GAN HW4 Final

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0.1 GANs: Generative Adversarial Networks

Image from here

A generative adversarial network (GAN) is a generative model composed of two neural networks: a generator and a discriminator. These two networks are trained in unsupervised way via competition. The generator creates "realistic" fake images from random noise to fool the discriminator, while the discriminator evaluates the given image for authenticity. The loss function that the generator wants to minimize and the discriminator to maximize is as follows:

$$\min G \max D L(D, G) = \operatorname{Ex} \operatorname{pdata}(x)[\log D(x)] + \operatorname{Ez} \operatorname{pz}(z)[\log(1 - D(G(z)))]$$

Here, G and D are the generator and the discriminator. The first and second term of the loss represent the correct prediction of the discriminator on the real images and on the fake images respectively.

0.2 DCGAN

- \bullet You will implement deep convolutional GAN model on the MNIST dataset with Pytorch. The input image size is 28 x 28.
- The details of the generator of DCGAN is described below.
- You will start with batch size of 128, input noise of 100 dimension and Adam optimizer with learning rate of 2e-4. You may vary these hyperparameters for better performance.

0.3 Architectures

Generator:

The goal for the generator is to use layers such as convolution, maybe also upsampling layer/transposedConvolution to produce image from the given input noise vector. As this is DC-GAN (deep convolutional GAN), we expect you to use convolution in the generator. You will get full credit if you can produce [batchsize, 1, 28, 28] vector (image) from the given [batchsize, 100, 1, 1] vector (noise).

Linear Layers that you may use:

• torch.nn.Conv2d

- torch.nn.UpsamplingBilinear2d
- torch.nn.ConvTranspose2d

Non-linear layer:

- torch.nn.LeakyReLU with slope=0.2 between all linear layers.
- torch.nn.Tanh for the last layer's activation. Can you explain why do we need this in the code comment?

You may use view to change the vector size: https://pytorch.org/docs/stable/generated/torch.Tensor.view.html

We recommend to use 2 Conv/TransposedConv layers. When you are increasing the feature map size, considering upsample the feature by a factor of 2 each time. If you have width of 7 in one of your feature map, to get output with width of 28, you can do upsampling with factor of 2 and upsampling 2 times.

Discriminator:

You will get full credit if you can produce an output of [batchsize, 1] vector (image) from the given input [batchsize, 1, 28, 28] vector (noise).

Linear Layers that you may use:

- torch.nn.Conv2d
- torch.nn.Linear

Non-linear Layers:

- torch.nn.LeakyReLU with slope=0.2 between all linear layers.
- torch.nn.Sigmoid for the last layer's activation. Can you explain why do we need this in the code comment?

Use Leaky ReLu as the activation function between all layers, except after the last layer use Sigmoid.

You may use view to change the vector size: https://pytorch.org/docs/stable/generated/torch.Tensor.view.html

As an example, you may use 2 convolution layer and one linear layer in the discriminator, you can also use other setup. Note that instead of using pooling to downsampling, you may also use stride=2 in convolution to downsample the feature.

```
[1]: # NOTE: Referenced From: https://pytorch.org/tutorials/beginner/

→dcgan_faces_tutorial.html

from torchvision.transforms.transforms import Normalize
import torch
import torch.nn as nn
import torch.nn.functional as F
import torch.optim as optim
from torchvision import datasets, transforms
from torch.autograd import Variable
from torchvision.utils import save_image
import matplotlib.pyplot as plt
```

```
import matplotlib.animation as animation
from IPython.display import HTML
import numpy as np
from torch.optim.lr_scheduler import StepLR
import torchvision.utils as vutils
from torch.utils.data import DataLoader, TensorDataset
from scipy import linalg
from scipy.stats import entropy
import tqdm
import cv2
# image input size
image_size=28
# Setting up transforms to resize and normalize
transform=transforms.Compose([transforms.Resize(image_size),
                               transforms.CenterCrop(image_size),
                               transforms.ToTensor(),
                               transforms.Normalize((0.5), (0.5))])
# batchsize of dataset
batch_size = 100
# Load MNIST Dataset
gan_train_dataset = datasets.MNIST(root='./MNIST/', train=True,_
 →transform=transform, download=True)
gan_train_loader = torch.utils.data.DataLoader(dataset=gan_train_dataset,__
 ⇒batch_size=batch_size, shuffle=True)
Downloading http://yann.lecun.com/exdb/mnist/train-images-idx3-ubyte.gz
Downloading http://yann.lecun.com/exdb/mnist/train-images-idx3-ubyte.gz to
./MNIST/MNIST/raw/train-images-idx3-ubyte.gz
  0%1
               | 0/9912422 [00:00<?, ?it/s]
Extracting ./MNIST/MNIST/raw/train-images-idx3-ubyte.gz to ./MNIST/MNIST/raw
Downloading http://yann.lecun.com/exdb/mnist/train-labels-idx1-ubyte.gz
Downloading http://yann.lecun.com/exdb/mnist/train-labels-idx1-ubyte.gz to
./MNIST/MNIST/raw/train-labels-idx1-ubyte.gz
  0%1
               | 0/28881 [00:00<?, ?it/s]
Extracting ./MNIST/MNIST/raw/train-labels-idx1-ubyte.gz to ./MNIST/MNIST/raw
Downloading http://yann.lecun.com/exdb/mnist/t10k-images-idx3-ubyte.gz
Downloading http://yann.lecun.com/exdb/mnist/t10k-images-idx3-ubyte.gz to
./MNIST/MNIST/raw/t10k-images-idx3-ubyte.gz
  0%1
               | 0/1648877 [00:00<?, ?it/s]
Extracting ./MNIST/MNIST/raw/t10k-images-idx3-ubyte.gz to ./MNIST/MNIST/raw
```

```
Downloading http://yann.lecun.com/exdb/mnist/t10k-labels-idx1-ubyte.gz Downloading http://yann.lecun.com/exdb/mnist/t10k-labels-idx1-ubyte.gz to ./MNIST/MNIST/raw/t10k-labels-idx1-ubyte.gz
```

```
0%| | 0/4542 [00:00<?, ?it/s]
```

Extracting ./MNIST/MNIST/raw/t10k-labels-idx1-ubyte.gz to ./MNIST/MNIST/raw

0.4 Model Definition (TODO)

```
[2]: class DCGAN_Generator(nn.Module):
         def __init__(self):
             super(DCGAN_Generator,self).__init__()
             self.gen_net = nn.Sequential(
                 nn.ConvTranspose2d(100, 256, 7, 1, 0, bias = False),
                 nn.BatchNorm2d(256),
                 nn.LeakyReLU(0.2, True),
                 nn.ConvTranspose2d(256, 128, 4, 2, 1, bias = False),
                 nn.BatchNorm2d(128),
                 nn.LeakyReLU(0.2, True),
                 nn.ConvTranspose2d(128, 1, 4, 2, 1, bias = False),
                 nn.Tanh()
             )
         def forward(self, input):
             out = self.gen_net(input)
             # Explain why Tanh is needed for the last layer
             111
             Answer: As we need to propagate more losses when the pixel changes are
             there in the lower range rather than in the higher brightness range, we
             want to use a similar activation for our last layer such that the
             generator generates data accordingly and in accordance with how our eyes
             perceive the image data. To model a similar behaviour as we are randomly
             generating the data here, we need an activation that models the same for
             11.5
             return out
     class DCGAN_Discriminator(nn.Module):
         def __init__(self):
```

```
super(DCGAN_Discriminator, self).__init__()
        self.disc_net = nn.Sequential(
            nn.Conv2d(1, 128, 4, 2, 1, bias = False),
            nn.BatchNorm2d(128),
            nn.LeakyReLU(0.2, True),
            nn.Conv2d(128, 64, 4, 2, 1, bias = False),
            nn.BatchNorm2d(64),
            nn.LeakyReLU(0.2, True),
            nn.Flatten(),
            # This is added to create a single output
            # and the number is actually the number of nodes coming out of
            # the previous layer
            nn.Linear(64*7*7, 1),
            nn.Sigmoid()
        )
    def forward(self, input):
        out = self.disc_net(input)
        # Explain why Sigmoid is needed for the last layer
        Answer: As we are doing Binary Classification here from the
\hookrightarrow discriminator,
        Real or Fake, for which we would need to calculate the losses using the
        logits/probabilities for the classes predicted and the target variable,
        we need to use Sigmoid function which gives us the inputs as needed for
        our problem statement and use case at hand.
        return out
# Code that check size
g=DCGAN_Generator()
batchsize=2
z=torch.zeros((batchsize, 100, 1, 1))
out = g(z)
print(out.size()) # You should expect size [batchsize, 1, 28, 28]
d=DCGAN_Discriminator()
x=torch.zeros((batchsize, 1, 28, 28))
```

```
out = d(x)
     print(out.size()) # You should expect size [batchsize, 1]
    torch.Size([2, 1, 28, 28])
    torch.Size([2, 1])
    GAN loss (TODO)
[3]: import torch
     def loss_discriminator(D, real, G, noise, Valid_label, Fake_label, criterion, U
      →optimizerD):
         111
         1. Forward real images into the discriminator
         2. Compute loss between Valid label and dicriminator output on real images
         3. Forward noise into the generator to get fake images
         4. Forward fake images to the discriminator
         5. Compute loss between Fake_label and discriminator output on fake images⊔
      → (and remember to detach the gradient from the fake images using detach()!)
         6. sum real loss and fake loss as the loss_D
         7. we also need to output fake images generate by G(noise) for \Box
      \hookrightarrow loss_generator computation
         111
         # Step-1
         output = D(real).view(-1)
         # Step-2
         loss D real = criterion(output, Valid label)
         # Step-3
         fake_imgs = G(noise)
         # Step-4
         output = D(fake_imgs.detach()).view(-1)
         loss_D_fake = criterion(output, Fake_label)
         # Step-6
         loss_D = loss_D_real + loss_D_fake
         # Step-7
         return loss_D, fake_imgs
     def loss_generator(netD, netG, fake, Valid_label, criterion, optimizerG):
         1. Forward fake images to the discriminator
         2. Compute loss between valid labels and discriminator output on fake images
         111
         # Step-1
```

```
output = netD(fake).view(-1)
# Step-2
loss_G = criterion(output, Valid_label)
return loss_G
```

```
[4]: import torchvision.utils as vutils
     from torch.optim.lr_scheduler import StepLR
     import pdb
     device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
     # Number of channels
     nc = 1
     # Size of z latent vector (i.e. size of generator input)
     nz = 100
     netG = DCGAN_Generator().to(device)
     netD = DCGAN_Discriminator().to(device)
     from torchsummary import summary
     print(summary(netG,(100,1,1)))
     print(summary(netD,(1, 28, 28)))
```

