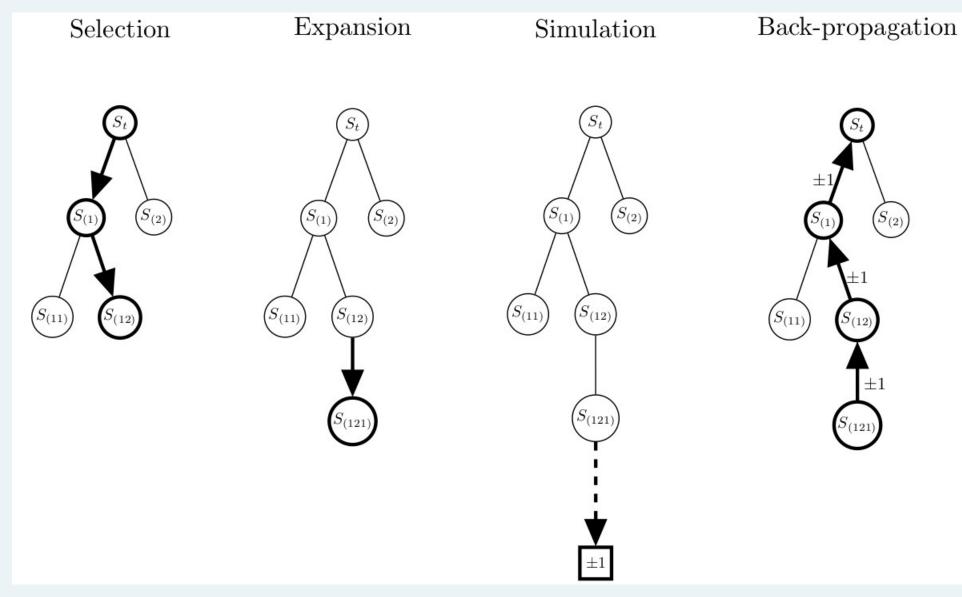
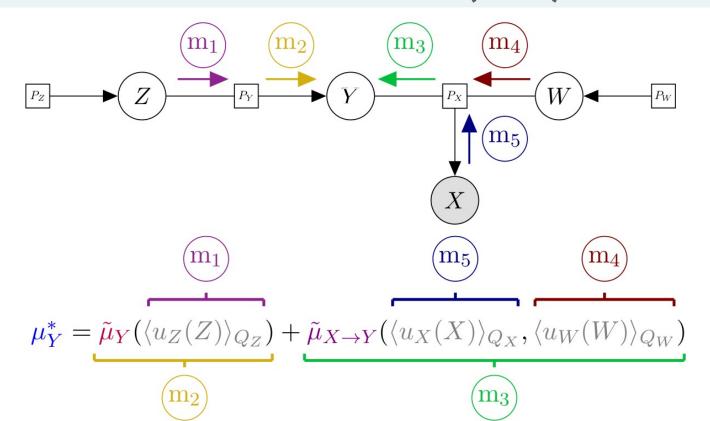
Branching Time Active Inference

Théophile Champion, Lancelot Da Costa, Howard Bowman and Marek Grześ

Overview

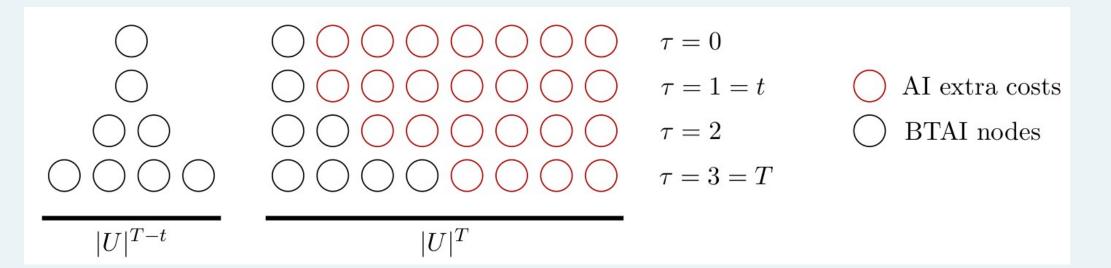


- → Tree search is performed by dynamically expanding the generative model of the agent.
- → The node selection is based on the upper confidence bound for tree (UCT).



