Context switch

- >LabO feedback
- >Recap interrupt
- > Context switch

Game submits

- total: 25 submits
- penalty
 - timing penalty
 - naming penalty 10%
 - only your student number
 - no Chinese or sepcial characters
 - upload to the wrong directory 10%
- plagiarism is found
 - no tolerance

Due Date & Hard Deadline

- Submits before Due Date will not receive timing penalty.
- Submits after Due Date will receive
 - 50% penalty for the first day
 - 60% penalty for the second day
 - 70% penalty for the third day
- Submits after Hard Deadline will receive 80% penalty.

LabO feedback

Congratulations!

- Most of you have finished the first game in your life!
 - excited? fulfill?
- share them with your friends
 - http://cslab.nju.edu.cn/ics/index.php/Game

Code smell

```
CFLAGS = -m32 -static -MD -std=gnu89 -ggdb \
-fno-builtin -fno-stack-protector -fno-omit-frame-pointer \
- Wall -Werror -O2 -I./include
+ -Wall -O2 -I./include
```

- Why use assert() and Werror?
 - capture faults & errors as soon as possible

More questions

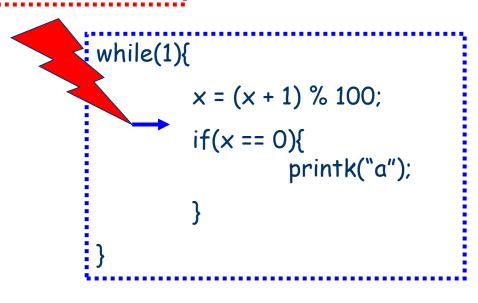
- What are GDT, GDTR, segment descriptor, segment selector, IDT, IDTR, gate descriptor?
- How is address translation performed in LabO?
- What happen to your game when an interrupt comes?
- How does game.img generate?

