

QUESTION 1

(a) Firstly use the Laplace transform

$$Y(s) = 3sX(s) - 0.5sY(s)$$

And move $Y(s)$ to the same side

$$(1+0.5s)Y(s) = 3sX(s)$$

Due to $H(s) = \frac{Y(s)}{X(s)}$, so the transfer function is

$$H(s) = \frac{3s}{1+0.5s} \quad \checkmark$$

When $1+0.5s$ equals 0, s equals -2 , so the pole is $s = -2$. \checkmark

When $3s$ equals 0, s equals 0, so the zero is $s = 0$.

(b) The input pulse signal can be written as

$$x(t) = u(t) - u(t-T)$$

Therefore

$$X(s) = \frac{1}{s} - e^{-sT} \left(\frac{1}{s} \right) = \frac{1-e^{-sT}}{s}$$

And

$$Y(s) = H(s)X(s) = \frac{3s(1-e^{-sT})}{(1+0.5s)s} = \frac{3(1-e^{-sT})}{1+0.5s} = 6\left(\frac{1}{s+2} - \frac{e^{-sT}}{s+2}\right)$$

$$Y(t) = L^{-1} [Y(s)] = 6u(t)e^{-2t} - 6u(t-T)e^{-2(t-T)}$$

(c) Use the ilaplace function to change $Y(s)$ into another function

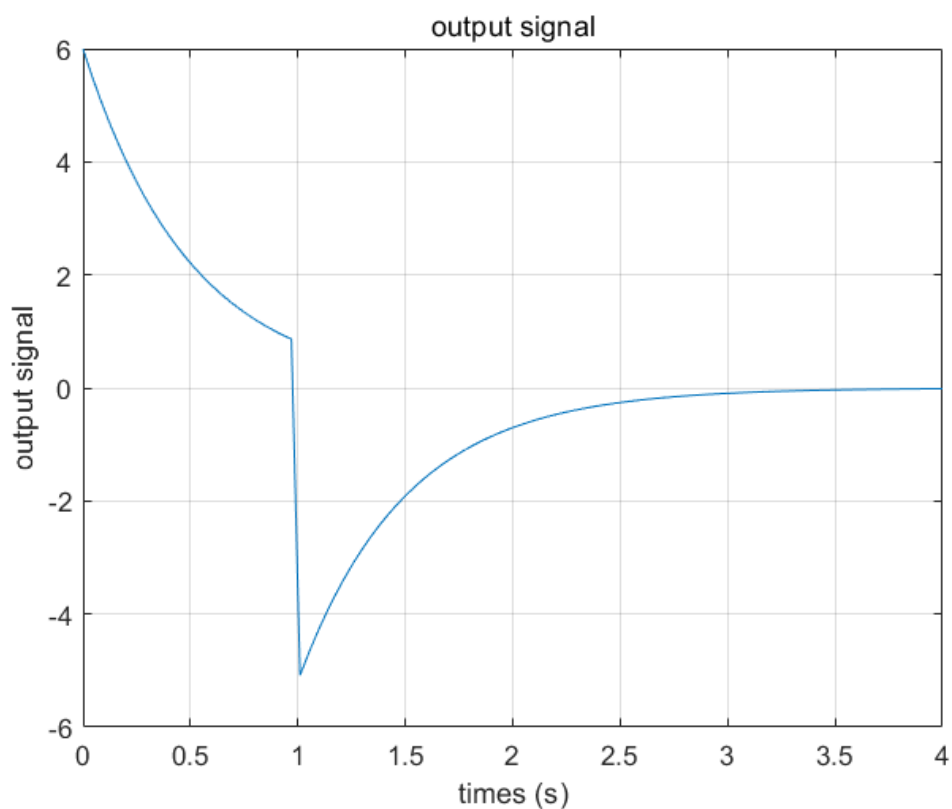
related to t . Then ~~plot~~ the output signal. *(Since use the syms s , so need to add subs in plot sentence)

