

Assignment -4

Assignment Date	27-October 2022
Team ID	PNT2022TMID30440
Project Name	Smart Farmer-IOT Enabled Smart Farming Application
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QUESTION:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events. Upload document with wokwi share link and images of ibm cloud.

CODE:

```
#include <WiFi.h>
#include <PubSubClient.h>
#include <ArduinoJson.h>

WiFiClient wifiClient;
#define ORG "fvdupc"

#define DEVICE_TYPE "abcd"
#define DEVICE_ID "rasp"
#define TOKEN "12345678"
#define speed 0.034

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/abcd_1/fmt/json"; char topic[]
= "iot-2/cmd/home/fmt/String"; char authMethod[] = "use-token-
auth"; char token[] = TOKEN; char clientId[] = "d:" ORG ":"
DEVICE_TYPE ":" DEVICE_ID; PubSubClient client(server, 1883,
wifiClient); void publishData();
const int trigpin=5;
const int echopin=18;
String command;
String data="";
String lat="14.167589";
String lon="80.248510";
String name="point2";
String
icon=""; long
duration; int
dist;
```

```

void setup()
{
    Serial.begin(115200);
    pinMode(trigpin, OUTPUT);
    pinMode(echopin, INPUT);
    wifiConnect();
    mqttConnect();
}
void loop()
{
    publishData();
    delay(500);
    if (!client.loop())
        {mqttConnect();
        }
}
void wifiConnect()
{
    Serial.print("Connecting to ");
    Serial.print("Wifi"); WiFi.begin("Wokwi-GUEST", "",
6); while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
}
    Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
}

void mqttConnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting MQTT client to ");
        Serial.println(server); while (!client.connect(clientId, authMethod,
token)) { Serial.print("."); delay(1000);
        }
        initManagedDevice();
        Serial.println();
    }
}
void initManagedDevice()
{
    if (client.subscribe(topic))
        { Serial.println(client.subscribe(topic));
        Serial.println("subscribe to cmd OK");
        } else {
        Serial.println("subscribe to cmd FAILED");
        } }
void publishData()
{ digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10);
}

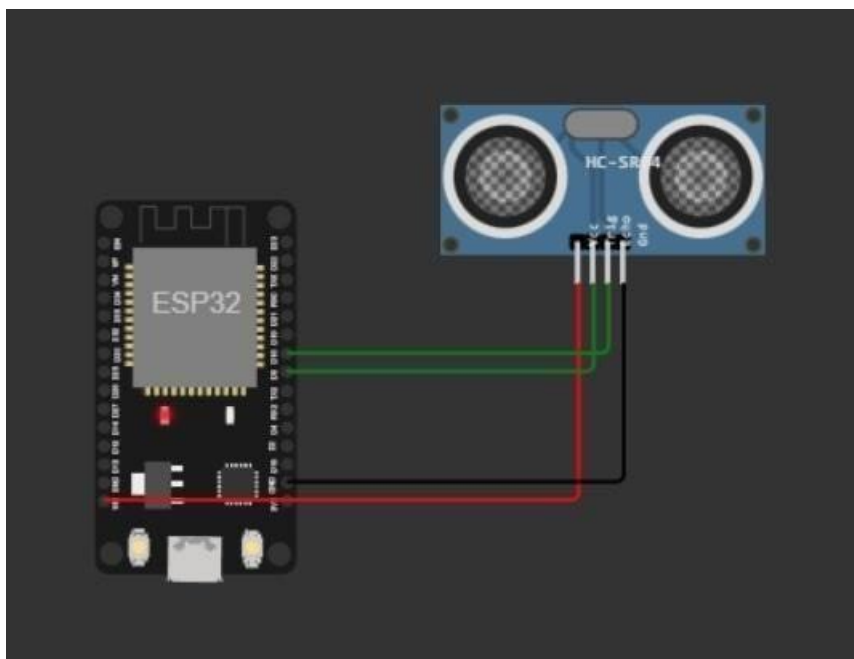
```

```

digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){
    dist=100-dist; icon="fa-
    trash";
}else{ dist=0;
    icon="fa-trash-
    o";
}
DynamicJsonDocument doc(1024);
String payload;
doc["Name"]=name;
doc["Latitude"]=lat;
doc["Longitude"]=lon;
doc["Icon"]=icon;
doc["FillPercent"]=dist;
serializeJson(doc, payload);
delay(3000);
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
} else {
    Serial.println("Publish FAILED");
}
}

```

CONNECTIONS:



WOKWI LINK:

<https://wokwi.com/projects/346590330080985684>

OUTPUT:

The screenshot displays the Wokwi web interface for a simulation. On the left, the 'sketch.ino' file contains the following code:

```
1 #include <WiFi.h>
2 #include <PubSubClient.h>
3 #include <ArduinoJson.h>
4
5 WiFiClient wificlient;
6
7 #define ORG "fvdupc"
8 #define DEVICE_TYPE "abcd"
9 #define DEVICE_ID "rasp"
10 #define TOKEN "12345678"
11 #define speed 0.034
12
13 char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
14 char publishTopic[] = "iot-2/evt/abcd_1/fmt/json";
15 char topic[] = "iot-2/cmd/home/fmt/String";
16 char authMethod[] = "use-token-auth";
17 char token[] = TOKEN;
18 char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
19 PubSubClient client(server, 1883, wificlient);
20 void publishData();
21
22 const int trigpin=5;
23 const int echopin=18;
24 String command;
25 String data="";
26 String lat="14.167589";
27 String lon="80.248510";
28 String name="point2";
29 String icon="";
30
31 long duration;
32 int dist;
33
34 void setup()
35 {
```

The simulation area on the right shows an ESP32 microcontroller connected to an HC-SR04 ultrasonic sensor. The sensor's VCC pin is connected to the ESP32's 5V pin, GND to GND, and the Trig pin to pin 5. The Echo pin is connected to pin 18. The simulation is running, and the output console shows the following messages:

```
subscribe to cmd OK

Sending payload:
{"Name":"point2","Latitude":"14.167589","Longitude":"80.248510","Icon":"fa-trash-o","FillPercent":0}
Publish OK
```