• Recap - interrupt

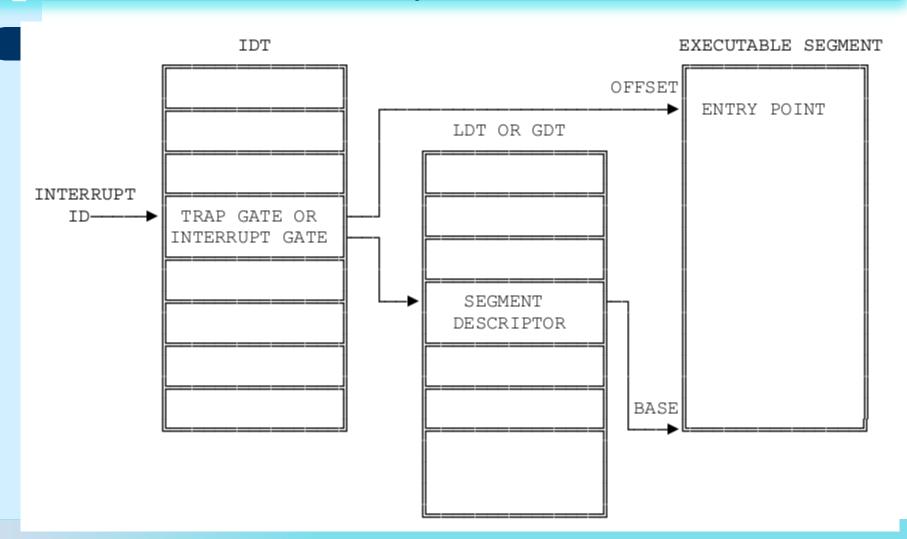
ESP 12

Example

time expires



Call the interrupt handler



12 EFLAGS CS EIP

ESP

```
中断处理函数会在IDT中为相应的中断/异常设置处理程序
 3 # 中断/异常的行为参见i386手册
  .globl vec0; vec0: pushl $0; jmp asm_do_irq
  .globl vec1; vec1: pushl $1; jmp asm do irq
  .globl vec2; vec2: pushl $2; jmp asm do irq
  .globl vec3; vec3: pushl $3; jmp asm_do_irq
  .globl vec4; vec4: pushl $4; jmp asm_do_irq
  .globl vec5; vec5: pushl $5; jmp asm do irq
  .globl vec6; vec6: pushl $6; jmp asm do irq
11 .globl vec7; vec7: pushl $7; jmp asm_do_irq
12 .globl vec8; vec8: pushl $8; jmp asm_do_irq
  .globl vec9; vec9: pushl $9; jmp asm do irq
  .globl vec10; vec10: pushl $10; jmp asm do irq
  .globl vec11; vec11: pushl $11; jmp asm do irq
16 .globl vec12; vec12: pushl $12; jmp asm_do_irq
17 .globl vec13; vec13: pushl $13; jmp asm do irq
18
  .globl irq0; irq0: pushl $1000; jmp asm do irq
20
21 .globl irq empty; irq empty: pushl $-1; jmp asm do irq
```

```
12
EFLAGS
CS
EIP
1000
```

```
ESP<sup>1</sup>
24 .globl asm_do_irq
25 .extern irq handle push all GPRs
26 asm do irq:
        pushal
27
28
        pushl %esp
29
                              # ???
        call irq_handle
30
        addl $4, %esp
31
32
33
        popal
        addl $4, %esp
34
        iret
```

```
24 .globl asm do irq
25 .extern irq_handle
26 asm do irq:
                  555
       pushal
27
28
       pushl %esp
29
                              ???
       call irq_handle
30
       addl $4, %esp
31
32
       popal
33
       addl $4, %esp
34
```

12	
EFLAGS	
C5	
EIP	
1000	
EAX	
EBX	
ECX EDX	
old ESP	
EBP	
FSI	
EDI	

```
24 .globl asm do irq
25 .extern irq handle
26 asm do irq:
       pushal
27
28
       pushl %esp
29
                             # ???
       call irq_handle
30
       addl $4, %esp
31
                             ESP.
32
       popal
33
       addl $4, %esp
34
```

12
EFLAGS
C5
EIP
1000
EAX
EBX
ECX
EDX
old_ESP
EBP
ESI
EDI
ESP???

```
18 void
19 irg handle(struct TrapFrame *tf) {
       if(tf->irq < 1000) {
21
           if(tf->irq == -1) {
               printk("%s, %d: Unhandled exception!\n",
23
                          FUNCTION , LINE );
24
25
           else {
               ፡ {
printk("%s, %d: Unexpected exception #%d!\n",
26
27
                          FUNCTION , LINE , tf->irq);
28
29
           assert(0);
30
31
32
       if (tf->irg == 1000) {
33
           do timer():
       } else if (tf->irq == 1001) {
34
           uint32 t code = in byte(0x60);
35
           uint32 t val = in \overline{b}yte(0x61);
36
           out byte(0x61, val | 0x80);
37
           out byte(0x61, val);
38
39
           printk("%s, %d: key code = %x\n",
40
41
                      FUNCTION , LINE , code);
           do keyboard(code);
42
43
       } else {
44
           assert(0);
45
46 }
```

12 **EFLAGS** CS. EIP 1000 EAX EBX ECX EDX old_ESP EBP ESI EDI ESP??? save EIP

```
24 .globl asm do irq
25 .extern irq handle
26 asm do irq:
       pushal
27
28
       pushl %esp
29
                             # ???
       call irq_handle
30
       addl $4, %esp
31
32
                       remove "ESP?
       popal
33
       addl $4, %esp
34
```

12
EFLAGS
C5
EIP
1000
EAX
EBX
ECX
EDX
old_ESP
EBP
ESI
EDI
ESP???

```
24 .globl asm do irq
25 .extern irq handle
26 asm do irq:
       pushal
27
28
       pushl %esp
29
                             # ???
       call irq_handle
30
       addl $4, %esp
31
32
                       restore GPRs
       popal
33
       addl $4, %esp
34
```