And here is the code. ~~this does not plot the answer as obtained under (b)~~

```

DSP_Q1.m
1      syms s
2      T = 1;
3      % % % A = 3 - 3*(exp(-s*T));
4      % % % B = 1+0.5*s;
5      Y = (3 - 3*(exp(-s*T)))/(1+0.5*s);
6      Y_T = ilaplace(Y);
7
8
9      t = linspace(0, 4);
10     plot(t,subs(Y_T));
11
12
13     xlabel('times (s)');
14     ylabel('output signal');
15     title('output signal');
16     grid;

```



QUESTION 2

(a) We have

$$H(z) = \frac{Y(z)}{X(z)} = \frac{a+z^{-1}}{1+az^{-1}}$$

Thus

$$Y(z) = \frac{(a+z^{-1})X(z)}{1+az^{-1}}$$

And eliminate the denominator

$$Y(z) (1 + az^{-1}) = (a + z^{-1})X(z)$$

or

$$Y(z) = (a + z^{-1})X(z) - Y(z)az^{-1}$$

So now we can transform this equation to the time domain by taking the inverse z-transform

$$y(n) = ax(n) + x(n-1) - ay(n-1) \quad \checkmark$$

(b) Multiply both numerator and denominator with z

$$H(z) = \frac{az+1}{z+a}$$

The poles are the roots of the denominator

$$z+a = 0$$

which has the solution

$$z = -a \quad \checkmark$$

The poles of this system thus lie at $z = -a$ which mean $a \in \underline{[-1, 1]}$ $(-1,1)$

(c) The complex frequency response is

$$H(\omega) = H(z)|_{z=e^{j\omega T}} = \frac{a + e^{-j\omega T}}{1 + ae^{-j\omega T}}$$

And use the Euler's formula

$$H(\omega) = \frac{a + \cos\omega T - j\sin\omega T}{1 + a\cos\omega T - aj\sin\omega T}$$

So

$$|H(\omega)|^2 = \left| \frac{(a + \cos\omega T)^2 + \sin^2\omega T}{(1 + a\cos\omega T)^2 + (a\sin\omega T)^2} \right| \quad \checkmark$$

$$\begin{aligned}
&= \left| \frac{a^2 + 2a \cos \omega T + \cos^2 \omega T + \sin^2 \omega T}{1 + 2a \cos \omega T + a^2 \cos^2 \omega T + a^2 \sin^2 \omega T} \right| \\
&= \left| \frac{a^2 + 2a \cos \omega T + 1}{1 + 2a \cos \omega T + a^2} \right| \\
&= 1
\end{aligned}$$



(d) If $x(t) = \sin \omega t$, $X(z) = \frac{z \sin \omega T}{z^2 - 2z \cos \omega T + 1}$

So

$$\begin{aligned}
Y(z) &= H(z)X(z) = \frac{a+z^{-1}}{1+az^{-1}} \times \frac{z \sin \omega T}{z^2 - 2z \cos \omega T + 1} \\
&= \frac{az \sin \omega T + \sin \omega T}{z^2 - 2z \cos \omega T - 2a \cos \omega T + az^{-1} + az + 1}
\end{aligned}$$

this does not clarify how y is different from x;

(e) When $a = 0.5$ then $y(n) = 0.5x(n) + x(n-1) - 0.5y(n-1)$

which is

$$y(n) + 0.5y(n-1) = 0.5x(n) + x(n-1)$$

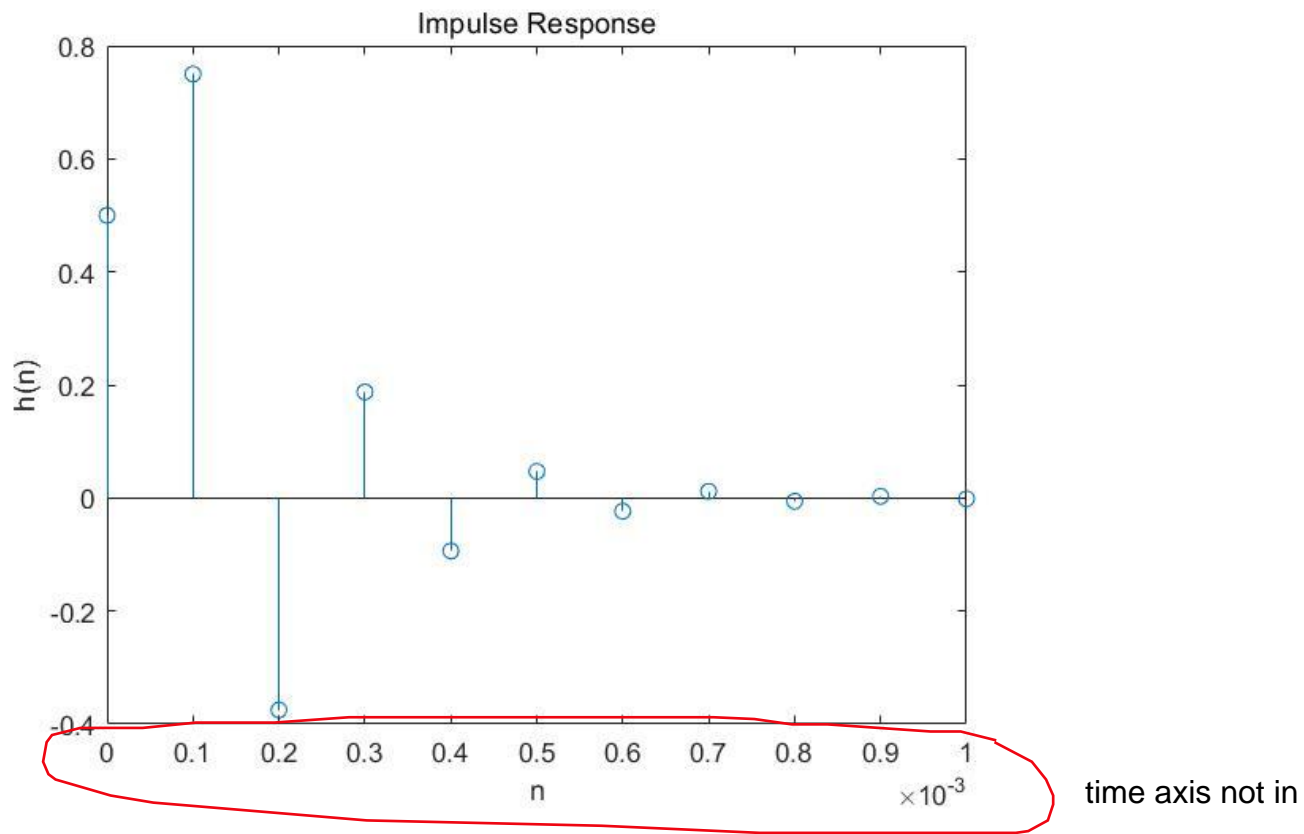
Use the `impz(b,a,n)` function where a is the difference equation