Layer (type)	Output Shape	Param #
ConvTranspose2d-1 BatchNorm2d-2 LeakyReLU-3 ConvTranspose2d-4 BatchNorm2d-5 LeakyReLU-6 ConvTranspose2d-7 Tanh-8	[-1, 256, 7, 7] [-1, 256, 7, 7] [-1, 256, 7, 7] [-1, 128, 14, 14] [-1, 128, 14, 14] [-1, 128, 14, 14] [-1, 1, 28, 28] [-1, 1, 28, 28]	1,254,400 512 0 524,288 256 0 2,048

Total params: 1,781,504 Trainable params: 1,781,504 Non-trainable params: 0

Input size (MB): 0.00

Forward/backward pass size (MB): 0.87

Params size (MB): 6.80

Estimated Total Size (MB): 7.67

None

Layer (type) Output Shape Param #

```
[-1, 128, 14, 14]
         Conv2d-1
                                             2,048
                       [-1, 128, 14, 14]
     BatchNorm2d-2
                                               256
       LeakyReLU-3
                       [-1, 128, 14, 14]
                                                 0
         Conv2d-4
                        [-1, 64, 7, 7]
                                          131,072
     BatchNorm2d-5
                         [-1, 64, 7, 7]
                                              128
       LeakyReLU-6
                         [-1, 64, 7, 7]
                                                 0
        Flatten-7
                             [-1, 3136]
         Linear-8
                               [-1, 1]
                                             3,137
                               [-1, 1]
        Sigmoid-9
______
```