12	
EFLAGS	
C5	
EIP	
1000	
EAX	
EBX	
ECX	
EDX	
old_ESP	
EBP	
ESI	
FDT	

```
12
EFLAGS
CS
EIP
1000
```

```
ESP
24 .globl asm do irq
25 .extern irq handle
26 asm do irq:
       pushal
27
28
       pushl %esp
29
                            # ???
       call irq_handle
30
       addl $4, %esp
31
32
                       remove #irq
33
       popal
34
       addl $4, %esp
       iret
```

12 EFLAGS CS EIP

```
ESPI
```

```
24 .globl asm do irq
25 .extern irq handle
26 asm do irq:
        pushal
27
28
        pushl %esp
29
                             # ???
        call irq_handle
30
       addl $4, %esp
31
32
                       restore the
33
        popal
                      "current state"
       addl $4, %esp stored by hardware
34
        iret
```



we are back!!!

Context switch

Unitasking

- Only one program executing at a time.
 - occupies all resources (CPU, memory, I/O...)
- To let B run, A must exit first.

```
C:\>dir
Volume in drive C is FREEDOS C95
Volume Serial Number is 0E4F-19EB
Directory of C:\
                           08-26-04 6:23p
FDOS
                    <DIR>
                      435
                           08-26-04
                                    6:24p
BOOTSECT BIN
                      512 08-26-04
                                    6:23p
COMMAND
        COM
                   93,963 08-26-04
                                    6:24p
        SYS
CONFIG
                      801
                           08-26-04
                                    6:24p
FDOSBOOT BIN
                      512
                           08-26-04
                                     6:24p
KERNEL
        SYS
                   45,815
                           04-17-04
                                     9:19p
        6 file(s)
                         142,038 bytes
        1 dir(s)
                   1,064,517,632 bytes free
```

Multitasking

- Two or more programs can run "simultaneously"
 - resources are shared
- process: a running program
- fact: for unicore CPU, only one process can run at any point in time

Solution

- Allow different processes use CPU in turn.
- A running process may relinquish CPU
 - actively
 - wait for I/O
 - sleep
 - passively
 - time's up

Context switch

- the action of swapping the current process out of CPU, and let the next process run
 - save current state
 - choose another process
 - switch to the new process
 - restore current state
- Cuttent state is saved and restored by the interrupt procedure!!!
 - we do not need to manually implement them

Context switch (cont.)

• process #1 is running...

34
EFLAGS
CS
EIP
#irq

GPRs

p2.tf

12

Context switch (cont.)

- process #1 is running...
- time's up

34
EFLAGS
CS
EIP
#irq

GPRS

p2.tf

Oxfffffff

Context switch (cont.)

process #1 is running...

