Tung-Cheng Wu

☐ +1-412-721-6334 | ■ tungcheng.wu@na.denso.com | ★ https://tcwu.space

EXPERIENCE

• DENSO International America, Inc. [

Nov 2024 - Present

Research Engineer

Pittsburgh, PA, USA

Develop motion planning algorithm for autonomous driving system

• Carnegie Mellon University [

Nov 2024 - Present

Visiting Researcher

Pittsburgh, PA, USA

• **Research Topic**: Autonomous driving and uncertainty quantification

DENSO Corporation []

Apr 2020 - Nov 2024

Research Engineer

Tokyo, Japan

Develop a DNN-based DNN-based algorithm for advanced driver assistance systems. This technology
can forecast the lane-changing and cut-in intentions of surrounding vehicles early. It has already passed
proof-of-concept (PoC) and been transferred to the product team.

• Industrial Technology Research Institute [

Jul 2018 - Sep 2018

Hsinchu, Taiwan

• Develop a DQN-based navigation algorithm for quadcopter

EDUCATION

• National Cheng Kung University

Sep 2017 - Jun 2019

Master of Science in Engineering Science, GPA: 4.1 / 4.3 (best 0.7%)

Tainan, Taiwan

- Thesis topic: Design new updating strategy to improve deep reinforcement learning
- Major: Path planning under uncertain situation

National Cheng Kung University

Sep 2013 - Jun 2017

Bachelor of Science in Psychology, GPA: 3.76 / 4.0

Tainan, Taiwan

Major: Computational Cognitive Neuroscience, Statistical learning theory

PUBLICATIONS

C=CONFERENCE, J=JOURNAL, S=IN SUBMISSION, T=THESIS

- [C.1] Tung-Cheng Wu, Jon-Fan Hu, Shu-Ling Peng. (2017). Influences of the Matching Effects of Cognitive and Emotional Factors on Attitude Change, In *Proceedings of the Annual Meeting of the Cognitive Science Society*, Vol. 39, Cognitive Science Society
- [C.2] Tung-Cheng Wu, Shau-Yin Tseng, Chin Feng Lai, Chia Yu Ho, Ying Hsun Lai. (2018). Navigating Assistance System for Quadcopter with Deep Reinforcement Learning. In 1st International Cognitive Cities Conference (IC3), pp. 16-19. IEEE.
- [T.1] Tung-Cheng Wu. (2019). Moderating Maximal Value a Practical Expectation-Based Method for Value Function Approximation in Reinforcement Learning.
- [J.1] Ying-Hsun Lai, Tung-Cheng Wu, Chin-Feng Lai, Laurence Tianruo Yang, Xiaokang Zhou. (2020). Cognitive optimal-setting control of AIoT industrial applications with deep reinforcement learning. *IEEE Transactions on Industrial Informatics*, vol.17(3), pp.2116-2123, IEEE

SKILLS

- Programming Languages: Python, Matlab, ROS, C++, R
- Data Science & Machine Learning Toolkit: PyTorch, TensorFlow, Keras, sk-learn
- Other Tools & Technologies: LaTeX, git
- Research Skills: Calibration, Data collection

HONORS AND AWARDS

 Excellent Master Thesis Dec 2019

Institute of Information & Computing Machinery • Excellent paper of CS theses in the same year from entire country

• Excellent Paper Award Sep 2018

International Cognitive Cities Conference

• 1 of 4 excellent papers from entire conference papers Scholar Award Jul 2018

Department of Engineering Science

• awarded to 5% best students across entire department, Aachen, 2016

ADDITIONAL INFORMATION

- Languages: Chinese (native), English (fluent), Japanese (intermediate)
- Interests: swimming, hiking, real-time strategy (RTS) game

REFERENCES

1. Jon-Fan Hu

Associate Professor, Psychology National Cheng Kung University Email: jfhu@mail.ncku.edu.tw Relationship: Advisor in BS

2. Chin-Feng Lai

Professor, Engineering Science National Cheng Kung University Email: cinfon@ieee.org Relationship: Advisor in MS

3. Yuki Asada

Manager, AI R&I Div. **DENSO** Corporation

Email: yuki.asada.j3g@jp.denso.com

Relationship: Manager

4. Shinya Tanaka

Manager, Pittsburgh Innovation Lab DENSO International America, Inc. Email: shinya.tanaka@na.denso.com

Relationship: Manager