## CSIE 5432 — Machine Learning Foundations

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**Student Number:** r08922a27 **Due Date:** November 20 2020, 13:00

# Linear Regression

1. Answer: [b]

代入  $\sigma = 0.1, d = 11,$ 則  $\mathbb{E}_{\mathcal{D}}[E_{in}(\mathbf{W_{lin}})] = 0.01 \cdot (1 - \frac{12}{N}),$  代入不同 N 可得下列表格:

N	25	30	35	40	45
$\mathbb{E}_{\mathcal{D}}[E_{in}(\mathbf{W_{lin}})]$	0.0052	0.006	0.0066	0.007	0.0073

N=30 為最小值使得  $\mathbb{E}_{\mathcal{D}}[E_{in}(\mathbf{W}_{lin})]$  不少於 0.006。

### 2. Answer: [a]

根據 Lecture 9 slides 第 10 頁,  $X^TXw = X^T\mathbf{y}$ , 當  $X^TXw = 0$  時,  $w^TX^TXw = \|Xw\|^2 = 0$ , 則 Xw = 0 必成立,得  $\mathcal{N}(X^TX) \subseteq \mathcal{N}(X^T)$ ; 當 Xw = 0 時,  $X^T(Xw) = X^T(0) = 0$ , 則  $X^TXw = 0$  必成立,得  $\mathcal{N}(X^T) \subseteq \mathcal{N}(X^TX)$ 。綜上所述,因為  $\mathcal{N}(X^T) = \mathcal{N}(X^TX)$ ,因此可推至  $\mathcal{C}(X^T) = \mathcal{C}(X^TX)$ ,  $\mathcal{C}(X^T)$  的任一向量  $\mathbf{X}^T\mathbf{y}$ ,一定可以找到對應的 w 使得  $X^TXw = X^T\mathbf{y}$ ,當  $X^TX$  可逆時,表示 w 存在唯一解;當  $X^TX$  不可逆時,w 存在多組解。

根據 Lecture 9 slides 第 14 頁, 當 w 有解時,  $E_{in}(\mathbf{w}) = \frac{1}{N} ||(I - XX^{\dagger})\mathbf{y}|| \neq 0$ , 故僅有「There exists at least one solution for the normal equation.」敘述正確。

### 3. Answer: [c]

H 為 X 的 column space 的投影矩陣,  $H\mathbf{y}$  為 X 的 column space 中離  $\mathbf{y}$  最近的點, [a], [b] 和 [d] 僅對 column 做 scaling 的運算, 展開的空間是一樣的, 不影響  $\mathbf{y}$  投影到 column space 的結

果。令 
$$X = \begin{pmatrix} 1 & 1 \\ 4 & 2 \\ 0 & 3 \end{pmatrix}$$
,經過 [c] 的運算得  $X' = \begin{pmatrix} 1 & 1 \\ 2 & 1 \\ 0 & 1 \end{pmatrix}$ , $X(X^TX)^{-1}X^T = \begin{pmatrix} \frac{13}{157} & \frac{36}{157} & \frac{24}{157} \\ \frac{157}{157} & \frac{153}{157} & \frac{15}{157} \\ \frac{24}{157} & \frac{7}{157} & \frac{153}{157} \end{pmatrix}$ , $X(X^TX)^{-1}X^T = \begin{pmatrix} \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{pmatrix}$ ,運算前後  $H$  結果不相同, [c] 會改變  $H$  結果。

## Likelihood and Maximum Likelihood

#### 4. Answer: [e]

(1) 因為 head 代表的  $y_n$  為 1, 另外一面是 0,  $\nu=\frac{1}{N}\sum_{n=1}^N y_n=\frac{1}{N}\sum_{n=1}^N [y_n=1]]$ ,  $\nu$  亦為 sample 到 head 的 fraction, 描述正確。

(2) 由題意得, likelihood(
$$\hat{\theta}$$
) =  $\prod_{n=1}^{N} \hat{\theta}^{y_n} (1 - \hat{\theta})^{1-y_n} = \hat{\theta}^{\sum_{n=1}^{N} y_n} (1 - \hat{\theta})^{N - \sum_{n=1}^{N} y_n}$ , 令  $L = \hat{\theta}^{\nu N} (1 - \hat{\theta})^{N - \nu N}$ , 對  $\hat{\theta}$  取微分為 0:

