

# False position Method

In this chapter, we solve the following equation using the **Bisection Method**:

$$f(x) = x^3 - 10x^2 + 5 = 0 \quad (1)$$

## Step 1: assuming $g(x)$ from $f(x)$

First, we assume the non linear  $f(x)$  as linear  $g(x)$ .

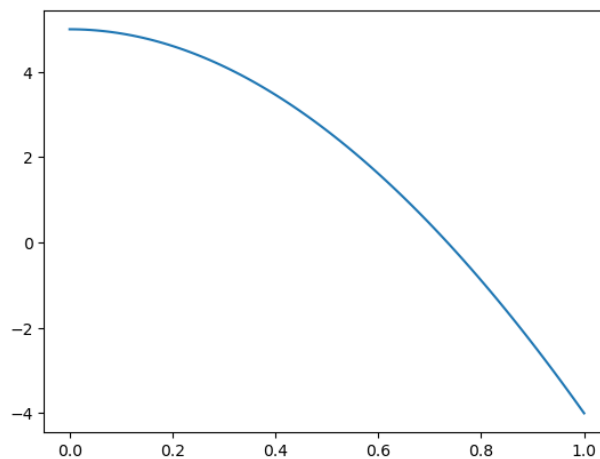


Figure 1: Plot of  $f(x) = x^3 - 10x^2 + 5$

Then take slope of  $g(x)$  in two ways using  $a, b$  and varying point  $c$  (between  $a, b$ ) and find relation for  $c$  in terms of  $a, b$  then find  $c$

taking  $f(c)=0$

$$g'(x) = \frac{f(b) - f(a)}{a - b} = \frac{f(b) - f(c)}{b - c} \quad (2)$$

$$c = b - \frac{(b - a)f(b)}{f(b) - f(a)} \quad (3)$$

## Step 2: Manual Calculation

Using the Bisection Method, we iteratively compute the midpoints and narrow the interval until we find the root.

### Initial Calculations:

- For  $x = 0.6$ ,  $f(x) = 0.6^3 - 10(0.6)^2 + 5 = 1.616$
- For  $x = 0.8$ ,  $f(x) = 0.8^3 - 10(0.8)^2 + 5 = -0.888$

### Iteration Results:

newpoint ( $c$ )	$f(c)$	Interval
0.729073	0.072056	(0.729073, 0.8)
0.734396	0.002701	(0.734396, 0.8)
0.734595	0.000100	(0.734595, 0.8)
0.7346035	0.000	—

Table 1: Manual Calculation of the False position Method

## Step 3: Approximate Root

From the table above, the root of the equation is approximately:

$$x = 0.7346035$$

We've successfully found the root using the False position Method.

Let's see the python implementation

```
1
2     def f(x):
3         return x**3 -10*x**2 +5
4
5     import matplotlib.pyplot as plt
6     import numpy as np
7     x=np.linspace(0,1,100)
8     y=[]
9
10    for i in range(len(x)):
11        y.append(f(x[i]))
12
13    plt.plot(x,y)
14
15
16    tolerance=0.0001
17    x3=[]
18    x2=0.8
19    x1=0.6
20    x3_=(x2+x1)/2
21    x3.append(x3_)
22    i=0
23
24
```

```
25
26     while abs(f(x3_))>0 :
27         x3_=(x2+x1)/2
28         x3.append(x3_)
29         if f(x3_)*f(x1)>0 :
30             x1=x3_
31
32         elif f(x3_)*f(x1)<0 :
33             x2=x3_
34         i+=1
35
36     print(x3_)
```

**Answer got from python code : 0.7346035077893033**