→ Inference of the latent variables is performed by variational message passing.

Result: Complexity Classes



- → Active Inference (AI).
- → Branching Time Active Inference BTAI.

Result: BTAI outperforms AI

Environment		Policy size	P(goal)		P(trap)
first		3	1		0
second		5	1		0
third		8	crash		crash
Environment	Planning iterations			P(goal)	P(trap)
first	10			1	0
second		10		0.49	0.51
	15		1	0	
third		10		0.47	0.53
		15		0.55	0.45
		20		1	0

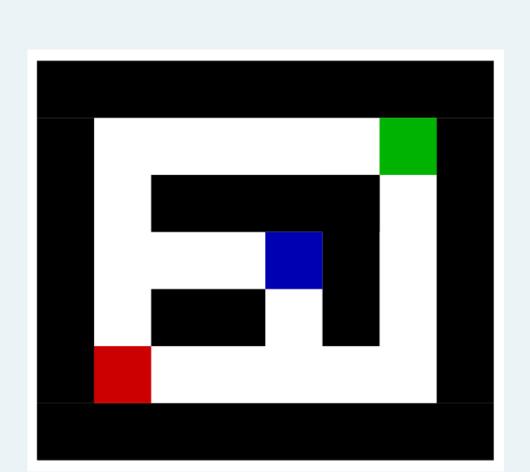
Active inference is a unified framework for action and perception that can be scaled up using Monte Carlo tree search to expand the generative model dynamically.