- time's up
- save current state

ESP

34
EFLAGS
CS
EIP
#irq

GPRs

12

EFLAGS

CS

EIP

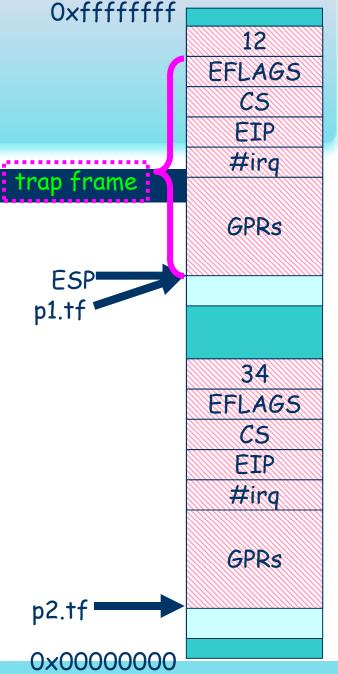
#irq

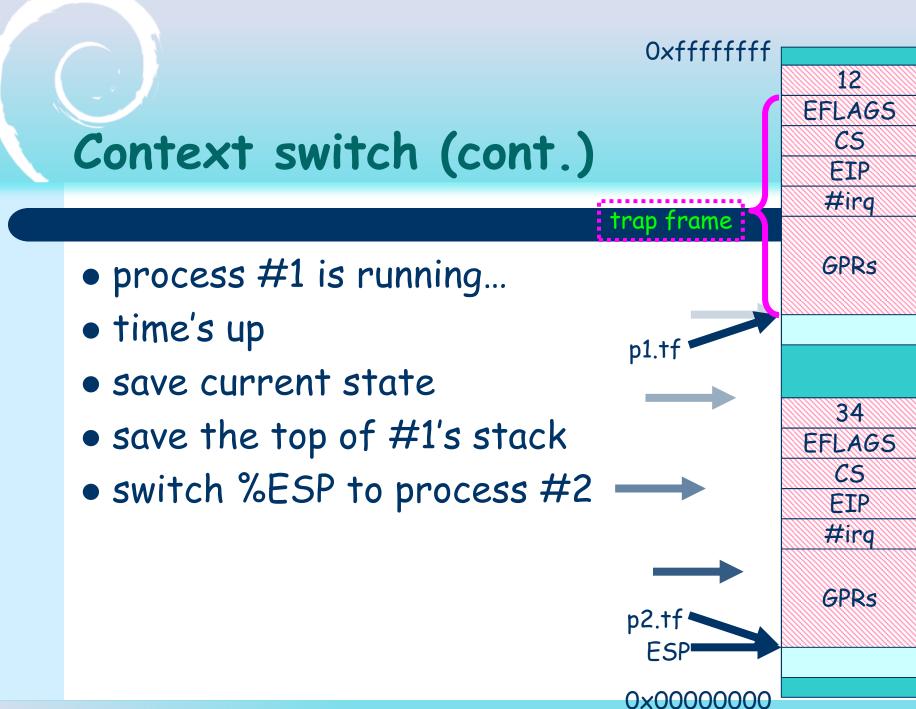
GPRS

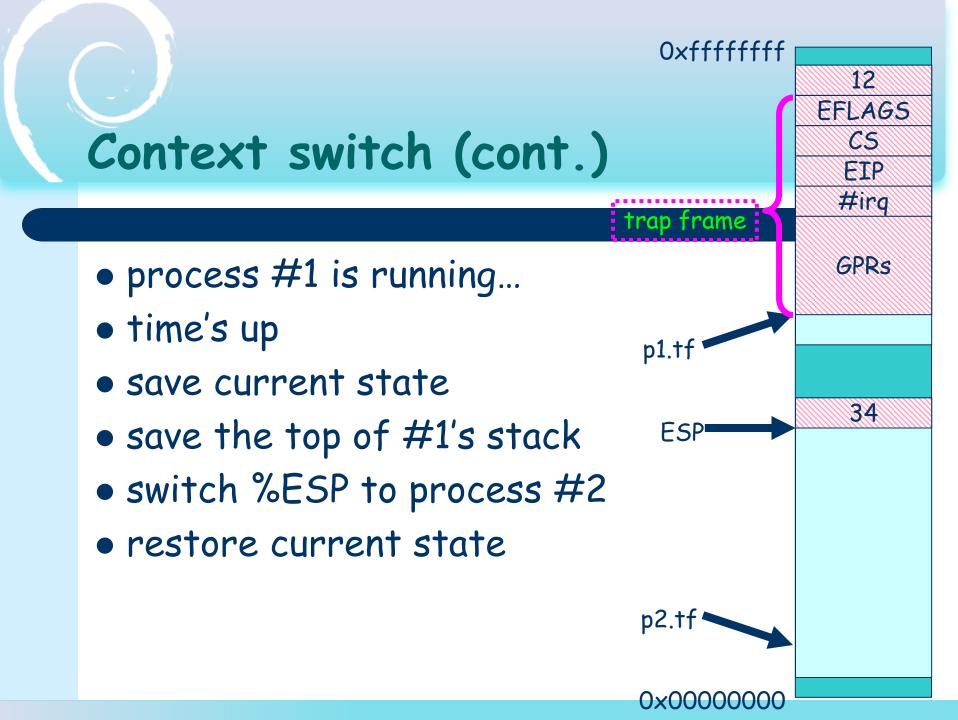
p2.tf