Total params: 136,641 Trainable params: 136,641 Non-trainable params: 0

Input size (MB): 0.00

Forward/backward pass size (MB): 0.67

Params size (MB): 0.52

Estimated Total Size (MB): 1.19

None

TRAINING

```
[5]: import torchvision.utils as vutils
     from torch.optim.lr_scheduler import StepLR
     import pdb
     device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
     # Number of channels
     nc = 1
     # Size of z latent vector (i.e. size of generator input)
     # Create the generator and discriminator
     netG = DCGAN_Generator().to(device)
     netD = DCGAN_Discriminator().to(device)
     # Initialize BCELoss function
     criterion = nn.BCELoss()
     # Create latent vector to test the generator performance
     fixed_noise = torch.randn(36, nz, 1, 1, device=device)
     # Establish convention for real and fake labels during training
     real_label = 1
     fake_label = 0
```

```
learning_rate = 0.0002
beta1 = 0.5
# Setup Adam optimizers for both G and D
######################################
# Please fill in your code here:
optimizerD = optim.Adam(netD.parameters(), lr=learning_rate, betas=(beta1, 0.
→999))
optimizerG = optim.Adam(netG.parameters(), lr=learning_rate, betas=(beta1, 0.
img_list = []
real_img_list = []
G_{losses} = []
D_losses = []
iters = 0
num_epochs = 50 # Changed this to get better results
def load param(num eps):
 model_saved = torch.load('/content/gan_{}.pt'.format(num_eps))
 netG.load_state_dict(model_saved['netG'])
 netD.load_state_dict(model_saved['netD'])
# GAN Training Loop
for epoch in range(num_epochs):
   for i, data in enumerate(gan_train_loader, 0):
       real = data[0].to(device)
       b size = real.size(0)
       noise = torch.randn(b_size, nz, 1, 1, device=device)
       Valid_label = torch.full((b_size,), real_label, dtype=torch.float,_u
 →device=device)
       Fake_label = torch.full((b_size,), fake_label, dtype=torch.float,__
→device=device)
       # (1) Update D network: maximize log(D(x)) + log(1 - D(G(z)))
       #############################
       netD.zero_grad()
```

```
loss_D, fake_imgs = loss_discriminator(netD, real, netG, noise,_
 →Valid_label, Fake_label, criterion, optimizerD)
        loss_D.backward()
        optimizerD.step()
        ###################################
        # (2) Update G network: maximize log(D(G(z)))
        ##############################
        netG.zero_grad()
        loss_G = loss_generator(netD, netG, fake_imgs, Valid_label, criterion,_
 →optimizerG)
        loss_G.backward()
        optimizerG.step()
        # Output training stats
        if i % 50 == 0:
            print('[%d/%d][%d/%d]\tLoss_D: %.4f\tLoss_G: %.4f\t'
                  % (epoch, num_epochs, i, len(gan_train_loader),
                     loss_D.item(), loss_G.item()))
        # Save Losses for plotting later
        G_losses.append(loss_G.item())
        D losses.append(loss D.item())
        # Check how the generator is doing by saving G's output on fixed_noise
        if (iters \% 500 == 0) or ((epoch == num_epochs-1) and (i ==_
→len(gan_train_loader)-1)):
            with torch.no_grad():
                fake = netG(fixed_noise).detach().cpu()
            img_list.append(vutils.make_grid(fake, padding=2, normalize=True))
        iters += 1
plt.title("Generator and Discriminator Loss During Training")
plt.plot(G_losses,label="G")
plt.plot(D losses,label="D")
plt.xlabel("iterations")
plt.ylabel("Loss")
plt.legend()
plt.show()
```

```
checkpoint = {'netG': netG.state_dict(),
              'netD': netD.state_dict()}
torch.save(checkpoint, 'gan_{}.pt'.format(num_epochs))
[0/50] [0/600]
               Loss_D: 1.5680 Loss_G: 0.8732
[0/50][50/600] Loss_D: 0.8541 Loss_G: 1.4793
[0/50][100/600] Loss D: 1.0419 Loss G: 0.6862
[0/50][150/600] Loss_D: 1.0198 Loss_G: 0.9973
[0/50][200/600] Loss D: 1.0158 Loss G: 1.6525
[0/50][250/600] Loss_D: 0.8398 Loss_G: 1.4010
[0/50][300/600] Loss_D: 0.7039 Loss_G: 1.2722
[0/50][350/600] Loss_D: 0.5747 Loss_G: 1.9331
[0/50][400/600] Loss_D: 0.5572 Loss_G: 1.5470
[0/50][450/600] Loss_D: 0.6471 Loss_G: 1.7121
[0/50][500/600] Loss_D: 0.5147 Loss_G: 1.8375
[0/50][550/600] Loss D: 0.4706 Loss G: 1.8235
               Loss D: 0.4593 Loss G: 1.7749
[1/50] [0/600]
[1/50][50/600] Loss D: 0.5812 Loss G: 1.6918
[1/50][100/600] Loss_D: 0.5394 Loss_G: 1.4933
[1/50][150/600] Loss_D: 0.6323 Loss_G: 0.6902
[1/50][200/600] Loss_D: 0.7331 Loss_G: 1.4061
[1/50][250/600] Loss D: 0.5846 Loss G: 1.7611
[1/50][300/600] Loss_D: 0.7295 Loss_G: 1.5103
[1/50][350/600] Loss D: 0.4963
                               Loss G: 1.5023
[1/50][400/600] Loss_D: 0.7561
                               Loss_G: 0.8506
[1/50][450/600] Loss_D: 0.6414 Loss_G: 1.9196
[1/50][500/600] Loss_D: 0.7856
                               Loss_G: 1.4955
[1/50][550/600] Loss_D: 0.8247 Loss_G: 2.4358
[2/50] [0/600]
               Loss_D: 0.7197 Loss_G: 1.4258
[2/50][50/600] Loss_D: 0.5601 Loss_G: 1.8779
[2/50][100/600] Loss_D: 0.5649
                               Loss_G: 1.7796
[2/50][150/600] Loss D: 0.4427
                               Loss G: 2.0067
[2/50][200/600] Loss D: 0.8113 Loss G: 1.0601
[2/50][250/600] Loss_D: 0.8420
                               Loss G: 3.4616
[2/50][300/600] Loss D: 0.7018 Loss G: 2.3584
[2/50][350/600] Loss_D: 0.5479
                               Loss_G: 2.5846
[2/50][400/600] Loss D: 0.6443 Loss G: 1.6570
[2/50][450/600] Loss_D: 0.6682
                               Loss_G: 1.4708
[2/50][500/600] Loss D: 0.8416
                               Loss G: 1.5236
[2/50][550/600] Loss_D: 0.8563
                               Loss_G: 1.1306
[3/50] [0/600]
               Loss_D: 0.7467
                               Loss_G: 1.1430
[3/50][50/600] Loss_D: 1.1255
                               Loss_G: 2.1863
[3/50][100/600] Loss_D: 0.7164
                               Loss_G: 1.9378
[3/50][150/600] Loss_D: 0.6312 Loss_G: 1.8080
[3/50][200/600] Loss_D: 0.5837
                               Loss_G: 1.7076
[3/50][250/600] Loss_D: 0.5916
                               Loss_G: 1.2347
[3/50][300/600] Loss D: 0.8338
                               Loss G: 0.9688
```

```
[3/50][350/600] Loss_D: 1.2971
                                Loss_G: 2.7516
[3/50][400/600] Loss_D: 0.6095
                                Loss_G: 1.7204
[3/50][450/600] Loss_D: 0.6601
                                Loss_G: 1.3771
[3/50][500/600] Loss D: 0.6651
                                Loss G: 1.7613
                               Loss G: 2.0187
[3/50][550/600] Loss D: 0.4865
[4/50] [0/600]
                Loss D: 0.4695
                                Loss G: 1.8346
[4/50][50/600] Loss D: 0.7469
                                Loss G: 1.0282
                                Loss G: 3.1240
[4/50][100/600] Loss D: 0.9725
[4/50][150/600] Loss D: 0.5153
                                Loss G: 1.9743
[4/50][200/600] Loss_D: 0.8244
                                Loss_G: 2.6224
[4/50][250/600] Loss_D: 0.5597
                                Loss_G: 1.9392
[4/50][300/600] Loss_D: 0.5925
                                Loss_G: 2.5154
[4/50][350/600] Loss_D: 0.6282
                                Loss_G: 1.8843
[4/50][400/600] Loss D: 1.0299
                                Loss_G: 2.2887
[4/50][450/600] Loss_D: 0.7497
                                Loss_G: 1.7623
[4/50][500/600] Loss_D: 0.6163
                                Loss_G: 1.7632
[4/50][550/600] Loss_D: 0.6402
                                Loss_G: 1.3164
[5/50] [0/600]
                Loss_D: 0.7663
                               Loss_G: 1.1434
[5/50][50/600] Loss D: 0.7085
                               Loss G: 2.0353
                               Loss G: 1.5692
[5/50][100/600] Loss D: 0.5353
[5/50][150/600] Loss D: 0.5225
                                Loss G: 1.5850
[5/50][200/600] Loss_D: 0.6587
                                Loss G: 1.5748
[5/50][250/600] Loss_D: 0.5477
                                Loss G: 1.8129
[5/50][300/600] Loss_D: 0.5301
                                Loss G: 1.8204
[5/50][350/600] Loss_D: 0.5406
                                Loss_G: 1.7260
[5/50][400/600] Loss_D: 0.6253
                                Loss_G: 2.3640
                                Loss_G: 1.5431
[5/50][450/600] Loss_D: 0.5149
[5/50][500/600] Loss_D: 0.5446
                                Loss_G: 1.4730
[5/50][550/600] Loss D: 0.5942
                                Loss G: 1.8001
[6/50] [0/600]
                Loss_D: 0.5778
                                Loss_G: 2.4183
[6/50] [50/600]
               Loss_D: 0.9447
                                Loss_G: 0.7604
[6/50][100/600] Loss_D: 0.8141
                                Loss_G: 0.7797
[6/50][150/600] Loss_D: 0.4591
                                Loss_G: 2.0422
[6/50][200/600] Loss D: 0.5944
                               Loss G: 1.9065
[6/50][250/600] Loss D: 1.1560
                                Loss G: 0.9100
[6/50][300/600] Loss D: 0.5470