(3) 
$$\nabla E_{in}(\hat{y}) = \frac{d}{d\hat{y}} \{ \frac{1}{N} \sum_{n=1}^{N} (\hat{y} - y_n)^2 \} = \frac{1}{N} \sum_{n=1}^{N} 2 \cdot (\hat{y} - y_n) = 2 \cdot (\hat{y} - \nu) = 0, \ \text{得} \ \hat{y} = \nu,$$
 當  $\hat{y} = \nu$  時,  $E_{in}(\hat{y})$  為極小值, 描述正確。

(4) 由 (3) 得 
$$\nabla E_{in}(\hat{y}) = 2 \cdot (\hat{y} - \nu)$$
, 代入  $\hat{y} = 0$ ,  $\nabla E_{in}(\hat{y}) = -2\nu$ ,  $2\nu = -\nabla E_{in}(\hat{y})$ , 描述正確。

### 5. Answer: [a]

任意  $y_n$  的機率為  $P(y_n|\theta)=\frac{1}{\theta}$ , 因為  $\theta$  未知, 令  $\hat{\theta}$  為估計  $\theta$  的隨機變數。根據 likelihood 定義, N 筆 sample 形成的 likelihood 為  $\prod_{n=1}^N P(y_n|\hat{\theta})=(\frac{1}{\hat{\theta}})^N$ 。

## Gradient and Stochastic Gradient Descent

6. Answer: [b]

在 point-wise 的情況, 參數更新式可寫作  $\mathbf{w_{t+1}} = \mathbf{w_t} + \eta \cdot [[y_n \neq \text{sign}(\mathbf{w_t}^T \mathbf{x_n})]]y_n \mathbf{x_n}$ , 根據 Lecture 10 slides 第 22 頁,  $\nabla err(\mathbf{w}, \mathbf{x}, y) = -[[y_n \neq \text{sign}(\mathbf{w_t}^T \mathbf{x_n})]]y_n \mathbf{x_n}$ 。  $\max(0, -y\mathbf{w}^T\mathbf{x})$  在  $y = \text{sign}(\mathbf{w}^T\mathbf{x})$  的情況, 數值為 0, 則  $\nabla err(\mathbf{w}, \mathbf{x}, y) = 0$ ; 在  $y \neq \text{sign}(\mathbf{w}^T\mathbf{x})$  的情況, 數值為  $-y\mathbf{w}^T\mathbf{x}$ , 則  $\nabla err(\mathbf{w}, \mathbf{x}, y) = \frac{d}{d\mathbf{w}}\{-y\mathbf{w}^T\mathbf{x}\} = -y\frac{d}{d\mathbf{w}}\{\mathbf{w}^T\mathbf{x}\} = -y\mathbf{x}$ 。 綜上所述,  $\nabla err(\mathbf{w}, \mathbf{x}, y) = -[[y_n \neq \text{sign}(\mathbf{w_t}^T\mathbf{x_n})]]y_n \mathbf{x_n} = \nabla \max(0, -y\mathbf{w}^T\mathbf{x})$ , 因為微分結果相同,  $\max(0, -y\mathbf{w}^T\mathbf{x})$  可作為  $err(\mathbf{w}, \mathbf{x}, y)$ 。

7. Answer: [a]

$$-\nabla err_{exp}(\mathbf{w}, \mathbf{x_n}, y_n) = -\frac{d}{d\mathbf{w}} \{ \exp(-y_n \mathbf{w}^T \mathbf{x_n}) \} = -\exp(-y_n \mathbf{w}^T \mathbf{x_n}) \frac{d}{d\mathbf{w}} \{ -y_n \mathbf{w}^T \mathbf{x_n} \}$$
$$= \exp(-y_n \mathbf{w}^T \mathbf{x_n}) y_n \frac{d}{d\mathbf{w}} \{ \mathbf{w}^T \mathbf{x_n} \} = y_n \mathbf{x_n} \exp(-y_n \mathbf{w}^T \mathbf{x_n})$$