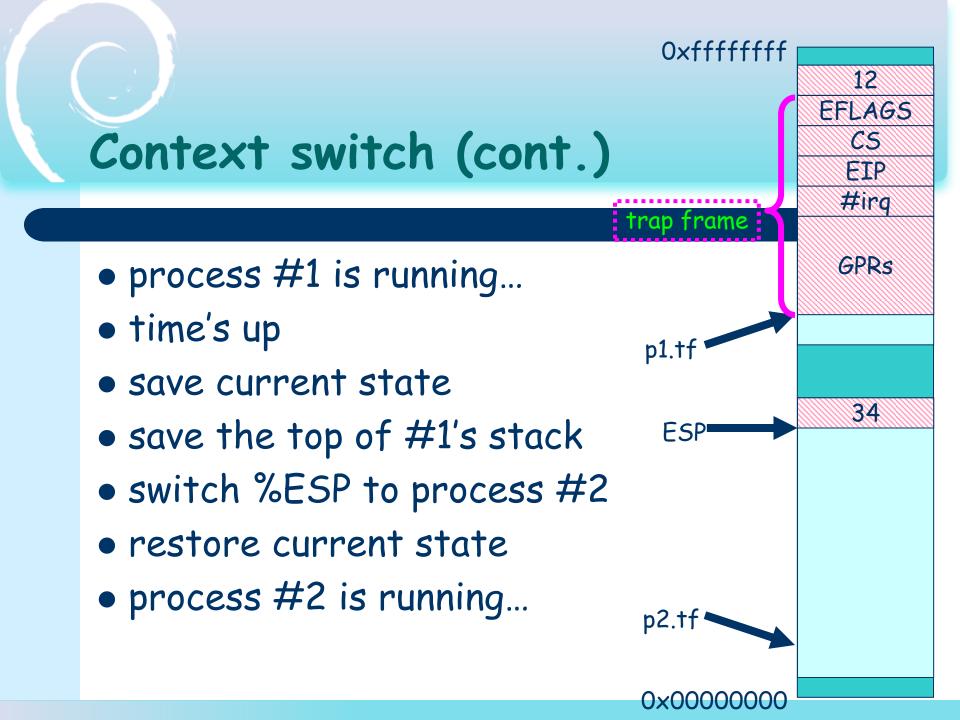
Context switch (cont.)

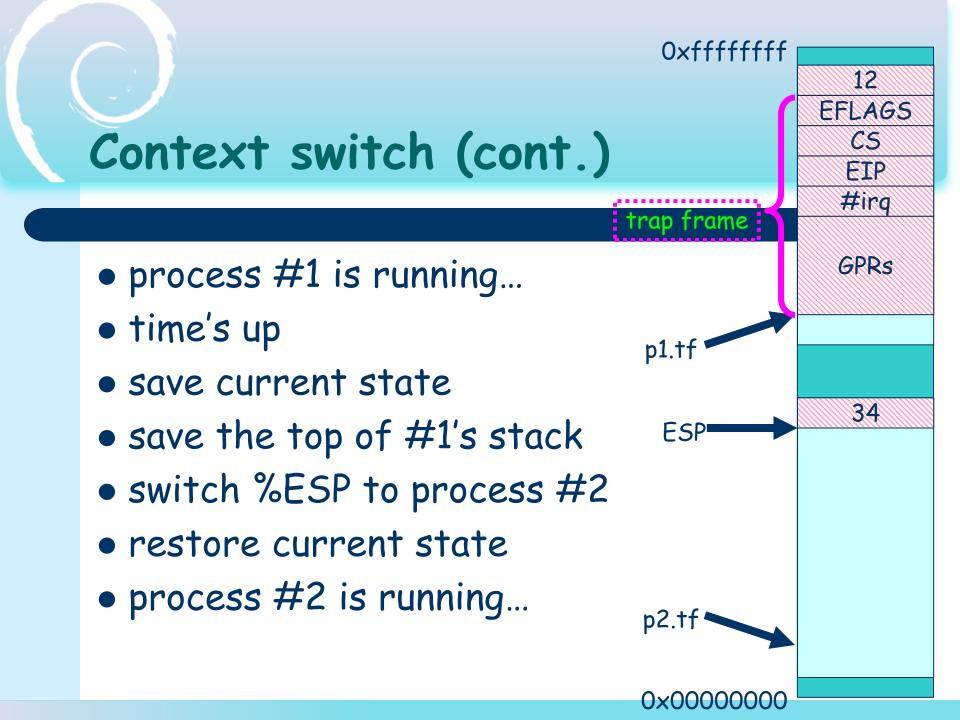
- process #1 is running...
- time's up
- save current state
- save the top of #1's stack











How to present a process?