                                Loss G: 1.9697
[6/50][350/600] Loss_D: 0.7468
                                Loss G: 0.8224
[6/50][400/600] Loss D: 0.5075
                                Loss G: 2.6210
[6/50][450/600] Loss_D: 0.5725
                                Loss_G: 1.9285
[6/50][500/600] Loss D: 1.0137
                                Loss_G: 1.3215
[6/50][550/600] Loss_D: 0.6190
                                Loss_G: 2.4138
                                Loss_G: 1.3992
[7/50] [0/600]
                Loss_D: 0.9757
[7/50] [50/600]
               Loss_D: 0.5559
                                Loss_G: 1.6948
[7/50][100/600] Loss D: 0.6236
                                Loss G: 1.1428
[7/50][150/600] Loss_D: 0.4608
                                Loss_G: 1.9500
[7/50][200/600] Loss_D: 0.5825
                                Loss_G: 1.2220
[7/50][250/600] Loss_D: 0.7078
                                Loss_G: 1.5409
[7/50][300/600] Loss_D: 0.8064
                                Loss_G: 0.5129
```

```
[7/50][350/600] Loss_D: 0.4742
                                Loss_G: 2.0002
[7/50][400/600] Loss_D: 0.5666
                                Loss_G: 2.5095
[7/50][450/600] Loss_D: 0.4478
                                Loss_G: 2.3693
[7/50][500/600] Loss D: 0.4590
                                Loss G: 1.8243
[7/50][550/600] Loss D: 0.4973
                                Loss G: 2.4245
                Loss D: 0.7239
                                Loss G: 1.9520
[8/50] [0/600]
[8/50] [50/600]
               Loss D: 0.8380
                                Loss G: 0.9201
[8/50][100/600] Loss D: 0.4183
                                Loss G: 2.1505
[8/50][150/600] Loss D: 0.5030
                                Loss G: 1.8009
[8/50][200/600] Loss_D: 0.7264
                                Loss_G: 1.1231
[8/50][250/600] Loss_D: 0.4455
                                Loss_G: 1.9563
[8/50][300/600] Loss_D: 0.5998
                                Loss_G: 2.3868
[8/50][350/600] Loss_D: 0.6192
                                Loss_G: 2.0435
[8/50][400/600] Loss D: 0.6469
                                Loss G: 1.7227
[8/50][450/600] Loss_D: 0.5065
                                Loss_G: 2.9479
[8/50][500/600] Loss_D: 0.5106
                                Loss_G: 2.2250
[8/50][550/600] Loss_D: 0.7189
                                Loss_G: 2.7596
                Loss_D: 0.6857
                                Loss_G: 1.1795
[9/50] [0/600]
[9/50] [50/600]
               Loss D: 0.4736 Loss G: 2.1352
[9/50][100/600] Loss D: 0.5780
                                Loss G: 2.6128
[9/50][150/600] Loss D: 0.4336
                                Loss G: 2.4512
[9/50][200/600] Loss D: 0.4159
                                Loss G: 2.6024
[9/50][250/600] Loss_D: 0.9202
                                Loss G: 0.7810
[9/50][300/600] Loss D: 0.5433
                                Loss_G: 1.4477
[9/50][350/600] Loss_D: 1.1141 Loss_G: 3.3660
[9/50][400/600] Loss_D: 0.4418
                                Loss_G: 2.9481
[9/50][450/600] Loss_D: 0.5587
                                Loss_G: 2.1139
[9/50][500/600] Loss_D: 0.8284
                                Loss_G: 2.3588
[9/50][550/600] Loss D: 0.4412
                                Loss G: 1.9901
[10/50][0/600] Loss_D: 0.5160
                                Loss_G: 1.4835
[10/50][50/600] Loss_D: 0.5135
                                Loss G: 2.8555
[10/50] [100/600]
                        Loss_D: 0.5093 Loss_G: 2.4332
[10/50] [150/600]
                        Loss_D: 0.8908 Loss_G: 4.1359
[10/50] [200/600]
                        Loss_D: 0.6449 Loss_G: 1.2802
                        Loss D: 0.6190 Loss G: 2.3388
[10/50] [250/600]
                        Loss D: 0.8450 Loss G: 2.2125
[10/50] [300/600]
                        Loss D: 0.6131 Loss G: 1.6909
[10/50] [350/600]
[10/50] [400/600]
                        Loss_D: 0.5714 Loss_G: 1.6612
                        Loss_D: 0.4141 Loss_G: 2.4889
[10/50] [450/600]
[10/50] [500/600]
                        Loss_D: 0.6252 Loss_G: 1.7478
                        Loss_D: 0.7324 Loss_G: 0.7077
[10/50] [550/600]
[11/50][0/600] Loss_D: 0.9154 Loss_G: 3.2214
[11/50][50/600] Loss_D: 0.4208 Loss_G: 2.2572
                        Loss_D: 0.6015 Loss_G: 2.4370
[11/50] [100/600]
[11/50] [150/600]
                        Loss_D: 0.6133
                                        Loss_G: 2.0986
[11/50] [200/600]
                        Loss_D: 0.5487
                                        Loss_G: 2.7824
[11/50] [250/600]
                        Loss_D: 0.7259
                                        Loss_G: 3.1681
[11/50] [300/600]
                        Loss_D: 0.6101
                                        Loss_G: 2.9995
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[11/50] [350/600]
                        Loss_D: 0.6723
                                        Loss_G: 1.4365
[11/50] [400/600]
                        Loss_D: 0.6147
                                        Loss_G: 2.0612
[11/50] [450/600]
                        Loss_D: 0.7283
                                        Loss_G: 1.4230
                                        Loss_G: 2.5009
[11/50] [500/600]
                        Loss_D: 0.5265
                        Loss D: 0.5370 Loss G: 2.4616
[11/50] [550/600]
[12/50][0/600] Loss D: 0.6134 Loss G: 2.3842
[12/50][50/600] Loss D: 0.4849 Loss G: 2.3870
[12/50] [100/600]
                        Loss_D: 0.8420
                                        Loss_G: 2.9040
[12/50] [150/600]
                        Loss D: 0.5166
                                        Loss G: 1.7637
[12/50] [200/600]
                        Loss_D: 0.6453
                                        Loss_G: 1.9602
[12/50] [250/600]
                        Loss_D: 0.5065
                                        Loss_G: 1.9799
[12/50] [300/600]
                        Loss_D: 0.5314 Loss_G: 2.3480
                        Loss_D: 0.8205
                                        Loss_G: 3.3575
[12/50] [350/600]
[12/50] [400/600]
                        Loss_D: 0.3985
                                        Loss_G: 2.2193
[12/50] [450/600]
                        Loss_D: 0.5392
                                        Loss_G: 1.9862
[12/50] [500/600]
                        Loss_D: 0.7159
                                        Loss_G: 1.6564
[12/50] [550/600]
                        Loss_D: 0.4407
                                        Loss_G: 2.7636
[13/50][0/600] Loss_D: 0.4477 Loss_G: 2.2256
[13/50][50/600] Loss_D: 0.5763 Loss_G: 1.9199
                        Loss D: 0.5879
                                        Loss G: 1.5820
[13/50] [100/600]
[13/50] [150/600]
                        Loss D: 0.8220
                                        Loss G: 2.9888
[13/50] [200/600]
                        Loss D: 0.4443
                                        Loss G: 2.1864
[13/50] [250/600]
                        Loss_D: 0.5201 Loss_G: 2.2581
[13/50] [300/600]
                        Loss_D: 0.5409
                                        Loss_G: 0.9988
                        Loss_D: 0.4180 Loss_G: 2.3652
[13/50] [350/600]
[13/50] [400/600]
                        Loss_D: 0.5411 Loss_G: 2.1003
[13/50] [450/600]
                        Loss_D: 0.3635 Loss_G: 2.8073
[13/50] [500/600]
                        Loss_D: 0.4991
                                        Loss_G: 2.4565
[13/50] [550/600]
                        Loss_D: 0.5492
                                        Loss_G: 2.8100
[14/50] [0/600]
               Loss_D: 1.1791 Loss_G: 0.3085
[14/50][50/600] Loss_D: 0.4686 Loss_G: 2.4309
[14/50] [100/600]
                        Loss_D: 0.5037
                                        Loss_G: 0.9371
[14/50] [150/600]
                        Loss_D: 0.4244
                                        Loss_G: 2.5694
                        Loss_D: 0.4888 Loss_G: 1.8678
[14/50] [200/600]
                        Loss D: 0.6060 Loss G: 1.9319
[14/50] [250/600]
[14/50] [300/600]
                        Loss D: 0.5269
                                        Loss G: 2.0915
[14/50] [350/600]
                        Loss D: 0.5891 Loss G: 2.2497
[14/50] [400/600]
                        Loss_D: 0.5099
                                        Loss_G: 1.9081
[14/50] [450/600]
                        Loss_D: 0.5432
                                        Loss_G: 2.0123
[14/50] [500/600]
                        Loss_D: 0.5089
                                        Loss_G: 1.8210
[14/50] [550/600]
                        Loss_D: 0.4007
                                        Loss_G: 2.5216
[15/50][0/600] Loss_D: 0.4090 Loss_G: 2.3912
[15/50][50/600] Loss_D: 0.4126 Loss_G: 2.7302
[15/50] [100/600]
                        Loss_D: 0.2593
                                        Loss_G: 2.8944
[15/50] [150/600]
                        Loss_D: 0.5037
