#### **Initial Settings Upon Power Up**

1 RA/DEC: 000000/00000

2 Telescope Side: West

3 Handbox: Direction keys operational

4 RA/DEC Correction Speeds: 90%/90%

5 Tracking: Northern Hemisphere

Note: Tracking is reversed by holding the [S1] key while turning on power.

#### **Command**

All commands to the mount end with a [CR] [LF].

All replies from the mount end with a [CR] [LF].

The delay time to process a command varies, but if you allow 1/4 second that should allow enough time for all commands.

Nothing is kept in memory. Latitude & LST must be set each time mount is powered up. If these are not set the "Get" commands return garbage.

#### **Set Local Sidereal Time**

Τ	9	9	9	9	9	9				
							-			
					Sec	onds	s (0 - 59)			
			Minutes (0 - 59)							
	Hours (0 - 23)									

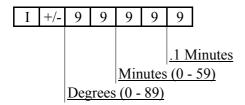
#### **Get Local Sidereal Time**



Reply Structure:

g	9	9	9	9	9	9				
							•			
					Sec	onds	s(0-59)			
			Mir	utes	(0 -	59)				
	Hours (0 - 23)									

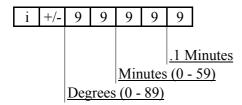
## **Set Latitude**



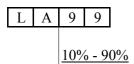
# **Get Latitude**

i

Reply structure:



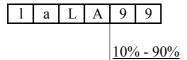
## **Set RA Correction Speed**



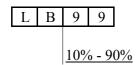
# **Get RA Correction Speed**

1 a Note: This is a lower case "L"

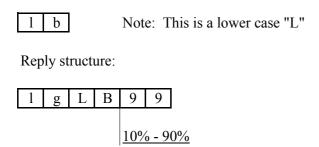
Reply structure:



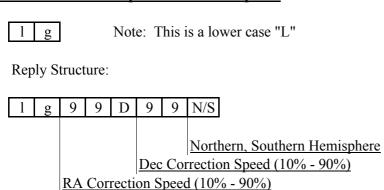
#### **Set DEC Correction Speed**



#### **Get Dec Correction Speed**



### **Get Both Correction Speeds With Hemisphere**



#### **Set Comet Tracking**

L	M	+/-	9	9	9	9	9	,	+/-	9	9	9	9
									Deg	ree-	Min	utes	Per Day
		Adjust Sidereal time by seconds per Day											

### Example:

LM+120,+30 would slow the RA speed by 86164/86284 and the Dec would track at 30 minutes a day.

To stop tracking either send a LM0,0 or a PS.

## **Get Comet Speed**

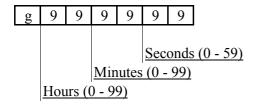
l m Note: This is a lower case "L" Reply Structure: m L M +/-9 9 9 9 9 9 9 9 9 +/-Dec Speed Adjustment RA Speed Adjustment

Note: RA Speed adjustment is how many RA seconds are added/subtracted per 24 hour period, DEC adjustment is how many degrees per 24 hour period.

#### **Get Local Sidereal Time**

g

Reply Structure:



#### **Get Automatic Introduction Motions??? Setting Error???**

S

Reply Structure:

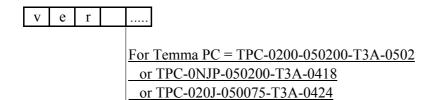
s 9

0 or 1. I have no idea what this stands for. It seems to always be 0.

## **Get Version**



Reply Structure:



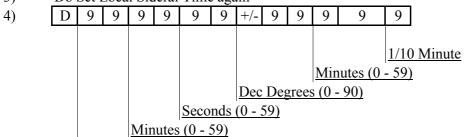
# **Do Slew**



Bit:	Value = 0	Value = 1
1	Low Speed	High Speed
2		RA Right
3		RA Left
4		DEC Up
5		DEC Down
6	Encoder On	Encoder Off
7		Always 1
8	Always 0	

## **Set Location**

- 1) Do Set Local Sidereal Time
- 2) Z
- 3) Do Set Local Sideral Time again



# RA Hours (0 - 23)

Reply Structure:

R \*

1 = Ok

2 = RA Error

3 = Dec Error

4 = Too many digits

## **Get Current Location**

Е

Reply structure:

Е	9	9	9	9	9	9	+/-	9	9	9	9	9	E/W/F	Н
										Min	utes	<u>1/10</u>	$E/W = \frac{F - Aut}{Minute}$	H = Handbox (operational?) Side of mount telescope is on tomatic introduction complete? e (some models only even allowed)
								Deg	grees	(0 -	89)			
							DEC	<u> </u> + =	= Ea	st, - :	= W	est,	space] v	$\underline{\text{when Dec} = 00000}$
					Sec	onds	s (0 - :	<u>59)</u>						
			Mir	utes	s (0 <b>-</b>	59)								
	RA	Ηου	ır (0	- 23	)									

Note: After automatic introduction the E/W/F byte will read "F" for the first four readings. After that it will read E/W.

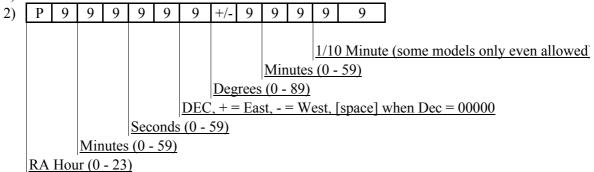
## Switch Side Of Mount (E/W)

PT

Note: Side of mount that telescope is on.

### **Goto**

1) Do a Set Local Sidereal Time



Reply Structure:



1 = Ok

2 = RA Error

3 = Dec Error

4 = Too many digits

#### **Stop GOTO**

P S

To confirm us "S" command, S0 = canceled, S1 = send again.

## **Set Hemisphere Tracking**

Determined by Latitude

#### **Set Solar Rate**

L K

#### **Set Stellar Rate**

L L

Set 12V Power

v 1

Set 24V Power

v 2