8. Answer: [b]

代入 
$$\mathbf{w} = \mathbf{u} + \mathbf{v}$$
,  $E(\mathbf{w}) = E(\mathbf{u} + \mathbf{v}) \approx E(\mathbf{u}) + \mathbf{b}_E(\mathbf{u})^T \mathbf{v} + \frac{1}{2} \mathbf{v}^T \mathbf{A}_E(\mathbf{u}) \mathbf{v}$ 

$$\frac{\partial}{\partial \mathbf{v}} \{ E(\mathbf{u}) + \mathbf{b}_E(\mathbf{u})^T \mathbf{v} + \frac{1}{2} \mathbf{v}^T \mathbf{A}_E(\mathbf{u}) \mathbf{v} \} = 0 + \frac{\partial}{\partial \mathbf{v}} \{ \mathbf{b}_E(\mathbf{u})^T \mathbf{v} \} + \frac{\partial}{\partial \mathbf{v}} \{ \frac{1}{2} \mathbf{v}^T (\mathbf{A}_E(\mathbf{u}) \mathbf{v}) \}$$

$$= \mathbf{b}_E(\mathbf{u}) + \frac{1}{2} (\frac{\partial}{\partial \mathbf{v}} \{ \mathbf{v} \} \mathbf{A}_E(\mathbf{u}) \mathbf{v} + \frac{\partial}{\partial \mathbf{v}} \{ \mathbf{A}_E(\mathbf{u}) \mathbf{v} \} \mathbf{v} )$$

$$= \mathbf{b}_E(\mathbf{u}) + \frac{1}{2} (\mathbf{A}_E(\mathbf{u}) + \mathbf{A}_E(\mathbf{u})^T) \mathbf{v},$$

$$\mathbf{A}_E(\mathbf{u}) \stackrel{\text{height}}{=} \mathbf{A}_E(\mathbf{u}) + \mathbf{A}_E(\mathbf{u}) \stackrel{\text{height}}{=} \mathbf{A}_E(\mathbf{u}) + \mathbf{A}_E(\mathbf{u}) \stackrel{\text{height}}{=} \mathbf{A}_E(\mathbf{u}) + \mathbf{A}_E(\mathbf{u}) \mathbf{v}$$

當 
$$\nabla_{\mathbf{v}} E(\mathbf{w}) = 0$$
 時,  $-\mathbf{b}_E(\mathbf{u}) = \mathbf{A}_E(\mathbf{u})\mathbf{v}$ , 得  $\mathbf{v} = -\mathbf{A}_E(\mathbf{u})^{-1}\mathbf{b}_E(\mathbf{u})$  °

9. Answer: [b]

$$\nabla_{\mathbf{w_t}} E(\mathbf{w_t}) \approx \frac{\partial}{\partial \mathbf{w_t}} \{ E(\mathbf{u}) + \mathbf{b}_E(\mathbf{u})^T \mathbf{w_t} - \mathbf{b}_E(\mathbf{u})^T \mathbf{v} + \frac{1}{2} [\mathbf{w_t}^T \mathbf{A}_E(\mathbf{u}) \mathbf{w_t} + \mathbf{v}^T \mathbf{A}_E(\mathbf{u}) \mathbf{v}] \}$$

$$= \frac{\partial}{\partial \mathbf{w_t}} \{ \mathbf{b}_E(\mathbf{u})^T \mathbf{w_t} \} + \frac{\partial}{\partial \mathbf{w_t}} \{ \frac{1}{2} \mathbf{w_t}^T \mathbf{A}_E(\mathbf{u}) \mathbf{w_t} \} , \text{ 微分過程和上題一樣, 可得下面結果,}$$

$$= \mathbf{b}_E(\mathbf{u}) + \mathbf{A}_E(\mathbf{u}) \mathbf{w_t}$$

$$\mathbf{A}_E(\mathbf{w_t}) = \nabla_{\mathbf{w_t}}[\nabla_{\mathbf{w_t}}E(\mathbf{w_t})] \approx \frac{\partial}{\partial \mathbf{w_t}}\{\mathbf{b}_E(\mathbf{u}) + \mathbf{A}_E(\mathbf{u})\mathbf{w_t}\} = 0 + \mathbf{A}_E(\mathbf{u})^T = \mathbf{A}_E(\mathbf{u})$$
[: 對稱性]

得  $\mathbf{A}_E(\mathbf{w_t}) = \mathbf{A}_E(\mathbf{u})$ , 其中  $\mathbf{u}$  為更新前的參數點,  $\mathbf{u} = \mathbf{w_{t-1}}$ , 則  $\mathbf{A}_E(\mathbf{w_t}) = \mathbf{A}_E(\mathbf{w_{t-1}})$ 。由上式可知每次參數更新時  $\mathbf{A}_E$  不會被參數變化而影響。

求取 linear regression 的  $\mathbf{A}_E$  無需考慮時間點, 任一參數  $\mathbf{w}$  求得的  $\mathbf{A}_E(\mathbf{w})$  和 Newton's method 得到的  $\mathbf{A}_E(\mathbf{w_t})$  相同。根據 Lecture 9 slides 的第 9 頁,  $\nabla_w E_{in}(\mathbf{w}) = \frac{2}{N}(X^TX\mathbf{w} - X^T\mathbf{y})$ ,  $\mathbf{A}_E(\mathbf{w}) = \nabla_w [\nabla_w E_{in}(\mathbf{w})] = \frac{d}{d\mathbf{w}} \{\frac{2}{N}(X^TX\mathbf{w} - X^T\mathbf{y})\} = \frac{2}{N}\frac{d}{d\mathbf{w}} \{((X^TX)\mathbf{w}) + 0 = \frac{2}{N}(X^TX)^T = \frac{2}{N}X^TX$ 

## **Multinomial Logistic Regression**

10. Answer: [b]

$$\frac{\partial}{\partial W_{ik}} \{err(W, \mathbf{x}, y)\} = \frac{\partial}{\partial W_{ik}} \{-\llbracket y = k \rrbracket \ln h_k(\mathbf{x})\} = -\llbracket y = k \rrbracket \frac{\partial}{\partial W_{ik}} \{\mathbf{w_k}^T \mathbf{x} - ln(\sum_{i=1}^K \exp(\mathbf{w_i}^T \mathbf{x}))\} 
= -(\llbracket y = k \rrbracket x_i - \frac{1}{\sum_{i=1}^K \exp(\mathbf{w_i}^T \mathbf{x})} \frac{\partial}{\partial W_{ik}} \{\sum_{i=1}^K \exp(\mathbf{w_i}^T \mathbf{x})\}) 
= -(\llbracket y = k \rrbracket x_i - \frac{\exp(\mathbf{w_k}^T \mathbf{x})}{\sum_{i=1}^K \exp(\mathbf{w_i}^T \mathbf{x})} x_i) = (h_k(\mathbf{x}) - \llbracket y = k \rrbracket) x_i$$

11. Answer: [e]

當 
$$y_n = 2, y'_n = +1$$
 時,  $h_2(\mathbf{x_n}) = \frac{\exp(\mathbf{w_2}^{*T}\mathbf{x})}{\exp(\mathbf{w_1}^{*T}\mathbf{x}) + \exp(\mathbf{w_2}^{*T}\mathbf{x})} = \frac{1}{\exp(-(\mathbf{w_2}^* - \mathbf{w_1}^*)^T\mathbf{x}) + 1};$   
當  $y_n = 1, y'_n = -1$  時,  $h_1(\mathbf{x_n}) = \frac{\exp(\mathbf{w_1}^{*T}\mathbf{x})}{\exp(\mathbf{w_1}^{*T}\mathbf{x}) + \exp(\mathbf{w_2}^{*T}\mathbf{x})} = \frac{\exp(-(\mathbf{w_2}^* - \mathbf{w_1}^*)^T\mathbf{x})}{\exp(-(\mathbf{w_2}^* - \mathbf{w_1}^*)^T\mathbf{x}) + 1} = 1 - \frac{1}{\exp(-(\mathbf{w_2}^* - \mathbf{w_1}^*)^T\mathbf{x}) + 1} = 1 - h_2(\mathbf{x_n})$ 

令  $\mathbf{w_2}^* - \mathbf{w_1}^*$  為 binary logistic regression 之解,  $\nabla E_{in}(\mathbf{w_2}^* - \mathbf{w_1}^*) = \frac{1}{N} \sum_{n=1}^{N} \theta(-y_n(\mathbf{w_2}^* - \mathbf{w_1}^*)^T \mathbf{x_n})(-y_n \mathbf{x_n})$  °

當 
$$N=1, y'_n=+1$$
 時,

$$\nabla E_{in}(\mathbf{w_2}^* - \mathbf{w_1}^*) = \theta(-(\mathbf{w_2}^* - \mathbf{w_1}^*)^T \mathbf{x_n})(-\mathbf{x_n}) = h_1(\mathbf{x_n})(-\mathbf{x_n})|_{\mathbf{w_1}^*, \mathbf{w_2}^*} \circ$$
在  $y'_n = +1$  的條件下,  $\mathbf{w_1}^*$  為最佳解, 使得  $h_1(\mathbf{x_n}) = 0$ , 則  $\nabla E_{in}(\mathbf{w_2}^* - \mathbf{w_1}^*) = 0 \cdot (-\mathbf{x_n}) = 0 \circ$ 

當 
$$N=1, y'_n=-1$$
 時,

$$\nabla E_{in}(\mathbf{w_2}^* - \mathbf{w_1}^*) = \theta((\mathbf{w_2}^* - \mathbf{w_1}^*)^T \mathbf{x_n})(\mathbf{x_n}) = h_2(\mathbf{x_n})(\mathbf{x_n})|_{\mathbf{w_1}^*, \mathbf{w_2}^*} \circ$$
  
在  $y'_n = -1$  的條件下,  $\mathbf{w_2}^*$  為最佳解, 使得  $h_2(\mathbf{x_n}) = 0$ , 則  $\nabla E_{in}(\mathbf{w_2}^* - \mathbf{w_1}^*) = 0 \cdot (\mathbf{x_n}) = 0 \circ$ 

綜上所述, 在所有  $y'_n$  的情況下,  $\nabla E_{in}(\mathbf{w_2}^* - \mathbf{w_1}^*) = \frac{1}{N} \sum_{n=1}^N 0 = 0$ , 得  $\mathbf{w_2}^* - \mathbf{w_1}^*$  為 binary logistic regression 之最佳解。

## **Nonlinear Transformation**

#### 12. Answer: [e]

choice	[a]	[b]	[c]	[d]	[e]
$err_{0/1}$	0.1429	0.1429	0.4286	0.5714	0

#### 13. Answer: [b]

令  $\mathcal{H}_k$  的參數為  $(w_0, w_k)$ , boundary 等式為  $w_0 + w_k \cdot x_k = 0$ , 分類的門檻值為  $x_k = -\frac{w_0}{w_k}$ , 若資料有 N 筆, 在第 k 維度有 N-1 個間隔可以插入,等價於第 k 維度上 Decision Stump 的 hypothesis, 不討論 全為 positive/negative 的 2 種情況,間隔數量 N-1 個以及考慮對稱性數量為兩倍,得 dichotomy 的數量最多可以有 2(N-1) 個,令  $\bigcup_{k=1}^d \mathcal{H}_k$  的 growth function 為  $m_{\mathcal{H}}(N)$ , 如果 d 個維度的  $\bigcup_{k=1}^d \mathcal{H}_k$  的 交集只有全為 positive/negative 的 2 種情況,則 dichotomy 的數量為  $2(N-1) \cdot d + 2$ ,若有其他交集的可能 dichotomy 的數量只會變小,得  $m_{\mathcal{H}}(N) \leq 2(N-1) \cdot d + 2$ 。

選項大小排序為  $2(d^2+1) \ge 2(d\log_2 d+1) \ge 2(d+1) \ge 2(\log_2 d+1) \ge 2(\log_2 \log_2 d+1)$ , 若右方為 VC upper bound, 左方必為更寬鬆的 VC upper bound, 最右邊是 VC upper bound 的選項即為 tightest upper bound。

當  $N = 2(\log_2 \log_2 d + 1)$  時:

每個維度至少存在一邊界可以得到 2 種 dichotomy, 則 d 個維度至少會有 2d 種 dichotomy, 考慮全為 positive/negative 的 2 種情況,  $m_{\mathcal{H}}(N) \geq 2d+2 > 2d$ , 可以確定  $d_{vc} > \log_2(2d)$ 。若  $2(\log_2\log_2d+1) < \log_2(2d)$  恆成立, 代表  $2(\log_2\log_2d+1)$  必小於  $d_{vc}$ 。

 $2(\log_2\log_2d+1)<\log_2(2d), 2\log_2\log_2d-\log_2d+1<0, \ \diamondsuit t=\log_2d,$ 

$$\frac{d}{dt}\{2\log_2 t - t + 1\} = \frac{1}{\ln 2} \cdot (\frac{2}{t} - 1), \ \diamondsuit \ \frac{1}{\ln 2} \cdot (\frac{2}{t} - 1) \le 0, \ \varnothing \ \frac{2}{t} - 1 \le 0,$$

得  $t \ge 2$  時,  $d \ge 4$ ,  $2\log_2\log_2 d - \log_2 d + 1$  為嚴格遞減,

因此, 在  $d \ge 5$  時,  $2\log_2\log_2 d - \log_2 d + 1 < 0$  恆成立。

在  $d \ge 5$  時,  $2\log_2\log_2 d - \log_2 d + 1 < 0$  恆成立, 即  $2(\log_2\log_2 d + 1) < d_{vc}$ , 得  $2(\log_2\log_2 d + 1)$  並非 VC upper bound  $\circ$ 

當  $N = 2(\log_2 d + 1)$  時:

根據 Lecture 7 slides 第 4 頁, 若 N 為  $d_v c$  的 upper bound, 則必符合  $m_{\mathcal{H}}(N) \leq 2^N$ 。

$$\begin{cases} 2^N = 2^{2(\log_2 d + 1)} = 4d^2 \end{cases}$$

$$\int m_{\mathcal{H}}(N) = 2(2(\log_2 d + 1) - 1) \cdot d + 2 = 4(\log_2 d) \cdot d + 2d + 2$$

$$4(\log_2 d) \cdot d + 2d + 2 \le 4d^2$$
,  $\text{ } \# 2(\log_2 d) \cdot d + d - 2d^2 + 1 \le 0$ 

由題意, 當
$$d \ge 4$$
 時,  $\log_2 d \le \frac{d}{2}$ , 則  $2(\log_2 d) \cdot d + d - 2d^2 + 1 \le d - d^2 + 1$ 

# Experiment

程式碼實作細節如下,可以透過 parser 的 --tra\_path/--tst\_path 設置訓練資料和測試資料的路徑 python code.py --tra\_path hw3\_train.dat --tst\_path hw3\_test.dat

```
import numpy as np
import random
import argparse
'''Define Function'''
def get_data(path, bias=1.0, transform=None):
    X = []
    for x in open(path, 'r'):
        x = x.strip().split('\t')
        x = [float(v) for v in x]
        X.append([bias] + x)
    X = np.array(X)
    X, Y = np.array(X[:, :-1]), np.array(X[:, -1])
    if transform is not None:
        X = transform(X)
    return X, Y
def get_wLIN(X, Y):
    X_plus = np.matmul(np.linalg.inv(np.matmul(X.T, X)), X.T)
    return np.matmul(X_plus, Y)
def sigmoid(s):
    return 1 / (1 + np.exp(-s))
def sign(s):
    s = np.sign(s)
    s[s == 0] = -1
    return s
def Q_transform(X, Q=3):
    return np.hstack([X]+[X[:, 1:]**q for q in range(2, Q+1)])
def err(w, X, Y, mode='sqr'):
    Y_pred = np.matmul(X, w)
```

```
if mode == 'sqr':
        return ((Y_pred - Y)**2).mean()
    elif mode == 'ce':
        return -np.log(sigmoid(Y * Y_pred)).mean()
    elif mode == '0/1':
        Y_pred = sign(Y_pred)
        return (Y.astype(int) != Y_pred.astype(int)).mean()
def SGD(X, Y, lr, w_init=None, step_num=1000000, mode='sqr'):
    def random_pick(X, Y):
        idx = random.randint(0, X.shape[0] - 1)
        return X[idx:idx+1], Y[idx:idx+1]
    def grad_func(w, X, Y, mode):
        batch_size = X.shape[0]
        if mode == 'sqr':
            return -(2 / batch_size) * np.matmul(X.T, np.matmul(X, w) - Y)
        elif mode == 'ce':
            return np.mean(sigmoid(-Y * np.matmul(X, w)).reshape(-1, 1) * (Y.reshape(-1, 1) * X), axi
    def update_w(w, x, y, lr):
        return w + lr * grad_func(w, x, y, mode)
    if mode == 'sqr':
        wLIN = get_wLIN(X, Y)
        E_in_sqr_LIN = err(wLIN, X, Y, mode='sqr')
    # initialization
   step = 0
   w = np.zeros(X.shape[1:]) if w_init is None else w_init
    # training
    while step < step_num:
        x, y = random_pick(X, Y)
        w = update_w(w, x, y, lr)
        step += 1
        # check early stopping
        if mode == 'sqr':
            E_in_sqr = err(w, X, Y, mode='sqr')
            if E_in_sqr <= 1.01 * E_in_sqr_LIN:</pre>
   return w, step
def main():
    '''Parsing'''
   parser = argparse.ArgumentParser(
        description='Argument Parser for MLF HW3.')
```

```
parser.add_argument('--tra_path', default='hw3_train.dat')
parser.add_argument('--tst_path', default='hw3_test.dat')
args = parser.parse_args()
# load data
X_tra, Y_tra = get_data(args.tra_path)
X_tst, Y_tst = get_data(args.tst_path)
'''Answer questions'''
print('RUNNING Q14...')
wLIN = get_wLIN(X_tra, Y_tra)
print('Answer of Q14 : {:.4f}\n'.format(
    err(wLIN, X_tra, Y_tra, mode='sqr')))
print('RUNNING Q15...')
update_num_list = []
for _ in range(1000):
    _, update_num = SGD(X_tra, Y_tra, lr=0.001)
    update_num_list.append(update_num)
print('Answer of Q15 : {:.4f}\n'.format(np.mean(update_num_list)))
print('RUNNING Q16...')
ce_loss_list = []
for _ in range(1000):
    w, _ = SGD(X_tra, Y_tra, lr=0.001, step_num=500, mode='ce')
    ce_loss = err(w, X_tra, Y_tra, mode='ce')
    ce_loss_list.append(ce_loss)
print('Answer of Q16 : {:.4f}\n'.format(np.mean(ce_loss_list)))
print('RUNNING Q17...')
wLIN = get_wLIN(X_tra, Y_tra)
ce_loss_list = []
for _ in range(1000):
    w, _ = SGD(X_tra, Y_tra, lr=0.001, w_init=wLIN,
               step_num=500, mode='ce')
    ce_loss = err(w, X_tra, Y_tra, mode='ce')
    ce_loss_list.append(ce_loss)
print('Answer of Q17 : {:.4f}\n'.format(np.mean(ce_loss_list)))
print('RUNNING Q18...')
print('Answer of Q18 : {:.4f}\n'.format(
    abs(err(wLIN, X_tst, Y_tst, mode='0/1') - err(wLIN, X_tra, Y_tra, mode='0/1'))))
print('RUNNING Q19...')
X_tra_Q = Q_transform(X_tra, Q=3)
X_{tst_Q} = Q_{transform}(X_{tst_Q} = 3)
wLIN_Q = get_wLIN(X_tra_Q, Y_tra)
print('Answer of Q19 : {:.4f}\n'.format(abs(
    err(wLIN_Q, X_tst_Q, Y_tst, mode='0/1') - err(wLIN_Q, X_tra_Q, Y_tra, mode='0/1'))))
print('RUNNING Q20...')
```

```
X_tra_Q = Q_transform(X_tra, Q=10)
     X_tst_Q = Q_transform(X_tst, Q=10)
     wLIN_Q = get_wLIN(X_tra_Q, Y_tra)
     print('Answer of Q20 : {:.4f}\n'.format(abs(
           \texttt{err}(\texttt{wLIN\_Q}, \ \texttt{X\_tst\_Q}, \ \texttt{Y\_tst}, \ \texttt{mode='0/1'}) \ - \ \texttt{err}(\texttt{wLIN\_Q}, \ \texttt{X\_tra\_Q}, \ \texttt{Y\_tra}, \ \texttt{mode='0/1'}))))
if __name__ == "__main__":
     main()
                                                       17. [b]
                                                                                                         20. [d]
    14. [d]
                     15. [c]
                                      16. [c]
                                                                       18. [a]
                                                                                        19. [b]
    0.6053
                     1889.73
                                      0.5691
                                                       0.5028
                                                                       0.3227
                                                                                        0.3737
                                                                                                         0.4467
```