coefficient of output y, b is the coefficient of input x

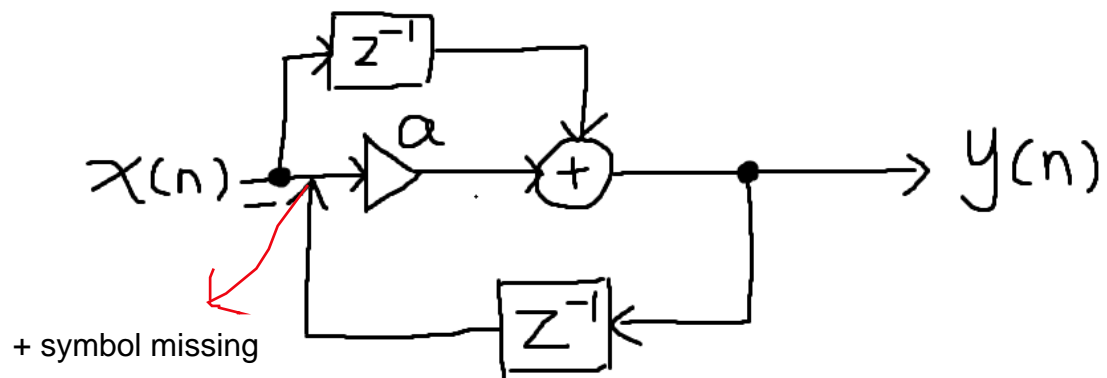
```

DSP_Q1.m x DSP_Q2.m x DSP_Q
1      b = [0.5, 1];
2      a = [1, 0.5];
3      n = 0:10;
4      [h,n] = impz(b,a,n,10000)
5
6      stem(n,h);
7      title('Impulse Response');
8      xlabel('n');
9      ylabel('h(n)');

```



(f) $y(n] = ax(n)+x(n-1)-ay(n-1)$



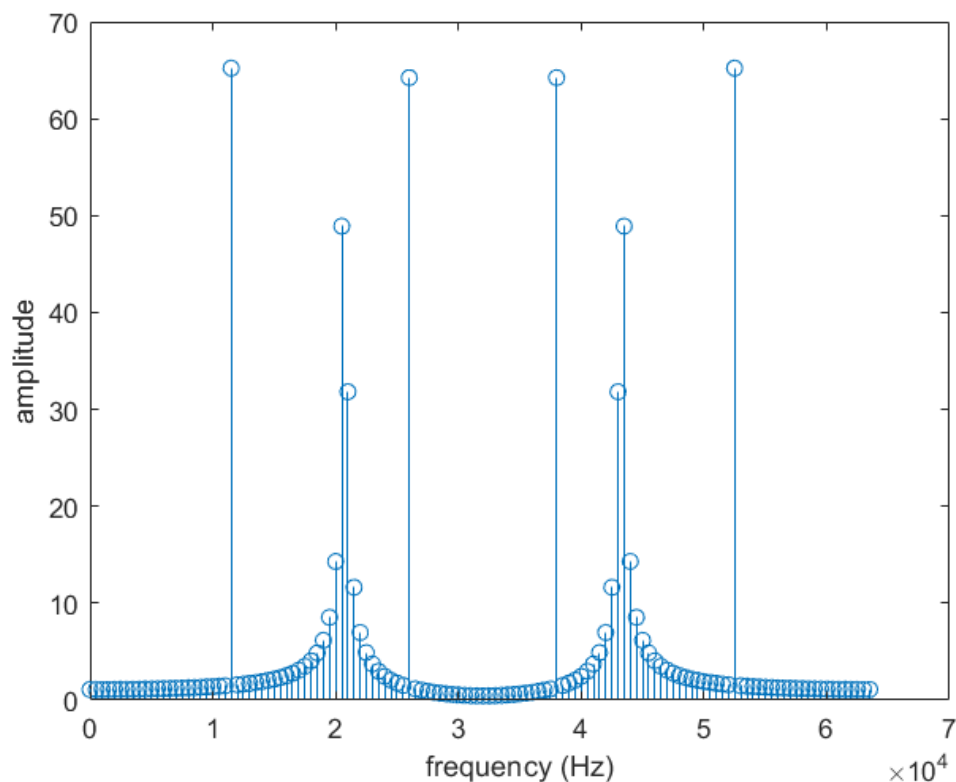
QUESTION 3

(a)

```

DSP_Q1.m x DSP_Q2.m x DSP_Q3.m x +
1  Fs = 64000;
2  T = 1/Fs;
3  Ns = 128;
4  t = (0:Ns-1)*T;
5  f = (0:Ns-1)*(Fs/Ns);
6
7  x = cos(2*pi*11500*t) + cos(2*pi*20700*t) + cos(2*pi*38000*t);
8
9  X = fft(x);
10
11 stem(f,abs(X));
12 xlabel('frequency (Hz)');
13 ylabel('amplitude');

```



where?