                                        Loss_G: 2.1723
[15/50] [200/600]
                        Loss_D: 0.6851
                                        Loss_G: 1.1594
[15/50] [250/600]
                        Loss_D: 0.6233
                                        Loss_G: 3.6549
[15/50] [300/600]
                        Loss_D: 0.6081
                                        Loss_G: 2.1778
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[15/50] [350/600]
                        Loss_D: 0.4454
                                        Loss_G: 1.8431
[15/50] [400/600]
                        Loss_D: 0.7657
                                        Loss_G: 1.4584
[15/50] [450/600]
                        Loss_D: 0.5282
                                        Loss_G: 2.7681
                                        Loss_G: 2.2664
[15/50] [500/600]
                        Loss_D: 0.4853
                        Loss D: 0.5464
[15/50] [550/600]
                                        Loss G: 2.0667
[16/50][0/600] Loss D: 0.3650 Loss G: 2.1825
[16/50][50/600] Loss D: 0.4608 Loss G: 2.6197
[16/50] [100/600]
                        Loss_D: 0.5209 Loss_G: 1.1353
[16/50] [150/600]
                        Loss_D: 0.3581 Loss_G: 2.3860
[16/50] [200/600]
                        Loss_D: 0.5978
                                        Loss_G: 1.8348
[16/50] [250/600]
                        Loss_D: 0.6517
                                        Loss_G: 1.6790
[16/50] [300/600]
                        Loss_D: 0.7297
                                        Loss_G: 0.9317
                        Loss_D: 0.4783
                                        Loss_G: 1.9181
[16/50] [350/600]
[16/50] [400/600]
                        Loss_D: 0.4156
                                        Loss_G: 2.5709
[16/50] [450/600]
                        Loss_D: 0.3198
                                        Loss_G: 2.4515
[16/50] [500/600]
                        Loss_D: 0.4511 Loss_G: 2.7146
[16/50] [550/600]
                        Loss_D: 0.4560
                                        Loss_G: 2.4058
[17/50][0/600] Loss_D: 0.3842 Loss_G: 2.3754
[17/50][50/600] Loss_D: 0.4562 Loss_G: 3.0873
                        Loss D: 1.0836
                                        Loss G: 4.2010
[17/50] [100/600]
[17/50] [150/600]
                        Loss D: 0.6746
                                        Loss G: 2.8064
[17/50] [200/600]
                        Loss D: 0.6271 Loss G: 3.0622
[17/50] [250/600]
                        Loss_D: 0.4099 Loss_G: 2.1811
[17/50] [300/600]
                        Loss_D: 0.4947
                                        Loss_G: 2.7384
                        Loss_D: 0.4168 Loss_G: 3.0599
[17/50] [350/600]
[17/50] [400/600]
                        Loss_D: 0.4412 Loss_G: 2.7751
[17/50] [450/600]
                        Loss_D: 0.5118 Loss_G: 2.4599
[17/50] [500/600]
                        Loss_D: 0.6439
                                        Loss_G: 2.5736
[17/50] [550/600]
                        Loss_D: 0.5484
                                        Loss_G: 2.2172
[18/50] [0/600]
               Loss_D: 0.4781 Loss_G: 2.0604
[18/50][50/600] Loss_D: 0.4487 Loss_G: 2.3756
[18/50] [100/600]
                        Loss_D: 0.4613 Loss_G: 1.8476
[18/50] [150/600]
                        Loss_D: 0.6545
                                        Loss_G: 1.3752
                        Loss_D: 0.3753 Loss_G: 2.5228
[18/50] [200/600]
                        Loss D: 0.8594 Loss G: 3.5642
[18/50] [250/600]
[18/50] [300/600]
                        Loss D: 0.3813
                                        Loss G: 2.6581
[18/50] [350/600]
                        Loss D: 0.4225
                                        Loss G: 2.5186
[18/50] [400/600]
                        Loss_D: 0.4506
                                        Loss_G: 2.5827
[18/50] [450/600]
                        Loss_D: 0.5712
                                        Loss_G: 2.7535
[18/50] [500/600]
                        Loss_D: 0.3870
                                        Loss_G: 2.8117
[18/50] [550/600]
                        Loss_D: 0.5489
                                        Loss_G: 1.3144
[19/50][0/600] Loss_D: 0.3847 Loss_G: 1.5133
[19/50][50/600] Loss_D: 0.4420 Loss_G: 2.0989
[19/50] [100/600]
                        Loss_D: 0.7285
                                        Loss_G: 1.2114
[19/50] [150/600]
                        Loss_D: 0.4386
                                        Loss_G: 2.6242
[19/50] [200/600]
                        Loss_D: 0.4943
                                        Loss_G: 2.2584
[19/50] [250/600]
                        Loss_D: 0.4580
                                         Loss_G: 2.6593
[19/50] [300/600]
                        Loss_D: 0.4468
                                        Loss_G: 2.2591
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[19/50] [350/600]
                        Loss_D: 0.5018
                                        Loss_G: 1.6970
[19/50] [400/600]
                        Loss_D: 0.4474
                                        Loss_G: 1.9971
[19/50] [450/600]
                        Loss_D: 0.7919
                                        Loss_G: 5.4139
                                        Loss_G: 2.9695
[19/50] [500/600]
                        Loss_D: 0.5171
                        Loss D: 0.4902 Loss G: 3.2663
[19/50] [550/600]
[20/50][0/600] Loss D: 0.3468 Loss G: 2.6855
[20/50][50/600] Loss D: 0.4483 Loss G: 2.3953
[20/50] [100/600]
                        Loss_D: 0.3076 Loss_G: 2.5926
[20/50] [150/600]
                        Loss_D: 0.4806 Loss_G: 2.0785
[20/50] [200/600]
                        Loss_D: 0.3695
                                        Loss_G: 2.7140
[20/50] [250/600]
                        Loss_D: 0.6151
                                        Loss_G: 1.9065
[20/50] [300/600]
                        Loss_D: 0.4619 Loss_G: 2.7809
                        Loss_D: 0.4249
[20/50] [350/600]
                                        Loss_G: 2.5803
[20/50] [400/600]
                        Loss_D: 0.9134
                                        Loss_G: 0.9734
[20/50] [450/600]
                        Loss_D: 0.5461
                                        Loss_G: 3.0596
                        Loss_D: 0.3644 Loss_G: 2.7626
[20/50] [500/600]
[20/50] [550/600]
                        Loss_D: 0.4132
                                        Loss_G: 2.0365
[21/50][0/600] Loss_D: 0.3752 Loss_G: 2.3820
[21/50][50/600] Loss D: 0.3490 Loss G: 1.9043
                        Loss D: 0.4020
                                        Loss G: 2.7695
[21/50] [100/600]
[21/50] [150/600]
                        Loss D: 0.6093
                                        Loss G: 1.5078
[21/50] [200/600]
                        Loss D: 0.3587
                                        Loss G: 2.3946
[21/50] [250/600]
                        Loss_D: 0.4425 Loss_G: 1.7601
[21/50] [300/600]
                        Loss_D: 0.4073 Loss_G: 1.9388
                        Loss_D: 0.4610 Loss_G: 2.1884
[21/50] [350/600]
[21/50] [400/600]
                        Loss_D: 0.4678 Loss_G: 2.8628
[21/50] [450/600]
                        Loss_D: 1.1613 Loss_G: 0.5835
[21/50] [500/600]
                        Loss_D: 0.4447
                                        Loss_G: 2.2785
[21/50] [550/600]
                        Loss_D: 0.5107
                                        Loss G: 4.0338
[22/50] [0/600]
               Loss_D: 0.4632 Loss_G: 3.4068
[22/50][50/600] Loss_D: 0.9521 Loss_G: 4.4375
[22/50] [100/600]
                        Loss_D: 0.5719 Loss_G: 1.8787
[22/50] [150/600]
                        Loss_D: 0.4713
                                        Loss_G: 2.8289
                        Loss_D: 0.6529 Loss_G: 2.4574
[22/50] [200/600]
                        Loss D: 0.5635 Loss G: 1.4811
[22/50] [250/600]
[22/50] [300/600]
                        Loss D: 0.6406
                                        Loss G: 3.1498
[22/50] [350/600]
                        Loss D: 0.4578 Loss G: 3.1000
[22/50] [400/600]
                        Loss_D: 0.2703
                                        Loss_G: 2.3436
[22/50] [450/600]
                        Loss_D: 0.4154
                                        Loss_G: 2.3268
[22/50] [500/600]
                        Loss_D: 0.6092
                                        Loss_G: 2.8286
[22/50] [550/600]
                        Loss_D: 0.6320
                                        Loss_G: 1.0916
[23/50][0/600] Loss_D: 0.4400 Loss_G: 3.1943
[23/50][50/600] Loss_D: 0.5092 Loss_G: 1.3804
                        Loss_D: 0.6050
[23/50] [100/600]
                                        Loss_G: 2.3896
[23/50] [150/600]
                        Loss_D: 0.4067
                                        Loss_G: 2.5373
[23/50] [200/600]
                        Loss_D: 0.3574
                                        Loss_G: 2.2258
