

Assignment 3

Machine Learning COMS 4771

Spring 2017, Itsik Pe'er

Assigned: Feb 16th

Due: Wednesday, March 1st, class time

Submission: Courseworks.

- 1) Create a simulator python class `SimClasses` for data that is drawn from two D-dimensional circular Gaussians with prescribed distance. Include a method `[X,Y] = GetData(N, D, Distance)` that produces N points X (numpy matrix), whose category assignments are fair coin-flips Y (numpy array), where the Heads category is drawn from a standard normal distribution, and the Tails category is drawn from an equal-covariance distribution whose mean is `Distance` standard deviations away along the first coordinate in the positive direction.

Create python classes `Classifier_A`, `Classifier_B`, `Classifier_C`, `Classifier_D` that are each constructed from training data (inputs X and outputs Y), and offer a method `Classify` on test inputs, returning predicted output. Classifiers should respectively :

- A. use `sklearn`'s `LogisticRegression`
- B. use `sklearn`'s `Perceptron`
- C. use `sklearn`'s linear `svm`
- D. explicitly implement one of the three methods above of your choice, on your own with explicit matrix operations (you may use a QP-solver for SVM).

Measure and report (i) accuracy on 100 points of test data and (ii) training compute times:

- a) For fixed N and fixed `Distance`, increasing (5 values of) D
- b) For fixed D and fixed `Distance`, increasing (5 values of) N
- c) For fixed D a fixed N, increasing (5 values of) `Distance`

Report your results in a Pickled dictionary

`Results[measurement][method][item][value]`

Where `measurement` is 'i' or 'ii' , `method` is 'A'...'D' , `item` is 'a'...'c' , and `value` is the increasing value. Further save a dictionary `Parameters`

Further each of (i)/(ii) and a/b/c in a plot `Plot_[measurement]_[item].pdf` (with lines corresponding to A-D). The entire process would be run by a function `TestClassifiers`

This question leaves unspecified details for you to deal with: Primal QP or dual QP? 0/1 or -1/+1 classes? How to deal with unseparable data? How to fix the fixed values? This is deliberate and is part of the assignment. Exercise your best judgment and explain your thinking.

[100pts]

- 2) Define $F: \mathbf{R}^{+^D} \rightarrow \mathbf{R}$ as $(\vec{x}) = \sum_{d=1}^D d \log x(d)$.
- Use Lagrange multipliers to find its maximum s.t. the sum of the coordinates is a constant C .
 - Use KKT multipliers to find its maximum within the unit sphere.
- [20 points]
- 3) Consider the quadratic program $\max_{\vec{x}} (\vec{x}^T H \vec{x} + \vec{b}^T \vec{x})$ s.t. $\forall i = 1, \dots, N : \vec{C}_i^T \vec{x} \leq a_i$ in \mathbf{R}^D for symmetric H . Give examples (explicit values for $H, \vec{b}, \{\vec{C}_i^T\}$, and $\{a_i\}$) of:
- No solution at all
 - No finite solution because the maximization includes values that go to infinity
 - A single solution
 - A continuum of solutions
- [20 points]
- 4) You can represent hyperplanes in \mathbf{R}^D by D -dimensional vectors of coefficients. Each such nonzero vector $\vec{\theta}$ can represent the hyperplane $\{\vec{x} | \vec{\theta}^T \vec{x} = 1\}$, or $\vec{\theta}^T \vec{x} = 1$ for short. Consider a family of hyperplanes $\vec{\theta}^j{}^T \vec{x} = 1$ for $j = 1, \dots, N$. Each hyperplane splits the space in two, with only one half-space not containing the origin of axis. Suppose a point \vec{x}_0 is in the intersection of these half-spaces that don't contain the origin of axes.
- Consider a dual space where you treat each vector $\vec{\theta}^j$ as a point. In this space \vec{x}_0 defines a hyperplane through the equation $\vec{x}_0^T \vec{\theta} = 1$.
- What do you know about the points $\vec{\theta}^j$ in the dual space? Prove your claim
- [25 points]
- 5) Develop gradient descent for Poisson regression, that assumes a log-linear relation to the input: $y_i \sim \text{Poisson}(\lambda_i = e^{\theta x_i})$. Specifically, define likelihood-based loss and risk, derive update equations for gradient descent and prove convergence.
- [25 points]

Good luck!