(b) Leakage happens when that frequency component does not have an integer number of periods within the analysed window of N samples.

As a result, the energy of the signal is 'spread out' out over neighbouring bins.

question asks "eliminate"

(c)

~~(d)~~

explain further

(d)

~~(é) D~~

C

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C

7

[illegible]

x_1			1	0	3	2			
x_2				1	-1	0	2	1	
Y	0-3+0=-3								
x_1				1	0	3	2		
x_2				1	-1	0	2	1	
Y	1+0+0+4=5								
x_1					1	0	3	2	
x_2				1	-1	0	2	1	
Y	-1+0+6+2=7								
x_1						1	0	3	2
x_2				1	-1	0	2	1	
Y	0+0+3=3								
x_1				1	0	3	2		
x_2	1	-1	0	2	1				
Y	2+0=2								
x_1					1	0	3	2	
x_2	1	-1	0	2	1				
Y	1								

So

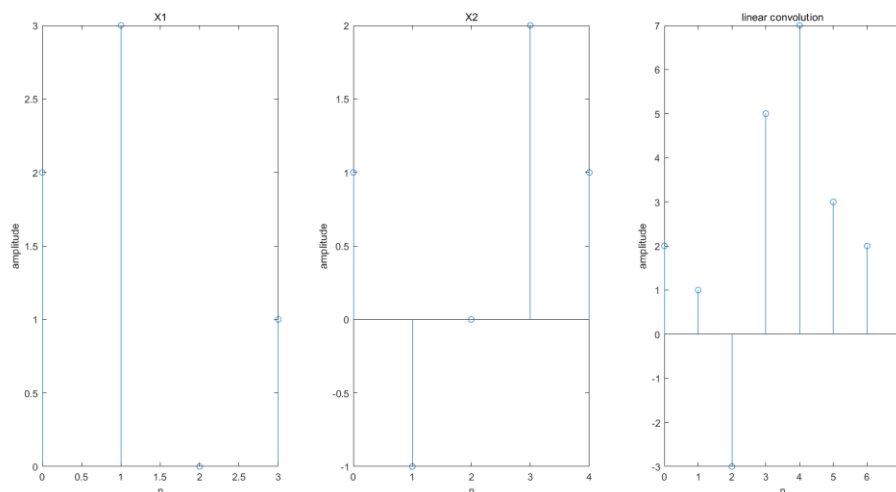
$$Y = [2, 1, -3, 5, 7, 3, 2, 1] \checkmark$$

(b)


```

DSP_Q1.m x DSP_Q2.m x DSP_Q3.m x DSP_Q4.m x +
1      x1 = [2,3,0,1];
2      nx1=[0:length(x1)-1];
3      x2 = [1,-1,0,2,1];
4      nx2=[0:length(x2)-1];
5      y=conv(x1,x2); -> this does not use DFTs
6      ny=[0:1:length(y)-1];
7      subplot(1,3,1)
8      stem(nx1,x1);
9      xlabel('n')
10     ylabel('amplitude')
11     title('X1')
12     subplot(1,3,2)
13     stem(nx2,x2)
14     xlabel('n')
15     ylabel('amplitude')
16     title('X2')
17     subplot(1,3,3)
18     stem(ny,y);
19     xlabel('n')
20     ylabel('amplitude')
21     title('linear convolution')

```



(c) Segmentation of signal into fixed-size data blocks, to avoid transform of very long sequences. Avoids large memory requirements and long lag in case of on-line processing

OVERLAP-SAVE

OVERLAP-ADD