[23/50] [250/600]
                        Loss_D: 0.4669
                                        Loss_G: 2.1299
[23/50] [300/600]
                        Loss_D: 0.3434
                                        Loss_G: 2.5590
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[23/50] [350/600]
                        Loss_D: 0.4865
                                        Loss_G: 2.6968
[23/50] [400/600]
                        Loss_D: 0.5011
                                        Loss_G: 2.5833
[23/50] [450/600]
                        Loss_D: 0.7573
                                        Loss_G: 1.5433
                        Loss_D: 0.4163
                                        Loss_G: 2.0754
[23/50] [500/600]
                        Loss D: 0.3347
[23/50] [550/600]
                                        Loss G: 3.0486
[24/50][0/600] Loss D: 1.1936 Loss G: 3.6934
[24/50][50/600] Loss D: 0.5378 Loss G: 0.9680
[24/50] [100/600]
                        Loss_D: 0.4388
                                        Loss_G: 2.6490
[24/50] [150/600]
                        Loss D: 0.5724
                                        Loss_G: 2.1959
[24/50] [200/600]
                        Loss_D: 0.4244
                                        Loss_G: 2.1329
[24/50] [250/600]
                        Loss_D: 0.4455 Loss_G: 3.0406
[24/50] [300/600]
                        Loss_D: 0.3321 Loss_G: 2.4134
                        Loss_D: 0.5988
                                        Loss_G: 1.7616
[24/50] [350/600]
[24/50] [400/600]
                        Loss_D: 0.3427
                                        Loss_G: 2.2826
[24/50] [450/600]
                        Loss_D: 0.4813
                                        Loss_G: 2.8834
                        Loss_D: 0.5007
[24/50] [500/600]
                                        Loss_G: 2.4519
[24/50] [550/600]
                        Loss_D: 0.4260
                                        Loss_G: 3.0648
[25/50][0/600] Loss_D: 0.4607 Loss_G: 3.1425
[25/50][50/600] Loss D: 0.2991 Loss G: 2.6936
[25/50] [100/600]
                        Loss D: 0.5063 Loss G: 2.0340
[25/50] [150/600]
                        Loss D: 0.4259
                                        Loss G: 3.1865
[25/50] [200/600]
                        Loss D: 0.3900 Loss G: 2.2875
[25/50] [250/600]
                        Loss_D: 0.3750 Loss_G: 2.2474
[25/50] [300/600]
                        Loss_D: 0.3889 Loss_G: 1.9969
[25/50] [350/600]
                        Loss_D: 0.5852 Loss_G: 3.1533
[25/50] [400/600]
                        Loss_D: 0.3487
                                        Loss_G: 2.3261
[25/50] [450/600]
                        Loss_D: 0.5378 Loss_G: 1.7190
[25/50] [500/600]
                        Loss_D: 0.4487
                                        Loss_G: 2.7538
[25/50] [550/600]
                        Loss_D: 0.3041
                                        Loss G: 3.2458
[26/50] [0/600]
               Loss_D: 0.4503 Loss_G: 2.2842
[26/50][50/600] Loss_D: 0.3489 Loss_G: 2.6564
[26/50] [100/600]
                        Loss_D: 0.6579 Loss_G: 2.8939
[26/50] [150/600]
                        Loss_D: 0.3353
                                        Loss_G: 2.2434
                        Loss_D: 0.4773 Loss_G: 3.1342
[26/50] [200/600]
                        Loss D: 0.3662 Loss G: 2.8379
[26/50] [250/600]
[26/50] [300/600]
                        Loss D: 0.5131
                                        Loss G: 3.4970
[26/50] [350/600]
                        Loss D: 0.3792 Loss G: 2.6981
[26/50] [400/600]
                        Loss_D: 0.4323
                                        Loss_G: 2.5704
[26/50] [450/600]
                        Loss_D: 0.3947
                                        Loss_G: 2.3975
[26/50] [500/600]
                        Loss_D: 0.2977
                                        Loss_G: 3.4269
[26/50] [550/600]
                        Loss_D: 0.5514
                                        Loss_G: 2.5667
[27/50][0/600] Loss_D: 0.6379 Loss_G: 1.1618
[27/50][50/600] Loss_D: 0.6599 Loss_G: 3.7506
                        Loss_D: 0.4977
[27/50] [100/600]
                                        Loss_G: 1.8961
[27/50] [150/600]
                        Loss_D: 0.1920
                                        Loss_G: 3.8254
[27/50] [200/600]
                        Loss_D: 0.6461
                                        Loss_G: 3.0744
[27/50] [250/600]
                        Loss_D: 0.4106
                                        Loss_G: 2.4324
[27/50] [300/600]
                        Loss_D: 0.4349
                                        Loss_G: 1.9785
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[27/50] [350/600]
                        Loss_D: 0.4464
                                        Loss_G: 2.2109
[27/50] [400/600]
                        Loss_D: 0.5049
                                        Loss_G: 2.7734
[27/50] [450/600]
                        Loss_D: 0.6087
                                        Loss_G: 1.1244
                        Loss_D: 0.4084
                                        Loss_G: 1.7516
[27/50] [500/600]
                        Loss D: 0.5655
[27/50] [550/600]
                                        Loss G: 2.4316
[28/50][0/600] Loss D: 0.3783 Loss G: 2.8445
[28/50][50/600] Loss D: 0.5295 Loss G: 3.6603
[28/50] [100/600]
                        Loss_D: 0.4289
                                        Loss_G: 1.7051
[28/50] [150/600]
                        Loss_D: 0.5941 Loss_G: 1.5720
[28/50] [200/600]
                        Loss_D: 0.4873
                                        Loss_G: 2.4065
[28/50] [250/600]
                        Loss_D: 0.3905 Loss_G: 2.7666
[28/50] [300/600]
                        Loss_D: 0.3130 Loss_G: 3.4284
                        Loss_D: 0.4086
                                        Loss_G: 2.4225
[28/50] [350/600]
[28/50] [400/600]
                        Loss_D: 0.5132 Loss_G: 1.6603
[28/50] [450/600]
                        Loss_D: 0.3748
                                        Loss_G: 3.0326
                        Loss_D: 0.5273 Loss_G: 3.4994
[28/50] [500/600]
[28/50] [550/600]
                        Loss_D: 0.4206
                                        Loss_G: 1.7373
[29/50][0/600] Loss_D: 0.3478 Loss_G: 3.4001
[29/50][50/600] Loss D: 0.5086 Loss G: 3.8521
[29/50] [100/600]
                        Loss D: 0.5763
                                        Loss G: 2.9643
                        Loss D: 0.9782
[29/50] [150/600]
                                        Loss G: 1.3463
[29/50] [200/600]
                        Loss D: 0.2830
                                        Loss G: 3.0713
[29/50] [250/600]
                        Loss_D: 0.3920 Loss_G: 3.0967
[29/50] [300/600]
                        Loss D: 0.3733 Loss G: 2.6111
[29/50] [350/600]
                        Loss_D: 0.4270 Loss_G: 2.9006
[29/50] [400/600]
                        Loss_D: 0.4295 Loss_G: 3.3327
[29/50] [450/600]
                        Loss_D: 0.5538 Loss_G: 3.8329
[29/50] [500/600]
                        Loss_D: 0.4733 Loss_G: 2.9616
[29/50] [550/600]
                        Loss_D: 0.3111
                                        Loss G: 2.9044
[30/50] [0/600]
               Loss_D: 0.4345 Loss_G: 2.0259
[30/50][50/600] Loss_D: 0.6200 Loss_G: 3.9743
[30/50] [100/600]
                        Loss_D: 0.4313 Loss_G: 3.2020
[30/50] [150/600]
                        Loss_D: 0.3279
                                        Loss_G: 3.0166
                        Loss_D: 0.3512 Loss_G: 3.5357
[30/50] [200/600]
                        Loss D: 0.5063 Loss G: 2.4043
[30/50] [250/600]
[30/50] [300/600]
                        Loss D: 0.5311
                                        Loss G: 1.3589
[30/50] [350/600]
                        Loss D: 0.4467
                                        Loss G: 3.5378
[30/50] [400/600]
                        Loss_D: 0.4281
                                        Loss_G: 1.9756
[30/50] [450/600]
                        Loss_D: 0.4603 Loss_G: 4.0650
[30/50] [500/600]
                        Loss_D: 0.3081
                                        Loss_G: 3.1654
[30/50] [550/600]
                        Loss_D: 0.5886 Loss_G: 1.0939
[31/50][0/600] Loss_D: 0.8689 Loss_G: 4.5905
[31/50][50/600] Loss_D: 0.3414 Loss_G: 3.1185
[31/50] [100/600]
                        Loss_D: 0.2474
                                        Loss_G: 3.6269
[31/50] [150/600]
                        Loss_D: 0.3096
                                        Loss_G: 2.9890
[31/50] [200/600]
                        Loss_D: 0.3116
                                        Loss_G: 2.0922
[31/50] [250/600]
                        Loss_D: 0.5200
                                        Loss_G: 3.3630
[31/50] [300/600]
                        Loss_D: 0.3644
                                        Loss_G: 2.8833
```

