```
In [1]: import pandas as pd
    import numpy as np
    import matplotlib.pyplot as plt
    import skimage
    %matplotlib inline
```

```
In [2]: x = np.arange(-300, 300)
y = 0.5*x + 50

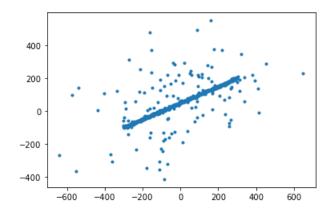
data = np.column_stack([x,y])

data_faulty = np.array(40* [(200.0, -130)])
data_faulty += 4* np.random.normal(size = data_faulty.shape)
data_faulty = data[:data_faulty.shape[0]]

data_noise = np.random.normal(size = data.shape)

data += 2* data_noise
data[::2] += 3* data_noise[::2]
data[::5] += 150* data_noise[::5]
plt.plot(data[:,0], data [:,1], '.')
```

Out[2]: [<matplotlib.lines.Line2D at 0x1ebdb59d6a0>]



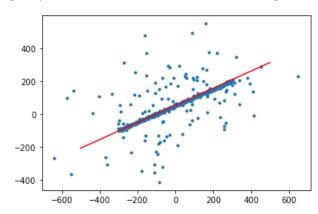
In [3]: #import LineModelND(Total least squares estimator for N-dimensional lines) and ransac
from skimage.measure import LineModelND, ransac

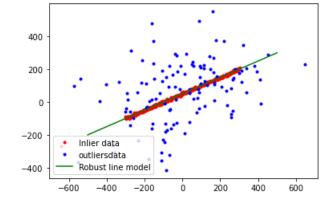
```
In [4]: # Starting point
    nd_model = LineModelND()
    nd_model.estimate(data)
    # Instead of m and c, it parameterizes the line by origin and direction --- much safer when dealing w
    nd_model.params
```

```
Out[4]: (array([-1.19627653, 52.48406056]), array([0.88671635, 0.46231387]))
```

```
In [5]: #draw a Line
x1 = np.arange(-500,500)
orig, direc = nd_model.params
plt.plot(data[:,0], data[:,1], '.')
plt.plot(x1, nd_model.predict_y(x1), 'r-')
```

Out[5]: [<matplotlib.lines.Line2D at 0x1ebdd534dc0>]





In []: