

Chankyo Kim

Interest in understanding Robotics, Human, and Startup Strategy

RESEARCH INTERESTS	Planning and Control under Uncertainty, Learning for Human-Robot Interaction, Probabilistic Approach, Theoretical Research in Planning and Control	
EDUCATION	Seoul National University (SNU) , Seoul, Korea <i>Department of Mechanical & Aerospace Engineering</i> <i>Interdisciplinary Major in Artificial Intelligence</i> <ul style="list-style-type: none">Graduation with Honors, Summa Cum Laude, Advanced GPA : 3.98/4.0, Physics TA for 2 semesters University of Florida (UF) , English Language Institute, Florida, USA	Mar. 2015 – Present Fall. 2015
RESEARCH & WORK EXPERIENCES	Joined as Project Manager Metalab, AI Avatar and Motion Tracking SW Startup (since 2021) in KOR <ul style="list-style-type: none">Managed AI-Metaverse service development project (Size:\$500M Core Tech: Transformer based Vocal Generative Model, Face Generative Model)Present IR and fundraised \$430M from VC and financial institution Software Engineer Intern Bear Robotics, Autonomous Driving Serving Robot Startup in CA SLAM Engineer <ul style="list-style-type: none">Modified pre-developed SLAM algorithm to achieve more accurate mapping quality with less mapping effort for product-level serving robot('Servi')Collected and analyzed physical test data sets of the modified algorithm installed in the robot in diverse indoor areas for QA Undergraduate Researcher Visual Information Processing Lab, SNU (<i>Advisor: Prof. Joonseok Lee</i>) Project Title: Domain Generalization in Human Pose Estimation via Meta-learning <ul style="list-style-type: none">Developed modified meta-learning and human pose dataset for domain generalization in various view points, resolution, and luminous intensity Undergraduate Researcher Clean Energy & Nanoheat Lab, SNU (<i>Advisor: Prof. Sangwook Park</i>) Project Title: Design and Optimization of Intelligent Renewable Power System <ul style="list-style-type: none">Led intelligent power system research of renewable energy;Designed power-tracking method considering operational limit of power system componentWrote paper about optimization in intelligent power system Founder, Tech Team Leader OUTTA, Initiative for AI development and education for next generation	June. 2022 - Dec. 2022 March. 2022 – June. 2022 Aug. 2021 – Jan. 2022 Mar. 2021 – Jan. 2022 Jan. 2021 – Present Boston, USA / Seoul, Korea <ul style="list-style-type: none">Co-Founded non-profit organization OUTTA with support of MIT Beaver Works and SNULaunched 2022, 2021 Autonomous Racecar AI coding Competition in South KoreaFirst-author educational book of control theory, image processing, SLAM, and Python July. 2020 – Feb. 2021 Seoul, Korea Mar. 2020 – Sep. 2020

Biorobotics Lab, SNU (Advisor: Prof. Kyujin Cho)

Project Title: **Development of Novel Tendon-clutching Algorithm Integrated of Trajectory Estimation and Feedback Control in Soft Teleoperation Glove**

- Developed novel wearable master system with one-way clutch mechanism, providing feedback control and trajectory estimation at once
- Presentation was awarded at Robotic Fair at Seoul National University

Full-Time/Part-Time Researcher

Dec. 2019 – Jun. 2020

Dynamic Robotic Systems Lab, SNU (Advisor: Prof. Jaeheung Park)

- Initial member of TEAM SNU for ANA Avatar Xprize Competition, robot control challenge sponsored over \$10M in prizes by ANA, judges included Ed Colgate, Thomas Ferris, Guy Hoffman

Project Topic: **MPC-based Control of Slave Robot and Design for Master System**

- Modified a control framework for torque distribution to achieve stability in upper body
- Developed virtual space environment to test control of teleoperated robot hands using Unity

PAPERS

- [1] **C. Kim**, et al., AI Python Coding in Easy Words with MIT Autonomous Race Car, *Hongreung Publishing Company*, Korea, 2021. [link]
- [2] Y. Choi, **C. Kim**, Y. Hwang, C. Park, *J.Lee**, Domain generalization in human pose estimation via meta-learning, Manuscript in preparation. [pdf]
- [3] **C. Kim**, *S.Park**, Optimization and Efficiency analysis of intelligent power system of Floating PV and Hydrogen System [pdf]

RESEARCH FUNDINGS, AWARDS, HONORS

Research Grant (\$7,000), SNU X-Corps, College of Engineering, SNU 2021

Sinyang Eminence Scholarship, Sinyang Cultural Foundation Spring. 2020 – Present

Certificate of Appreciation, Dean of the College of Engineering, SNU July. 2021

- Acknowledgement of genuine and creative efforts at the forefront of AI education in Korea

Special Award, Creative Design Fair, College of Engineering, SNU Sep. 2020

1st Prize, Engineering Design, SNU ME Mechanical Product Design July. 2020

Best Teaching Assistant Award, SNU Fall. 2019

Eminence Scholarship (full tuition), SNU Spring. 2017, Fall. 2019

Merit-Based Scholarship (50% tuition), SNU Fall. 2016

Bronze Award, Samsung Humantech Paper Award, Samsung Feb. 2014

ORAL PRESENTATIONS

- [1] **C. Kim**, J. Song, J. Seol, J. Park, S. Park, Optimization and efficiency analysis of intelligent power system of floating PV and hydrogen system, SNU X-CORPS, 2021.
- [2] **C. Kim**, S. Hwang, K. Cho, Development of Novel Tendon-clutching Algorithm Integrated of Trajectory Estimation and Feedback Control in Soft Teleoperation Glove, Creative Design Fair, SNU, 2020.

TEACHING EXPERIENCES

Teaching Assistant

Physics (034.006 001), (034.006 002), Department of Physics & Astronomy, SNU Fall. 2019, 2021

- Tutored 5-10 undergraduate students 2 hours per week for 2 semester.
- Developed contents for weekly recitation on diverse theories in field of dynamics, electronics, physics
- Provided periodical one-on-one instruction and Q&A session for additional advice in background knowledge of calculus and linear algebra

LEADERSHIP AND EXTRA CURRICULAR ACTIVITIES

10th Vice Chairman/ Team Leader of General Affairs Mar. 2020 – June. 2021

STEM: SNU Tomorrow's Edge Membership, SNU Engineers Honor Society Seoul, Korea

- Wrote book for future engineers: "I want to go to engineering school" (pub : Jan. 2022)
- Organized teenager mentoring program "2021 Vision Mentoring for Prospective Engineer"