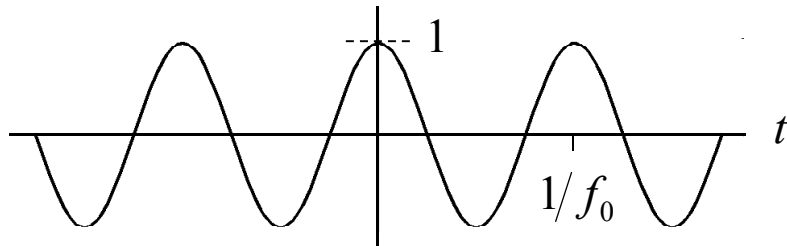


Important 1-D Fourier Transform Pairs (2)

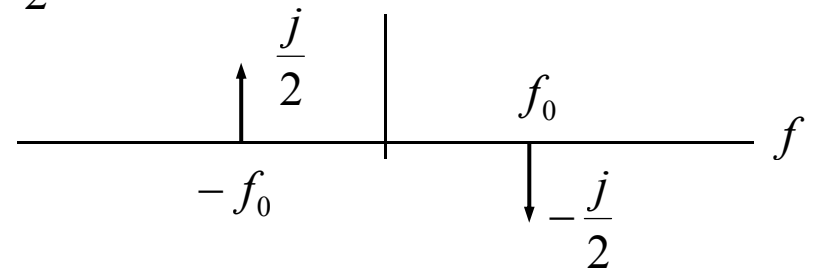
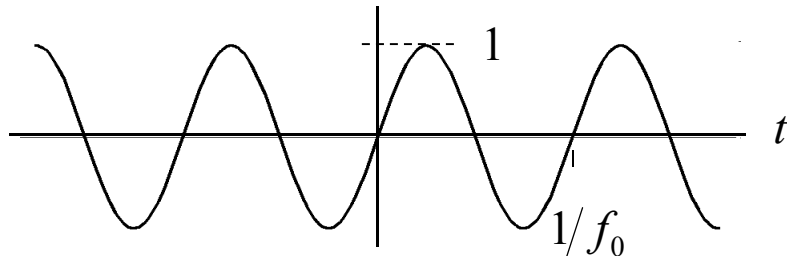


Important 1-D Fourier Transform Pairs (3)

$$\cos(2\pi f_0 t) \longleftrightarrow \frac{1}{2}(\delta(f + f_0) + \delta(f - f_0))$$



$$\sin(2\pi f_0 t) \longleftrightarrow \frac{j}{2}(\delta(f + f_0) - \delta(f - f_0))$$



$$\exp(j2\pi f_0 t) \longleftrightarrow \delta(f - f_0)$$