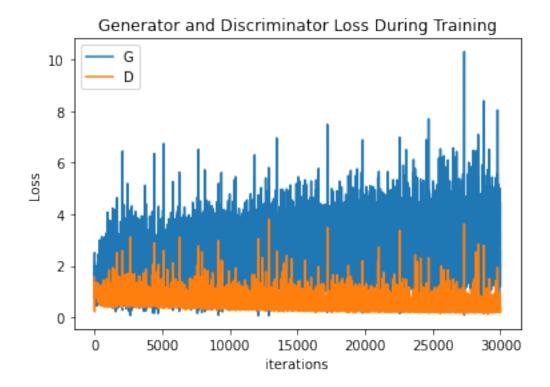
```
[31/50] [350/600]
                        Loss_D: 1.6041
                                        Loss_G: 4.9094
                        Loss_D: 0.3132    Loss_G: 2.9788
[31/50] [400/600]
[31/50] [450/600]
                        Loss_D: 0.3865
                                        Loss_G: 2.5429
                        Loss_D: 0.4075
                                        Loss_G: 2.4534
[31/50] [500/600]
                        Loss D: 0.5046
[31/50] [550/600]
                                        Loss G: 3.5429
[32/50][0/600] Loss D: 0.2764 Loss G: 2.5847
[32/50][50/600] Loss D: 0.2628 Loss G: 2.8947
[32/50] [100/600]
                        Loss_D: 0.3731 Loss_G: 2.0577
[32/50] [150/600]
                        Loss_D: 0.3320 Loss_G: 2.7404
[32/50] [200/600]
                        Loss_D: 1.0678 Loss_G: 1.3551
[32/50] [250/600]
                        Loss_D: 0.3645
                                        Loss_G: 3.4444
[32/50] [300/600]
                        Loss_D: 0.2835 Loss_G: 3.0432
                        Loss_D: 0.2536
                                        Loss_G: 2.4499
[32/50] [350/600]
[32/50] [400/600]
                        Loss_D: 0.3275
                                        Loss_G: 2.7927
[32/50] [450/600]
                        Loss_D: 1.0435
                                        Loss_G: 0.7323
                        Loss_D: 0.3904 Loss_G: 2.7155
[32/50] [500/600]
[32/50] [550/600]
                        Loss_D: 0.3482
                                        Loss_G: 2.6860
[33/50][0/600] Loss_D: 0.3934 Loss_G: 3.0200
[33/50][50/600] Loss_D: 0.4311 Loss_G: 2.4619
[33/50] [100/600]
                        Loss D: 0.4472 Loss G: 3.2822
[33/50] [150/600]
                        Loss D: 0.6425
                                        Loss G: 1.4607
[33/50] [200/600]
                        Loss D: 0.4673 Loss G: 2.0442
[33/50] [250/600]
                        Loss_D: 0.6093 Loss_G: 3.3594
[33/50] [300/600]
                        Loss_D: 0.3678 Loss_G: 2.3336
[33/50] [350/600]
                        Loss_D: 0.4184 Loss_G: 1.7541
[33/50] [400/600]
                        Loss_D: 0.3495 Loss_G: 2.5977
[33/50] [450/600]
                        Loss_D: 0.7288 Loss_G: 1.6039
[33/50] [500/600]
                        Loss_D: 0.2965
                                        Loss_G: 2.7350
[33/50] [550/600]
                        Loss_D: 0.4555
                                        Loss G: 1.4545
[34/50] [0/600]
               Loss_D: 0.3652 Loss_G: 2.6418
[34/50][50/600] Loss_D: 0.8202 Loss_G: 1.6545
[34/50] [100/600]
                        Loss_D: 0.2907 Loss_G: 3.0217
[34/50] [150/600]
                        Loss_D: 0.5128
                                        Loss_G: 3.0366
                        Loss_D: 0.3619 Loss_G: 2.8879
[34/50] [200/600]
                        Loss D: 0.3836 Loss G: 3.0205
[34/50] [250/600]
[34/50] [300/600]
                        Loss D: 0.3622
                                        Loss G: 2.3906
[34/50] [350/600]
                        Loss D: 0.2583 Loss G: 3.2764
[34/50] [400/600]
                        Loss_D: 0.3155
                                        Loss_G: 2.9346
[34/50] [450/600]
                        Loss_D: 0.4238
                                        Loss_G: 2.5269
[34/50] [500/600]
                        Loss_D: 0.4223
                                        Loss_G: 3.0099
[34/50] [550/600]
                        Loss_D: 0.5615
                                        Loss_G: 3.7028
[35/50][0/600] Loss_D: 0.4051 Loss_G: 2.3831
[35/50][50/600] Loss_D: 0.3993 Loss_G: 1.9620
[35/50] [100/600]
                        Loss_D: 0.3837
                                        Loss_G: 2.8485
[35/50] [150/600]
                        Loss_D: 0.5369
                                        Loss_G: 1.1946
[35/50] [200/600]
                        Loss_D: 0.5355
                                        Loss_G: 4.3950
[35/50] [250/600]
                        Loss_D: 0.2782
                                        Loss_G: 3.1907
[35/50] [300/600]
                        Loss_D: 0.4606
                                        Loss_G: 3.6238
```