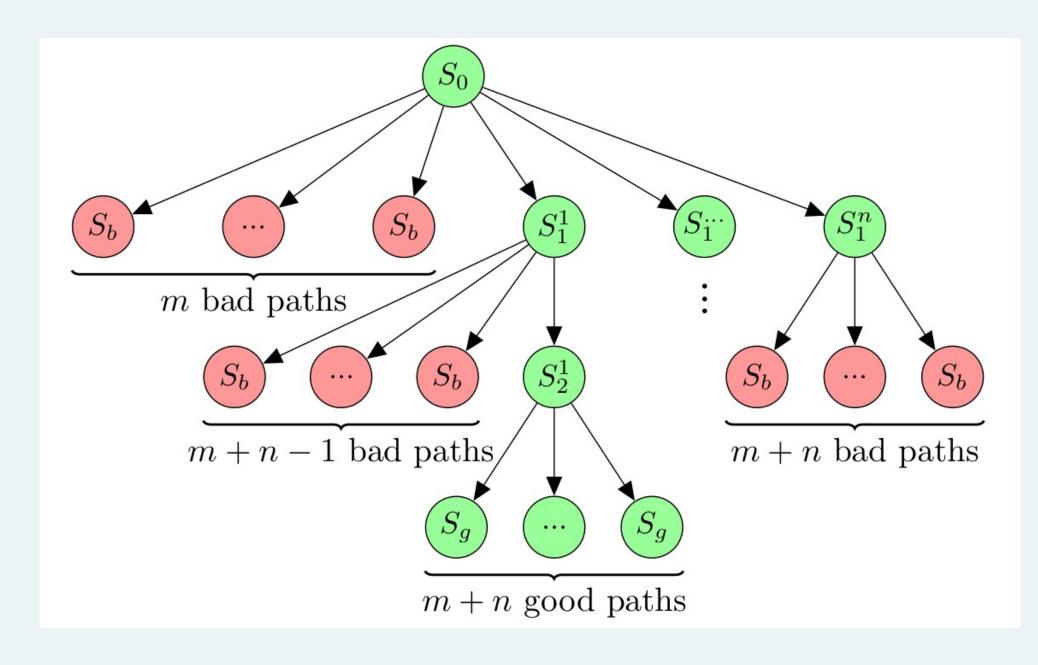


Maze Environment



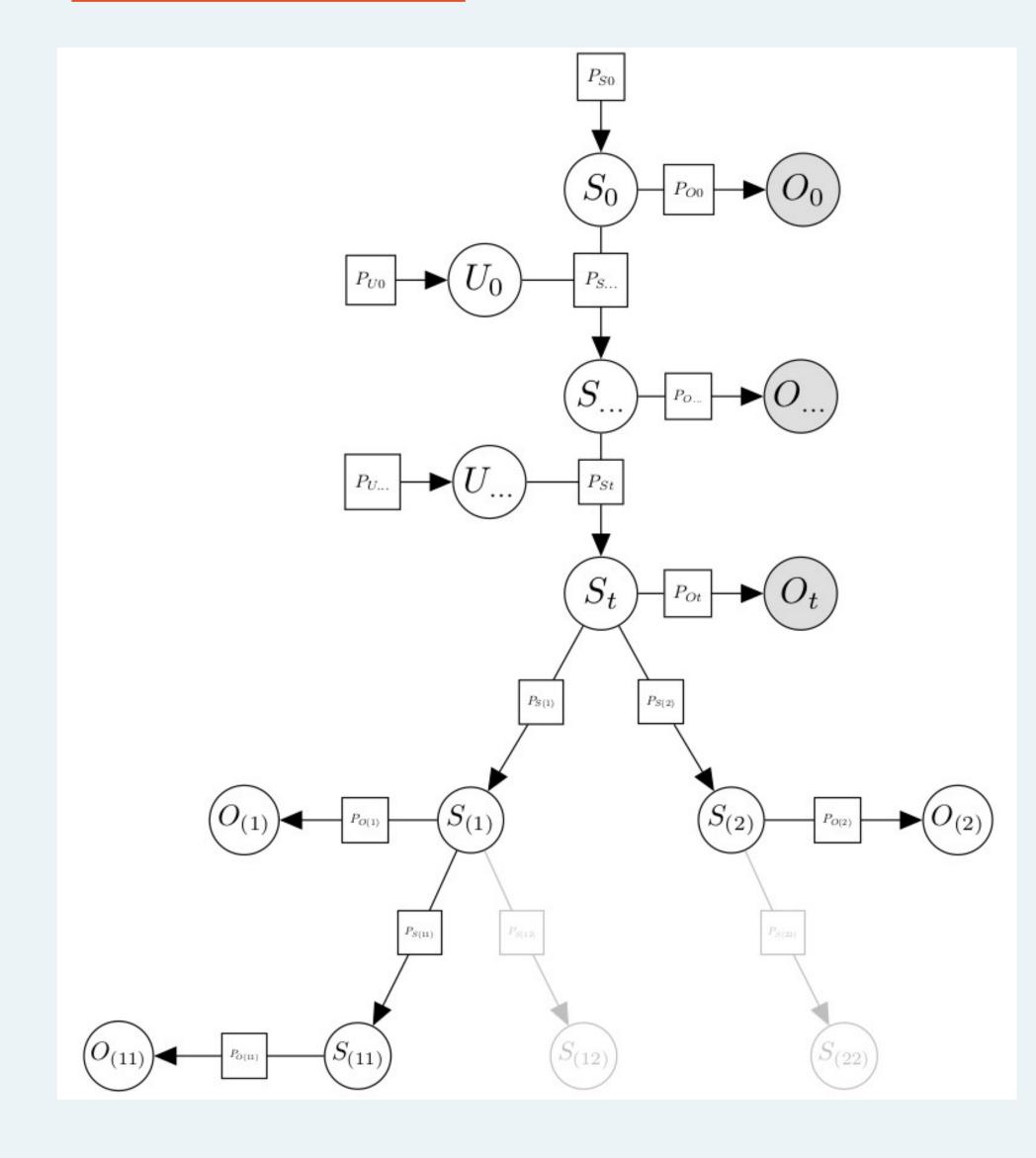
- → starting position in red.
- \rightarrow exit in green.
- → local minimum in blue.

Deep Reward Environment



- → bad states in red.
- → good states in green.

Generative Model



- → squares are factors.
- → white circles are latent variables.
- → gray circles are observed variables.