- process control block
 - contains information for process management
- Currently, two members are sufficient.
 - stack
 - context information

```
#define KSTACK_SIZE 4096
struct PCB {
  void *tf;
  uint8_t kstack[KSTACK_SIZE];
} *current;
```

current points to the running process

Remaining problems

- How to choose the next process?
 - schedule policy
 - round robin, multi-level queue, ...
- How to switch to the new process?
 - hint: all information needed is in PCB
- How to create new process?

Process?

- A process has its own resource.
 - address space
 - code, data, stack
 - semaphore, file, ...
- By now we can only create kernel threads.
 - share codes and data with kernel
 - has it own stack
- Current information in PCB is not enough to identify different address spaces.
 - You will implement real processes in the future.

Create a kernel thread

- write a test function
- allocate a PCB
- initialize the PCB
 - stack
 - context information
 - you should initialize the "current state" correctly
 - pay attention to the IF bit of EFLAGS
- add the thread into the ready queue
 - feel free to use ListHead

Test functions

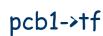
```
void A () {
   int x = 0;
   while(1) {
      if(x % 100000 == 0) {printk("a");}
      x ++;
   }
}
void B () {
   int x = 0;
   while(1) {
      if(x % 100000 == 0) {printk("b");}
      x ++;
   }
}
```



Initialize "current state"

trap frame

- GPRs = ?
 - GPRs.eps = ?
- #irq = ?
- EIP = ?
- CS = ?
- EFLAGS = ?
- new fields in Lab1
 - error code = ?
 - DS, ES, GS, FS = ?



34 EFLAGS CS

12

EFLAGS

CS

EIP

#irq

GPRS

EIP

#irq

GPRs

pcb2->tf ESP

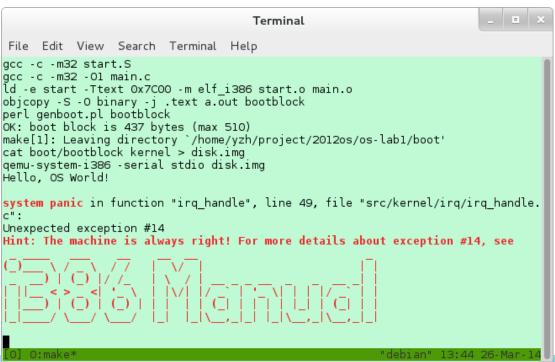
IDLE thread

- allocate a PCB to it
 - it will be scheduled when no other thread is ready

```
Terminal
File Edit View Search Terminal Help
43 +--- 2 lines: Set up interrupt and exception handlers,-----
      init_idt();
      /* Initialize the intel 8259 PIC. */
      init intr();
      /* Initialize processes. You should fill this. */
      init proc();
      welcome();
      sti();
      /* This context now becomes the idle process. */
      while (1) {
          wait intr();
61 }
~/project/2012os/os-lab1/src/kernel/main.c[1] [c] unix utf-8 Ln 46, Col 0/66\
```

NOTICE

- you can not return from a thread
 - or you will get an exception like





Summary

- context switch = interrupt driven stack switch
- new problems
 - thread management
 - create, destroy, sleep, wakeup
 - schedule
 - resource management
 - memory, files...
 - memory protection
 - critical area
 - IPC

Lab1 is partially out!

- the first stage
 - implement context switch
 - create 2 kernel thread to print "a" and "b" in turn
 - this is what Linux kernel did at the beginning
- Have fun!