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[35/50] [350/600]
                        Loss_D: 0.4234
                                        Loss_G: 1.9958
[35/50] [400/600]
                        Loss_D: 0.3367
                                        Loss_G: 3.1958
[35/50] [450/600]
                        Loss_D: 0.3010
                                        Loss_G: 2.8204
                        Loss_D: 0.7831
                                        Loss_G: 1.2004
[35/50] [500/600]
                        Loss D: 0.3775
[35/50] [550/600]
                                        Loss G: 2.8842
[36/50][0/600] Loss D: 0.6196 Loss G: 3.0022
[36/50][50/600] Loss D: 0.4513 Loss G: 3.4217
[36/50] [100/600]
                        Loss_D: 0.3493 Loss_G: 2.7002
[36/50] [150/600]
                        Loss_D: 0.2066 Loss_G: 2.9066
[36/50] [200/600]
                        Loss_D: 0.3736 Loss_G: 2.8409
[36/50] [250/600]
                        Loss_D: 0.4067
                                        Loss_G: 2.0511
[36/50] [300/600]
                        Loss_D: 0.3782 Loss_G: 3.6178
                        Loss_D: 0.4185
                                        Loss_G: 2.5789
[36/50] [350/600]
[36/50] [400/600]
                        Loss_D: 0.2481
                                        Loss_G: 3.1238
[36/50] [450/600]
                        Loss_D: 0.3644
                                        Loss_G: 3.7502
                        Loss_D: 0.5213 Loss_G: 2.7446
[36/50] [500/600]
[36/50] [550/600]
                        Loss_D: 0.4592
                                        Loss_G: 2.2412
[37/50][0/600] Loss_D: 0.4160 Loss_G: 2.1919
[37/50][50/600] Loss_D: 0.4353 Loss_G: 2.3490
[37/50] [100/600]
                        Loss D: 0.4088 Loss G: 1.6267
                                        Loss G: 2.2698
[37/50] [150/600]
                        Loss D: 0.3623
[37/50] [200/600]
                        Loss D: 0.3693 Loss G: 2.3021
[37/50] [250/600]
                        Loss_D: 0.5287 Loss_G: 1.3885
[37/50] [300/600]
                        Loss_D: 0.3488 Loss_G: 3.1347
[37/50] [350/600]
                        Loss_D: 0.3630 Loss_G: 2.8821
[37/50] [400/600]
                        Loss_D: 0.3213 Loss_G: 2.8725
[37/50] [450/600]
                        Loss_D: 0.3983 Loss_G: 1.9511
[37/50] [500/600]
                        Loss_D: 0.5234
                                        Loss_G: 1.6110
[37/50] [550/600]
                        Loss_D: 0.8884
                                        Loss G: 4.2840
[38/50] [0/600]
               Loss_D: 0.3729 Loss_G: 3.1187
[38/50][50/600] Loss_D: 0.4320 Loss_G: 2.7468
[38/50] [100/600]
                        Loss_D: 0.3374 Loss_G: 2.7341
[38/50] [150/600]
                        Loss_D: 0.3782 Loss_G: 2.5960
                        Loss_D: 0.3604 Loss_G: 3.3073
[38/50] [200/600]
                        Loss D: 0.4785 Loss G: 3.3855
[38/50] [250/600]
[38/50] [300/600]
                        Loss D: 0.4315
                                        Loss G: 4.0737
[38/50] [350/600]
                        Loss D: 0.6209
                                        Loss G: 2.3096
[38/50] [400/600]
                        Loss_D: 0.3882
                                        Loss_G: 2.9599
[38/50] [450/600]
                        Loss_D: 0.5241
                                        Loss_G: 1.6130
[38/50] [500/600]
                        Loss_D: 0.5954
                                        Loss_G: 3.6850
[38/50] [550/600]
                        Loss_D: 0.3635
                                        Loss_G: 3.2555
[39/50][0/600] Loss_D: 0.4620 Loss_G: 1.8979
[39/50][50/600] Loss_D: 0.3697 Loss_G: 2.6793
[39/50] [100/600]
                        Loss_D: 0.2963
                                        Loss_G: 2.5822
[39/50] [150/600]
                        Loss_D: 0.3988
                                        Loss_G: 2.6256
[39/50] [200/600]
                        Loss_D: 0.3062
                                        Loss_G: 2.2848
[39/50] [250/600]
                        Loss_D: 0.5799
                                        Loss_G: 1.6071
[39/50] [300/600]
                        Loss_D: 0.5138
                                        Loss_G: 3.1001
```

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[39/50] [350/600]
                        Loss_D: 0.4303
                                        Loss_G: 3.3637
[39/50] [400/600]
                        Loss_D: 1.2605
                                        Loss_G: 0.7932
[39/50] [450/600]
                        Loss_D: 0.3828
                                        Loss_G: 2.3003
                                        Loss_G: 1.8306
[39/50] [500/600]
                        Loss_D: 0.3983
                        Loss D: 0.2377
[39/50] [550/600]
                                        Loss G: 3.4827
[40/50][0/600] Loss D: 0.3497 Loss G: 2.9943
[40/50][50/600] Loss D: 0.3828 Loss G: 3.0228
[40/50] [100/600]
                        Loss_D: 0.4290 Loss_G: 3.4715
[40/50] [150/600]
                        Loss D: 0.6010
                                        Loss G: 0.8889
[40/50] [200/600]
                        Loss_D: 0.3811
                                        Loss_G: 3.1070
[40/50] [250/600]
                        Loss_D: 0.3665
                                        Loss_G: 2.4469
[40/50] [300/600]
                        Loss_D: 0.2657
                                        Loss_G: 2.9776
                        Loss_D: 0.3270
                                        Loss_G: 2.2996
[40/50] [350/600]
[40/50] [400/600]
                        Loss_D: 0.3180
                                        Loss_G: 2.8596
[40/50] [450/600]
                        Loss_D: 0.3360
                                        Loss_G: 1.9991
                        Loss_D: 0.4300 Loss_G: 4.0851
[40/50] [500/600]
[40/50] [550/600]
                        Loss_D: 0.4734
                                        Loss_G: 3.9404
[41/50][0/600] Loss_D: 0.3528 Loss_G: 3.4866
[41/50][50/600] Loss_D: 0.3737 Loss_G: 3.0201
[41/50] [100/600]
                        Loss D: 0.7469
                                        Loss G: 3.5014
[41/50] [150/600]
                        Loss D: 0.6690
                                        Loss G: 3.5134
[41/50] [200/600]
                        Loss D: 0.2876
                                        Loss G: 2.8294
[41/50] [250/600]
                        Loss_D: 0.4412 Loss_G: 3.8998
[41/50] [300/600]
                        Loss_D: 0.3474 Loss_G: 4.0863
[41/50] [350/600]
                                        Loss_G: 2.6298
                        Loss_D: 0.4137
[41/50] [400/600]
                        Loss_D: 0.3332 Loss_G: 2.3180
[41/50] [450/600]
                        Loss_D: 0.7884 Loss_G: 1.3356
[41/50] [500/600]
                        Loss_D: 0.4272 Loss_G: 1.8199
[41/50] [550/600]
                        Loss_D: 0.3224
                                        Loss_G: 2.4811
[42/50] [0/600]
               Loss_D: 0.5255 Loss_G: 3.1990
[42/50][50/600] Loss_D: 0.5070 Loss_G: 3.5041
[42/50] [100/600]
                        Loss_D: 0.3403 Loss_G: 2.4938
[42/50] [150/600]
                        Loss_D: 0.3783
                                        Loss_G: 4.6584
                        Loss D: 0.3537
                                        Loss_G: 3.4901
[42/50] [200/600]
                        Loss D: 0.4538 Loss G: 1.5073
[42/50] [250/600]
                        Loss_D: 0.2776
[42/50] [300/600]
                                        Loss G: 3.0560
[42/50] [350/600]
                        Loss D: 0.2829
                                        Loss G: 2.2972
[42/50] [400/600]
                        Loss_D: 0.4503
                                        Loss_G: 2.8642
[42/50] [450/600]
                        Loss_D: 0.4558
                                        Loss_G: 3.5721
[42/50] [500/600]
                        Loss_D: 0.4410
                                        Loss_G: 2.9038
[42/50] [550/600]
                        Loss_D: 0.7229
                                        Loss_G: 4.7295
[43/50][0/600] Loss_D: 0.3984 Loss_G: 4.6831
[43/50][50/600] Loss_D: 0.3118 Loss_G: 2.6163
[43/50] [100/600]
                        Loss_D: 0.6643
                                        Loss_G: 2.5711
[43/50] [150/600]
                        Loss_D: 0.2515
                                        Loss_G: 3.7695
[43/50] [200/600]
                        Loss_D: 0.3989
                                        Loss_G: 2.9739
[43/50] [250/600]
                        Loss_D: 0.3593
                                        Loss_G: 1.9063
[43/50] [300/600]
                        Loss_D: 0.4481
                                        Loss_G: 1.9534
```

```
[43/50] [350/600]
                        Loss_D: 0.4579
                                        Loss_G: 2.3176
[43/50] [400/600]
                        Loss_D: 0.5154
                                        Loss_G: 3.3844
[43/50] [450/600]
                        Loss_D: 0.4674
                                        Loss_G: 3.8261
                                        Loss_G: 2.4485
[43/50] [500/600]
                        Loss_D: 0.2979
[43/50] [550/600]
                        Loss D: 0.5502 Loss G: 3.7772
[44/50][0/600] Loss D: 0.2417 Loss G: 2.7986
[44/50][50/600] Loss D: 0.3715 Loss G: 2.4556
[44/50] [100/600]
                        Loss_D: 0.4538 Loss_G: 3.3152
[44/50] [150/600]
                        Loss D: 0.7957
                                        Loss_G: 1.4152
[44/50] [200/600]
                        Loss_D: 0.3138
                                        Loss_G: 3.5790
[44/50] [250/600]
                        Loss_D: 0.3789
                                        Loss_G: 2.4691
[44/50] [300/600]
                        Loss_D: 0.3978 Loss_G: 1.8773
                        Loss_D: 0.3948
[44/50] [350/600]
                                        Loss_G: 2.3810
[44/50] [400/600]
                        Loss_D: 0.4049
                                        Loss_G: 2.3045
[44/50] [450/600]
                        Loss_D: 0.2649
                                        Loss_G: 2.2568
                        Loss_D: 0.3354 Loss_G: 3.4026
[44/50] [500/600]
[44/50] [550/600]
                        Loss_D: 0.4050
                                        Loss_G: 3.3628
[45/50][0/600] Loss_D: 0.2532 Loss_G: 2.7829
[45/50][50/600] Loss_D: 0.3550 Loss_G: 3.5631
[45/50] [100/600]
                        Loss D: 0.3185
                                        Loss G: 3.4133
[45/50] [150/600]
                        Loss D: 0.3679
                                        Loss G: 3.7935
[45/50] [200/600]
                        Loss D: 0.3040
                                        Loss G: 3.0477
[45/50] [250/600]
                        Loss_D: 0.3765 Loss_G: 2.8988
[45/50] [300/600]
                        Loss_D: 0.3360 Loss_G: 2.3916
                        Loss_D: 0.3614 Loss_G: 3.0630
[45/50] [350/600]
[45/50] [400/600]
                        Loss_D: 0.3288
                                        Loss_G: 2.9440
[45/50] [450/600]
                        Loss_D: 0.5104 Loss_G: 3.6972
[45/50] [500/600]
                        Loss_D: 0.3421
                                        Loss_G: 3.8595
[45/50] [550/600]
                        Loss_D: 0.4026
                                        Loss G: 1.8263
[46/50] [0/600]
               Loss_D: 0.2482 Loss_G: 3.3445
[46/50][50/600] Loss_D: 0.5996 Loss_G: 4.2720
[46/50] [100/600]
                        Loss_D: 0.2575 Loss_G: 3.1200
[46/50] [150/600]
                        Loss_D: 0.4688
                                        Loss_G: 1.6901
                        Loss_D: 0.3923 Loss_G: 2.2267
[46/50] [200/600]
                        Loss D: 0.5835 Loss G: 1.7922
[46/50] [250/600]
[46/50] [300/600]
                        Loss D: 0.8190
                                        Loss G: 1.2642
[46/50] [350/600]
                        Loss D: 0.4624 Loss G: 3.8113
[46/50] [400/600]
                        Loss_D: 0.6133
                                        Loss_G: 2.4126
[46/50] [450/600]
                        Loss_D: 0.5923
                                        Loss_G: 1.6736
[46/50] [500/600]
                        Loss_D: 0.4448
                                        Loss_G: 1.6860
[46/50] [550/600]
                        Loss_D: 0.2382
                                        Loss_G: 3.9120
[47/50][0/600] Loss_D: 0.4586 Loss_G: 3.8590
[47/50][50/600] Loss_D: 0.4774 Loss_G: 2.8442
[47/50] [100/600]
                        Loss_D: 0.3341
                                        Loss_G: 3.4906
[47/50] [150/600]
                        Loss_D: 0.2103
                                        Loss_G: 3.3713
[47/50] [200/600]
                        Loss_D: 0.3644
                                        Loss_G: 2.3649
[47/50] [250/600]
                        Loss_D: 0.4324
                                        Loss_G: 1.9970
[47/50] [300/600]
                        Loss_D: 0.7659
                                        Loss_G: 1.6945
```

```
[47/50] [350/600]
                        Loss_D: 0.2646
                                        Loss_G: 2.9827
[47/50] [400/600]
                        Loss_D: 0.3491 Loss_G: 3.5705
[47/50] [450/600]
                        Loss_D: 0.4345
                                        Loss_G: 4.0074
[47/50] [500/600]
                        Loss_D: 0.3407
                                        Loss_G: 2.9295
                        Loss D: 0.4654
                                       Loss G: 1.8896
[47/50] [550/600]
[48/50][0/600] Loss D: 0.4462 Loss G: 2.5714
[48/50][50/600] Loss D: 0.3556 Loss G: 2.9966
                        Loss_D: 0.2191 Loss_G: 2.7932
[48/50] [100/600]
                        Loss D: 0.2010
                                        Loss_G: 3.1783
[48/50] [150/600]
[48/50] [200/600]
                        Loss_D: 0.3863
                                        Loss_G: 2.4399
                                        Loss_G: 2.5135
[48/50] [250/600]
                        Loss_D: 0.3241
                        Loss_D: 0.3415 Loss_G: 1.8424
[48/50] [300/600]
[48/50] [350/600]
                        Loss_D: 0.4284 Loss_G: 3.5664
                        Loss_D: 0.1710
                                        Loss_G: 3.7601
[48/50] [400/600]
[48/50] [450/600]
                        Loss_D: 0.3622
                                        Loss_G: 3.2441
[48/50] [500/600]
                        Loss_D: 0.7117
                                        Loss_G: 1.2641
[48/50] [550/600]
                        Loss_D: 0.4622
                                        Loss_G: 2.4253
[49/50][0/600] Loss_D: 0.8841 Loss_G: 5.4495
[49/50][50/600] Loss_D: 0.5757 Loss_G: 1.9121
[49/50] [100/600]
                        Loss D: 0.3230
                                        Loss G: 2.2311
                        Loss D: 0.5445
[49/50] [150/600]
                                        Loss G: 2.5606
                        Loss D: 0.5118
                                        Loss G: 1.9560
[49/50] [200/600]
[49/50] [250/600]
                        Loss_D: 0.2729
                                        Loss_G: 2.8002
                        Loss D: 0.5223
                                        Loss_G: 4.3253
[49/50] [300/600]
[49/50] [350/600]
                        Loss_D: 0.2614 Loss_G: 3.1697
                        Loss_D: 1.7870
[49/50] [400/600]
                                        Loss_G: 0.4338
[49/50] [450/600]
                        Loss_D: 0.2505
                                        Loss_G: 2.7221
                                        Loss_G: 2.6830
[49/50] [500/600]
                        Loss_D: 0.2571
[49/50] [550/600]
                        Loss_D: 0.3396
                                        Loss_G: 3.8744
```



0.5 Qualitative Visualisations

[6]: <IPython.core.display.HTML object>

